Emilio Gomez-Gonzalez, PhD ^[] *[‡]

Francisco Javier Munoz-Gonzalez, ME [®]*

Alejandro Barriga-Rivera,

PhD ⁽¹⁾ *^S Manuel A. Perales-Esteve, PhD ⁽¹⁾

Manuel Guerrero-Claro, ME* Isabel Fernandez-Lizaranzu, ME ()) *[‡]

Desirée Requena-Lancharro, BE ⁽¹⁾*

Marina Rosales-Martinez, PhD • *

Javier Marquez-Rivas, MD, PhD () **1

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Correspondence:

Emilio Gomez-Gonzalez, PhD, Department of Applied Physics III, School of Engineering, University of Seville, Camino de los Descubrimientos s/n, 41092 Sevilla, Spain. Email: egomez@us.es

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OPEN

Contactless Ultrasonic Cavitation for the Prevention of Shunt Obstruction in Hydrocephalus: A Proof-of-Concept Study

BACKGROUND: Obstructive failure of implanted shunts is the most common complication in the treatment of hydrocephalus. Biological material and debris accumulate in the inner walls of the valve and catheters block the normal flow of the drained cerebrospinal fluid causing severe symptoms with high morbidity and mortality. Unfortunately, at present, there is no effective preventive protocol or cleaning procedure available.

OBJECTIVE: To assess whether externally applied, focused ultrasound beams can be used to resuspend deposits accumulated in brain shunts safely.

METHODS: A computational model of an implanted brain shunt was implemented to test the initial design parameters of a system comprising several ultrasound transducers. Under laboratory conditions, configurations with 3 and 4 transducers were arranged in a triangle and square pattern with their radiation axis directed towards a target model of the device, 2 catheters and a brain shunt filled with water and deposited graphite powder. The ultrasound beams were then concentrated on the device across a head model.

RESULTS: The computational model revealed that by using only 3 transducers, the acoustic field intensity on the valve was approximately twice that on the brain surface suggesting that acoustic cavitation could be selectively achieved. Resuspension of graphite deposits inside the catheters and the valve were then physically demonstrated and video-recorded with no temperature increase.

CONCLUSION: The technology presented here has the potential to be used routinely as a noninvasive, preventive cleaning procedure to reduce the likelihood of obstruction-related events in patients with hydrocephalus treated with an implanted shunt.

KEY WORDS: Hydrocephalus, Shunt cleaning, Ultrasound cavitation, Valve obstruction, Ventricular catheter, Cerebrospinal fluid

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he abnormal accumulation of fluids in the brain, known as hydrocephalous, is a severe health condition¹ that affects patients of all age groups.²⁻⁴ It comprises a wide set of ailments associated with alterations in the cerebrospinal fluid (CSF) hydrodynamics and the biomechanical properties of the structures of the central nervous system. In many cases, these pathologies are characterized by an enlargement of the lateral ventricles of the brain, caused by the accumulation of CSF, and by the physiological and cognitive consequences of the compression of the brain structures produced by the increased intracranial pressure.⁵ Symptoms range from

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fatigue or memory problems to loss of cortical functions (speech, motion, vision, etc), and if untreated, it can lead to death.^{6,7} Normally, clinical management of hydrocephalus requires the neurosurgical implantation of a brain shunt to drain the CSF excess.^{8,9} Unfortunately, shunt failures are common¹⁰⁻¹² and can lead to lifethreatening medical situations if not rapidly replaced.^{13,14} In a recent review, Paff et al¹⁵ stated that the most frequent cause of shunt malfunction was the obstruction of the implant. Although this obstruction can occur at any point along the brain shunt, the authors concluded that the implant is most likely to be clogged at the proximal catheter. At present, there is no clear consensus on the cause of the brain shunt blockade; it may be explained by particles of brain parenchyma¹⁶ or fragments of the choroid

plexus¹⁷ clogging the luminal space or by a progressive buildup of other tissue debris, proteins, or blood cells producing an eventual occlusion.^{18,19} Although there are no preventive technologies or medical approaches to avoid such complications in the long term, ²⁰ refinement of the surgical technique can decrease rates of infection in the short term.^{21,22}

There have been different attempts to devise a method to clear blocked shunts: thermal cauterization of the obstruction, ²³ delivery of high-energy laser pulses using fiber optics,^{24,25} and generation of cavitation by delivering ultrasonic waves from a transducer coupled to a wire.²⁶ All these techniques require positioning a probe inside the shunt in the proximity of the blockade to locally deliver energy thus compromising the patency of the catheter and increasing substantially the temperature of the treated area. Although these techniques possess clear benefits over surgical replacement, the inherent risks associated with the insertion of a probe within the luminal space of the shunt restrict the use of these technologies to shunt failure events. By contrast, this study presents a proof of concept of a contactless technology to prevent shunt blockade. In a laboratory model of a patient head, by delivering focused ultrasound²⁷ from an external array of piezoelectric transducers, we generated cavitation within the device causing the resuspension of the deposited materials with minimal temperature increase.

