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NUMERICAL METHODS FOR SOLVING THE CAHN-HILLIARD EQUATION AND ITS  
APPLICABILITY TO MIXTURES OF NEMATIC-ISOTROPIC FLOWS WITH ANCHORING  
EFFECTS

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## 1 Motivation

## 2 Second order schemes and time-step adaptivity for the Cahn-Hilliard equation

Cahn-Hilliard Model

Second Order Schemes

Approximations of potential term  $f^k(\phi^{n+1}, \phi^n)$

Time step adaptivity

Numerical Simulations

## 3 Linear unconditional energy-stable splitting schemes for nematic-isotropic flows with anchoring effects

Nematic Liquid Crystals

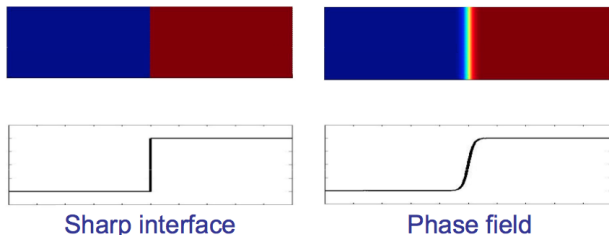
Mixtures of Nematic Liquid Crystals with Newtonian fluid

The model

Numerical schemes

Numerical simulations

## 4 References



- **Sharp-interface** models
  - PDE for each phase + coupled interface conditions
  - Very difficult numerically (interface tracking)
- **Diffuse interface** Phase-field models
  - Phase function with distinct values (for instance +1 and -1) in each phase, with a smooth change in the interface (of width  $\varepsilon$ ).
  - Surface motion depending on the physical energy dissipation.
  - When interface width  $\varepsilon$  tends to zero, recover a sharp interface model.

Design numerical schemes for **diffuse-interface phase-field** problems:

- 1 Efficient in time (Linear schemes, adaptive time-step).
- 2 Suitable to use (standard) Finite Elements (mesh adaptation)
- 3 Mimic properties of the continuous problem: Dissipative Energy law, maximum principle, mass conservation, ...
- 4 Good finite and large time accuracy (infinite equilibrium states)

## Numerical analysis:

- 1 Large time Energy Stability
- 2 Unique Solvability of the schemes
- 3 Convergence of iterative algorithms approximating nonlinear schemes

# Allen-Cahn and Cahn-Hilliard models

The **Allen-Cahn** and the **Cahn-Hilliard** models are **gradient flows** for the same **Free Energy** (Liapunov functional):

$$E(\phi) = E_{philic}(\phi) + E_{phobic}(\phi) := \int_{\Omega} \left( \frac{1}{2} |\nabla \phi|^2 + F(\phi) \right) dx$$

where  $F(\phi)$  is a **double-well potential** taking two minimum (stable) values:

$$F(\phi) = \frac{1}{4\varepsilon^2} (\phi^2 - 1)^2 \quad \text{at } \phi = \pm 1 \quad (\text{polynomial potential: } \mathbf{Ginzburg-Landau})$$

- **Allen-Cahn** :  $\phi_t + \gamma \frac{\delta E}{\delta \phi} = 0 \Rightarrow$  Maximum Principle
- **Cahn-Hilliard**:  $\phi_t - \nabla \cdot \left( M(\phi) \nabla \frac{\delta E}{\delta \phi} \right) = 0 \Rightarrow$  Mass Conservation

where  $\frac{\delta E}{\delta \phi} = -\Delta \phi + f(\phi)$  with  $f(\phi) = F'(\phi) = \frac{1}{\varepsilon^2} (\phi^3 - \phi)$ .

In both cases:

$$d_t E(\phi(t)) \leq 0.$$

**Weak formulation:** Find  $(\phi, w)$  such that

$$\phi \in L^\infty((0, T); H^1(\Omega)) \quad \text{and} \quad w \in L^2((0, T); H^1(\Omega))$$

satisfying

$$\begin{cases} \langle \phi_t, \bar{w} \rangle + \gamma (\nabla w, \nabla \bar{w}) = 0 & \forall \bar{w} \in H^1(\Omega) \\ (\nabla \phi, \nabla \bar{\phi}) + (f(\phi), \bar{\phi}) - (w, \bar{\phi}) = 0 & \forall \bar{\phi} \in H^1(\Omega). \end{cases}$$

**Energy Law:**

$$\frac{d}{dt} E(\phi(t)) + \gamma \int_{\Omega} |\nabla w|^2 dx = 0.$$

Mathematical Analysis: [Abels](#), [Garcke](#), [Grasselli](#), [Miranville](#), [Schimperna](#), ...

Numerical Analysis: [Boyer](#), [Elliot](#), [Feng](#), [Gómez](#), [Hughes](#), [Prohl](#),

...

**Generic Second order Finite Difference schemes** (Crank-Nicolson for linear terms)

$$\begin{cases} (\delta_t \phi^{n+1}, \bar{w}) + \gamma (\nabla w^{n+\frac{1}{2}}, \nabla \bar{w}) = 0 & \forall \bar{w} \in H^1(\Omega) \\ \left( \nabla \left( \frac{\phi^{n+1} + \phi^n}{2} \right), \nabla \bar{\phi} \right) + (f^k(\phi^{n+1}, \phi^n), \bar{\phi}) - (w^{n+\frac{1}{2}}, \bar{\phi}) = 0 & \forall \bar{\phi} \in H^1(\Omega), \end{cases}$$

where  $\delta_t \phi^{n+1} = (\phi^{n+1} - \phi^n)/k$  (discrete time derivative).

**Discrete Energy Law:** Testing by  $(\bar{w}, \bar{\phi}) = (w^{n+\frac{1}{2}}, \delta_t \phi^{n+1})$

$$\delta_t E(\phi^{n+1}) + \gamma \|\nabla w^{n+\frac{1}{2}}\|_{L^2}^2 + \cancel{ND_{phobic}(\phi^{n+1}, \phi^n)} + ND_{phobic}(\phi^{n+1}, \phi^n) = 0,$$

where

$$ND_{phobic}(\phi^{n+1}, \phi^n) := \left( \nabla \left( \frac{\phi^{n+1} + \phi^n}{2} \right), \nabla \delta_t \phi^{n+1} \right) - \delta_t \left( \int_{\Omega} \frac{1}{2} |\nabla \phi^{n+1}|^2 \right) = 0$$

and

$$ND_{phobic}(\phi^{n+1}, \phi^n) := (f^k(\phi^{n+1}, \phi^n), \delta_t \phi^{n+1}) - \delta_t \left( \int_{\Omega} F(\phi^{n+1}) \right)$$

## Definition

Numerical schemes are **energy-stable** if

$$\delta_t E(\phi^{n+1}) + \gamma \int_{\Omega} |\nabla w^{n+\frac{1}{2}}|^2 \leq 0, \quad \forall n.$$

In particular, the discrete energy decreases,

$$E(\phi^{n+1}) \leq E(\phi^n), \quad \forall n.$$



## [Eyre]

Splitting the potential term

$$F(\phi) = F_c(\phi) + F_e(\phi) \quad \text{with} \quad F_c'' \geq 0 \text{ (convex)} \quad \text{and} \quad F_e'' \leq 0 \text{ (concave)}$$

Taking implicitly the convex term and explicitly the non-convex one, i.e.

$$f^k(\phi^{n+1}, \phi^n) = f_c(\phi^{n+1}) + f_e(\phi^n) = \frac{1}{\varepsilon^2} ((\phi^{n+1})^3 - \phi^n),$$

## Properties:

- First order accurate
- Nonlinear scheme
- Unconditionally unique solvable
- Unconditionally energy-stable

Midpoint approximation of the potential term **[Elliot]**, **[Du]**, **[Lin]**,...

$$f^k(\phi^{n+1}, \phi^n) = \frac{F(\phi^{n+1}) - F(\phi^n)}{\phi^{n+1} - \phi^n}$$

Then

$$ND_{phobic}(\phi^{n+1}, \phi^n) = 0 \quad \Rightarrow \quad \delta_t E(\phi^{n+1}) + \gamma \|\nabla w^{n+\frac{1}{2}}\|_{L^2}^2 = 0$$

## Properties:

- Second order accurate
- Nonlinear scheme
- Conditionally unique solvable ( $k < \varepsilon^4/\gamma$ )
- Unconditionally energy-stable

## Theorem

- *Solvability hypothesis*

$$k < \frac{4\varepsilon^4}{\gamma}$$

- *Convergence hypothesis*

$$\frac{k^{1/2}}{\varepsilon^4} < C \quad \text{and} \quad \lim_{(k,h) \rightarrow 0} \frac{k}{h^2} = 0.$$

