

Linear splitting schemes for a nematic-isotropic model with anchoring effects

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Planning

- 1 Description of the fluid
 - The model
 - The variational formulation
- 2 Numerical schemes
 - Nematic-Isotropic. Well-Posedness of the Schemes
- 3 Numerical simulations

Complex Fluids

It will not be possible to decouple the interactions between microscopic and macroscopic effects.

- **Fluids with elastic properties.** They possess intermediate properties between solids and liquids.
Examples: liquid crystals, polymers (macromolecules), ...
- **Phase-field models.**
Examples: **multi-fluids (mixture of fluids)**, multi-phases (solidification), ...

These complex materials have practical utilities because the microstructure can be handled in order to produce good mechanical, optical or thermic properties.

thermotropic liquid crystals

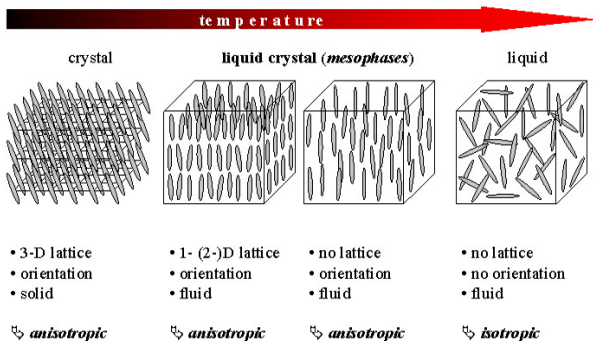


Figure : Types of Liquid Crystals

Types of Liquid Crystals

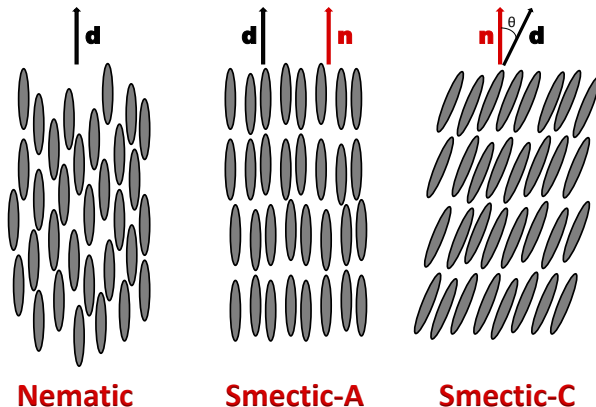
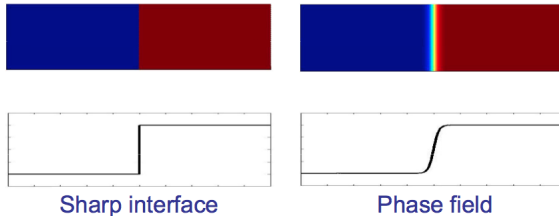


Figure : Types of Liquid Crystals

Phase field or Diffuse interface models



- **Sharp-interface** models
 - PDE for each phase + coupled interface conditions
 - Very difficult numerically (interface tracking)
- **Diffuse interface** Phase-field models
 - Phase function with distinct values (for instance +1 and -1) in each phase, with a smooth change in the interface (of width ε).
 - Surface motion depending on the physical energy dissipation.
 - When interface width ε tends to zero, recover a sharp interface model.

The variables of the problem

The following variable will take part in the description of the model:

- the solenoidal velocity $\mathbf{u}(t, \mathbf{x})$, $t \in (0, T)$, $\mathbf{x} \in \Omega \subset \mathbb{R}^3$
- the pressure of the fluid $p(t, \mathbf{x})$,
- the director field $\mathbf{d}(t, \mathbf{x})$, that represents the average orientation of the liquid crystal molecules,
- the function $c(t, \mathbf{x})$ localizing the two components along the domain $\Omega \subset \mathbb{R}^d$ ($d = 2$ or 3) filled by the mixture,

$$c(t, \mathbf{x}) = \begin{cases} -1 & \text{in the Newtonian Fluid part,} \\ \in (-1, 1) & \text{in the interface part,} \\ 1 & \text{in the Nematic Liquid Crystal part.} \end{cases}$$

The total energy

The total energy of the system is given by

$$E_{\text{tot}}(\mathbf{u}, \mathbf{d}, c) = E_{\text{kin}}(\mathbf{u}) + \lambda_{\text{mix}} E_{\text{mix}}(c) \\ + \lambda_{\text{nem}} E_{\text{nem}}(\mathbf{d}, c) + \lambda_{\text{anch}} E_{\text{anch}}(\mathbf{d}, c)$$

The energies

$$E_{\text{kin}}(\mathbf{u}) = \frac{1}{2} \int_{\Omega} |\mathbf{u}|^2 dx \quad \text{kinetic energy,}$$

$$E_{\text{mix}}(\mathbf{c}) = \int_{\Omega} \left(\frac{1}{2} |\nabla \mathbf{c}|^2 + F(\mathbf{c}) \right) dx \quad \text{mixing energy,}$$

$$E_{\text{nem}}(\mathbf{d}, \mathbf{c}) = \int_{\Omega} I(\mathbf{c}) \left(\frac{1}{2} |\nabla \mathbf{d}|^2 + G(\mathbf{d}) \right) dx \quad \text{elastic energy,}$$

The double-well potentials

They have their minimums (and consequently their equilibrium states) at ± 1 :

$$F(\mathbf{c}) = \frac{1}{4\epsilon^2} (\mathbf{c}^2 - 1)^2, \quad G(\mathbf{d}) = \frac{1}{4\eta^2} (|\mathbf{d}|^2 - 1)^2,$$

The anchoring effect

At the interface between the nematic and newtonian fluids, liquid crystals prefer to orientate following a certain direction (called as **easy direction**).

