

Phase diagram for a cubic- Q interacting boson model Hamiltonian: Signs of triaxiality

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An extension of the Interacting Boson Model that includes the cubic $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ term is proposed. The potential energy surface for the cubic quadrupole interaction is explicitly calculated within the coherent state formalism using the complete (χ -dependent) expression for the quadrupole operator. The Q -cubic term is found to depend on the asymmetry deformation parameter γ as a linear combination of $\cos(3\gamma)$ and $\cos^2(3\gamma)$ terms, thereby allowing for triaxiality. The phase diagram of the model in the large N limit is explored: The orders of the phase transition surfaces that define the phase diagram are described, and the possible nuclear equilibrium shapes are established. It is found that for this particular Hamiltonian, contrary to expectations, there is only a very tiny region of triaxiality, and that the transition from prolate to oblate shapes is so fast that, in most cases, the onset of triaxiality might go unnoticed.

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I. INTRODUCTION

Triaxiality has been a matter of interest for nuclear physics since the 1950s [1,2]. From the theoretical point of view the simplest approaches correspond to the triaxial rotor model of Davidov and Filippov [3] and to the anisotropic harmonic oscillator [4]. In both models the Hill-Wheeler coordinates, β and γ , are taken as constant values and therefore the deformation, either axial or triaxial, is static. The Bohr-Mottelson collective model [5] instead considers β and γ as dynamic collective variables, where it is possible to have rigid triaxial shapes as well as rather floppy or soft triaxial structures [6–9]. Another model that is very successful to study triaxiality is the geometric collective model (or Frankfurt model) [10,11]. The formulation of this model is such that more general terms, made up of powers of the canonical variables α_μ and momenta π_μ , can be included in the Hamiltonian allowing a more general study of the effects of the various terms in favoring or disfavoring triaxiality. However, this is not necessarily an advantage for two reasons: one has Hamiltonians with many more parameters and it is harder to motivate the physics behind each of the more complicated terms (for example, momentum-dependent terms). Nowadays the triaxial degree of freedom can also be taken into account in Hartree-Fock-Bogoliubov calculations and it is shown to be a crucial ingredient to explain the evolution of the nuclear shapes in the region of Xe and Ba [12] or for the Yb, Hf, W, Os, and Pt [13,14] isotopes. In all these cases there is an evolution from oblate to prolate shapes passing through triaxial forms.

An alternative model to study triaxiality is the interacting boson model (IBM) [15]. This model is made up of bosons carrying either angular momentum equal to zero, s bosons, or angular momentum equal to two, d bosons. In its simplest form, called IBM-1, the IBM Hamiltonian is written considering only up to two-body terms and no explicit distinction between proton and neutron degrees of freedom is done.

Although this approach has been shown to be very successful for many applications, it has, as a drawback, the impossibility to accommodate triaxial shapes. There are several possibilities for correcting this. One is to include three-body terms in the Hamiltonian. In particular, in Refs. [16–18] it is shown that a very simple way to induce static triaxiality is the use of terms $[d^\dagger d^\dagger d^\dagger]^{(L)} \cdot [\tilde{d} \tilde{d} \tilde{d}]^{(L)}$. Along this line, a recent detailed study of the Ru, Pd, Xe, Ba, Os, and Pt isotopes [19] using an IBM Hamiltonian including three-body terms has been carried out, showing that the role of triaxiality to reproduce excitation energies and transition rates is very reduced. A second option to induce triaxiality in IBM is to use up to two-body terms but including angular momentum equal to four bosons, g bosons [20]. A third alternative way to study triaxial forms within the IBM is to calculate effective γ deformations as in Ref. [21], hence, with this approach it is not necessary to include three-body terms to induce effective triaxial shapes. There is still a fourth alternative for the IBM to accommodate triaxial shapes and it is to go to the formulation in which the proton and neutron degrees of freedom are explicitly taken into account, IBM-2 [22–25]. The present work concentrates in studying the possibility of inducing triaxiality in the IBM by including three-body terms in the Hamiltonian, in particular, when these three-body terms are constructed in terms of quadrupole operators. This approach has been proven to be successful in the interpretation of double phonon anharmonicities using the IBM [26]. The aim of this paper is to study how the cubic term induces triaxiality in a general case.

It is well known that the quadrupole operator plays a central role in nuclear physics because it is essential in the description of nuclear deformation, in the calculation of energy terms, and in the evaluation of electromagnetic quadrupole transitions and moments [5]. Its presence is also of key importance within the IBM, where its components are defined as

$$\hat{Q}_\mu = [d^\dagger \tilde{s} + s^\dagger \tilde{d}]_\mu^{(2)} + \chi [d^\dagger \tilde{d}]_\mu^{(2)}. \quad (1)$$

Various relevant operators (including scalar terms in the Hamiltonian or the $E2$ electromagnetic transition operator) are usually built from \hat{Q} by appropriate tensor couplings. Within the IBM a useful and, at the same time, extremely simple Hamiltonian (with only three free parameters) is the one used in the so-called consistent- Q formalism (CQF) introduced some time ago by Warner and Casten [27].¹ The Hamiltonian usually used in CQF contains just a one body (\hat{n}_d) term and a two-body quadrupole-quadrupole ($\hat{Q} \cdot \hat{Q}$) interaction. In spite of its simplicity, it can generate spherical, symmetric axially deformed as well as deformed γ -unstable nuclear shapes [15]. As mentioned before, within the standard IBM several authors have shown (for example, in Refs. [15,17,18,26,28], in chapter 6 of Ref. [29], chapter 2.2 of Ref. [30], and in Ref. [31]) that the triaxiality can be successfully introduced by adding three-body terms of the type $[d^\dagger d^\dagger d^\dagger]^{(L)} \cdot [\tilde{d}\tilde{d}\tilde{d}]^{(L)}$. These terms, together with the simple CQF Hamiltonian, generate a relatively broad region of triaxiality in the parameter space of the Hamiltonian. Although this is a valid way of generating triaxiality, it is not completely satisfactory because there is a priori no reason to invoke such terms and moreover one moves away of the desirable simplicity of the CQF Hamiltonian. An alternative is to use higher-order terms in \hat{Q} as, for instance, the cubic ($\hat{Q} \times \hat{Q} \times \hat{Q}$)⁽⁰⁾ interaction. The explicit expression for the cubic order interaction reads

$$(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)} = \sum_{\nu, \mu} \langle 2\nu 2 - \nu | 00 \rangle \langle 2\mu 2(\nu - \mu) | 2\nu \rangle \times \hat{Q}_\mu \hat{Q}_{\nu-\mu} \hat{Q}_{-\nu}, \quad (2)$$

where $\langle \dots | \dots \rangle$ stands for Clebsh-Gordan coefficients. Here three quadrupole operators (with rank-2 tensorial properties) are coupled to give a scalar term. This operator couples states with $\Delta\tau = 3$ as well as $\Delta\tau = 1$, where τ is the $O(5)$ seniority quantum number.

Several studies have been carried out for disentangling the properties of Hamiltonians containing $\hat{Q} \times \hat{Q} \times \hat{Q}$ terms. On the one hand, Van Isacker [32] has studied the tensorial properties of the $\hat{Q} \times \hat{Q} \times \hat{Q}$ operator, within the IBM, and has shown that, even with $\chi = 0$, this cubic operator can give spectra and band structures that are qualitatively similar to those usually associated with a $SU(3)$ type of symmetry (axial rotor). On the other hand, Rowe and Thiamova [33] have recently investigated, in the context of the Bohr-Mottelson collective model, the spectrum generated by using the following Hamiltonian:

$$\hat{H} = \hat{\Lambda} + k(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}, \quad (3)$$

where $\hat{\Lambda}$ is the Casimir operator of $O(5)$, reaching similar conclusions to those of Van Isacker: The spectrum obtained by increasing the strength of the cubic term with $\chi = 0$ displays the properties of an axially symmetric rotor. In their paper and, more recently in Ref. [34], it is shown that the contraction

of the $O(6)$ algebra indicates that $\cos(3\gamma)$ is an image of the cubic term and therefore the only possible stable shapes are axially deformed. Following this reasoning, a quadratic term in the \hat{Q} cubic scalar [i.e., $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)} \cdot (\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$] is necessary to generate potential energy terms displaying a $\cos^2(3\gamma)$ behavior. While this is most certainly true with their assumption on the form of the quadrupole operator ($\hat{Q}_\mu = [d^\dagger s + s^\dagger \tilde{d}]_\mu^{(2)}$, i.e., $\chi = 0$), we will show by explicit calculation that a term quadratic in the cosine is already present in the matrix elements of the $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ operator alone, if one includes the χ -dependent term in the definition of the quadrupole operator as in Eq. (1). Therefore the possible onset of triaxiality can be studied at the level of the cubic- Q Hamiltonian (to be defined below) without the need to resort to higher-order terms, in agreement with the already mentioned studies on the $[d^\dagger d^\dagger d^\dagger]^{(L)} \cdot [\tilde{d}\tilde{d}\tilde{d}]^{(L)}$ operators.

The organization of this paper is as follows. In Sec. II we introduce the cubic- Q Hamiltonian and then obtain the potential energy surfaces (PESs) generated by the $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ operator. In Sec. III we explore the phase diagram and discuss the order of the phase transition surfaces. Interesting limiting situations of this Hamiltonian are explored in Sec. IV and, finally, we present our conclusions in Sec. V.