**[Wang et al.]**

Splitting the potential term  $F(\phi) = F_c(\phi) + F_e(\phi)$  with  $F_c'' \geq 0$  (convex) and  $F_e'' \leq 0$  (concave), Taking **MP** for the convex term and **BDF2** for the non-convex:

$$f^k(\phi^{n+1}, \phi^n, \phi^{n-1}) = \frac{F_c(\phi^{n+1}) - F_c(\phi^n)}{\phi^{n+1} - \phi^n} + \frac{1}{2} \left( 3f_e(\phi^n) - f_e(\phi^{n-1}) \right).$$

**Properties:**

- Second order accurate
- Nonlinear scheme
- Unconditionally unique solvable
- Unconditionally energy-stable for a perturbed energy

$$\tilde{E}(\phi^{n+1}) = E(\phi^{n+1}) + k^2 \int_{\Omega} \frac{1}{4\varepsilon^2} |\delta_t \phi^{n+1}|^2 dx,$$

## Theorem

- *Unconditionally unique solvable*
- *Convergence hypothesis (Idem **MP**)*

$$\frac{k^{1/2}}{\varepsilon^4} < C \quad \text{and} \quad \lim_{(k,h) \rightarrow 0} \frac{k}{h^2} = 0.$$

**Aim:** Design  $f^k(\phi^{n+1}, \phi^n)$ , linear, second order accurate and

$$ND_{phobic}(\phi^{n+1}, \phi^n) = O(k^2)$$

**Idea:** Using a Hermite quadrature formula,

$$\begin{aligned} \frac{F(\phi^{n+1}) - F(\phi^n)}{\phi^{n+1} - \phi^n} &= \frac{1}{\phi^{n+1} - \phi^n} \int_{\phi^n}^{\phi^{n+1}} f(\phi) d\phi \\ &= f(\phi^n) + \frac{f'(\phi^n)}{2}(\phi^{n+1} - \phi^n) + C f''(\phi^{n+\zeta})(\phi^{n+1} - \phi^n)^2 \end{aligned}$$

We define

$$f^k(\phi^{n+1}, \phi^n) := f(\phi^n) + \frac{1}{2}(\phi^{n+1} - \phi^n)f'(\phi^n)$$

**Properties:**

- Second order
- Linear scheme
- Conditionally solvable ( $k < 8\varepsilon^4/\gamma$ )

**Remark:** We can not control the sign of  $ND_{phobic}(\phi^{n+1}, \phi^n)$

Splitting the potential term  $F(\phi) = F_c(\phi) + F_e(\phi)$  with  $F_c'' \geq 0$  (convex) and  $F_e'' \leq 0$  (concave), **OD2** approximation of the convex term and **BDF2** the non-convex one,

$$f^k(\phi^{n+1}, \phi^n, \phi^{n-1}) = f_c(\phi^n) + \frac{1}{2}(\phi^{n+1} - \phi^n)f_c'(\phi^n) + \frac{1}{2}(3f_e(\phi^n) - f_e(\phi^{n-1})).$$

## Properties:

- Second order
- Linear scheme
- Unconditionally solvable

**Remark:** We can not control the sign of  $ND_{phobic}(\phi^{n+1}, \phi^n)$

We have developed a new adaptive-in-time algorithm by using a criterion related to the 'residual energy law'.

## Generic Algorithm:

Given  $\phi^n, \phi^{n-1}, dt^{n-1}, dt^n$ , **resmax** and **resmin**:

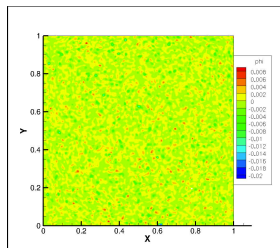
- 1 Compute  $\phi^{n+1}$  and

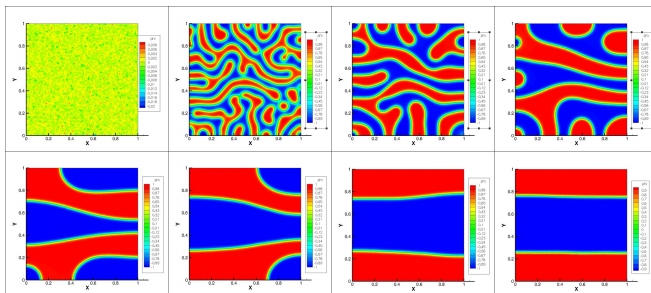
$$RE^{n+1} := \frac{E(\phi^{n+1}) - E(\phi^n)}{dt^n} + \|\nabla w^{n+1/2}\|_{L^2}^2.$$

- 2 If  $|RE^{n+1}| > \mathbf{resmax}$ , take  $dt^n = dt^n / \theta$  and go to 1).  
( $\theta > 1$ )
- 3 If  $|RE^{n+1}| < \mathbf{resmin}$ , take  $dt^{n+1} = \theta dt^n$ .
- 4 Take  $t^{n+1} = t^n + dt^n$  and go to next time step.



- $\mathcal{P}_1$ -cont. FE for  $\phi_h, w_h$ .
- $\Omega = [0, 1]^2$ ,  $h = 1/90$ ,  $\gamma = 10^{-4}$ ,  $\varepsilon = 10^{-2}$ , **resmax** = 10 and **resmin** = 1.
- In Newton's method, a tolerance parameter  $tol = 10^{-3}$ . The time-step is reduced in the case that the method does not converge in 10 iterations.
- Random initial data (the same for all the schemes).

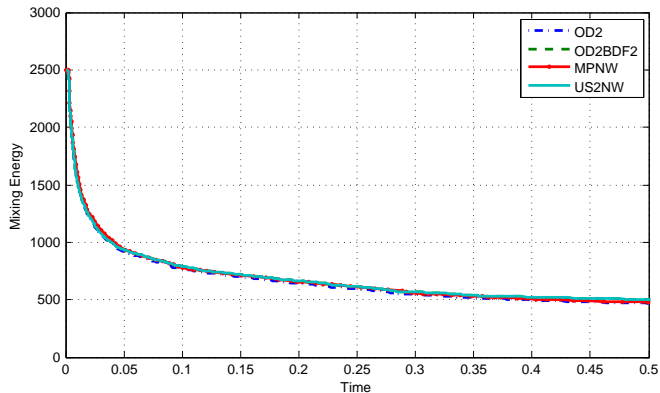




**Figura:** Dynamic of the model for the random initial condition

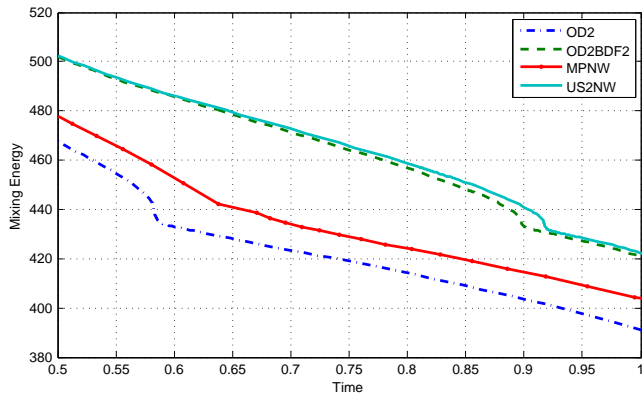


## Mixing energy



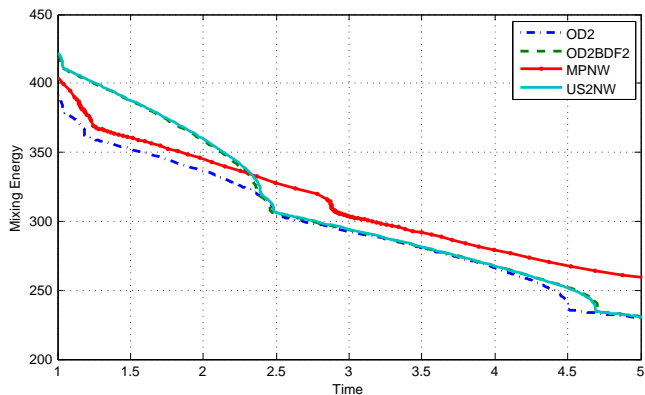
**Figura:** Mixing energy in  $[0, 0.5]$

## Mixing energy



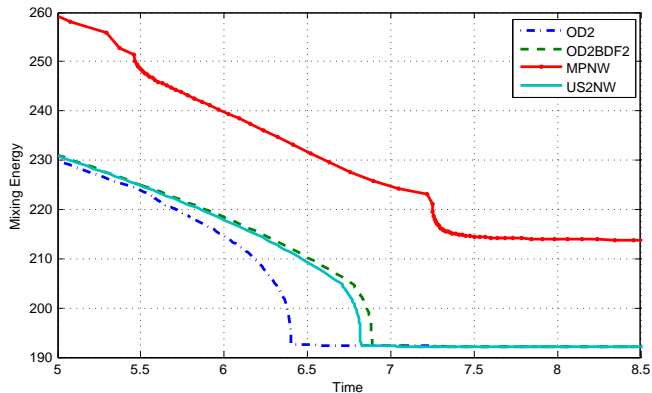
**Figura:** Mixing energy in  $[0.5, 1]$