Three effects can be described:

- the **parallel case**, where all directions are easy,
- the **homeotropic case**, where the direction is the normal to the interface,
- **no anchoring**.

The anchoring energy

$$E_{\text{anch}}(\mathbf{d}, c) = \frac{1}{2} \int_{\Omega} \left(\delta_1 |\mathbf{d}|^2 |\nabla c|^2 + \delta_2 |\mathbf{d} \cdot \nabla c|^2 \right) dx$$

where the anchoring energy will take different forms depending on the anchoring effect considered, that is,

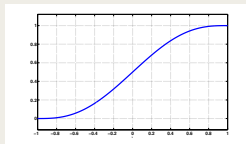
$$(\delta_1, \delta_2) = \begin{cases} (0, 0) & \text{no anchoring,} \\ (0, 1) & \text{parallel anchoring,} \\ (1, -1) & \text{homeotropic anchoring.} \end{cases} \quad (1)$$

The localizing functional $I(c)$

It represents the volume fraction of liquid crystal at each point $x \in \Omega$ and its derivative will be denoted by $i(c) := I'(c)$. It could take different forms but any admissible form must satisfy the following properties:

$$I \in C^2(\mathbb{R}), \quad I(c) = \begin{cases} 0 & \text{if } c \leq -1, \\ \in (0, 1) & \text{if } c \in (-1, 1), \\ 1 & \text{if } c \geq 1. \end{cases}$$

$$I(c) := \begin{cases} 0 & \text{if } c \leq -1, \\ \frac{1}{16} (c+1)^3 (3c^2 - 9c + 8) & \text{if } c \in (-1, 1), \\ 1 & \text{if } c \geq 1, \end{cases}$$



The model

Combining the Least Action Principle (LAP) and the Maximum Dissipation Principle (MDP), we arrive to the following PDE system, fulfilled in the time space domain $(0, T) \times \Omega$:

$$\left\{ \begin{array}{l} \mathbf{u}_t + \mathbf{u} \cdot \nabla \mathbf{u} + \nabla p - \nabla \cdot \boldsymbol{\sigma}_{\text{tot}} = 0, \quad \nabla \cdot \mathbf{u} = 0, \\ \mathbf{d}_t + (\mathbf{u} \cdot \nabla) \mathbf{d} + \gamma_{\text{nem}} \mathbf{w} = 0, \quad \mathbf{w} = \frac{\delta E_{\text{tot}}}{\delta \mathbf{d}}, \\ c_t + \mathbf{u} \cdot \nabla c - \nabla \cdot (\gamma_{\text{mix}} \nabla \mu) = 0, \quad \mu = \frac{\delta E_{\text{tot}}}{\delta c}. \end{array} \right. \quad (2)$$

The total stress tensor

$$\sigma_{\text{tot}} = \sigma_{\text{vis}} + \sigma_{\text{mix}} + \sigma_{\text{nem}} + \sigma_{\text{anch}},$$

being:

$$\sigma_{\text{vis}} = 2\nu \mathbf{D}\mathbf{u} \quad \text{viscosity,}$$

$$\sigma_{\text{mix}} = -\lambda_{\text{mix}} \nabla \mathbf{c} \otimes \nabla \mathbf{c} \quad \text{mixing tensor,}$$

$$\sigma_{\text{nem}} = -\lambda_{\text{nem}} I(\mathbf{c})(\nabla \mathbf{d})^t \nabla \mathbf{d} \quad \text{nematic tensor,}$$

and the anchoring tensor σ_{anch} has the form:

$$(\sigma_{\text{anch}})_{ij} = \lambda_{\text{anch}} \left[\delta_1 |\mathbf{d}|^2 \nabla \mathbf{c} \otimes \nabla \mathbf{c} + \delta_2 (\mathbf{d} \cdot \nabla \mathbf{c}) (\nabla \mathbf{c} \otimes \mathbf{d}) \right]$$

The expression for w

The variational derivative of E_{tot} with respect to the nematic part, w , is

$$w = \frac{\delta E_{\text{tot}}}{\delta \mathbf{d}} = \lambda_{\text{nem}}[-\nabla \cdot (I(\mathbf{c})\nabla \mathbf{d}) + I(\mathbf{c}) G'(\mathbf{d})] + \lambda_{\text{anch}} \frac{\delta E_{\text{anch}}}{\delta \mathbf{d}}.$$

The chemical potential of the phase-field function, μ

$$\begin{aligned} \mu = \frac{\delta E_{\text{tot}}}{\delta \mathbf{c}} &= \lambda_{\text{mix}}[-\Delta \mathbf{c} + F'(\mathbf{c})] + \lambda_{\text{nem}} I'(\mathbf{c}) \left(\frac{1}{2} |\nabla \mathbf{d}|^2 + G(\mathbf{d}) \right) \\ &+ \lambda_{\text{anch}} \frac{\delta E_{\text{anch}}}{\delta \mathbf{c}}. \end{aligned}$$

The PDE system (2) is closed with the following initial and boundary conditions:

$$\begin{aligned} \mathbf{u}|_{t=0} &= \mathbf{u}_0, & \mathbf{d}|_{t=0} &= \mathbf{d}_0, & c|_{t=0} &= c_0 & \text{in } \Omega, \\ \mathbf{u}|_{\partial\Omega} &= (I(c)\nabla\mathbf{d})\mathbf{n}|_{\partial\Omega} = \mathbf{0} & & & & & \text{in } (0, T), \end{aligned} \tag{3}$$

$$\left. \frac{\partial c}{\partial \mathbf{n}} \right|_{\partial\Omega} = (\nabla\mu) \cdot \mathbf{n}|_{\partial\Omega} = 0 \quad \text{in } (0, T).$$