II. CUBIC- Q HAMILTONIAN

The consistent- Q formalism (CQF) is based on a simple IBM Hamiltonian [27] that allows to investigate not only the three dynamical symmetries of the IBM-1, but also the transitional regions in between. We propose in this section an extension of the CQF by adding to the original Hamiltonian a cubic combination of \hat{Q} operators coupled to zero angular momentum,

$$H = \xi \hat{n}_d - (1 - \xi) \left[\frac{(\hat{Q} \cdot \hat{Q})}{N} + k_3 \frac{(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}}{N^2} \right]. \quad (4)$$

We call Eq. (4) the cubic- Q Hamiltonian (CQH). We keep the same value of χ in all the quadrupole operators appearing in the above equation, up to the cubic degree. As usual, the various terms have been divided by the appropriate power of the boson number (N) in order to preserve the same kind of N dependence in the large N limit and also to make sure that, in this limit, each term does not go to an infinite value. Although many other three-body terms can be used (for instance the seventeen linear independent three-body terms discussed in Refs. [28]), this looks like the simplest one and it is easy to justify on physical grounds as the first higher-order interaction term in an expansion based on the quadrupole operator. The \hat{Q} cubic term can be interpreted as a correction to the dominant quadrupole-quadrupole scalar product rather than an additional term.

This Hamiltonian has a rich structure that will be analyzed in depth in the following sections. Clearly, when $\xi = 1$, one falls back into the $U(5)$ spherical limit. When $\xi = 0$ and $k_3 = 0$, one recovers the deformed γ -unstable ($\chi = 0$) and the axially deformed ($\chi = \pm\sqrt{7}/2$) IBM limits. For values $k_3 \neq 0$ there will be a competition between different possible deformed shapes that could produce, in principle, stable

¹The name comes from the fact that both the quadrupole operator contained in the Hamiltonian and the quadrupole operator contained in the $E2$ electromagnetic transition operator use the same value of the χ parameter. This was not the case in earlier studies, where different parameters have been used to reproduce the data.

triaxiality. In order to analyze this competition, and consequently the appearance of triaxiality, let us first investigate the geometry produced by the Q -cubic term in the Hamiltonian.

A. Geometry of the $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ operator

One fundamental step in the investigation of the cubic- Q term is its connection with geometry, which can be obtained within the well-known intrinsic state formalism. A coherent, or intrinsic, state [35–37] is defined as a properly normalized application of the N th power of a linear combination of scalar and quadrupole boson creation operators to the vacuum, namely,

$$|\beta, \gamma, N\rangle = \frac{1}{\sqrt{N!(1+\beta^2)^N}} \times \left[s^\dagger + \beta \cos \gamma d_0^\dagger + \frac{\beta}{\sqrt{2}} \sin \gamma (d_2^\dagger + d_{-2}^\dagger) \right]^N |0\rangle, \quad (5)$$

where β and γ are related to the deformation and asymmetry parameters, respectively. The main difficulty, when one deals with matrix elements of complicated operators within the coherent state formalism, is the length of the calculations. We have, therefore, set up a symbolic computer code that can evaluate in an analytic fashion complicated terms, keeping in account the noncommutative nature of the basic operators [38]. This code adopts the technique introduced in Ref. [16] of transforming the creation (annihilation) operators into derivatives acting on the left (right). After having carefully tested the procedure with several known quantities [29], we have obtained the following result for the matrix element

$$\langle \beta, \gamma, N | (\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)} | \beta, \gamma, N \rangle = \sum_i t_i, \quad (6)$$

that is split for simplicity into one-, two-, and three-body terms ($i = 1, 2, 3$) given by

$$t_1 = \frac{N}{14\sqrt{5}} \frac{1}{(1+\beta^2)} [14\chi(5+2\beta^2) - 3\chi^3\beta^2], \quad (7)$$

$$t_2 = \frac{N(N-1)}{49\sqrt{5}} \frac{3\beta^2}{(1+\beta^2)^2} [14\chi(14+\beta^2) - 3\chi^3\beta^2 - \sqrt{14}(14+11\chi^2)\beta \cos 3\gamma], \quad (8)$$

$$t_3 = \frac{N(N-1)(N-2)}{49\sqrt{5}} \frac{4\beta^3}{(1+\beta^2)^3} [42\chi\beta - \sqrt{14}(14+3\chi^2\beta^2) \times \cos 3\gamma + \chi^3\beta^3(2\cos^2 3\gamma - 1)]. \quad (9)$$

To obtain the full matrix element these three terms have to be summed up, keeping in mind that, in the intrinsic state formalism, only the leading order in N is correctly evaluated and, hence, only t_3 is meaningful [39,40].

From these expressions it is clear that the dependence on γ when $\chi = 0$ is of the type $\cos 3\gamma$ and therefore the cubic operator with $\chi = 0$ cannot generate triaxiality. The full expression, valid for any value of χ , contains one term proportional to $\cos 3\gamma$ together with another proportional to $\cos^2 3\gamma$. Therefore these contributions, in addition to a CQH energy surface, might generate a triaxial minimum in the potential energy surface.

In order to analyze the energy surface in Eq. (6), we will examine in Fig. 1 the potential energy surface given by $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}/N^3$ in the large N limit for $\chi = 0$. The upper left part of the figure displays the value of the matrix element on the vertical coordinate, while the lower left part is its projection on the plane with coordinates $x = \beta \cos \gamma$ and $y = \beta \sin \gamma$. The surface has prolate minima at $\beta = 1$ and $\gamma = \frac{2\pi}{3}n$ and oblate maxima at $\beta = 1$ and $\gamma = \frac{\pi}{3}(1+2n)$, with $n = 0, 1, 2$. The contour map on the x - y plane gives a color-coded projection of the surface values, with black-blue representing the (prolate)

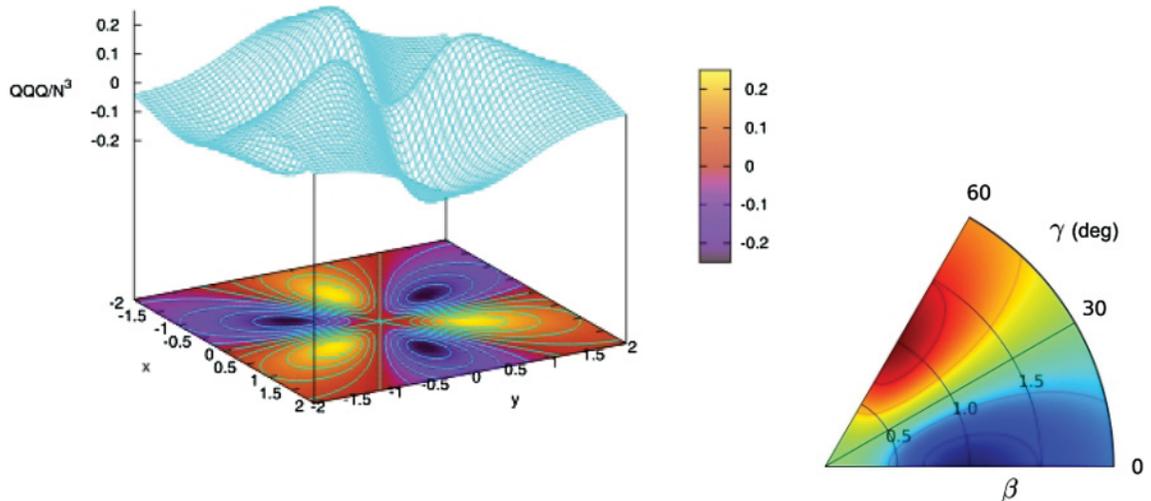


FIG. 1. (Color online) Left: surface (grid) and contours (colored) representing $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}/N^3$ in the large N limit with $\chi = 0$ as a function of $\{x, y\}$. The coordinates on the plane are $x = \beta \cos \gamma$ and $y = \beta \sin \gamma$. Right: the same function in the fundamental $0^\circ \leq \gamma \leq 60^\circ$ wedge with contours (slightly different coloring scheme).

minimum and yellow-red representing the (oblate) maximum (see color bar on the right). For the sake of completeness we also give in the right part of the figure a contour plot in the more standard (β, γ) polar coordinates, limited to the $0^\circ \leq \gamma \leq 60^\circ$ wedge with a slightly different coloring scheme. Of course the character of the maxima and minima can be interchanged by an overall sign change. In conclusion, the cubic- Q term with $\chi = 0$ only produces either prolate or oblate minima. Triaxiality or γ -unstability are not allowed with the $\hat{Q} \times \hat{Q} \times \hat{Q}$ term if $\chi = 0$.

III. PHASE DIAGRAM IN THE LARGE N LIMIT

The study of the shape of a quantum system, in particular of atomic nuclei, proceeds through the study of the energy surface in the large N limit. The shape is strictly defined in the thermodynamical limit. The procedure starts by calculating the potential energy surface in the large N limit, then a minimization should be done, getting the equilibrium value of the deformation parameters.

A. Potential energy surface

The energy per boson in the large N limit can be readily calculated from Eq. (4),

$$E(\xi, k_3, \chi, \beta, \gamma) = \xi \frac{\beta^2}{1 + \beta^2} - (1 - \xi) \left\{ \frac{2}{7} \frac{\beta^2}{(1 + \beta^2)^2} \right. \\ \times (\chi^2 \beta^2 - 2\sqrt{14}\chi\beta \cos 3\gamma + 14) \\ + k_3 \frac{4}{49\sqrt{5}} \frac{\beta^3}{(1 + \beta^2)^3} \\ \times [\chi^3 \beta^3 (2 \cos^2 3\gamma - 1) - \sqrt{14} \\ \left. \times (3\chi^2 \beta^2 + 14) \cos 3\gamma + 42\chi\beta \right\}. \quad (10)$$

Note that the N dependence is eliminated due to the proper N scaling of the different terms in the Hamiltonian and to the use of the energy per boson.