## Mixing energy

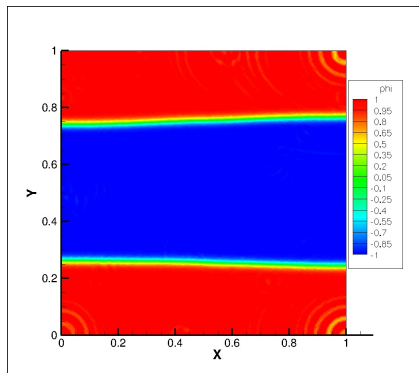


**Figura:** Mixing energy in  $[1, 5]$

## Mixing energy

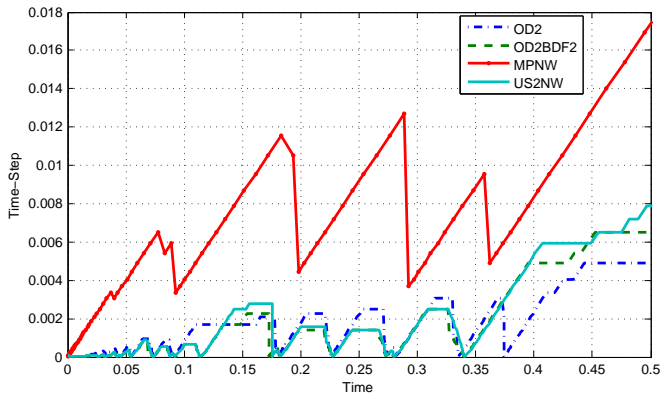


**Figura:** Mixing energy in  $[5, 8.5]$



**Figura:** Equilibrium solution of MP

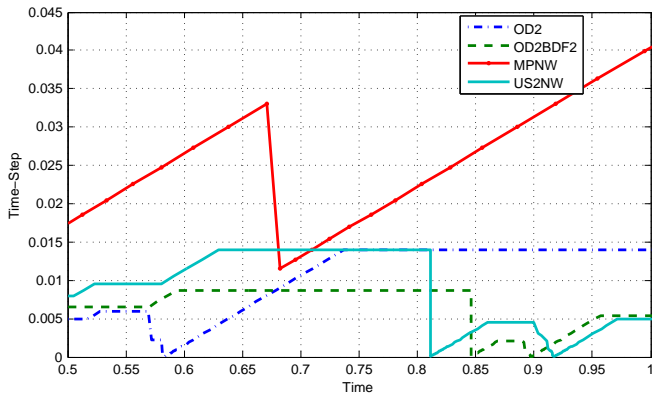
## Time steps



**Figura:** Time steps in  $[0, 0.5]$

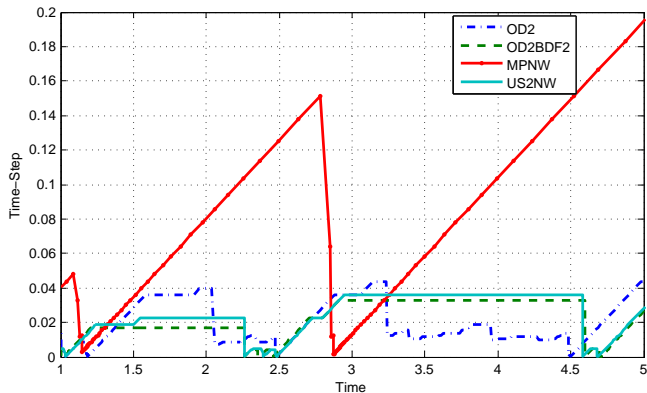


## Time steps



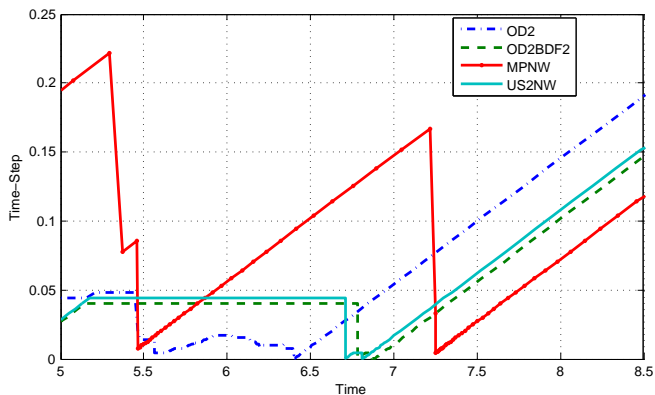
**Figura:** Time steps in  $[0.5, 1]$

## Time steps



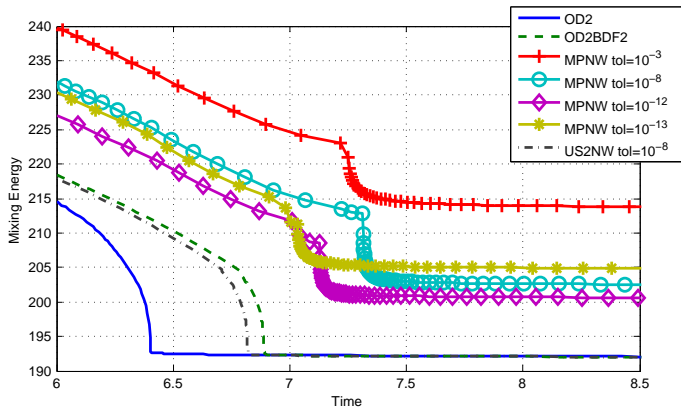
**Figura:** Time steps in  $[1, 5]$

## Time steps



**Figura:** Time steps in [5, 8.5]

## Time steps



**Figura:** Mixing energy in [6, 8.5]

## Computational cost:

	MP	OD2	OD2-BDF2	US2
# Time steps	339	2642	4340	3691
# Linear systems solved	3896	3533	5687	12812

(OD2 with constant time step  $k = 10^{-4} \Rightarrow \simeq 80000$  iterations)

## Conclusions:

	MP	OD2	OD2-BDF2	US2	LM2
Linear	X	✓	✓	X	✓
Unconditionally Unique Solvable	X	X	✓	✓	✓
Conditionally Unique Solvable	✓	✓			
Unconditionally Energy-Stable $E(\phi)$	✓	X	X	X	X
Uncond. (Modified-Energy)-Stable $\tilde{E}(\phi)$		X	X	✓	✓
One-Step Algorithm	✓	✓	X	X	X
Time-step Adaptivity	X	✓	✓	✓	X

**Figura:** Features of schemes

- **OD2** time scheme.
- Finite element discretization in space, with  $\phi_h$  and  $w_h$  in  $\mathcal{P}_1$ -cont. FE
- $\Omega = [0, 1]^3$ ,  $h = 1/30$ ,  $\gamma = 10^{-4}$ ,  $\varepsilon = 10^{-2}$ , **resmax** = 10 and **resmin** = 1.
- Random initial data.



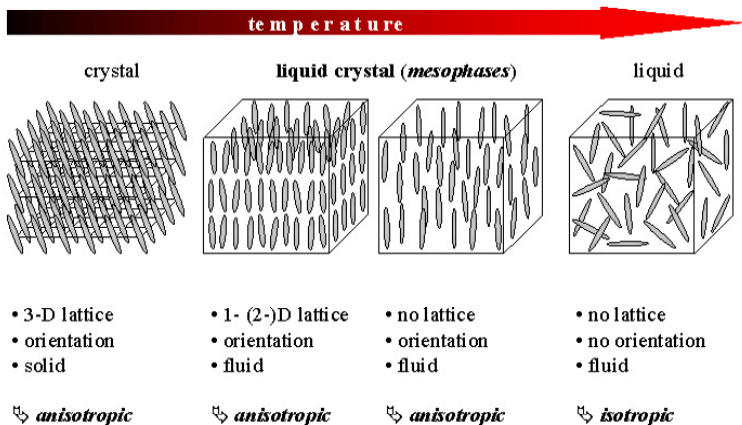
View I



View II

## **LINEAR UNCONDITIONAL ENERGY-STABLE SPLITTING SCHEMES FOR A PHASE-FIELD MODEL FOR NEMATIC-ISOTROPIC FLOWS WITH ANCHORING EFFECTS**