Reformulation of the stress tensor

The following relation holds:

$$-\nabla \cdot \sigma_{\text{mix}} - \nabla \cdot \sigma_{\text{nem}} - \nabla \cdot \sigma_{\text{anch}} = -\mu \nabla \mathbf{c} - (\nabla \mathbf{d})^t \mathbf{w} + \nabla \varphi$$

where

$$\begin{aligned} \varphi = & \lambda_{\text{nem}} I(\mathbf{c}) \left(\frac{1}{2} |\nabla \mathbf{d}|^2 + G(\mathbf{d}) \right) + \lambda_{\text{mix}} \left(\frac{1}{2} |\nabla \mathbf{c}|^2 + F(\mathbf{c}) \right) \\ & + \frac{\lambda_{\text{anch}}}{2} W(\mathbf{d}, \mathbf{c}), \end{aligned}$$

with $W(\mathbf{d}, \mathbf{c}) = (\delta_1 |\mathbf{d}|^2 |\nabla \mathbf{c}|^2 + \delta_2 |\mathbf{d} \cdot \nabla \mathbf{c}|^2)$.

$$\langle \mathbf{u}_t, \bar{\mathbf{u}} \rangle + ((\mathbf{u} \cdot \nabla) \mathbf{u}, \bar{\mathbf{u}}) + (\nu(\mathbf{c}) \mathbf{D} \mathbf{u}, \mathbf{D} \bar{\mathbf{u}}) - (\tilde{p}, \nabla \cdot \bar{\mathbf{u}}) \\ - ((\nabla \mathbf{d})^t \mathbf{w}, \bar{\mathbf{u}}) + (\mathbf{c} \nabla \mu, \bar{\mathbf{u}}) = 0,$$

$$\tilde{p} = p + \varphi, \quad (\nabla \cdot \mathbf{u}, \bar{p}) = 0,$$

$$\langle \mathbf{d}_t, \bar{\mathbf{w}} \rangle + ((\mathbf{u} \cdot \nabla) \mathbf{d}, \bar{\mathbf{w}}) + \gamma_{\text{nem}}(\mathbf{w}, \bar{\mathbf{w}}) = 0,$$

$$\lambda_{\text{nem}}(I(\mathbf{c}) \nabla \mathbf{d}, \nabla \bar{\mathbf{d}}) + \lambda_{\text{nem}}(I(\mathbf{c}) \mathbf{g}(\mathbf{d}), \bar{\mathbf{d}}) + \lambda_{\text{anch}} \frac{\delta E_{\text{anch}}}{\delta \mathbf{d}} = (\mathbf{w}, \bar{\mathbf{d}}),$$

$$(\mathbf{c}_t, \bar{\mu}) - (\mathbf{c} \mathbf{u}, \nabla \bar{\mu}) + \gamma_{\text{mix}}(\nabla \mu, \nabla \bar{\mu}) = 0,$$

$$\lambda_{\text{mix}}(\nabla \mathbf{c}, \nabla \bar{\mathbf{c}}) + \lambda_{\text{mix}}(f(\mathbf{c}), \bar{\mathbf{c}})$$

$$+ \lambda_{\text{nem}} \left(i(\mathbf{c}) \left[\frac{|\nabla \mathbf{d}|^2}{2} + G(\mathbf{d}) \right], \bar{\mathbf{c}} \right) + \lambda_{\text{anch}} \frac{\delta E_{\text{anch}}}{\delta \mathbf{c}} = (\mu, \bar{\mathbf{c}}),$$

for each $(\bar{\mathbf{u}}, \bar{p}, \bar{\mathbf{w}}, \bar{\mathbf{d}}, \bar{\mu}, \bar{\mathbf{c}}) \in \mathbf{H}_0^1(\Omega) \times L_0^2(\Omega) \times \mathbf{H}^1(\Omega) \times \mathbf{H}^1(\Omega) \times \mathbf{H}^1(\Omega) \times \mathbf{H}^1(\Omega)$.

Continuous energy law

Using adequate test functions, we can prove that (2)-(3) satisfies the following (dissipative) energy law:

$$\begin{aligned} \frac{d}{dt} E_{\text{tot}}(\mathbf{u}, \mathbf{d}, c) + \int_{\Omega} \nu(c) |\mathbf{D}\mathbf{u}|^2 dx + \gamma_{nem} \int_{\Omega} |\mathbf{w}|^2 dx \\ + \gamma_{mix} \int_{\Omega} |\nabla \mu|^2 dx = 0. \end{aligned}$$

From the energy law, we deduce the following regularity for a (possible) solution:

$$\left\{ \begin{array}{l} \mathbf{u} \in L^\infty(0, T; \mathbf{L}^2(\Omega)) \cap L^2(0, T; \mathbf{H}^1(\Omega)), \\ \mathbf{w} \in L^2(0, T; \mathbf{L}^2(\Omega)), \\ \nabla \mathbf{c} \in L^\infty(0, T; \mathbf{L}^2(\Omega)), \\ \nabla \boldsymbol{\mu} \in L^2(0, T; \mathbf{L}^2(\Omega)), \\ \int_{\Omega} F(\mathbf{c}) d\mathbf{x} \in L^\infty(0, T), \\ \int_{\Omega} I(\mathbf{c}) \left(\frac{1}{2} |\nabla \mathbf{d}|^2 + G(\mathbf{d}) \right) d\mathbf{x} \in L^\infty(0, T) \\ E_{anch}(\mathbf{c}, \mathbf{d}) \in L^\infty(0, T), \\ \mathbf{c} \in L^\infty(0, T; H^1(\Omega)), \\ \int_{\Omega} I(\mathbf{c}) |\mathbf{d}|^4 \in L^\infty(0, T), \\ \mathbf{d} \in L^\infty(0, T; \mathbf{L}^2(\Omega)). \end{array} \right. \quad (4)$$