The presence of $\cos 3\gamma$ and $\cos^2 3\gamma$ in Eq. (10) can give rise to triaxiality. Let us start discussing the possibility of triaxiality for a simpler situation: an energy surface independent of β , but with the γ dependence as in Eq. (10). In that case, one can write the energy surface as

$$E(\gamma) = a \cos^2 3\gamma + b \cos 3\gamma + c, \quad (11)$$

where we take a , b , and c as constants for the moment. This function admits triaxial extrema at

$$\gamma = [\pm \arccos(-b/2a) + 2n\pi]/3 \quad (12)$$

if $|-b/2a| \leq 1$, with $n = 0, 1, 2$. When instead $|-b/2a| > 1$, the extrema sit at $\gamma = 2\pi n/3$ and $\gamma = (2n + 1)\pi/3$, with $n = 0, 1, 2$, and triaxiality is excluded.

In the general case, in which the coefficients a and b depend on β , as in the energy functional Eq. (10), the presence of terms depending on $\cos 3\gamma$ and $\cos^2 3\gamma$ can, in principle, produce triaxial shapes. It is clear that the existence of a triaxial minimum is linked to the inclusion of the cubic- Q term

($k_3 \neq 0$) in the IBM Hamiltonian. The argument discussed above could, in principle, be valid even when the coefficients a and b depend on β , as long as their dependence on the equilibrium value of β , β_0 , is smooth enough with respect to the control parameters of the Hamiltonian. However, for the cubic- Q Hamiltonian, the latter argument is not so obvious, mainly due to the noncontinuous or very fast dependence of the β equilibrium value in some intervals of the control parameters. To shed some light on this, one can calculate the value of $|-b/2a|$ [see Eq. (12)], which is the only necessary quantity for getting the value of γ , obtaining,

$$\left| -\frac{b}{2a} \right| = \left| -\frac{7\sqrt{70}\chi(1 + \beta_0^2) + \sqrt{14}k_3(14 + 3\chi^2\beta_0^2)}{4k_3\chi^3\beta_0^3} \right|, \quad (13)$$

where β_0 is the equilibrium value of β , that is, at the minimum of the energy. To rule out the possible existence of a triaxial region one has to prove as necessary and sufficient condition that $|\frac{-b}{2a}| > 1$, for any value of the parameters in the Hamiltonian. In fact, this is true for $\xi = 0$. Note that Eq. (13) does not depend explicitly on ξ , but its dependence comes in, implicitly, through the dependence of the equilibrium value of β on ξ , χ , and k_3 .

To start with, we can easily calculate the value of $|\frac{-b}{2a}|$ in some limiting situations. In particular, $\lim_{\beta \rightarrow \infty} |\frac{-b}{2a}| = 0$ or $\lim_{|\chi| \rightarrow \infty} |\frac{-b}{2a}| = 0$ and therefore $\gamma = 30^\circ$, but these situations are quite unrealistic. More interesting limiting situations are: $\lim_{\beta \rightarrow 0} |\frac{-b}{2a}| = \infty$, $\lim_{k_3 \rightarrow \infty} |\frac{-b}{2a}| > 19$ [this can be obtained easily from Eq. (13) numerically], $\lim_{k_3 \rightarrow 0} |\frac{-b}{2a}| = \infty$, and $\lim_{\chi \rightarrow 0} |\frac{-b}{2a}| = \infty$. We will also prove later on that $|\frac{-b}{2a}| > 1$ for $\xi = 0$. On the other hand it is also true that the value of β obtained for $\xi = 0$ is always larger than the corresponding one for $\xi \neq 0$ (for the same values of χ and k_3). With these general ideas in mind, it is easy to see that $|\frac{-b}{2a}| \gg 1$ except, maybe, for a very narrow range of the parameters. Indeed, one can see that, once the values of the Hamiltonian parameters have been set, if we treat β as a free parameter and not as a equilibrium value, one gets $|\frac{-b}{2a}| < 1$ only in a very narrow range of β . In particular, it is possible to see, numerically, that this particular range of β is placed in a region where β exhibits a sudden drop. This is illustrated in Fig. 2, where the value of $|\frac{-b}{2a}|$ is plotted as a function of β , for $k_3 = 1$ and $\chi = -0.5$. It is clearly observed that only around $\beta \approx 0.934$ one gets $|\frac{-b}{2a}| < 1$, but this particular value of β falls in a rapidly changing region as it can be appreciated in the lower part of the figure, where the equilibrium value of β is represented as a function of ξ .

As a conclusion of this qualitative discussion on possible triaxiality produced by the Hamiltonian Eq. (4), it can be said that one expects that the region supporting triaxial shapes is small, if any. We will quantify this idea in the following sections.

B. Coordinates

The pictorial representation of the phase space of the CQH is an extension of the well-known Casten triangle (left plot in Fig. 3). In our case the parameter space becomes a

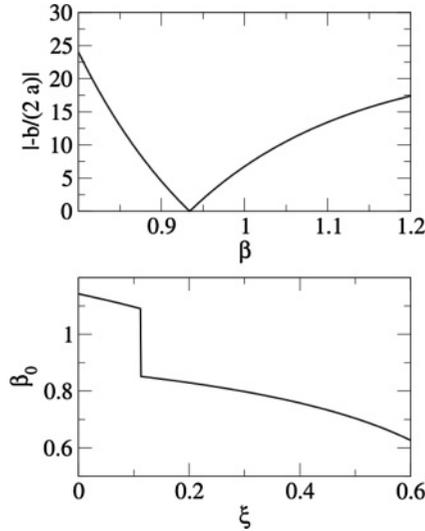


FIG. 2. Upper part: value of $|\frac{b}{2a}|$ (see text) as a function of β for $k_3 = 1$ and $\chi = -0.5$. Equilibrium value of β as a function of ξ .

tetrahedron, where the horizontal coordinates are related to the ξ and χ control parameters in the Hamiltonian, while the vertical coordinate is directly connected to the coefficient of the $\hat{Q} \times \hat{Q} \times \hat{Q}$ term. We use the following parametrization:

$$\left\{ \rho = 1 - \xi; \quad \phi = -\frac{\pi}{3} \frac{\chi}{\sqrt{7}}; \quad z = \rho k_3 \right\}. \quad (14)$$

In the studies presented below, the value of χ ranges from $-\sqrt{7}/2$ to 0 and therefore the amplitude of the ϕ angle is 30° , ρ ranges from 0 to 1, and k_3 is taken as positive. This range of control parameters allows to get the results for the full model space since the energy surface in Eq. (10) presents the following prolate-oblate symmetry: $\chi \rightarrow -\chi$, $k_3 \rightarrow -k_3$, $\gamma \rightarrow \pi/3 - \gamma$. This allows to extend the results obtained in

the case of $\chi < 0$ and $k_3 > 0$ to the regions with $\chi > 0$ and $k_3 < 0$.

It is worth noting that due to the form of the Hamiltonian in Eq. (4) it is not possible to reach a pure cubic- Q term in the Hamiltonian, except for $k_3 \rightarrow \infty$. However, in Fig. 3 the upper part of the tetrahedron is labeled with QQQ to denote that this limit is reached for large values of $z = \rho k_3$. Anyway, in this study we will limit ourselves to moderated large values of k_3 (up to 10) since the cubic- Q term is supposed to be a correction to the dominant QQ term.

First, the schematic phase diagram of the model Hamiltonian will be studied and then some particular relevant regions will be analyzed in more detail with the aim of singling out possible regions of triaxiality.

C. Geometry of the phase diagram

The resulting phase diagram for the Hamiltonian in Eq. (4) is depicted in the right-hand side of Fig. 3. Although a detailed explanation of the nature of this phase diagram will be given along this section, we already present the complete diagram here to facilitate the following analysis. The position of the critical surfaces are determined numerically, except for some particular regions of the phase diagram that can be obtained analytically. We have explored the parameter space to find out the position of the critical surfaces, following certain selected paths across the parameter space to clearly illustrate where the critical surfaces are placed and what is their character. This phase diagram is characterized by the existence of four different phases: spherical ($\rho \lesssim 0.2$, or $1 > \xi \gtrsim 0.8$), prolate and oblate axially deformed shapes ($\rho \gtrsim 0.2$, or $\xi \lesssim 0.8$), and a very tiny region of triaxial shapes, occurring between the oblate (prolate) separation surface close to the $\chi = \pm\sqrt{7}/2$ faces of the tetrahedron. Note that the existence of a spherical region is limited to moderate values of k_3 . Due to the particular