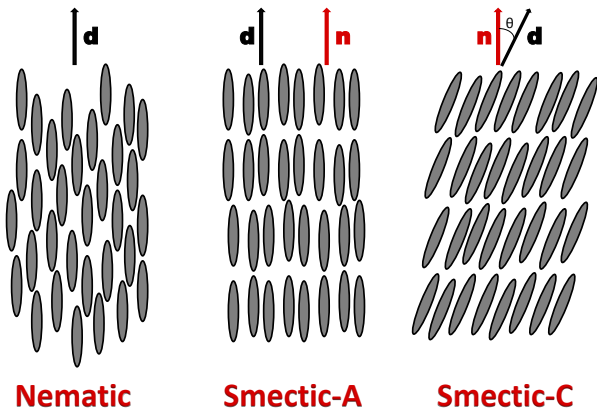
## *thermotropic liquid crystals*



**Figura:** Types of Liquid Crystals



# Types of Liquid Crystals



**Figura:** Types of Liquid Crystals

# Nematic Liquid Crystals

Ginzburg-Landau formulation (penalized version of Ericksen-Leslie system):

$$\left\{ \begin{array}{l} \mathbf{u}_t + \mathbf{u} \cdot \nabla \mathbf{u} + \nabla p - \nabla \cdot \sigma_{\text{vis}} - \nabla \cdot \sigma_{\text{nem}} = 0, \\ \nabla \cdot \mathbf{u} = 0, \\ \mathbf{d}_t + (\mathbf{u} \cdot \nabla) \mathbf{d} + \gamma_{\text{nem}} \mathbf{w} = 0, \\ \mathbf{w} = \frac{\delta E_{\text{nem}}}{\delta \mathbf{d}}, \end{array} \right. \quad (1)$$

where  $(\delta \cdot / \delta \mathbf{d})$  denotes the variational derivative with respect to  $\mathbf{d}$ ,  $\gamma_{\text{nem}} > 0$  is the relaxation time coefficient,

$$\begin{aligned} \sigma_{\text{vis}} &= 2\nu \mathbf{D}\mathbf{u}, \\ \sigma_{\text{nem}} &= -\lambda_{\text{nem}} (\nabla \mathbf{d})^t \nabla \mathbf{d}, \end{aligned}$$

and

$$E_{\text{nem}}(\mathbf{d}) = \int_{\Omega} \left( \frac{1}{2} |\nabla \mathbf{d}|^2 + G(\mathbf{d}) \right) d\mathbf{x} \quad \text{with} \quad G(\mathbf{d}) = \frac{1}{4\eta^2} (|\mathbf{d}|^2 - 1)^2.$$

It is known that this system satisfies the following energy law,

$$\frac{d}{dt} [E_{\text{kin}}(\mathbf{u}) + \lambda_{\text{nem}} E_{\text{nem}}(\mathbf{d})] + 2 \int_{\Omega} \nu |\mathbf{D}\mathbf{u}|^2 d\mathbf{x} + \lambda_{\text{nem}} \int_{\Omega} \gamma_{\text{nem}} \left| \frac{\delta E_{\text{nem}}}{\delta \mathbf{d}} \right|^2 d\mathbf{x} = 0.$$

The following variable will take part in the description of the model:

- the solenoidal velocity  $\mathbf{u}(t, \mathbf{x})$ ,  $t \in (0, T)$ ,  $\mathbf{x} \in \Omega \subset \mathbb{R}^3$
- the pressure of the fluid  $p(t, \mathbf{x})$ ,
- the director field  $\mathbf{d}(t, \mathbf{x})$ , that represents the average orientation of the liquid crystal molecules,
- the function  $c(t, \mathbf{x})$  localizing the two components along the domain  $\Omega \subset \mathbb{R}^d$  ( $d = 2$  or  $3$ ) filled by the mixture,

$$c(t, \mathbf{x}) = \begin{cases} -1 & \text{in the Newtonian Fluid part,} \\ \in (-1, 1) & \text{in the interface part,} \\ 1 & \text{in the Nematic Liquid Crystal part.} \end{cases}$$

# Nematic-Isotropic. Energy

The total energy of the system is given by

$$E_{\text{tot}}(\mathbf{u}, \mathbf{d}, \mathbf{c}) = E_{\text{kin}}(\mathbf{u}) + \lambda_{\text{mix}} E_{\text{mix}}(\mathbf{c}) + \lambda_{\text{nem}} E_{\text{nem}}(\mathbf{d}, \mathbf{c}) + \lambda_{\text{anch}} E_{\text{anch}}(\mathbf{d}, \mathbf{c})$$

with

$$E_{\text{kin}}(\mathbf{u}) = \frac{1}{2} \int_{\Omega} |\mathbf{u}|^2 d\mathbf{x} \quad \text{kinetic energy,}$$

$$E_{\text{mix}}(\mathbf{c}) = \int_{\Omega} \left( \frac{1}{2} |\nabla \mathbf{c}|^2 + F(\mathbf{c}) \right) d\mathbf{x} \quad \text{mixing energy,}$$

$$E_{\text{nem}}(\mathbf{d}, \mathbf{c}) = \int_{\Omega} I(\mathbf{c}) \left( \frac{1}{2} |\nabla \mathbf{d}|^2 + G(\mathbf{d}) \right) d\mathbf{x} \quad \text{elastic energy,}$$

where

$$F(\mathbf{c}) = \frac{1}{4\varepsilon^2} (\mathbf{c}^2 - 1)^2, \quad G(\mathbf{d}) = \frac{1}{4\eta^2} (|\mathbf{d}|^2 - 1)^2,$$

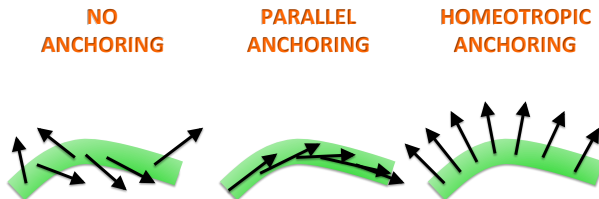
and we represent their derivatives as  $f(\mathbf{c}) := F'(\mathbf{c})$  and  $\mathbf{g}(\mathbf{d}) := G'(\mathbf{d})$ .

# Nematic-Isotropic. The anchoring effect

At the interface between the nematic and newtonian fluids, liquid crystals prefer to orientate following a certain direction (called as **easy direction**).

Three effects can be described:

- the **parallel case**, where the director vector is parallel to the interface,
- the **homeotropic case**, where the director vector is normal to the interface,
- **no anchoring**.



$$E_{\text{anch}}(\mathbf{d}, \mathbf{c}) = \frac{1}{2} \int_{\Omega} \left( \delta_1 |\mathbf{d}|^2 |\nabla \mathbf{c}|^2 + \delta_2 |\mathbf{d} \cdot \nabla \mathbf{c}|^2 \right) d\mathbf{x}$$

where the anchoring energy will take different forms depending on the anchoring effect considered, that is,

$$(\delta_1, \delta_2) = \begin{cases} (0, 0) & \text{no anchoring,} \\ (0, 1) & \text{parallel anchoring,} \\ (1, -1) & \text{homeotropic anchoring.} \end{cases} \quad (2)$$

# Nematic-Isotropic. The localizing functional $I(c)$

It represents the volume fraction of liquid crystal at each point  $x \in \Omega$  and its derivative will be denoted by  $i(c) := I'(c)$ . It could take different forms but any admissible form must satisfy the following properties:

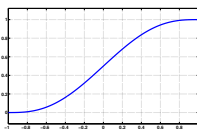
- $I \in C^2(\mathbb{R})$ ,
- $I(c) = 0$  if  $c \leq -1$ ,
- $I(c) = 1$  if  $c \geq 1$ ,
- $I(c) \in (0, 1)$  if  $c \in (-1, 1)$ .

We consider the following interpolation function

$$I(c) := \begin{cases} 0 & \text{if } c \leq -1, \\ \frac{1}{16} (c+1)^3 (3c^2 - 9c + 8) & \text{if } c \in (-1, 1), \\ 1 & \text{if } c \geq 1, \end{cases}$$

and its derivative is defined as

$$i(c) := I'(c) = \begin{cases} \frac{15}{16} (c+1)^2 (c-1)^2 & \text{if } c \in (-1, 1), \\ 0 & \text{otherwise.} \end{cases}$$



Combining the **Least Action Principle (LAP)** and the **Maximum Dissipation Principle (MDP)**, we arrive to the following PDE system, fulfilled in the time space domain  $(0, T) \times \Omega$ :

$$\left\{ \begin{array}{l} \mathbf{u}_t + \mathbf{u} \cdot \nabla \mathbf{u} + \nabla p - \nabla \cdot \sigma_{\text{tot}} = 0, \\ \nabla \cdot \mathbf{u} = 0, \\ \mathbf{d}_t + (\mathbf{u} \cdot \nabla) \mathbf{d} + \gamma_{\text{nem}} \mathbf{w} = 0, \\ \mathbf{w} = \frac{\delta E_{\text{tot}}}{\delta \mathbf{d}}, \\ \mathbf{c}_t + \mathbf{u} \cdot \nabla \mathbf{c} - \nabla \cdot (\gamma_{\text{mix}} \nabla \mu) = 0, \\ \mu = \frac{\delta E_{\text{tot}}}{\delta \mathbf{c}}. \end{array} \right. \quad (3)$$