For simplicity, we describe our numerical scheme using an uniform partition of the time interval: $t_n = nk$, where $k > 0$ denotes the (fixed) time step. Moreover, hereafter we denote

$$\delta_t a^{n+1} := \frac{a^{n+1} - a^n}{k}.$$

The concept of energy-stability, introduced for other energy-based systems by F. Guillén-González & Tierra

A numerical scheme is energy-stable if it satisfies

$$\delta_t E_{\text{tot}}(\mathbf{u}^{n+1}, \mathbf{d}^{n+1}, c^{n+1}) + \int_{\Omega} \nu(c^{n+1}) |\mathbf{D}\mathbf{u}^{n+1}|^2 d\mathbf{x} \\ + \gamma_{\text{nem}} \int_{\Omega} |\mathbf{w}^{n+1}|^2 d\mathbf{x} + \gamma_{\text{mix}} \int_{\Omega} |\nabla \mu^{n+1}|^2 d\mathbf{x} \leq 0, \quad \forall n.$$

In particular, energy-stable schemes satisfy the energy decreasing in time property, i.e.,

$$E_{\text{tot}}(\mathbf{u}^{n+1}, \mathbf{d}^{n+1}, c^{n+1}) \leq E_{\text{tot}}(\mathbf{u}^n, \mathbf{d}^n, c^n), \quad \forall n.$$

Nematic-Isotropic. Coupled Nonlinear Implicit Scheme

Given $(\mathbf{u}^n, p^n, \mathbf{d}^n, \mathbf{w}^n, \mathbf{c}^n, \mu^n)$, find $(\mathbf{u}^{n+1}, p^{n+1}, \mathbf{d}^{n+1}, \mathbf{w}^{n+1}, \mathbf{c}^{n+1}, \mu^{n+1})$ such that,

$$\begin{aligned} & \left(\frac{\mathbf{u}^{n+1} - \mathbf{u}^n}{k}, \bar{\mathbf{u}} \right) + \left((\mathbf{u}^{n+1} \cdot \nabla) \mathbf{u}^{n+1}, \bar{\mathbf{u}} \right) - (p^{n+1}, \nabla \cdot \bar{\mathbf{u}}) + 2(\nu D \mathbf{u}^{n+1}, D \bar{\mathbf{u}}) \\ & \quad - \left((\nabla \mathbf{d}^{n+1})^t \mathbf{w}^{n+1}, \bar{\mathbf{u}} \right) + (\mathbf{c}^{n+1} \nabla \mu^{n+1}, \bar{\mathbf{u}}) = 0, \\ & \quad (\nabla \cdot \mathbf{u}^{n+1}, \bar{p}) = 0, \\ & \left(\frac{\mathbf{d}^{n+1} - \mathbf{d}^n}{k}, \bar{\mathbf{w}} \right) + \left((\mathbf{u}^{n+1} \cdot \nabla) \mathbf{d}^{n+1}, \bar{\mathbf{w}} \right) + \gamma_{nem}(\mathbf{w}^{n+1}, \bar{\mathbf{w}}) = 0, \\ & \lambda_{nem} (I(\mathbf{c}^{n+1}) \nabla \mathbf{d}^{n+1}, \nabla \bar{\mathbf{d}}) + \lambda_{nem} (I(\mathbf{c}^{n+1}) \mathbf{g}(\mathbf{d}^{n+1}), \bar{\mathbf{d}}) + \lambda_{anch} \left(\frac{\delta E_{anch}}{\delta \mathbf{d}}(\mathbf{c}^{n+1}, \mathbf{d}^{n+1}), \bar{\mathbf{d}} \right) - (\mathbf{w}^{n+1}, \bar{\mathbf{d}}) = 0, \\ & \left(\frac{\mathbf{c}^{n+1} - \mathbf{c}^n}{k}, \bar{\mu} \right) - (\mathbf{c}^{n+1} \mathbf{u}^{n+1}, \nabla \bar{\mu}) + \gamma_{mix}(\nabla \mu^{n+1}, \nabla \bar{\mu}) = 0, \\ & \lambda_{mix}(\nabla \mathbf{c}^{n+1}, \nabla \bar{\mathbf{c}}) + \lambda_{mix}(f(\mathbf{c}^{n+1}), \bar{\mathbf{c}}) + \lambda_{nem} \left(i(\mathbf{c}^{n+1}) \left[\frac{|\nabla \mathbf{d}^{n+1}|^2}{2} + G(\mathbf{d}^{n+1}) \right], \bar{\mathbf{c}} \right) \\ & \quad + \lambda_{anch} \left(\frac{\delta E_{anch}}{\delta \mathbf{c}}(\mathbf{c}^{n+1}, \mathbf{d}^{n+1}), \bar{\mathbf{c}} \right) - (\mu^{n+1}, \bar{\mathbf{c}}) = 0, \end{aligned} \tag{5}$$

Disadvantages of this scheme:

- High computational cost (Coupled + Nonlinear system)
- it is not clear that any iterative method to approximate the nonlinear scheme will converge (several nonlinearities)
- Energy-stability ?