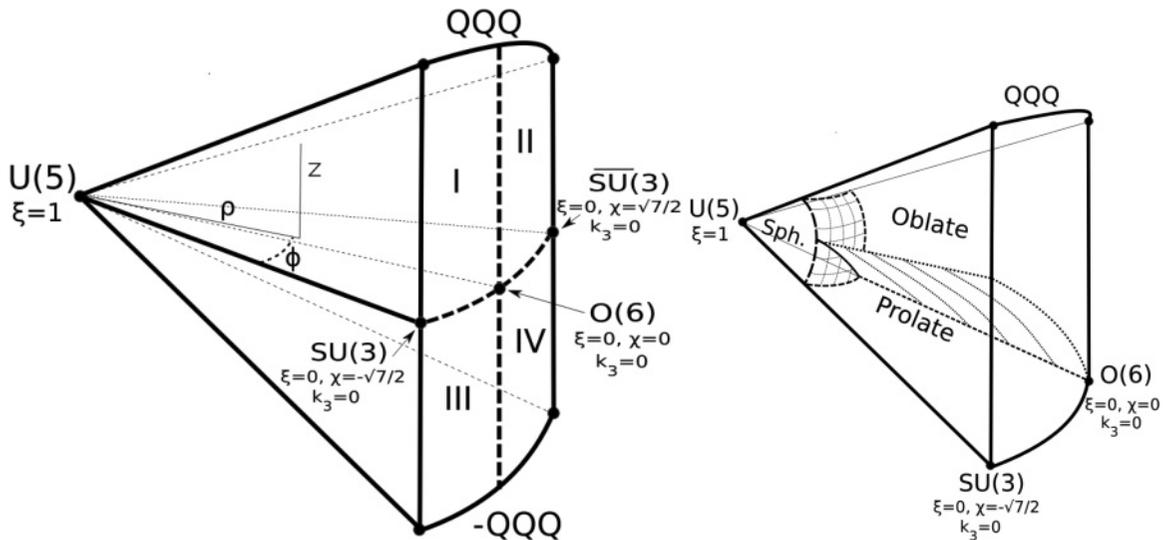


FIG. 3. Left: Schematic representation of the CQH parameter space and coordinates. Four quadrants are present, of which only the first one is studied in detail as explained in the text. As a reference, the IBM dynamical symmetry limits are explicitly shown. Right: Schematic phase diagram for the CQH, corresponding to quadrant I in the figure on the left.

form of Hamiltonian in Eq. (4), very large values of k_3 will transform the spherical region almost in a single point around the origin. The two plotted surfaces correspond to first-order phase transitions except along their intersection line, which is a second-order phase transition line (full line in the right panel of Fig. 3). As we will explain in detail along this section, the prolate-oblate first order transition surface becomes a two-fold second-order phase transitions surface for $\chi \approx -\sqrt{7}/2$, although these surfaces are extremely close and cannot be distinguished in Fig. 3.

The full phase space comprehends four tetrahedra (numbered I–IV) with a common $U(5)$ vertex, shown in the left part of Fig. 3, while in the right part of the figure only the upper left quarter (I) with positive values of k_3 and negative values of χ is plotted. Apart from the spherical region close to $\xi = 1$, which is always present, the upper right quadrant II ($k_3 > 0$ and $\chi > 0$) contains only oblate shapes, while the opposite lower left quadrant III ($k_3 < 0$ and $\chi < 0$) contains only prolate shapes. Finally, due to the prolate-oblate symmetry $\chi \rightarrow -\chi$, $k_3 \rightarrow -k_3$, $\gamma \rightarrow \pi/3 - \gamma$, the lower right quadrant IV can be obtained by rotating the first quadrant 180° with respect to the $U(5)$ - $O(6)$ axis. In order to illustrate how the phase diagram has been obtained we will show the results along several selected paths within quadrant I.

1. Paths from deformed to spherical shapes

First, we will explore the separation surface of spherical and deformed shapes. For that purpose, we start selecting $k_3 = 4$ and $\chi = -\sqrt{7}/2$ and we vary ξ . In Fig. 4 we observe a first-order phase transition, where β goes from a finite value to zero and γ goes from 60° (oblate shape) to undefined (spherical), when entering the spherical region. Note that the equilibrium value of β for $\xi = 0$ is $\beta = 1/\sqrt{2}$. In the right part of the figure we have displayed the position of the path (green thick line) inside the phase diagram and also the position of the phase transition point (green circle). It should be noted that $U(5)$ corresponds to $\xi = 1$ and the surface $SU(3)$ - $O(6)$ - QQQ to $\xi = 0$. In the following figures we include plots with similar

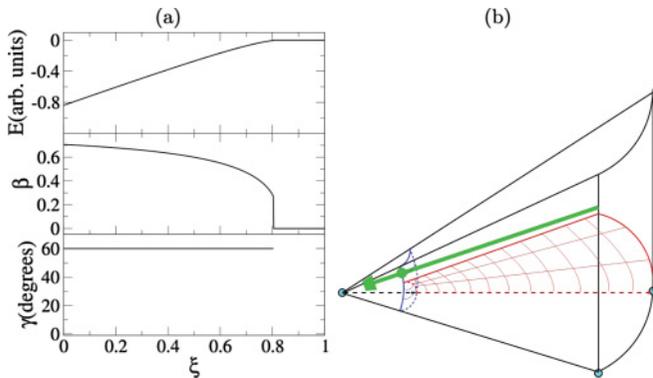


FIG. 4. (Color online) (a) Ground state energy and the equilibrium value of the shape variables β and γ as a function of ξ along the path shown in the right part of the figure (b), for $k_3 = 4$ and $\chi = -\sqrt{7}/2$. Notice that the equilibrium value of γ is undefined in the spherical region.

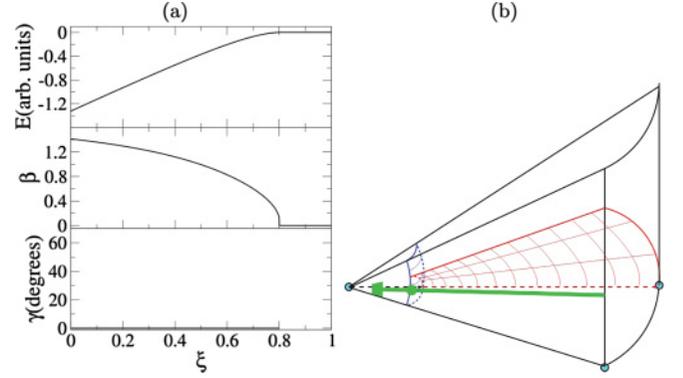


FIG. 5. (Color online) The same as in Fig. 4 but for $k_3 = 1$ and $\chi = -\sqrt{7}/2$.

interpretations. For $\chi = 0$ one can obtain plots similar to Fig. 4, although in this case the transition occurs for a slightly larger value of ξ . Now we consider a smaller value of k_3 . We impose $k_3 = 1$ and $\chi = -\sqrt{7}/2$ and we vary the value of ξ . This trajectory is plotted in Fig. 5 and once more the existence of a first-order phase transition can be noted, although it is not as abrupt as in the previous case. The value of γ passes from zero (prolate shape) to undefined in the spherical region. Finally note that $\beta = \sqrt{2}$ for $\xi = 0$.

Now, it is clear that there is a surface that separates spherical and deformed shapes at around $\xi = 0.8$. In order to investigate the character of this surface, where the system changes from a spherical to a deformed shape, it is possible to carry out a Taylor expansion of the energy around the value $\beta = 0$, obtaining

$$E(\xi, k_3, \chi, \beta, \gamma) = (-4 + 5\xi)\beta^2 - \frac{4}{35}(1 - \xi) \times (2\sqrt{70}k_3 + 5\sqrt{14}\chi) \cos 3\gamma \beta^3 + \left[-\xi + (1 - \xi) \left(8 - \frac{24k_3\chi}{7\sqrt{5}} - \frac{2\chi^2}{7} \right) \right] \times \beta^4 + \Theta(\beta^5). \quad (15)$$

This expression is very convenient because one can easily read off the order of the phase transition when crossing the surface. In general, the presence of a cubic term in β implies that the system undergoes a first-order phase transition [41], while its absence guarantees that the phase transition is of second order.

From Eq. (15) and the preceding discussion one notices that the spherical-deformed surface corresponds to a first-order phase transition except when

$$k_3 = -\frac{\sqrt{5}}{2}\chi, \quad (16)$$

which cancels the β^3 term and changes the transition type to second order. This second-order phase transition line is the intersection of the spherical-deformed surface (studied here) and the prolate-oblate surface (to be studied in the next subsection). Therefore along this line spherical, prolate, and oblate shapes coexist.

In order to show the characteristics of this second-order phase transition line we have followed a path that crosses the

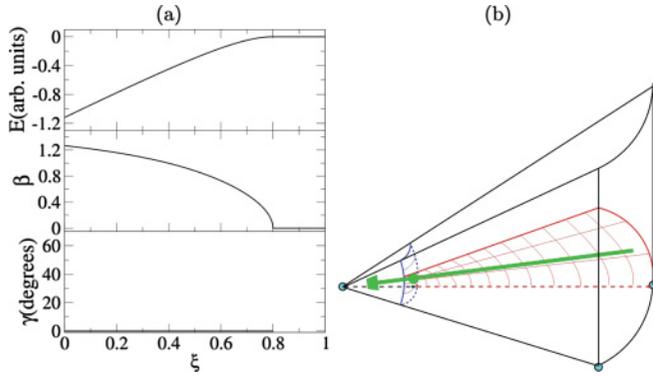


FIG. 6. (Color online) The same as in Fig. 4 or 5 but for $k_3 = 1$ and $\chi = -2/\sqrt{5}$ (second-order phase transition).

spherical-deformed surface precisely through this line. This is illustrated in Fig. 6, where a second-order phase transition appears at $\xi = 4/5$. No discontinuity is observed either in the order parameter β , or in the energy, or in its first derivative (not shown in the figure). The discontinuity appears in the second derivative of the energy confirming that the line in Eq. (16) is of the second-order type.