METHODS

A laboratory prototype was implemented to test whether contactless cavitation and reflow of adhered material could be achieved in brain shunts. In doing so, the first step was to build a 3-dimensional (3D) computational model to optimize ultrasound focusing within the targeted volume of interest while reducing energy transfer onto surrounding area. Then, an array of ultrasonic transducers, distributed to concentrate the ultrasound beams within a model of an occluded brain shunt, were used to demonstrate the viability of the technology proposed in this study.

Computational Model

A 3D computational model was built using COMSOL Multiphysics v.5.3a (COMSOL Inc) with different material properties²⁸⁻³³ (see details in the **Supplemental Digital Content**, http://links.lww.com/ONS/A786). In brief, the emitters were modeled as dipolar sources firstly and, thereafter, as vibrating surfaces, and the acoustic fields were obtained by solving the Helmholtz equation in the frequency domain using the acoustic module provided. Further details on the model equations and parameters are given in the **Supplemental Digital Content**, http://links.

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lww.com/ONS/A786. The model was solved within a simplified geometrical representation of an implanted brain shunt over a flat cranial surface of a 200 \times 200 mm², as shown in Figure 1. The biological domains included a layer of white matter (50 mm), gray matter (20 mm), cranial bone (6 mm), a thin layer of scar tissue surrounding the implant (1 mm), skin (2.5 mm), and CSF within the shunt. The geometry of the implant was obtained by generating a surface of revolution from the contour of a Codman–Hakim programmable valve (Codman, Johnson & Johnson Co.). Three ultrasonic transducers were modeled as 1-cm thick hollow cylinders with the radiation axis directed toward the center of the valve using different angular configurations. The acoustic pressure (expressed in Pa) and the acoustic intensity (expressed in W \cdot m⁻²) fields were then computed at 39 kHz, 40 kHz, and 41 kHz.

Shunt Obstruction Model

A simplified model of a brain catheter was built from transparent polyvinyl chloride conduits with inner diameters of 1 mm, 3 mm, and 10 mm. The tube was filled with a mix of water and graphite powder to generate high-quality videos (Videos 1 and 2) demonstrating contactless ultrasonic cavitation. A second fluid was prepared to simulate drained CSF from patients with conditions, ie, severe infections or hemorrhages among others, affecting the shunt flow. For that purpose, water was mixed with 30% egg white to form a colloidal solution with high protein content. These proteinaceous preparations were left to dry within the tubes for no less than 15 days to mimic the blocking deposits causing shunt failures.

In addition, ultrasonic cavitation was also demonstrated in a Codman-Hakim valve. It has to be noted that catheters used in conventional procedures are made of opaque medical-grade silicone. Therefore, demonstration of successful cavitation was limited to the interior of the valve and to nonmedical grade translucid plastic tubing. The experiments were conducted under standard laboratory conditions for temperature and humidity, approximately 22 °C and 50%, respectively.

Ultrasound Focusing

Four HS-4SH-3840 ultrasonic transducers (Hesentec) were arranged with their principal radiation axis directed toward the targeted area of the shunt model. The transducer array was powered by an ultrasonic frequency generator SET 1700W (TimeTech GmbH). The transducers were arranged in a square with 60 mm side and its center located approximately at 140 mm above the target volume to maximize focusing. All transducers were positioned with their radiation axis directed toward the sample. To demonstrate cavitation, ultrasonic radiation was applied during 30 seconds with total electric power of 60 W equally split over the 4 transducers in the array. Note that the shunt model was placed under water, and the radiating surfaces of the transducers were also immersed to mimic the use of a coupling gel. The process was recorded at 60 frames per second using a Blackmagic Micro Cinema Camera (Blackmagic Design) mounting a Rokinon 35 mm T1.5 Cine AS UMC lens (Samyang Optics). In addition, temperature was monitored using a thermocouple TESTO 925 (Testo) with a 4-mm diameter probe inserted in the target area.

Ethics Assessment

The described research does not include the use of human participants or animal subjects. It does not require approval by Institutional Review Board nor Ethics Committee. No patient consent form is needed.