The splitting schemes

We have designed two splitting first-order schemes (inspired in Cabrales, Guillén-González & Gutiérrez-Santacreu and Guillén-González & Tierra, denoted by

$$(\mathbf{d}^{n+1}, \mathbf{w}^{n+1}) \rightarrow (\mathbf{c}^{n+1}, \mu^{n+1}) \rightarrow (\mathbf{u}^{n+1}, \mathbf{p}^{n+1}),$$

or

$$(\mathbf{c}^{n+1}, \mu^{n+1}) \rightarrow (\mathbf{d}^{n+1}, \mathbf{w}^{n+1}) \rightarrow (\mathbf{u}^{n+1}, \mathbf{p}^{n+1}),$$

decoupling computations for nematic part (\mathbf{d}, \mathbf{w}) from the phase-field part (\mathbf{c}, μ) (or the contrary in the second case) and from the fluid part (\mathbf{u}, \mathbf{p}) .

Step 1: Find $(\mathbf{d}^{n+1}, \mathbf{w}^{n+1}) \in \mathbf{D}_h \times \mathbf{W}_h$ s. t, for each
 $(\bar{\mathbf{d}}, \bar{\mathbf{w}}) \in \mathbf{D}_h \times \mathbf{W}_h$

$$\left\{ \begin{array}{l} \left(\frac{\mathbf{d}^{n+1} - \mathbf{d}^n}{k}, \bar{\mathbf{w}} \right) + ((\mathbf{u}^* \cdot \nabla) \mathbf{d}^n, \bar{\mathbf{w}}) + \gamma_{\text{nem}}(\mathbf{w}^{n+1}, \bar{\mathbf{w}}) = 0, \\ \lambda_{\text{nem}} \left(l(\mathbf{c}^n) \nabla \mathbf{d}^{n+1}, \nabla \bar{\mathbf{d}} \right) + \lambda_{\text{nem}} \left(l(\mathbf{c}^n) \mathbf{g}_k(\mathbf{d}^{n+1}, \mathbf{d}^n), \bar{\mathbf{d}} \right) \\ \quad + \lambda_{\text{anch}} \left(\Lambda_{\mathbf{d}}(\mathbf{d}^{n+1}, \mathbf{c}^n), \bar{\mathbf{d}} \right) - (\mathbf{w}^{n+1}, \bar{\mathbf{d}}) = 0, \end{array} \right.$$

where $\mathbf{u}^* := \mathbf{u}^n + 2k(\nabla \mathbf{d}^n)^t \mathbf{w}^{n+1}$,

$\mathbf{g}_k(\mathbf{d}^{n+1}, \mathbf{d}^n)$ is a 1st order approximation of $\mathbf{g}(\mathbf{d}(t_{n+1}))$ and
 $\Lambda_{\mathbf{d}}(\mathbf{d}^{n+1}, \mathbf{c}^n)$ is the discrete approximation of $\frac{\delta E_{\text{anch}}}{\delta \mathbf{d}}(\mathbf{d}(t_{n+1}), \mathbf{c}(t_{n+1}))$:

$$\Lambda_{\mathbf{d}}(\mathbf{d}^{n+1}, \mathbf{c}^n) := \delta_1 |\nabla \mathbf{c}^n|^2 \mathbf{d}^{n+1} + \delta_2 (\mathbf{d}^{n+1} \cdot \nabla \mathbf{c}^n) \nabla \mathbf{c}^n$$

Step 2: Find $(c^{n+1}, \mu^{n+1}) \in C_h \times M_h$ s. t., for $(\bar{c}, \bar{\mu}) \in C_h \times M_h$

$$\left\{ \begin{array}{l} \left(\frac{c^{n+1} - c^n}{k}, \bar{\mu} \right) - (c^n \mathbf{u}^{**}, \nabla \bar{\mu}) + \gamma_{\text{mix}}(\nabla \mu^{n+1}, \nabla \bar{\mu}) = 0, \\ \lambda_{\text{mix}}(\nabla c^{n+1}, \nabla \bar{c}) + \lambda_{\text{mix}}(f_k(c^{n+1}, c^n), \bar{c}) \\ + \lambda_{\text{nem}} \left(i_k(c^{n+1}, c^n) \left[\frac{1}{2} |\nabla \mathbf{d}^{n+1}|^2 + G(\mathbf{d}^{n+1}) \right], \bar{c} \right) \\ + \lambda_{\text{anch}} \left(\Lambda_c(\mathbf{d}^{n+1}, c^{n+1}), \nabla \bar{c} \right) - (\mu^{n+1}, \bar{c}) = 0, \end{array} \right.$$

where $\mathbf{u}^{**} := \mathbf{u}^n - 2k c^n \nabla \mu^{n+1}$,

$f_k(c^{n+1}, c^n)$ and $i_k(c^{n+1}, c^n)$ are 1st order approximations of $f(c(t_{n+1}))$ and $i(c(t_{n+1}))$, resp.,

$\Lambda_c(\mathbf{d}^{n+1}, c^{n+1})$ is the discrete approximation of $\frac{\delta E_{\text{anch}}}{\delta c}(\mathbf{d}(t_{n+1}), c(t_{n+1}))$:

$$\Lambda_c(\mathbf{d}^{n+1}, c^{n+1}) := \delta_1 |\mathbf{d}^{n+1}|^2 \nabla c^{n+1} + \delta_2 (\mathbf{d}^{n+1} \cdot \nabla c^{n+1}) \mathbf{d}^{n+1}$$