The total tensor reads,

$$\sigma_{\text{tot}} = \sigma_{\text{vis}} + \sigma_{\text{mix}} + \sigma_{\text{nem}} + \sigma_{\text{anch}},$$

being:

$$\sigma_{\text{vis}} = 2\nu \mathbf{D}\mathbf{u} \quad \text{viscosity,}$$

$$\sigma_{\text{mix}} = -\lambda_{\text{mix}} \nabla \mathbf{c} \otimes \nabla \mathbf{c} \quad \text{mixing tensor,}$$

$$\sigma_{\text{nem}} = -\lambda_{\text{nem}} I(\mathbf{c})(\nabla \mathbf{d})^t \nabla \mathbf{d} \quad \text{nematic tensor,}$$

and the anchoring tensor  $\sigma_{\text{anch}}$  has the form:

$$(\sigma_{\text{anch}})_{ij} = \lambda_{\text{anch}} \left[ \delta_1 |\mathbf{d}|^2 \nabla \mathbf{c} \otimes \nabla \mathbf{c} + \delta_2 (\mathbf{d} \cdot \nabla \mathbf{c}) (\nabla \mathbf{c} \otimes \mathbf{d}) \right]$$

# Nematic-Isotropic. The expression for $w$ and $\mu$

Taking into account that the total energy of the system is given by

$$E_{\text{tot}}(\mathbf{u}, \mathbf{d}, \mathbf{c}) = E_{\text{kin}}(\mathbf{u}) + \lambda_{\text{mix}} E_{\text{mix}}(\mathbf{c}) + \lambda_{\text{nem}} E_{\text{nem}}(\mathbf{d}, \mathbf{c}) + \lambda_{\text{anch}} E_{\text{anch}}(\mathbf{d}, \mathbf{c})$$

then the variational derivatives of  $E_{\text{tot}}$  are

$$\mathbf{w} = \frac{\delta E_{\text{tot}}}{\delta \mathbf{d}} = \lambda_{\text{nem}} [-\nabla \cdot (I(\mathbf{c}) \nabla \mathbf{d}) + I(\mathbf{c}) G'(\mathbf{d})] + \lambda_{\text{anch}} \frac{\delta E_{\text{anch}}}{\delta \mathbf{d}},$$

and

$$\mu = \frac{\delta E_{\text{tot}}}{\delta \mathbf{c}} = \lambda_{\text{mix}} [-\Delta \mathbf{c} + F'(\mathbf{c})] + \lambda_{\text{nem}} I'(\mathbf{c}) \left( \frac{1}{2} |\nabla \mathbf{d}|^2 + G(\mathbf{d}) \right) + \lambda_{\text{anch}} \frac{\delta E_{\text{anch}}}{\delta \mathbf{c}},$$

where the anchoring terms will depend on each case:

$$\frac{\delta E_{\text{anch}}}{\delta \mathbf{d}} = \begin{cases} 0 & \text{No anchoring,} \\ (\mathbf{d} \cdot \nabla \mathbf{c}) \nabla \mathbf{c} & \text{Parallel anch.,} \\ |\nabla \mathbf{c}|^2 \mathbf{d} - (\mathbf{d} \cdot \nabla \mathbf{c}) \nabla \mathbf{c} & \text{Homeotropic anch..} \end{cases} \quad (4)$$

and

$$\frac{\delta E_{\text{anch}}}{\delta \mathbf{c}} = \begin{cases} 0 & \text{No anchoring,} \\ -\nabla \cdot [(\mathbf{d} \cdot \nabla \mathbf{c}) \mathbf{d}] & \text{Parallel anch.,} \\ -\nabla \cdot [|\mathbf{d}|^2 \nabla \mathbf{c} - (\mathbf{d} \cdot \nabla \mathbf{c}) \mathbf{d}] & \text{Homeotropic anch.} \end{cases} \quad (5)$$

The PDE system (3) is closed with the following initial and boundary conditions:

$$\begin{aligned} \mathbf{u}|_{t=0} &= \mathbf{u}_0, & \mathbf{d}|_{t=0} &= \mathbf{d}_0, & \mathbf{c}|_{t=0} &= \mathbf{c}_0 & \text{in } \Omega, \\ \mathbf{u}|_{\partial\Omega} &= (I(\mathbf{c})\nabla\mathbf{d})\mathbf{n}|_{\partial\Omega} = \mathbf{0} & & & & & \text{in } (0, T), \\ \frac{\partial\mathbf{c}}{\partial\mathbf{n}}\Big|_{\partial\Omega} &= \left(\nabla\frac{\delta E_{tot}}{\delta\mathbf{c}}\right) \cdot \mathbf{n}\Big|_{\partial\Omega} = 0 & & & & & \text{in } (0, T), \end{aligned} \tag{6}$$

# Nematic-Isotropic. Reformulation of the stress tensor

## Lemma

*The following relation holds:*

$$-\nabla \cdot \sigma_{\text{mix}} - \nabla \cdot \sigma_{\text{nem}} - \nabla \cdot \sigma_{\text{anch}} = -\mu \nabla \mathbf{c} - (\nabla \mathbf{d})^t \mathbf{w} + \nabla \varphi$$

where

$$\varphi = \lambda_{\text{nem}} I(\mathbf{c}) \left( \frac{1}{2} |\nabla \mathbf{d}|^2 + G(\mathbf{d}) \right) + \lambda_{\text{mix}} \left( \frac{1}{2} |\nabla \mathbf{c}|^2 + F(\mathbf{c}) \right) + \frac{\lambda_{\text{anch}}}{2} W(\mathbf{d}, \mathbf{c}),$$

$$\text{with } W(\mathbf{d}, \mathbf{c}) = (\delta_1 |\mathbf{d}|^2 |\nabla \mathbf{c}|^2 + \delta_2 |\mathbf{d} \cdot \nabla \mathbf{c}|^2).$$

$$\langle \mathbf{u}_t, \bar{\mathbf{u}} \rangle + ((\mathbf{u} \cdot \nabla) \mathbf{u}, \bar{\mathbf{u}}) + (\nu(\mathbf{c}) \mathbf{D}\mathbf{u}, \mathbf{D}\bar{\mathbf{u}}) - (\bar{\rho}, \nabla \cdot \bar{\mathbf{u}}) - ((\nabla \mathbf{d})^t \mathbf{w}, \bar{\mathbf{u}}) + (\mathbf{c} \nabla \mu, \bar{\mathbf{u}}) = 0,$$

$$(\nabla \cdot \mathbf{u}, \bar{\rho}) = 0,$$

$$\langle \mathbf{d}_t, \bar{\mathbf{w}} \rangle + ((\mathbf{u} \cdot \nabla) \mathbf{d}, \bar{\mathbf{w}}) + \gamma_{\text{nem}}(\mathbf{w}, \bar{\mathbf{w}}) = 0,$$

$$\lambda_{\text{nem}}(I(\mathbf{c}) \nabla \mathbf{d}, \nabla \bar{\mathbf{d}}) + \lambda_{\text{nem}}(I(\mathbf{c}) \mathbf{g}(\mathbf{d}), \bar{\mathbf{d}}) + \lambda_{\text{anch}} \frac{\delta E_{\text{anch}}}{\delta \mathbf{d}} = (\mathbf{w}, \bar{\mathbf{d}}),$$

$$(\mathbf{c}_t, \bar{\mu}) - (\mathbf{c} \mathbf{u}, \nabla \bar{\mu}) + \gamma_{\text{mix}}(\nabla \mu, \nabla \bar{\mu}) = 0,$$

$$\lambda_{\text{mix}}(\nabla \mathbf{c}, \nabla \bar{\mathbf{c}}) + \lambda_{\text{mix}}(f(\mathbf{c}), \bar{\mathbf{c}}) + \lambda_{\text{nem}} \left( i(\mathbf{c}) \left[ \frac{|\nabla \mathbf{d}|^2}{2} + G(\mathbf{d}) \right], \bar{\mathbf{c}} \right) + \lambda_{\text{anch}} \frac{\delta E_{\text{anch}}}{\delta \mathbf{c}} = (\mu, \bar{\mathbf{c}}),$$

for each  $(\bar{\mathbf{u}}, \bar{\rho}, \bar{\mathbf{w}}, \bar{\mathbf{d}}, \bar{\mu}, \bar{\mathbf{c}}) \in \mathbf{H}_0^1(\Omega) \times L_0^2(\Omega) \times \mathbf{H}^1(\Omega) \times \mathbf{H}^1(\Omega) \times H^1(\Omega) \times H^1(\Omega)$ .