^{*}Department of Applied Physics III, ETSI School of Engineering, University of Seville, Sevilla, Spain; [‡]Group of Applied Neuroscience, Institute of Biomedicine of Seville, Sevilla, Spain; [§]School of Biomedical Engineering, The University of Sydney, Sydney, NSW, Australia; ^{II}Department of Electronic Engineering, ETSI School of Engineering, University of Seville, Sevilla, Spain; [¶]Service of Neurosurgery, University Hospital 'Virgen del Rocio', Sevilla, Spain

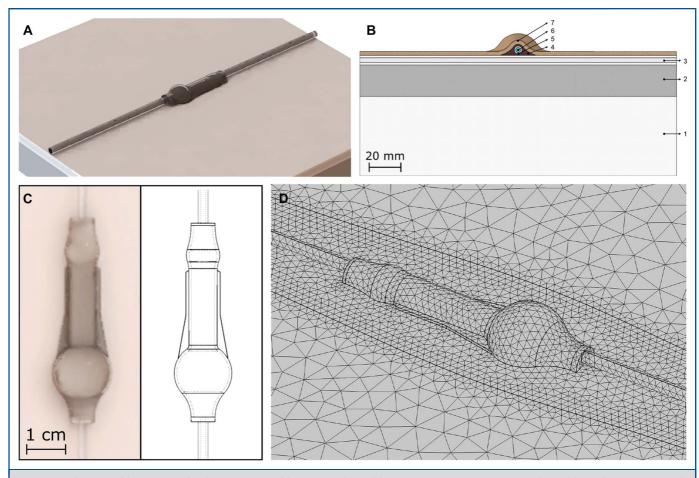


FIGURE 1. Illustration of the geometry used in the computation model. A, A 3D rendering of the geometric structures. B, A cross-sectional area of the 3D domains containing the different layers considered in the model formulation. 1: White matter, 2: gray matter, 3: cranial bone, 4: scar tissue, 5: implanted brain shunt, 6: cerebrospinal fluid, and 7: skin. C, The shunt used to render the 3D model. D, The mesh used in the 3D valve model. 3D, 3-dimensional

RESULTS

A prototype of a device able to generate contactless ultrasonic cavitation in a standard hydrocephalus shunt has been designed, and its application for noninvasive cleaning by removal of adhered deposits has been computationally and experimentally demonstrated and video-recorded in a physical laboratory setup. For that purpose, different transducer configurations were analyzed using the computational model previously described. Figure 2A shows final configuration with which the results had been obtained. This tool allows for adjusting the position of the transducers and the frequency of the radiation to maximize focusing of the acoustic energy on the obstructed shunt while reducing the amount of energy transferred onto surrounding tissues and structures. Figure 2B shows the results of the initial study conducted to assess whether higher intensities of acoustic energy could be locally delivered over the blocked shunt in a conceptually similar way as it is used for the treatment of tumors.³⁴ Although ablation of tumors is achieved because of the temperature increase produced by highintensity ultrasounds, intended cavitation can be induced using low-intensity ultrasonic waves at lower frequencies, as commonly used in cleaning devices³⁵ for industrial applications. Along these lines, the model revealed that a high degree of ultrasound focusing could be achieved at approximately 40 kHz with the elements of the array arranged symmetrically around the target. Note that a high-intensity node was demonstrated at 41 kHz with a 30° angle configuration in the proximity of the shunt.

After initial tests, the model was then reformulated to induce a relatively high level of acoustic intensity accurately focused on the valve. For that purpose, the transducers were arranged in a 45° angle configuration with ultrasound frequency set to 40 kHz, as shown in Figure 3. The acoustic intensity thus obtained over the shunt was between 2 and 3 times larger than that obtained on the surface of the brain, as illustrated in Figure 3A. The intensity pattern thus achieved was highly localized on the model of the shunt, as shown in Figure 3B. An additional configuration is presented in the

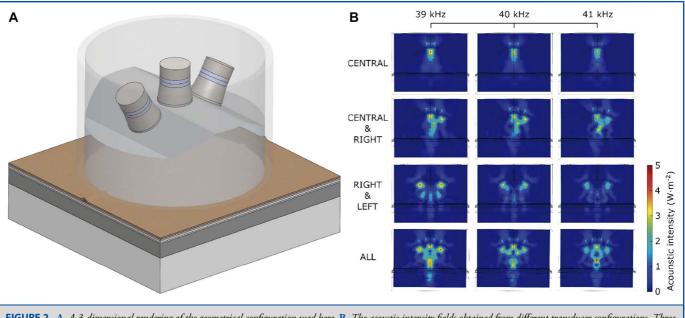


FIGURE 2. A, A 3-dimensional rendering of the geometrical configuration used here. **B**, The acoustic intensity fields obtained from different transducer configurations. Three different ultrasound frequencies were used. The transducers were position with their radiation axis in a 30° angle configuration relative to the vertical line. A high-intensity node was induced when all transducers were activated at 41 kHz. The amplitude of the emitters was set to 1 MN m^{-3} .