Step 3: Find $(\mathbf{u}^{n+1}, p^{n+1}) \in \mathbf{V}_h \times P_h$ s. t., for each $(\bar{\mathbf{u}}, \bar{p}) \in \mathbf{V}_h \times P_h$

$$\left\{ \begin{array}{l} \left(\frac{\mathbf{u}^{n+1} - \hat{\mathbf{u}}}{k}, \bar{\mathbf{u}} \right) + c(\mathbf{u}^n, \mathbf{u}^{n+1}, \bar{\mathbf{u}}) - (p^{n+1}, \nabla \cdot \bar{\mathbf{u}}) \\ \quad + (\nu(c^{n+1}) \mathbf{D}\mathbf{u}^{n+1}, \mathbf{D}\bar{\mathbf{u}}) = 0, \\ (\nabla \cdot \mathbf{u}^{n+1}, \bar{p}) = 0, \end{array} \right.$$

where

$$\hat{\mathbf{u}} := \frac{\mathbf{u}^* + \mathbf{u}^{**}}{2}.$$

Local (in time) discrete energy law:

Scheme given by **Step1-3** satisfies the following local discrete energy law:

$$\begin{aligned} & \delta_t E(\mathbf{d}^{n+1}, c^{n+1}, \mathbf{u}^{n+1}) + \gamma_{\text{nem}} \|\mathbf{w}^{n+1}\|_{L^2}^2 \\ & + \gamma_{\text{mix}} \|\nabla \mu^{n+1}\|_{L^2}^2 + \|\nu(c^{n+1})^{1/2} \mathbf{D}\mathbf{u}^{n+1}\|_{L^2}^2 \\ & + ND_{\mathbf{u}}^{n+1} + ND_{\text{elast}}^{n+1}(c^n) + ND_{\text{penal}}^{n+1}(c^n) \\ & + ND_{\text{philic}}^{n+1} + ND_{\text{phobic}}^{n+1} + ND_{\text{interp}}^{n+1} + ND_{\text{anch}}^{n+1} = 0 \end{aligned}$$

The numerical dissipation terms are:

$$ND_{\mathbf{u}}^{n+1} = \frac{1}{2k} \left(\|\mathbf{u}^{n+1} - \widehat{\mathbf{u}}\|_{L^2}^2 + \frac{\|\widehat{\mathbf{u}} - \mathbf{u}^*\|_{L^2}^2 + \|\widehat{\mathbf{u}} - \mathbf{u}^{**}\|_{L^2}^2}{2} + \frac{\|\mathbf{u}^* - \mathbf{u}^n\|_{L^2}^2 + \|\mathbf{u}^{**} - \mathbf{u}^n\|_{L^2}^2}{2} \right)$$

$$ND_{\text{elast}}^{n+1}(\mathbf{c}^n) = \lambda_{\text{nem}} \frac{k}{2} \int_{\Omega} i(\mathbf{c}^n) |\delta_t \nabla \mathbf{d}^{n+1}|^2 d\mathbf{x},$$

$$ND_{\text{penal}}^{n+1}(\mathbf{c}^n) = \lambda_{\text{nem}} \int_{\Omega} i(\mathbf{c}^n) (\mathbf{g}_k(\mathbf{d}^{n+1}, \mathbf{d}^n) \cdot \delta_t \mathbf{d}^{n+1} - \delta_t G(\mathbf{d}^{n+1})) d\mathbf{x},$$

$$ND_{\text{philic}}^{n+1} = \lambda_{\text{mix}} \frac{k}{2} \int_{\Omega} |\delta_t \nabla \mathbf{c}^{n+1}|^2 d\mathbf{x},$$

$$ND_{\text{phobic}}^{n+1} = \lambda_{\text{mix}} \int_{\Omega} (f_k(\mathbf{c}^{n+1}, \mathbf{c}^n) \delta_t \mathbf{c}^{n+1} - \delta_t F(\mathbf{c}^{n+1})) d\mathbf{x},$$

$$ND_{\text{interp}}^{n+1} = \lambda_{\text{nem}} \int_{\Omega} \left(\frac{|\nabla \mathbf{d}^{n+1}|^2}{2} + G(\mathbf{d}^{n+1}) \right) \\ \times (i_k(\mathbf{c}^{n+1}, \mathbf{c}^n) \delta_t \mathbf{c}^{n+1} - \delta_t l(\mathbf{c}^{n+1})) d\mathbf{x},$$

and

$$ND_{\text{anch}}^{n+1} \\ = \lambda_{\text{anch}} \frac{k}{2} \int_{\Omega} \left(\delta_1 (|\delta_t \mathbf{d}^{n+1}|^2 |\nabla \mathbf{c}^n|^2 + |\mathbf{d}^{n+1}|^2 |\delta_t \nabla \mathbf{c}^{n+1}|^2) \right. \\ \left. + \delta_2 (|\delta_t \mathbf{d}^{n+1} \cdot \nabla \mathbf{c}^n|^2 + |\mathbf{d}^{n+1} \cdot \nabla \delta_t \mathbf{c}^{n+1}|^2) \right) d\mathbf{x}.$$

with (δ_1, δ_2) defined in (1) depending on the type of anchoring.