With respect to the existence or not of triaxiality in the region close to spherical shapes, in Eq. (15) only the $\cos 3\gamma$ shows up, but the $\cos^2 3\gamma$ dependence will appear together with β^6 terms and therefore it will generate a value $|\frac{\partial}{\partial \alpha}| \gg 1$ since the coefficient of $\cos 3\gamma$ (a) is much smaller than the one of $\cos^2 3\gamma$ (b) for $\beta < 1$. Therefore, there is no possibility of triaxiality close to the spherical region.

Finally, note that for every value of ξ , with the exception of $\xi = 1$, there always exists a value of k_3 that marks the appearance of an additional deformed minimum. This situation is quite different with respect to the one obtained with two-body Hamiltonians, where a value of $\xi \gtrsim 0.8$ implies a spherical minimum regardless of the value of χ . In the phase diagram depicted in the right part of Fig. 3 this fact cannot be noticed because of the moderated values of k_3 used along the diagram.

2. Paths from deformed prolate to deformed oblate shapes

Now, we explore the separation surface between prolate and oblate shapes, starting from the $\xi = 0$ surface and then generalizing to $\xi \neq 0$.

a. The $\xi = 0$ case: interplay of $\hat{Q} \cdot \hat{Q}$ and $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$

In this subsection the $\xi = 0$ ($\rho = 1$) surface $[SU(3)-O(6)-QQQ]$ is studied. For pedagogical reasons we start our study by setting $\chi = -\sqrt{7}/2$ (the vertical line between $SU(3)$ and QQQ in Fig. 3) and later on we will generalize the outcome to arbitrary values of χ . For the case, $\xi = 0$, $\chi = -\sqrt{7}/2$, the extrema of the $-\hat{Q} \cdot \hat{Q}/N^2$ term in the large N limit are listed in Table I. In this Table the signs of the second derivative of the energy with respect to both shape parameters, β and γ , and the character of the extrema (M for maximum, m for minimum, and s.p. for saddle point) are given. To avoid equivalent shapes related with the symmetries of the PESs we impose the constraints

TABLE I. Extrema of $-\hat{Q} \cdot \hat{Q}/N^2$, for $\chi = -\sqrt{7}/2$, along with their character. The sign of the second derivatives with respect to β and γ are also given (see text).

β	γ (deg)	$\partial^2 E/\partial\beta^2$	$\partial^2 E/\partial\gamma^2$	character
0	—	0	—	M
$1/\sqrt{2}$	60	+	—	sp
$\sqrt{2}$	0	+	+	m
$2\sqrt{2}$	60	—	—	M

$\beta \geq 0$ and $0^\circ \leq \gamma \leq 60^\circ$. Summarizing the information in Table I, the surface obtained from the $-\hat{Q} \cdot \hat{Q}/N^2$ term presents: a spherical maximum with no dependence on γ , a prolate minimum for $\beta = \sqrt{2}$, a saddle point in the oblate side for $\beta = 1/\sqrt{2}$, and an oblate maximum for $\beta = 2\sqrt{2}$. Note that at the extrema there are no off-diagonal terms in the Hessian matrix. A similar study can be done for $-(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}/N^3$. The characters of the extrema for the surface produced by this term are listed in Table II. In this case there are a spherical maximum, an oblate minimum at $\beta = 1/\sqrt{2}$, a prolate maximum at $\beta = \sqrt{2}$ and, finally, an oblate saddle point at $\beta = 2\sqrt{2}$. Moreover there is also a minimum for $\beta \rightarrow \infty$ and $\gamma = 30^\circ$. Note that, again, at the extrema there are no off-diagonal terms in the Hessian matrix. It is worth noting that the extrema for both, $-\hat{Q} \cdot \hat{Q}/N^2$ and $-(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}/N^3$ coincide, although their character, either minimum or maximum, can be different.

A Hamiltonian built upon a linear combination of $-\hat{Q} \cdot \hat{Q}$ and $-(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ is expected to possess eigenstates with large quadrupole moments and small fluctuations around their equilibrium values. This kind of state is eigenstate of the quadrupole operator, as well as of both $\hat{Q} \cdot \hat{Q}$ and $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ [31,35]. This is the reason why the extrema points of both parts of the Hamiltonian under study coincide [31].

In general, a linear combination of $-\hat{Q} \cdot \hat{Q}$ and $-(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ always generates a spherical maximum for $\beta = 0$, an oblate maximum or saddle point at $\beta = 2\sqrt{2}$ and a competition between two minima, one prolate at $\beta = \sqrt{2}$ and the other one oblate at $\beta = 1/\sqrt{2}$. The above situation corresponds to a first-order phase transition and it excludes the presence of a triaxial minimum.

Figure 7 gives the evolution of the ground state energy and the equilibrium value of β and γ for the path along the line $\chi = -\sqrt{7}/2$ and $\xi = 0$. This figure shows the typical ingredients of a first-order phase transition. There is a discontinuity in the first derivative of the energy and a discontinuity in the value of β and γ . For low values of k_3 the minimum corresponds to $\beta =$

TABLE II. Same as Table I but for $-(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}/N^3$.

β	γ (deg)	$\partial^2 E/\partial\beta^2$	$\partial^2 E/\partial\gamma^2$	character
0	—	0	—	sp
$1/\sqrt{2}$	60	+	+	m
$\sqrt{2}$	0	—	—	M
$2\sqrt{2}$	60	0	0	sp

$\sqrt{2}$ and $\gamma = 0^\circ$, while for large values to $\beta = 1/\sqrt{2}$ and $\gamma = 60^\circ$. The critical value of the control parameter corresponds to $k_3 = \sqrt{35}/3$. This figure is similar to Fig. 2 appearing in Ref. [23] although there, the phase transition is second order and γ goes from 0° to 60° in a smooth way and therefore a broad region of triaxiality exists.

An interesting case happens for $k_3 = \frac{\sqrt{35}}{3}$, for which the prolate minimum ($\beta = \sqrt{2}$) flattens, i.e. $\partial^2 E/\partial\beta^2 = \partial^2 E/\partial\gamma^2 = 0$ (becoming a maximum for larger values). Additionally, the flat prolate and the oblate minima become degenerate with energy $E = -\frac{2}{3}$, being also degenerate with the minimum at $\beta \rightarrow \infty$, $\gamma = 30^\circ$. This is illustrated in Fig. 8.

For $k_3 < \frac{\sqrt{35}}{3}$ the only minimum is the prolate one, that becomes flat for $k_3 = \frac{\sqrt{35}}{3}$. For $k_3 > \frac{\sqrt{35}}{3}$, the only minimum is the oblate one. Therefore, at $k_3 = \frac{\sqrt{35}}{3}$ the spinodal and the antispinodal points coincide and also are degenerate (first-order phase transition point).

TABLE III. Position of the possible minima for a linear combination $-\hat{Q} \cdot \hat{Q}/N^2 - k_3(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}/N^3$, with a generic value of $\chi < 0$.

β	$\gamma(\text{deg})$
$\frac{\chi}{\sqrt{14}} + \frac{\sqrt{14 + \chi^2}}{\sqrt{14}}$	60
$-\frac{\chi}{\sqrt{14}} + \frac{\sqrt{14 + \chi^2}}{\sqrt{14}}$	0

It is possible to extend the preceding study to a generic value of χ . Without loss of generality, we choose $\chi < 0$. In this case the position of the possible minima are given in Table III. Again there is a competition between the prolate minimum, coming from the $-\hat{Q} \cdot \hat{Q}/N^2$ term and the oblate one, generated with the $-(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}/N^3$ term. In this case there exists a coexistence region, but again there is no room for triaxiality. In particular, the position of spinodal ($\gamma = 60^\circ$) and antispinodal ($\gamma = 0$) points are given by

$$k_3(\partial^2 E/\partial\gamma^2|_{\gamma=\{0^\circ, 60^\circ\}} = 0) = -\frac{49\sqrt{5}\chi(\chi^2 \pm \chi\sqrt{\chi^2 + 14} + 14)}{4\chi^6 \pm 4\chi^5\sqrt{\chi^2 + 14} + 63\chi^4 \pm 35\chi^3\sqrt{\chi^2 + 14} + 147\chi^2 + 686}, \quad (17)$$

the upper (lower) sign corresponds to $\gamma = 60^\circ$ (0°). The value of k_3 where the two minima become degenerate (critical line) reads

$$k_{3c} = -\frac{7\sqrt{5}\chi}{2\chi^2 + 7}. \quad (18)$$

In Fig. 9 the spinodal, the antispinodal and the critical values of k_3 are represented in the (k_3, χ) plane for $\xi = 0$. This figure clearly shows the existence of a coexistence region and the absence of a triaxial region in the $\xi = 0$ surface. Additional extrema to the ones given in the above-mentioned table can appear which do not correspond to minima.