# Nematic-Isotropic. Continuous energy law

Using adequate test functions, we can prove that the previous system satisfies the following (dissipative) energy law:

$$\frac{d}{dt} E_{\text{tot}}(\mathbf{u}, \mathbf{d}, \mathbf{c}) + \int_{\Omega} \nu(\mathbf{c}) |\mathbf{D}\mathbf{u}|^2 d\mathbf{x} + \gamma_{nem} \int_{\Omega} |\mathbf{w}|^2 d\mathbf{x} + \gamma_{mix} \int_{\Omega} |\nabla\mu|^2 d\mathbf{x} = 0.$$

From the energy law, we deduce the following regularity for a (possible) solution:

$$\left\{ \begin{array}{l} \mathbf{u} \in L^{\infty}(0, T; \mathbf{L}^2(\Omega)) \cap L^2(0, T; \mathbf{H}^1(\Omega)), \\ \mathbf{w} \in L^2(0, T; \mathbf{L}^2(\Omega)), \\ \nabla \mathbf{c} \in L^{\infty}(0, T; \mathbf{L}^2(\Omega)), \\ \nabla \mu \in L^2(0, T; \mathbf{L}^2(\Omega)), \\ \int_{\Omega} F(\mathbf{c}) d\mathbf{x} \in L^{\infty}(0, T), \\ \int_{\Omega} I(\mathbf{c}) \left( \frac{1}{2} |\nabla \mathbf{d}|^2 + G(\mathbf{d}) \right) d\mathbf{x} \in L^{\infty}(0, T) \\ E_{\text{anch}}(\mathbf{c}, \mathbf{d}) \in L^{\infty}(0, T), \\ \mathbf{c} \in L^{\infty}(0, T; H^1(\Omega)), \\ \int_{\Omega} I(\mathbf{c}) |\mathbf{d}|^4 \in L^{\infty}(0, T), \\ \mathbf{d} \in L^{\infty}(0, T; \mathbf{L}^2(\Omega)). \end{array} \right. \quad (7)$$

For simplicity, we describe our numerical scheme using an uniform partition of the time interval:  $t_n = nk$ , where  $k > 0$  denotes the (fixed) time step. Moreover, hereafter we denote

$$\delta_t \mathbf{a}^{n+1} := \frac{\mathbf{a}^{n+1} - \mathbf{a}^n}{k}.$$

## Definition

A numerical scheme is energy-stable if it satisfies

$$\delta_t E_{\text{tot}}(\mathbf{u}^{n+1}, \mathbf{d}^{n+1}, \mathbf{c}^{n+1}) + \int_{\Omega} \nu(\mathbf{c}^{n+1}) |\mathbf{D}\mathbf{u}^{n+1}|^2 d\mathbf{x} \\ + \gamma_{\text{nem}} \int_{\Omega} |\mathbf{w}^{n+1}|^2 d\mathbf{x} + \gamma_{\text{mix}} \int_{\Omega} |\nabla \mu^{n+1}|^2 d\mathbf{x} \leq 0, \quad \forall n.$$

In particular, energy-stable schemes satisfy the energy decreasing in time property, i.e.,

$$E_{\text{tot}}(\mathbf{u}^{n+1}, \mathbf{d}^{n+1}, \mathbf{c}^{n+1}) \leq E_{\text{tot}}(\mathbf{u}^n, \mathbf{d}^n, \mathbf{c}^n), \quad \forall n.$$



# Nematic-Isotropic. Coupled Nonlinear Implicit Scheme

Given  $(\mathbf{u}^n, p^n, \mathbf{d}^n, \mathbf{w}^n, c^n, \mu^n)$ , find  $(\mathbf{u}^{n+1}, p^{n+1}, \mathbf{d}^{n+1}, \mathbf{w}^{n+1}, c^{n+1}, \mu^{n+1})$  such that,

$$\left\{ \begin{aligned} & \left( \frac{\mathbf{u}^{n+1} - \mathbf{u}^n}{k}, \bar{\mathbf{u}} \right) + \left( (\mathbf{u}^{n+1} \cdot \nabla) \mathbf{u}^{n+1}, \bar{\mathbf{u}} \right) - (p^{n+1}, \nabla \cdot \bar{\mathbf{u}}) + 2(\nu \mathbf{D} \mathbf{u}^{n+1}, \mathbf{D} \bar{\mathbf{u}}) \\ & \quad - \left( (\nabla \mathbf{d}^{n+1})^t \mathbf{w}^{n+1}, \bar{\mathbf{u}} \right) + (c^{n+1} \nabla \mu^{n+1}, \bar{\mathbf{u}}) = 0, \\ & \quad (\nabla \cdot \mathbf{u}^{n+1}, \bar{p}) = 0, \\ & \left( \frac{\mathbf{d}^{n+1} - \mathbf{d}^n}{k}, \bar{\mathbf{w}} \right) + \left( (\mathbf{u}^{n+1} \cdot \nabla) \mathbf{d}^{n+1}, \bar{\mathbf{w}} \right) + \gamma_{nem}(\mathbf{w}^{n+1}, \bar{\mathbf{w}}) = 0, \\ & \lambda_{nem}(l(c^{n+1}) \nabla \mathbf{d}^{n+1}, \nabla \bar{\mathbf{d}}) + \lambda_{nem}(l(c^{n+1}) \mathbf{g}(\mathbf{d}^{n+1}), \bar{\mathbf{d}}) + \lambda_{anch} \left( \frac{\delta E_{anch}}{\delta \mathbf{d}}(c^{n+1}, \mathbf{d}^{n+1}), \bar{\mathbf{d}} \right) - (\mathbf{w}^{n+1}, \bar{\mathbf{d}}) = 0, \\ & \left( \frac{c^{n+1} - c^n}{k}, \bar{\mu} \right) - (c^{n+1} \mathbf{u}^{n+1}, \nabla \bar{\mu}) + \gamma_{mix}(\nabla \mu^{n+1}, \nabla \bar{\mu}) = 0, \\ & \lambda_{mix}(\nabla c^{n+1}, \nabla \bar{c}) + \lambda_{mix}(f(c^{n+1}), \bar{c}) + \lambda_{nem} \left( i(c^{n+1}) \left[ \frac{|\nabla \mathbf{d}^{n+1}|^2}{2} + G(\mathbf{d}^{n+1}) \right], \bar{c} \right) \\ & \quad + \lambda_{anch} \left( \frac{\delta E_{anch}}{\delta c}(c^{n+1}, \mathbf{d}^{n+1}), \bar{c} \right) - (\mu^{n+1}, \bar{c}) = 0, \end{aligned} \right. \quad (8)$$

Disadvantages of this scheme:

- High computational cost (Coupled + Nonlinear system)
- it is not clear that any iterative method to approximate the nonlinear scheme will converge (several nonlinearities)
- Energy-stability ?

We have designed two splitting first-order schemes, denoted by

$$(\mathbf{d}^{n+1}, \mathbf{w}^{n+1}) \rightarrow (\mathbf{c}^{n+1}, \mu^{n+1}) \rightarrow (\mathbf{u}^{n+1}, \mathbf{p}^{n+1}),$$

or

$$(\mathbf{c}^{n+1}, \mu^{n+1}) \rightarrow (\mathbf{d}^{n+1}, \mathbf{w}^{n+1}) \rightarrow (\mathbf{u}^{n+1}, \mathbf{p}^{n+1}),$$

decoupling computations for nematic part  $(\mathbf{d}, \mathbf{w})$  from the phase-field part  $(\mathbf{c}, \mu)$  (or the contrary in the second case) and from the fluid part  $(\mathbf{u}, \mathbf{p})$ .

## STEP 1:

Find  $(\mathbf{d}^{n+1}, \mathbf{w}^{n+1}) \in \mathbf{D}_h \times \mathbf{W}_h$  s. t, for each  $(\bar{\mathbf{d}}, \bar{\mathbf{w}}) \in \mathbf{D}_h \times \mathbf{W}_h$

$$\left\{ \begin{array}{l} \left( \frac{\mathbf{d}^{n+1} - \mathbf{d}^n}{k}, \bar{\mathbf{w}} \right) + ((\mathbf{u}^* \cdot \nabla) \mathbf{d}^n, \bar{\mathbf{w}}) + \gamma_{\text{nem}}(\mathbf{w}^{n+1}, \bar{\mathbf{w}}) = 0, \\ \lambda_{\text{nem}} \left( I(\mathbf{c}^n) \nabla \mathbf{d}^{n+1}, \nabla \bar{\mathbf{d}} \right) + \lambda_{\text{nem}} \left( I(\mathbf{c}^n) \mathbf{g}_k(\mathbf{d}^{n+1}, \mathbf{d}^n), \bar{\mathbf{d}} \right) \\ \quad + \lambda_{\text{anch}} \left( \Lambda_{\mathbf{d}}(\mathbf{d}^{n+1}, \mathbf{c}^n), \bar{\mathbf{d}} \right) - (\mathbf{w}^{n+1}, \bar{\mathbf{d}}) = 0, \end{array} \right.$$

where  $\mathbf{u}^* := \mathbf{u}^n + 2k(\nabla \mathbf{d}^n)^t \mathbf{w}^{n+1}$ ,

$\mathbf{g}_k(\mathbf{d}^{n+1}, \mathbf{d}^n)$  is an approximation of  $\mathbf{g}(\mathbf{d}(t_{n+1}))$  and