The function f_k

$$f_k(c^{n+1}, c^n) := \tilde{f}(c^n) + \frac{1}{2} \|\tilde{f}'\|_\infty (c^{n+1} - c^n),$$

in our case reduces to

$$f_k(c^{n+1}, c^n) = \tilde{f}(c^n) + (c^{n+1} - c^n) \quad (6)$$

where $\tilde{f}(c)$ is the C^1 -truncation of $F'(c)$:

$$\tilde{f}(c) = \begin{cases} \frac{2}{\varepsilon^2}(c+1) & \text{if } c \leq -1, \\ \frac{1}{\varepsilon^2}(c^2-1)c & \text{if } c \in [-1, 1], \\ \frac{2}{\varepsilon^2}(c-1) & \text{if } c \geq 1, \end{cases} \quad (7)$$

The function g_k

$$g_k(\mathbf{d}^{n+1}, \mathbf{d}^n) = \tilde{g}(\mathbf{d}^n) + \frac{\sqrt{51}}{2} (\mathbf{d}^{n+1} - \mathbf{d}^n), \quad (8)$$

where $\tilde{g}(\mathbf{d})$ is the C^1 -truncation of $g(\mathbf{d})$:

$$\tilde{g}(\mathbf{d}) = \begin{cases} 2 (|\mathbf{d}| - 1) \frac{\mathbf{d}}{|\mathbf{d}|} & \text{if } |\mathbf{d}| \geq 1, \\ (|\mathbf{d}|^2 - 1) \mathbf{d} & \text{if } |\mathbf{d}| \leq 1, \end{cases}$$

The function i_k

$$i_k(\mathbf{c}^{n+1}, \mathbf{c}^n) = i(\mathbf{c}^n) + \frac{5\sqrt{3}}{12} (\mathbf{c}^{n+1} - \mathbf{c}^n). \quad (9)$$

Lemma

If $D_h \subseteq W_h$, then there exist a unique solution $(\mathbf{d}^{n+1}, \mathbf{w}^{n+1})$ of **STEP 1** using the potential approximation (8) for $\mathbf{g}_k(\mathbf{d}^{n+1}, \mathbf{d}^n)$.

Lemma

If $1 \in C_h$, then there exist a unique solution (c^{n+1}, μ^{n+1}) of **STEP 2** using the potential approximations (6) and (9) for $f_k(c^{n+1}, c^n)$ and $i_k(c^{n+1}, c^n)$, respectively.

Lemma

If the pair of FE spaces (\mathbf{V}_h, P_h) satisfies the discrete inf-sup condition

$$\exists \beta > 0 \quad \text{such that} \quad \|p\|_{L^2} \leq \beta \sup_{\bar{\mathbf{u}} \in \mathbf{V}_h \setminus \{\Theta\}} \frac{(p, \nabla \cdot \bar{\mathbf{u}})}{\|\bar{\mathbf{u}}\|_{H^1}} \quad \forall p \in P_h, \quad (10)$$

then there exist a unique solution $(\mathbf{u}^{n+1}, p^{n+1})$ of **STEP 3**.

We propose the following choice for the discrete spaces:

$$(\mathbf{u}, p) \sim P_2 \times P_1, \quad (c, \mu) \sim P_1 \times P_1 \quad \text{and} \quad (\mathbf{d}, \mathbf{w}) \sim P_1 \times P_1, \quad (11)$$

that satisfy the assumptions of Lemmas 1, 2 and 3.

The discrete and physical parameters

The **newtonian fluid** is represented by **blue color** while the **nematic fluid** is represented by **red one**.

For simplicity we are considering constant viscosity $\nu(c) = \nu_0$.

Ω	$[0, T]$	h	dt	ν_0	η
$[-1, 1]^2$	$[0, 10]$	2/90	0.001	1.0	0.075

λ_{nem}	λ_{mix}	λ_{anch}	γ_{nem}	γ_{mix}	ε
0.1	0.01	0.1	0.5	0.01	0.05

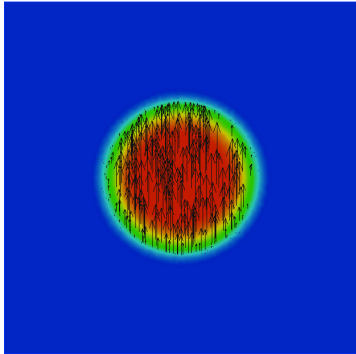
Table : Parameters

Nematic-Isotropic. Circular droplet and director field parallel to the y-axis



Circular droplet and director field parallel to the y -axis

(a)



(b)

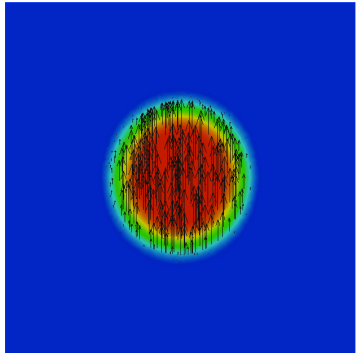


Figure : (a) initial configuration, (b) state at $t = 10$ without considering anchoring effects.

Circular droplet and director field parallel to the y-axis

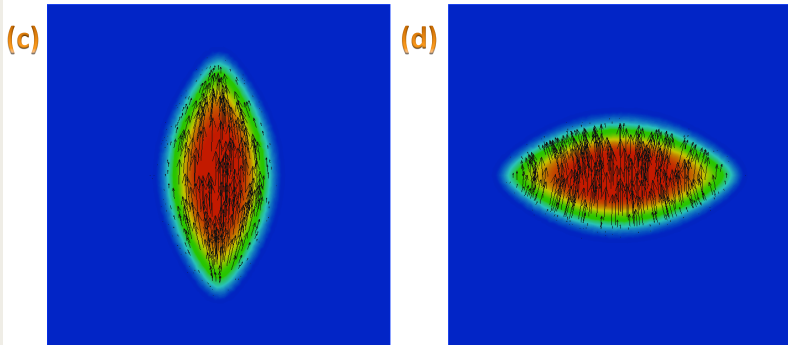
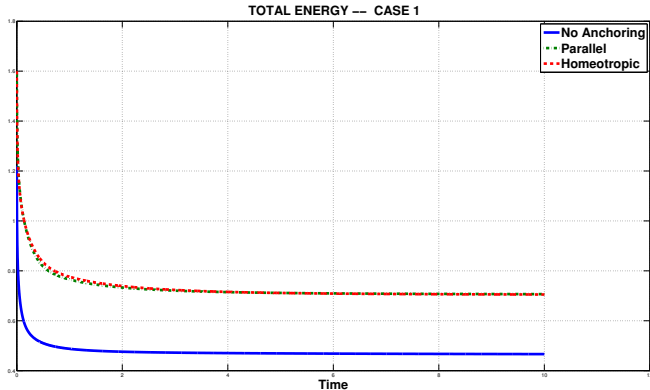