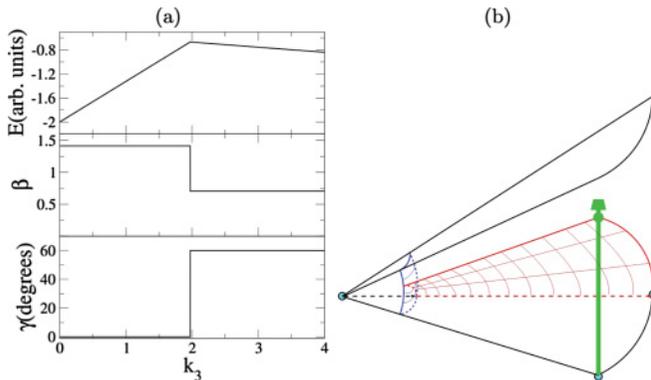


FIG. 7. (Color online) Ground state energy, equilibrium shape variables β and γ as a function of k_3 for $\xi = 0$ and $\chi = -\sqrt{7}/2$.

b. The $\xi \neq 0$ case: The prolate-oblate-triaxial critical surface

The analytical arguments used in the preceding discussion are no longer valid when the $U(5)$ term gives a contribution to the energy surface (i.e. $\xi \neq 0$), however they suggest that the parameter space region that gives rise to a triaxial minimum should be rather small. It is not possible to obtain analytically the expression of the equilibrium value of γ for a general energy surface.

To study numerically the deformed region for this particular Hamiltonian we calculate the value of the energy, and the

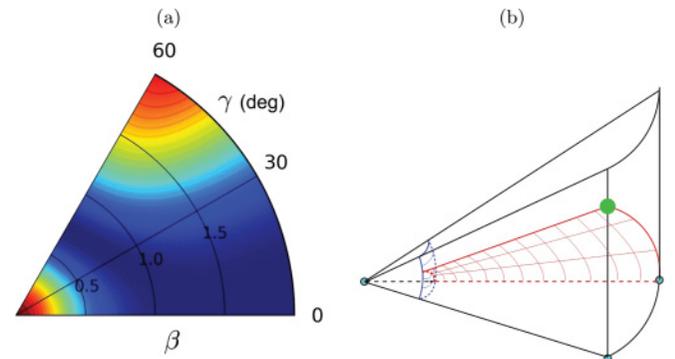


FIG. 8. (Color online) (a) Energy surface for $-\hat{Q} \cdot \hat{Q}/N^2 - \frac{\sqrt{35}}{3}(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}/N^3$ with $\chi = -\sqrt{7}/2$, corresponding to the green dot of part (b) of figure. Note the existence of a prolate and an oblate degenerated minima. With γ in deg.

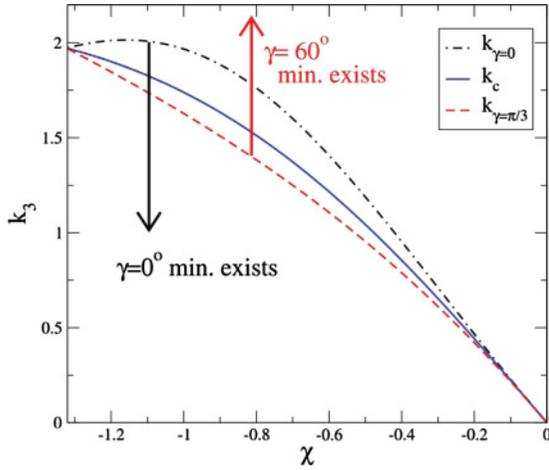


FIG. 9. (Color online) Value of spinodal ($\gamma = 60^\circ$), antispinodal ($\gamma = 0^\circ$), and critical value lines of k_3 as a function of χ for $\xi = 0$.

equilibrium value of β and γ along some particular lines that go through the phase diagram and cross the prolate-oblate separation surface. In Fig. 10 we select a particular path with $\xi = 0.5$ and $\chi = -1$ with k_3 ranging from 0 to 4. In this figure the presence of a first-order phase transition shows up because there exists a clear discontinuity in the values of β and γ , when crossing the prolate-oblate surface. Therefore there is a jump from the prolate to the oblate minimum at the point where they become degenerate and the triaxiality is forbidden. The same happens for other values of ξ and χ .

However a more detailed inspection shows that there exists a very tiny region of triaxiality around $\chi \approx -\sqrt{7}/2$, for $\xi < 4/5$. This is clearly illustrated in Fig. 11, where the lines that separate the prolate, oblate and triaxial regions are plotted for a value of $\xi = 0.5$. Note that the triaxial region occurs for χ close to the limiting value of $-\sqrt{7}/2$. At this limit $k_3 \in [1.752-1.791]$. The lower part of the figure corresponds to prolate minima, while the upper part to oblate minima. The box on the vertical left side shows the blowup of this region: There is indeed a small range of values where it is possible to find triaxial minima by numerical procedure. The more one moves away from the value $\chi = -\sqrt{7}/2$, the narrower this range

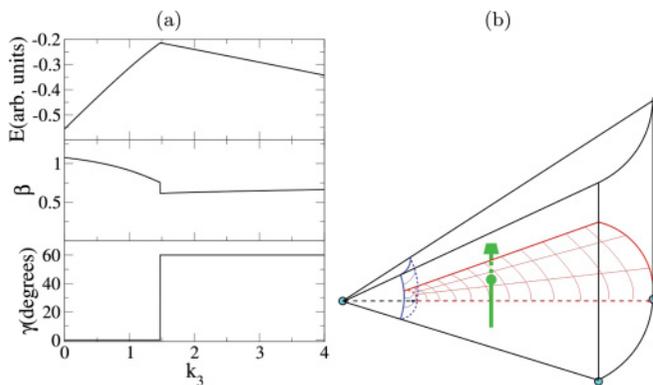


FIG. 10. (Color online) (a) Ground state energy and equilibrium value of the shape variables β and γ as a function of k_3 , for $\xi = 0.5$ and $\chi = -1$ for the path shown in (b).

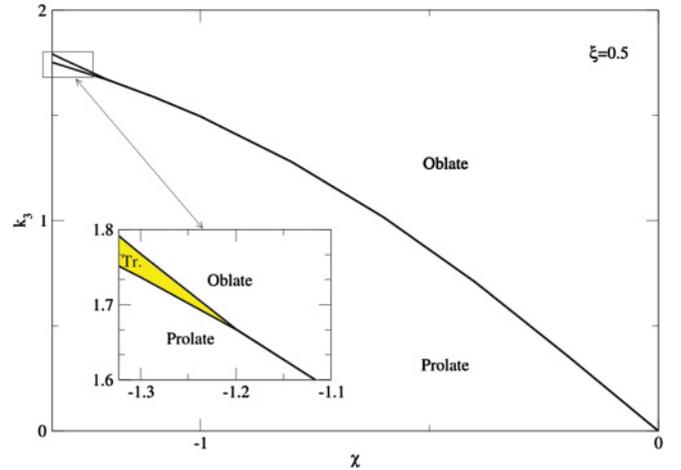


FIG. 11. (Color online) Section of the three-dimensional parameter space with $\xi = 0.5$ and $N \rightarrow \infty$. The yellow inset shows the tiny triaxial region (see text) that is found at $\chi \approx -\sqrt{7}/2$.

becomes, due to the delicate interplay between the quadratic and cubic terms.

We can see in a clearer way the onset of a triaxial minimum in Fig. 12. Here we have plotted several potential energy surfaces corresponding to points along the left vertical axis of Fig. 11 with $\chi = -\sqrt{7}/2$ and $\xi = 0.5$. The minimum is clearly prolate for small values of k_3 and it starts to widen as one approaches the region $k_3 \sim 1.7$. From approximately 1.752 to 1.791 the minimum is triaxial, but very shallow and therefore invisible at the present scale of (β, γ) . We show in Fig. 13, for the sake of completeness, the close up of the minimum for $k_3 = 1.77$. Increasing again the value of k_3 leads to an axially deformed oblate minimum. It is worth noting that the change through the triaxial region is extremely swift and some care must be taken in the minimization. One can appreciate the extremely shallow character of the triaxial minimum that extends from the axially prolate till the oblate minimum, very much in a similar way to Fig. 8 where prolate and oblate minima are degenerate and no triaxial minimum exists. The existence of the triaxial region is confirmed by inspecting contour plots of the potential energy surface along a suitable trajectory of the parameter space, rather than just looking at the plots of β and γ as a function of the parameters ξ , χ , and k_3 .

Finally we present in Fig. 14 a cut of the triaxial region as a function of ξ and k_3 for a constant value of $\chi = -\sqrt{7}/2$. A very small triaxial region is always found, except for $\xi = 0$, between the lower prolate region and the upper oblate one (see inset of Fig. 14) and terminates in correspondence with the spherical phase that occurs for high values of ξ . In a preceding subsection we have discussed that the point connecting with the spherical phase is indeed a single point as well as the one at $\xi = 0$.