Supplemental Digital Content, http://links.lww.com/ONS/ A786, with the lateral transducers in a 35° and 55° configurations. Ultrasonic energy appeared focused on the proximal site.

Stemming from these preliminary results on the geometrical distribution of the acoustic intensity, we sought to experimentally demonstrate, on the bench, whether lowintensity ultrasonic cavitation could be induced inside a real shunt. Graphite deposits within the catheter and the valve were resuspended using 4 ultrasound transducers symmetrically distributed above the center of the sonication volume. Figures 4 and 5 show details of said cavitation within a catheter and a valve, respectively, using images extracted from recorded videos files (Videos 1 and 2). At t = 0, the graphite tracer was deposited on the lower walls of the devices. After activation of the ultrasound, the particles commenced to emerge and then diffused within the fluid only in the target volume (Figures 4 and 5, and Videos 1 and 2). During the sonication time, no temperature increase was detected above the resolution of the sensor. Similarly, albumin deposits were successfully re-flown when using high-protein fluid media. Experimental demonstrations are recorded in 2 full-length videos (Videos 1 and 2).

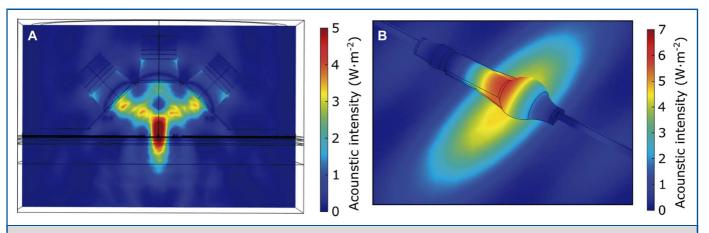
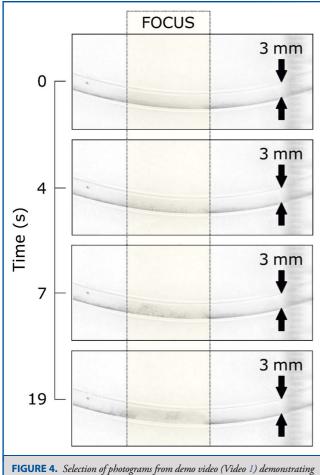


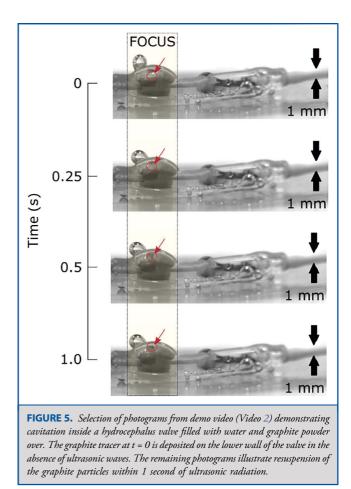
FIGURE 3. A, The acoustic intensity field obtained at 40 kHz in a 45° configuration with the 3 transducers activated simultaneously. B, A detail of the acoustic intensity field within the model of the shunt. The amplitude of the emitters was set to 1 MN m^{-3} .



cavitation within a 3-mm catheter filled with water and graphite powder. The graphite tracer can be observed at t = 0 deposited on the lower wall of the catheter in the absence of ultrasonic waves. The remaining photograms illustrate resuspension of the graphite particles.

DISCUSSION

The most frequent treatment for hydrocephalus relies on implanting a shunt—composed of 2 catheter segments and a valve—to drain cerebrospinal fluid from brain ventricles to a distal cavity.^{8,9} As device failure remains one of the major limitations of the therapy,¹⁰⁻¹² the scientific community has sought ways of restoring flow by delivering optical,^{24,25} acoustic,²⁶ or thermal energy²³ to achieve removal of blocking deposits. To date, state-of-the-art technologies require inserting a probe within the device to break down the blockade. First attempts to use ultrasonic cavitation date from 2001.³⁶ At that time, Ginsberg et al²⁶ described a device able to recanalize obstructed devices delivering 20-kHz ultrasonic waves from a probe inserted percutaneously in the shunt. One of the problems the initial design they reported was a temperature increase around the transducer able to trigger protein denaturalization.²⁶ Although it was mitigated by saline irrigation, there were other



important risks associated with this device, such as the potential to harm the brain if the occlusion was located proximal to the valve.