$\Lambda_{\mathbf{d}}(\mathbf{d}^{n+1}, \mathbf{c}^n)$  is the discrete approximation of  $\frac{\delta E_{\text{anch}}}{\delta \mathbf{d}}(\mathbf{d}(t_{n+1}), \mathbf{c}(t_{n+1}))$ :

$$\Lambda_{\mathbf{d}}(\mathbf{d}^{n+1}, \mathbf{c}^n) := \delta_1 |\nabla \mathbf{c}^n|^2 \mathbf{d}^{n+1} + \delta_2 (\mathbf{d}^{n+1} \cdot \nabla \mathbf{c}^n) \nabla \mathbf{c}^n$$

## STEP 2:

Find  $(\mathbf{c}^{n+1}, \mu^{n+1}) \in \mathcal{C}_h \times M_h$  s. t., for  $(\bar{\mathbf{c}}, \bar{\mu}) \in \mathcal{C}_h \times M_h$

$$\left\{ \begin{array}{l} \left( \frac{\mathbf{c}^{n+1} - \mathbf{c}^n}{k}, \bar{\mu} \right) - (\mathbf{c}^n \mathbf{u}^{**}, \nabla \bar{\mu}) + \gamma_{\text{mix}}(\nabla \mu^{n+1}, \nabla \bar{\mu}) = 0, \\ \lambda_{\text{mix}}(\nabla \mathbf{c}^{n+1}, \nabla \bar{\mathbf{c}}) + \lambda_{\text{mix}}(f_k(\mathbf{c}^{n+1}, \mathbf{c}^n), \bar{\mathbf{c}}) \\ + \lambda_{\text{nem}} \left( i_k(\mathbf{c}^{n+1}, \mathbf{c}^n) \left[ \frac{1}{2} |\nabla \mathbf{d}^{n+1}|^2 + G(\mathbf{d}^{n+1}) \right], \bar{\mathbf{c}} \right) \\ + \lambda_{\text{anch}} \left( \Lambda_{\mathbf{c}}(\mathbf{d}^{n+1}, \mathbf{c}^{n+1}), \nabla \bar{\mathbf{c}} \right) - (\mu^{n+1}, \bar{\mathbf{c}}) = 0, \end{array} \right.$$

where  $\mathbf{u}^{**} := \mathbf{u}^n - 2k \mathbf{c}^n \nabla \mu^{n+1}$ ,

$f_k(\mathbf{c}^{n+1}, \mathbf{c}^n)$  and  $i_k(\mathbf{c}^{n+1}, \mathbf{c}^n)$  are approximations of  $f(\mathbf{c}(t_{n+1}))$  and  $i(\mathbf{c}(t_{n+1}))$ , resp. and  $\Lambda_{\mathbf{c}}(\mathbf{d}^{n+1}, \mathbf{c}^{n+1})$  is the discrete approximation of  $\frac{\delta E_{\text{anch}}}{\delta \mathbf{c}}(\mathbf{d}(t_{n+1}), \mathbf{c}(t_{n+1}))$ :

$$\Lambda_{\mathbf{c}}(\mathbf{d}^{n+1}, \mathbf{c}^{n+1}) := \delta_1 |\mathbf{d}^{n+1}|^2 \nabla \mathbf{c}^{n+1} + \delta_2 (\mathbf{d}^{n+1} \cdot \nabla \mathbf{c}^{n+1}) \mathbf{d}^{n+1}$$

## STEP 3:

Find  $(\mathbf{u}^{n+1}, p^{n+1}) \in \mathbf{V}_h \times P_h$  s. t., for each  $(\bar{\mathbf{u}}, \bar{p}) \in \mathbf{V}_h \times P_h$

$$\left\{ \begin{array}{l} \left( \frac{\mathbf{u}^{n+1} - \hat{\mathbf{u}}}{k}, \bar{\mathbf{u}} \right) + c(\mathbf{u}^n, \mathbf{u}^{n+1}, \bar{\mathbf{u}}) - (p^{n+1}, \nabla \cdot \bar{\mathbf{u}}) \\ \quad + (\nu(\mathbf{c}^{n+1}) \mathbf{D}\mathbf{u}^{n+1}, \mathbf{D}\bar{\mathbf{u}}) = 0, \\ (\nabla \cdot \mathbf{u}^{n+1}, \bar{p}) = 0, \end{array} \right.$$

where

$$\hat{\mathbf{u}} := \frac{\mathbf{u}^* + \mathbf{u}^{**}}{2},$$

and

$$c(\mathbf{u}, \mathbf{v}, \mathbf{w}) := \left( (\mathbf{u} \cdot \nabla) \mathbf{v}, \mathbf{w} \right) + \frac{1}{2} \left( \nabla \cdot \mathbf{u}, \mathbf{v} \cdot \mathbf{w} \right).$$

Scheme given by **STEPS 1-3** satisfies the following local discrete energy law:

$$\begin{aligned}
 & \delta_t E(\mathbf{d}^{n+1}, \mathbf{c}^{n+1}, \mathbf{u}^{n+1}) + \gamma_{\text{nem}} \|\mathbf{w}^{n+1}\|_{L^2}^2 \\
 & + \gamma_{\text{mix}} \|\nabla \mu^{n+1}\|_{L^2}^2 + \|\nu(\mathbf{c}^{n+1})^{1/2} \mathbf{D}\mathbf{u}^{n+1}\|_{L^2}^2 \\
 & + ND_{\mathbf{u}}^{n+1} + ND_{\text{elast}}^{n+1}(\mathbf{c}^n) + ND_{\text{penal}}^{n+1}(\mathbf{c}^n) \\
 & + ND_{\text{philic}}^{n+1} + ND_{\text{phobic}}^{n+1} + ND_{\text{interp}}^{n+1} + ND_{\text{anch}}^{n+1} = 0.
 \end{aligned}$$

The numerical dissipation terms are:

$$ND_u^{n+1} = \frac{1}{2k} \left( \|u^{n+1} - \hat{u}\|_{L^2}^2 + \frac{\|\hat{u} - u^*\|_{L^2}^2 + \|\hat{u} - u^{**}\|_{L^2}^2}{2} + \frac{\|u^* - u^n\|_{L^2}^2 + \|u^{**} - u^n\|_{L^2}^2}{2} \right)$$

$$ND_{\text{elast}}^{n+1}(c^n) = \lambda_{\text{nem}} \frac{k}{2} \int_{\Omega} i(c^n) \left| \delta_t \nabla d^{n+1} \right|^2 dx,$$

$$ND_{\text{penal}}^{n+1}(c^n) = \lambda_{\text{nem}} \int_{\Omega} i(c^n) \left( g_k(d^{n+1}, d^n) \cdot \delta_t d^{n+1} - \delta_t G(d^{n+1}) \right) dx,$$

$$ND_{\text{phobic}}^{n+1} = \lambda_{\text{mix}} \frac{k}{2} \int_{\Omega} \left| \delta_t \nabla c^{n+1} \right|^2 dx,$$

$$ND_{\text{phobic}}^{n+1} = \lambda_{\text{mix}} \int_{\Omega} \left( f_k(c^{n+1}, c^n) \delta_t c^{n+1} - \delta_t F(c^{n+1}) \right) dx,$$

$$\begin{aligned}
 ND_{\text{interp}}^{n+1} &= \lambda_{\text{nem}} \int_{\Omega} \left( \frac{|\nabla \mathbf{d}^{n+1}|^2}{2} + G(\mathbf{d}^{n+1}) \right) \\
 &\quad \times (i_k(\mathbf{c}^{n+1}, \mathbf{c}^n) \delta_t \mathbf{c}^{n+1} - \delta_t l(\mathbf{c}^{n+1})) \, d\mathbf{x},
 \end{aligned}$$

and

$$\begin{aligned}
 ND_{\text{anch}}^{n+1} &= \lambda_{\text{anch}} \frac{k}{2} \int_{\Omega} \left( \delta_1 \left( |\delta_t \mathbf{d}^{n+1}|^2 |\nabla \mathbf{c}^n|^2 + |\mathbf{d}^{n+1}|^2 |\delta_t \nabla \mathbf{c}^{n+1}|^2 \right) \right. \\
 &\quad \left. + \delta_2 \left( |\delta_t \mathbf{d}^{n+1} \cdot \nabla \mathbf{c}^n|^2 + |\mathbf{d}^{n+1} \cdot \nabla \delta_t \mathbf{c}^{n+1}|^2 \right) \right) \, d\mathbf{x}.
 \end{aligned}$$

with  $(\delta_1, \delta_2)$  defined in (2) depending on the type of anchoring.



## QUESTION:

How to define  $f_k(\mathbf{c}^{n+1}, \mathbf{c}^n)$ ,  $g_k(\mathbf{d}^{n+1}, \mathbf{d}^n)$ ,  $i_k(\mathbf{c}^{n+1}, \mathbf{c}^n)$  to obtain linear unconditionally energy-stable schemes ?