A final question should be answered: What is the order of the phase transition developed in crossing the prolate-triaxial-oblate surface? In the region of triaxiality the surface evolves into two different sheets where second-order phase transitions exist. As far as we move from $\chi = -\sqrt{7}/2$ this two-fold

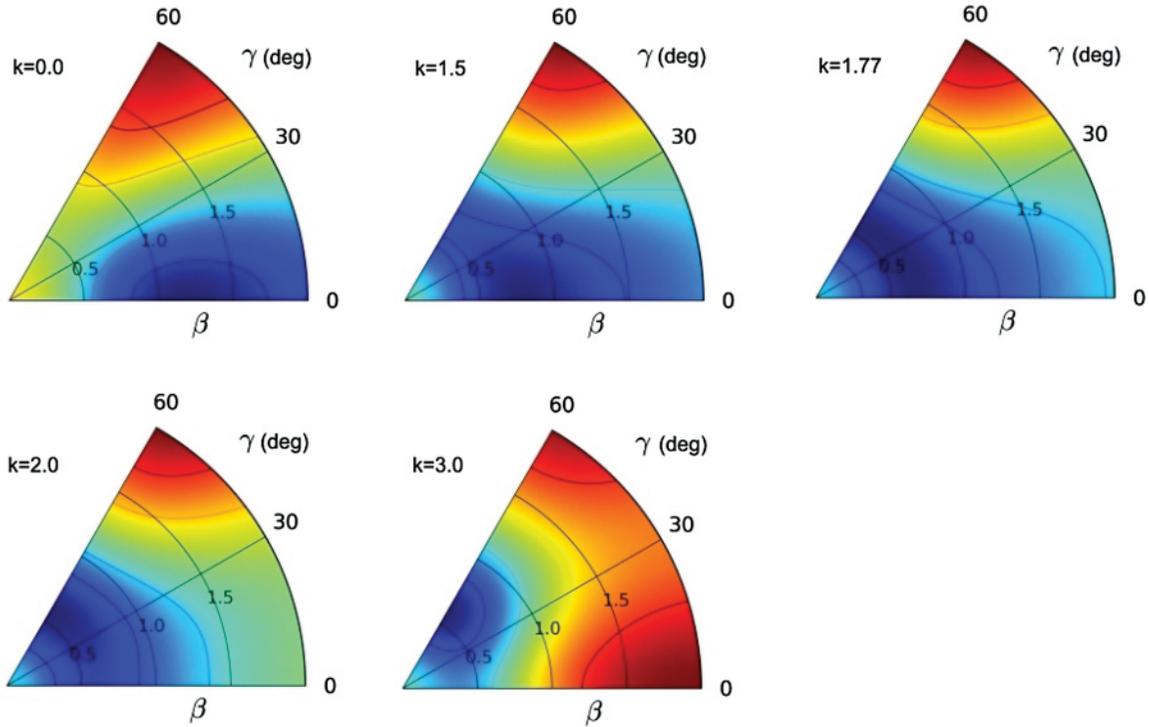


FIG. 12. (Color online) Potential energy surfaces for the CQH for $\chi = -\sqrt{7}/2$ and $\xi = 0.5$, with different values of k_3 indicated in the figure. The observed minima range from an axially deformed prolate minimum for $k_3 = 0.0$ and $k_3 = 1.5$ to an oblate one for $k_3 = 2.0$ and $k_3 = 3.0$, passing through the triaxial region. The triaxial minimum when $k_3 = 1.77$ is not apparent from this figure, because it is very shallow (see Fig. 12).

surface collapses in a single one and the phase transition becomes of the first order.

Since the small triaxial region appears in the deformed area close to $\chi = -\sqrt{7}/2$, we present in Fig. 15 a path with fixed $\chi = -\sqrt{7}/2$ and $\xi = 0.5$ and changing k_3 . Once more we plot in this figure the evolution of the ground state energy and the equilibrium value of β and γ . Again low values of k_3 give rise to prolate shapes, while the larger ones produce oblate forms, but a narrow region of triaxiality exists around

$k_3 \sim 1.75 - 1.79$. The scale does not allow to discriminate, therefore we have enlarged it in the inset that shows two, very close, second-order phase transitions: one from prolate to triaxial at around $k_3 = 1.75$ and a second one from triaxial to oblate at around $k_3 = 1.79$. As soon as we depart from the $\chi = -\sqrt{7}/2$ surface these two second-order surfaces approach more and more up to a point in which both coincide and apparently transform into a first-order surface that directly

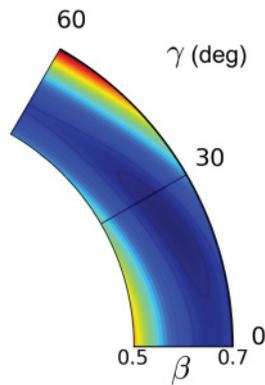


FIG. 13. (Color online) Closeup of the potential energy surface of Eq. (10) with $\chi = -\sqrt{7}/2$, $\xi = 0.5$ and $k_3 = 1.77$, clearly showing a shallow triaxial minimum at $\beta \sim 0.62$ and $\gamma \sim 23.4^\circ$. One can prove, with similar plots, that the prolate minimum smoothly shifts through the triaxial region and finally becomes oblate.

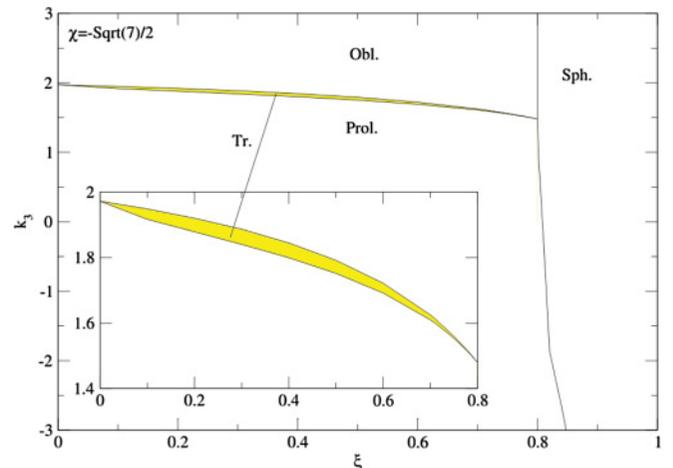


FIG. 14. (Color online) Section of the three-dimensional parameter space with $\chi = -\sqrt{7}/2$ as a function of ξ and k_3 . The inset shows the triaxial region in yellow on a finer vertical scale (see text).

separates prolate and oblate shapes, without any triaxiality in between. It is very difficult numerically to determine whether the triaxial region narrows indefinitely or rather ends up in a tricritical point.

3. A path going from spherical through oblate and prolate shapes

As a final calculation we study a trajectory that crosses the spherical-deformed surface as well as the prolate-oblate one. The appropriate values of k_3 and χ are constrained by Eqs. (16) and (18) and should verify

$$-\frac{7\sqrt{5}\chi}{2\chi^2+7} > k_3 > -\frac{\sqrt{5}}{2}\chi. \quad (19)$$

We choose $k_3 = 1.5$ and $\chi = -2/\sqrt{5}$, which fulfill Eq. (19), and vary the value of ξ . This path is depicted in Fig. 16 and two first-order phase transitions are clearly marked. From left to right, the first one has a discontinuity in β between two finite values changing at the same time γ from 0° to 60° . In the second one the system goes from the oblate phase to the spherical one, changing β from a finite to a zero value and γ from 60° to undefined.

IV. APPLICATIONS

A. Spherical to axially deformed critical point: $X(5)$

An interesting special case is to keep $\chi = 0$, in order to eliminate the driving effect of the $\hat{Q} \cdot \hat{Q}$ term toward axial deformation. In the left part of Fig. 17 a large value of k_3 generates a surface with an almost flat valley along the β direction, while the prolate (oblate) confinement in γ is due to the negative (positive) sign in front of the $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ term. This case has a potential energy surface that has a flat shape qualitatively similar to the $V(\beta, \gamma)$ potential used in the $X(5)$ critical point symmetry [42], with due differences: It is generated through a set of parameters $\chi = 0$, $\xi = 0.9$, and $k_3 = -9.5$ (a positive value would generate an equivalent oblate shape), the potential does not tend to infinity, but goes smoothly to an asymptotic value, and the periodicity in γ

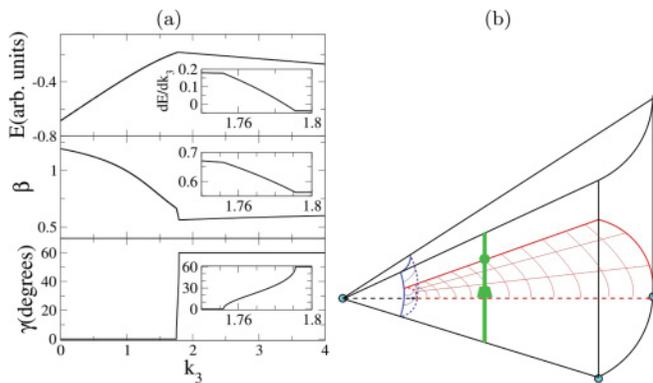


FIG. 15. (Color online) (a) Ground state energy, shape variables β and γ as a function of k_3 for $\xi = 0.5$ and $\chi = -\sqrt{7}/2$ for the path shown in (b).

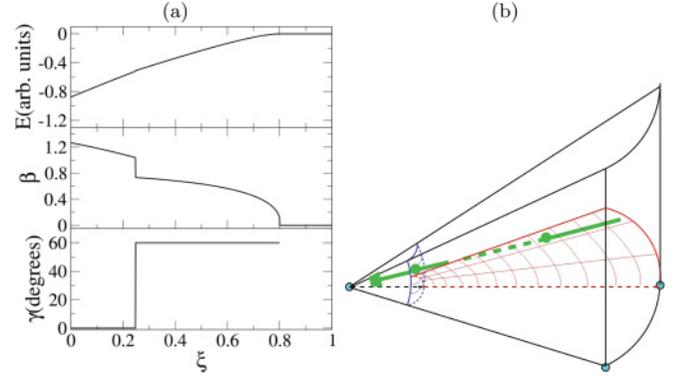


FIG. 16. (Color online) The same as in Fig. 4 but for $k_3 = 1.5$ and $\chi = -2/\sqrt{5}$.

is retained, at a variance with a harmonic oscillator. The bottom of the potential is not exactly flat, nor the behavior approximates a β^4 dependence, but the fact that a potential energy surface that mimics $X(5)$ could be obtained with $\chi = 0$ is somewhat surprising, because it has been used to associate $X(5)$ to a case that is intermediate between spherical and axially prolate shapes, while here we do not even need to set $\chi = -\sqrt{7}/2$.