The method presented here provides a noninvasive approach that might prevent failures. As this technology can produce contact-less cavitation within the target volume, it has the potential to be used routinely to remove the accumulation of biological deposits before they block the normal flow, particularly in the valve. However, as blockades tend to occur most frequently at the proximal catheter, the ultimate challenge lies with clearing plugged biological material in close proximity to sensitive brain tissue. Note that the use of multiple ultrasound transducers allows for creating regions of relatively high acoustic intensity able to induce cavitation locally while reducing overheating of the surrounding tissues, as demonstrated herein.

Limitations

High-intensity focused ultrasound has been extensively used in neurosurgery for noninvasive treatment of brain tumors³⁷ among others. The idea underlying this study was inspired on said applications,³⁸ but using lower acoustic energy and frequency instead. The ultimate goal was, therefore, to produce cavitation only with a minimum temperature increase. For these reasons, we

chose frequencies in the range of 30 to 100 kHz, as they have a demonstrated capacity for generating cavitation bubbles without tissue heating.³⁹ Nevertheless, the frequency, the number of transducers, and their relative positions need to be further studied in preclinical studies before developing a prototype for clinical trials. Note this study has demonstrated the feasibility of the technique in a laboratory setup using a relatively simple configuration and, therefore, statements on safety cannot be made at this instance. Without hesitation, the next steps should aim at verifying whether ultrasonic energy, focused in the fashion described here, disrupts the neighboring brain tissue. It can be anticipated that special attention will be required when delivering ultrasonic energy to the proximal catheter. A strategy for minimizing potential tissue harm would require the use of multiple ultrasonic sources. Note that although the real anatomy is substantially more complex, it is expected that the degree of ultrasound focusing improves with larger numbers of transducers. Optimization of the energy delivery process can be assisted by the use of artificial intelligence.⁴⁰ This together would reduce the energy required from each transducer and the amount of energy delivered during treatment while achieving more localized cavitation in the desired volume.

CONCLUSION

In this work, we present a computational and experimental proof-of-concept of the use of externally applied focused ultrasound to remove accumulated debris in models of implanted brain shunts and to improve cerebrospinal fluid flow through valves and catheters. This procedure may be used for noninvasive, preventive, cleaning of implanted shunts in patients with hydrocephalus.

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Disclosures

E. Gomez-Gonzalez, J. Marquez-Rivas, M. A. Perales-Esteve, M. Guerrero-Claro, F. J. Munoz-Gonzalez, and I. Fernandez-Lizaranzu have filed a patent application related to this technology. The other authors have no personal, financial, or institutional interest in any of the drugs, materials, or devices described in this article.

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VIDEO 1. A water-filled catheter (3 mm inner diameter, indicated by black arrows) with graphite deposits is placed within a container (also filled with water, to achieve acoustical coupling with the ultrasound emitters). Ultrasound beams are focused in the center region of the catheter, producing controlled cavitation and the

removal of deposits. Note that no effect is produced in the surrounding region around the focused target.

VIDEO 2. A standard hydrocephalus valve connected to catheters (1 mm inner diameter, indicated by black arrows) is water-filled and submerged in a container (also filled with water, to achieve acoustical coupling with the ultrasound emitters). The shunt is placed on top of a rigid holder (with a 1 mm glass layer and a 5 mm cork layer) to simulate the skull bone. The region under the holder is also filled with water. An additional plastic tube (7 mm inner diameter) is placed underneath. There are graphite deposits inside the valve and in the larger tube. When the ultrasound beams are focused in the target volume (ie, in the valve), achieved cavitation removes the deposits inside it but no effects are produced in the surrounding region nor in the other tube.

Supplemental digital content is available for this article at operativeneurosurgeryonline.com.

Supplemental Digital Content. Model Formulation.

Supplemental Table 1. Acoustic parameters of materials.²⁵⁻³⁰

Supplemental Figure 1. Details of the 3D computational model. A, An external view of the model structures including the scar tissue and skin. B and C, The tetrahedral mesh used to solve the acoustic problem in the different regions and layers. Different mesh sizes can be observed. D, A relative position of the valve and transducers.

Supplemental Figure 2. Spatial distribution (planar view) of the pressure field generated by 3 ultraosuind transducers activated simultaneously and arranged in a 30° configuration. The amplitude of the emitters was set to 1 MN m⁻³ to facilitate the visualization of the spatial distribution of the acoustic field.

Supplemental Figure 3. Example of nonsymetric ultrasonic transducer configuration. A, The geometry used in the simulation. B, An example of the acoustic intensity field preferentially focused on the proximal end of the implant.



Arithmometer built by Veuve Payen around 1914 and sold by Darras around 1915; by Ezrdr, Public domain, via Wikimedia Commons