That is, we want  $f_k(\mathbf{c}^{n+1}, \mathbf{c}^n)$ ,  $g_k(\mathbf{d}^{n+1}, \mathbf{d}^n)$ ,  $i_k(\mathbf{c}^{n+1}, \mathbf{c}^n)$  linear such that

$$ND_{\text{penal}}^{n+1}(\mathbf{c}^n) \geq 0, \quad ND_{\text{phobic}}^{n+1} \geq 0, \quad \text{and} \quad ND_{\text{interp}}^{n+1} \geq 0.$$

$$f_k(\mathbf{c}^{n+1}, \mathbf{c}^n) := \tilde{f}(\mathbf{c}^n) + \frac{1}{2} \|\tilde{f}'\|_\infty (\mathbf{c}^{n+1} - \mathbf{c}^n), \quad (9)$$

in our case reduces to

$$f_k(\mathbf{c}^{n+1}, \mathbf{c}^n) = \tilde{f}(\mathbf{c}^n) + (\mathbf{c}^{n+1} - \mathbf{c}^n) \quad (10)$$

where  $\tilde{f}(\mathbf{c})$  is the  $C^1$ -truncation of  $F'(\mathbf{c})$ :

$$\tilde{f}(\mathbf{c}) = \begin{cases} \frac{2}{\varepsilon^2}(\mathbf{c} + 1) & \text{if } \mathbf{c} \leq -1, \\ \frac{1}{\varepsilon^2}(\mathbf{c}^2 - 1) \mathbf{c} & \text{if } \mathbf{c} \in [-1, 1], \\ \frac{2}{\varepsilon^2}(\mathbf{c} - 1) & \text{if } \mathbf{c} \geq 1, \end{cases} \quad (11)$$

$$g_k(\mathbf{d}^{n+1}, \mathbf{d}^n) = \tilde{g}(\mathbf{d}^n) + \frac{\sqrt{51}}{2} (\mathbf{d}^{n+1} - \mathbf{d}^n), \quad (12)$$

where  $\tilde{g}(\mathbf{d})$  is the  $C^1$ -truncation of  $g(\mathbf{d})$ :

$$\tilde{g}(\mathbf{d}) = \begin{cases} 2 (|\mathbf{d}| - 1) \frac{\mathbf{d}}{|\mathbf{d}|} & \text{if } |\mathbf{d}| \geq 1, \\ (|\mathbf{d}|^2 - 1) \mathbf{d} & \text{if } |\mathbf{d}| \leq 1, \end{cases}$$

and we also take

$$i_k(\mathbf{c}^{n+1}, \mathbf{c}^n) = i(\mathbf{c}^n) + \frac{5\sqrt{3}}{12} (\mathbf{c}^{n+1} - \mathbf{c}^n). \quad (13)$$

## Lemma

If  $\mathbf{D}_h \subseteq \mathbf{W}_h$ , then there exist a unique solution  $(\mathbf{d}^{n+1}, \mathbf{w}^{n+1})$  of **STEP 1** using the potential approximation (12) for  $\mathbf{g}_k(\mathbf{d}^{n+1}, \mathbf{d}^n)$ .

## Lemma

If  $1 \in C_h$ , then there exist a unique solution  $(\mathbf{c}^{n+1}, \boldsymbol{\mu}^{n+1})$  of **STEP 2** using the potential approximations (10) and (13) for  $f_k(\mathbf{c}^{n+1}, \mathbf{c}^n)$  and  $i_k(\mathbf{c}^{n+1}, \mathbf{c}^n)$ , respectively.

## Lemma

If the pair of FE spaces  $(\mathbf{V}_h, P_h)$  satisfies the discrete inf-sup condition

$$\exists \beta > 0 \quad \text{such that} \quad \|p\|_{L^2} \leq \beta \sup_{\bar{\mathbf{u}} \in \mathbf{V}_h \setminus \{\Theta\}} \frac{(p, \nabla \cdot \bar{\mathbf{u}})}{\|\bar{\mathbf{u}}\|_{H^1}} \quad \forall p \in P_h, \quad (14)$$

then there exist a unique solution  $(\mathbf{u}^{n+1}, p^{n+1})$  of **STEP 3**.

We propose the following choice for the discrete spaces:

$$(\mathbf{u}, p) \sim P_2 \times P_1, \quad (\mathbf{c}, \boldsymbol{\mu}) \sim P_1 \times P_1 \quad \text{and} \quad (\mathbf{d}, \mathbf{w}) \sim P_1 \times P_1, \quad (15)$$

that satisfy the assumptions of Lemmas 6, 7 and 8.

The **newtonian fluid** is represented by **blue color** while the **nematic fluid** is represented by **red one**.

For simplicity we are considering constant viscosity  $\nu(\mathbf{c}) = \nu_0$ .

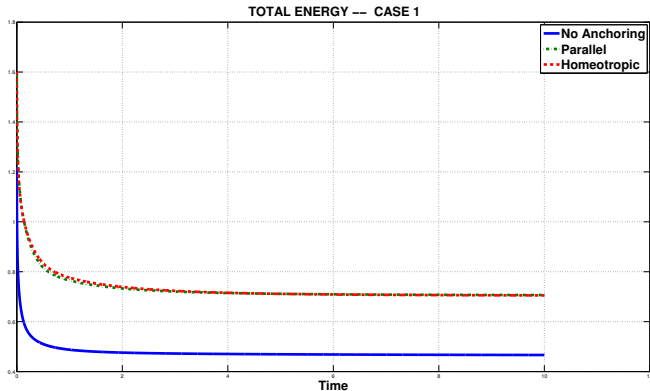
$\Omega$	$[0, T]$	$h$	$dt$	$\nu_0$	$\eta$
$[-1, 1]^2$	$[0, 10]$	2/90	0,001	1,0	0,075

$\lambda_{nem}$	$\lambda_{mix}$	$\lambda_{anch}$	$\gamma_{nem}$	$\gamma_{mix}$	$\varepsilon$
0,1	0,01	0,1	0,5	0,01	0,05

# Nematic-Isotropic. Circular droplet and director field parallel to the y-axis



# Nematic-Isotropic. Circular droplet and director field parallel to the y-axis



# Nematic-Isotropic. Elliptic droplet with two points defects at $(\pm 1/2, 0)$

- A Hedgehog defect at  $(1/2, 0)$  and an Antihedgehog defect at  $(-1/2, 0)$

$$\mathbf{d}_0(x) = \hat{\mathbf{d}} / \sqrt{|\hat{\mathbf{d}}|^2 + 0,05^2}, \text{ with } \hat{\mathbf{d}} = (x^2 + y^2 - 0,25, y).$$

Defect annihilation in Nematic Liquid Crystals

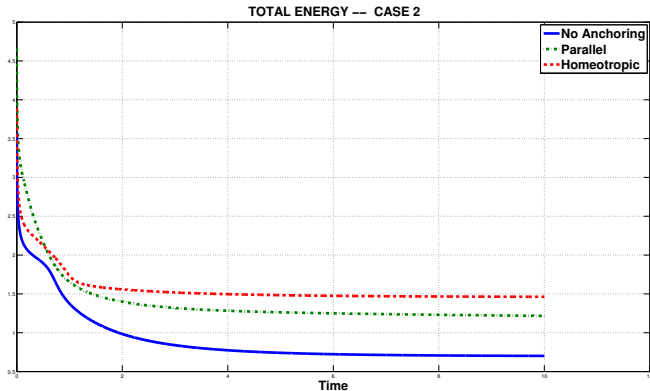


Defect annihilation in Nematic Liquid Crystals Drops





# Nematic-Isotropic. Circular droplet and director field parallel to the y-axis

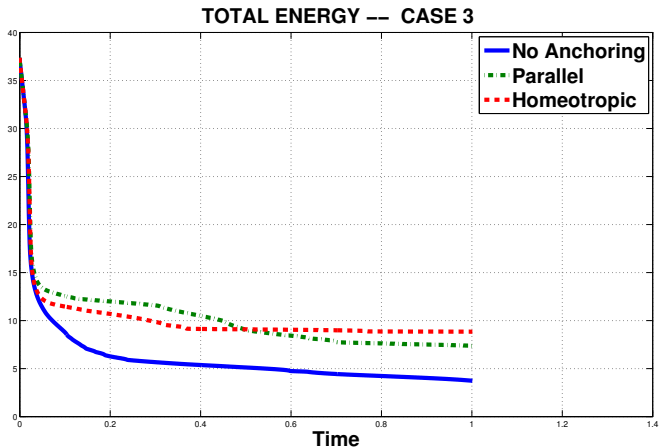


- Random initial data for  $c$ , i.e.,  $c \in [-10^{-2}, 10^{-2}]$  in  $\Omega = [0, 1] \times [0, 1]$ ,  $t \in [0, 1]$  and  $dt = 10^{-4}$ .
- The initial director vector is computed using the function:

$$\mathbf{d} = I(c) \left( \sin(x y) \sin(x y), \cos(x y) \cos(x y) \right).$$



# Nematic-Isotropic. Spinodal Decomposition





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**THANK YOU FOR YOUR ATTENTION!**