B. Application to a schematic Hamiltonian

As an application, we can now use the formula for the matrix element of the $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ operator with $\chi = 0$ within the boson coherent state formalism to give further insight into the results obtained by Rowe and Thiamova for

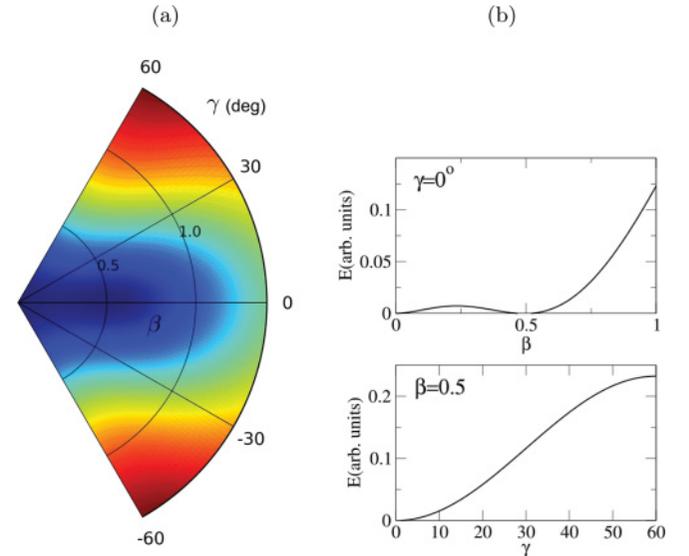


FIG. 17. (Color online) Potential energy surface (left) obtained from Eq. (4) with $\chi = 0$, $\xi = 0.9$, and $k_3 = -9.5$. The valley along the $\gamma = 0^\circ$ direction for prolate deformations resembles the potential used in the $X(5)$ solution of the Bohr Hamiltonian [42]. Right-hand side: two sections of the energy surface around the equilibrium value of the deformation parameters have been plotted as a function of β and γ , respectively.

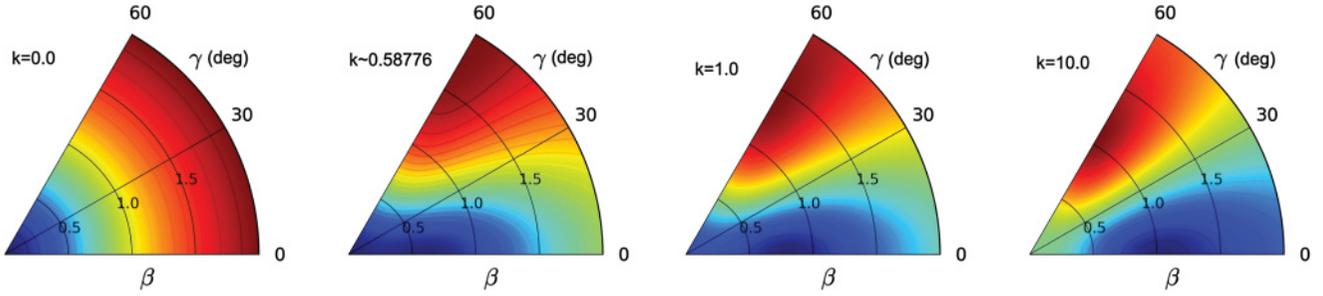


FIG. 18. (Color online) Potential energy surfaces for the Hamiltonian in Eq. (3) with $N = 10$ and different values of k : 0.0, k_{cr} , 1.0, and $k = 10$. The minimum (blue) ranges from spherical to axially deformed prolate. Vertical scales change along the transition.

the schematic Hamiltonian in Eq. (3) [33,34]. The parameter k is allowed to vary from zero to large positive values. In Fig. 18 we have plotted several contour maps corresponding to $k = 0.0, 0.58776, 1.0,$ and 10.0 . Notice that the Λ term alone ($k = 0$) just gives a spherical minimum, because its matrix element in the coherent state approach is just proportional to β^2 . From the figure one can appreciate how, with growing value of k , the minimum moves from the spherical configuration to the axially deformed prolate one. This is due to the competition between the spherically driving term Λ and the cubic interaction term $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ that has a stable axial minimum, despite having $\chi = 0$. We have collected in Fig. 19 several cuts of the potential energy surface along $\gamma = 0^\circ$, for the values $k = 0.0, 0.2, 0.4, k_{cr}, 0.8,$ and 1.0 . Alongside the ever-present minimum at $\beta = 0$, this potential admits a second deformed local minimum, that starts to appear after $k \sim 0.51$. The critical point for the first-order phase transition is found

around $k_{cr} \sim 0.58776$, where two minima are degenerate. After this point the deformed minimum prevails. The values discussed above are valid with the particular choice of $N = 10$ and with the Hamiltonian as given originally in Eq. (3). Although it is immaterial to the present discussion, one should notice that, while the $O(5)$ scalar term is linear with the boson number, the $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ term is cubic with N and therefore one should better choose a Hamiltonian that is properly normalized to get rid of the different scaling with the boson number. Notice that Ref. [32] uses a slightly different Hamiltonian having $\hat{L} \cdot \hat{L}$ as a spherical term: Although it is most certainly important to use the proper terms when calculating an IBM spectrum, it is less critical here, since both these operators have matrix elements proportional to β^2 (albeit not with the same coefficients). In both cases [32,33] triaxial minima are clearly not possible. Moreover, the inclusion of the cubic term, even with $\chi = 0$, forbids the existence of a γ -independent solution.

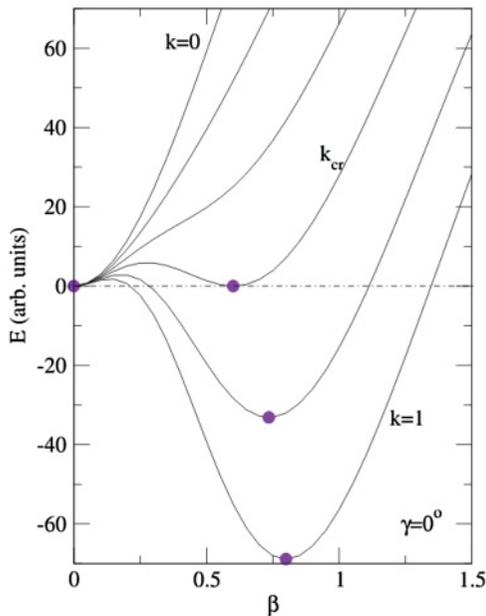


FIG. 19. (Color online) Cuts along $\gamma = 0^\circ$ of the potential energy surfaces for the Hamiltonian in Eq. (3) with $\chi = 0$ and $N = 10$ for several values of k from 0.0 to 1.0. At the value $k_{cr} \sim 0.58776$ it shows the typical signs of a first-order phase transition. Purple dots indicate the position of minima.

V. CONCLUSIONS

We have calculated the potential energy surface of the cubic $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ term within the coherent state formalism with the most general expression for the quadrupole operator. This has allowed us to confirm the results of Ref. [32,33] concerning the fact that this term with $\chi = 0$ can generate axially deformed minima, but in addition it has been shown that the cubic term has already a dependence on $\cos^2 3\gamma$ (for $\chi \neq 0$) together with the dependence on $\cos 3\gamma$ (obtainable also when $\chi = 0$). Therefore a Hamiltonian containing this term may generate triaxiality without the need to resort to the more complicated $(\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)} \cdot (\hat{Q} \times \hat{Q} \times \hat{Q})^{(0)}$ expression of Ref. [34].

After a discussion of its general features, we have used it to extend the consistent- Q Hamiltonian to the cubic- Q Hamiltonian, of which we have discussed the phase space, discovering that a triaxial region can indeed be found, between the oblate and prolate phases. This region is extremely tiny (at least in the particular parametrization chosen, if compared to the other phases), and can be pinpointed numerically only very close to the limiting values of $\chi \sim \pm\sqrt{7}/2$. The inspection of the PES confirmed that the minimum is indeed triaxial inside this region. It is not clear, at the moment, if the prolate and oblate phases are always separated by a region of triaxiality

that progressively tails off as one goes to $\chi = 0$ or if the triaxial region disappears at some point. The numerical results suggest that this tiny triaxial region finishes in a line where prolate, oblate, and triaxial shapes coexist (i.e., a tricritical line). One advantage of the present approach consists in the fact that the higher-order expansion in terms of the quadrupole operator arises naturally from the IBM formalism and the cubic term is easily justifiable in physical terms. One restriction is instead that the cubic terms contained in it have certain given weights and relations and therefore the relative importance of each term is *a priori* constrained. More general Hamiltonians can be envisaged, in which the appearance of triaxiality might be more important than in the present study [16,31]. In addition we want to stress the fact that, although the region of the parameter space that corresponds to triaxial shape is found to be small in this study, this does not, by any means, imply that triaxiality itself is uncommon. Indeed, Hamiltonians or models that

contain different parametrizations could generate different phase spaces.

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