Figure : (c) state at $t = 10$ considering parallel anchoring, (d) state at $t = 10$ considering homeotropic anchoring.

Nematic-Isotropic. Circular droplet and director field parallel to the y-axis



Elliptic droplet with two points defects at $(\pm 1/2, 0)$

a Hedgehog defect at $(1/2, 0)$ and an Antihedgehog defect at $(-1/2, 0)$

$$\mathbf{d}_0(x) = \hat{\mathbf{d}} / \sqrt{|\hat{\mathbf{d}}|^2 + 0.05^2}, \text{ with } \hat{\mathbf{d}} = (x^2 + y^2 - 0.25, y).$$

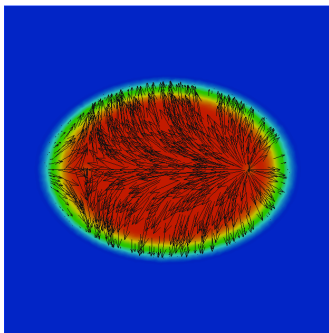
Defect annihilation in Nematic Liquid Crystals



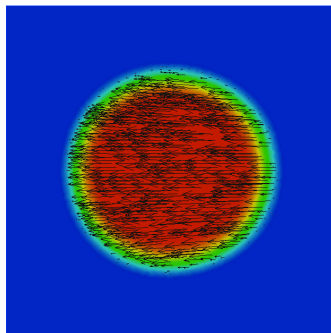
Defect annihilation in Nematic Liquid Crystals Drops



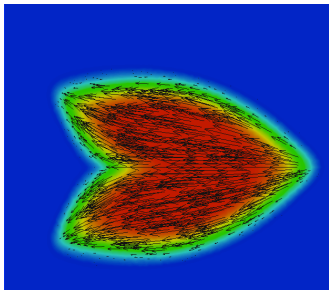
(a)



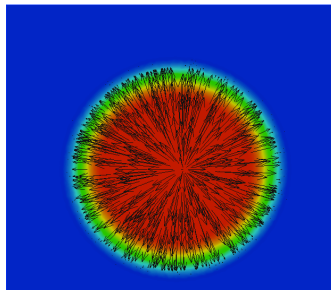
(b)



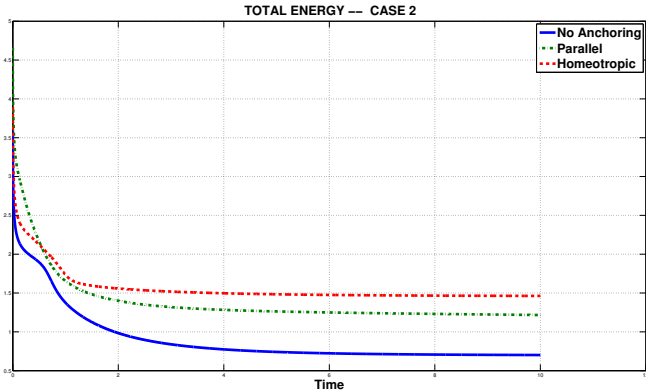
(c)



(d)



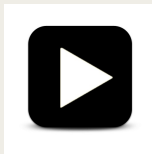
Nematic-Isotropic. Circular droplet and director field parallel to the y-axis



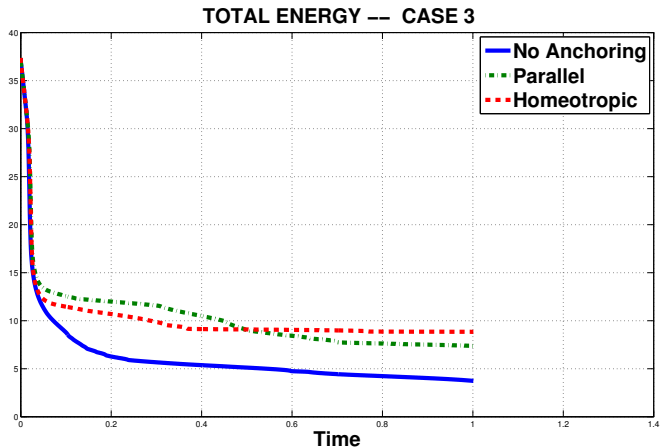
Nematic-Isotropic. Spinodal Decomposition

- Random initial data for c , i.e., $c \in [-10^{-2}, 10^{-2}]$ in $\Omega = [0, 1] \times [0, 1]$, $t \in [0, 1]$ and $dt = 10^{-4}$.
- The initial director vector is computed using the function:

$$\mathbf{d} = I(c) \left(\sin(x y) \sin(x y), \cos(x y) \cos(x y) \right).$$



Nematic-Isotropic. Spinodal Decomposition





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Thank you very much for your
attention!