

## Programa de doctorado "Matemáticas"

#### PhD Dissertation

## CLASSIFICATION AND REGRESSION WITH FUNCTIONAL DATA. A MATHEMATICAL OPTIMIZATION APPROACH

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A mis padres.
A mi hermana.

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## Resumen

El objetivo de esta tesis doctoral es desarrollar nuevos métodos para la clasificación y regresión supervisada en el Análisis de Datos Funcionales. En particular, las herramientas de Optimización Matemática analizadas en esta tesis explotan la naturaleza funcional de los datos, dando lugar a nuevas técnicas que pueden mejorar los métodos clásicos y que conectan las matemáticas con las aplicaciones.

El Capítulo 1 presenta las ideas generales, los retos y la notación usada a lo largo de la tesis.

El Capítulo 2 trata el problema de seleccionar el conjunto finito de instantes de tiempo que mejor clasifica datos funcionales multivariados en dos clases predefinidas. El uso, no sólo de la información proporcionada por la propia función, sino también por sus derivadas será decisivo para mejorar la predicción, como se pondrá de manifiesto posteriormente. Para ello se formula un problema de optimización binivel continuo. Dicho problema combina la aplicación de la conocida técnica SVM (Support Vector Machine) con la maximización de la correlación entre la etiqueta de la clase y la denominada función score, vinculada a dicha técnica.

El Capítulo 3 también se centra en la clasificación binaria de datos funcionales usando SVM. Sin embargo, en lugar de buscar los instantes de tiempo más relevantes, aquí se define un ancho de banda funcional para la denominada función kernel. De esta forma, se puede mejorar el rendimiento del clasificador, a la vez que se identifican los diferentes intervalos del dominio de la función, de acuerdo a su capacidad predictiva, mejorando además la interpretabilidad del modelo resultante. La obtención de tales intervalos se lleva a cabo mediante la resolución de un problema de optimización binivel por medio de un algoritmo alternante.

El Capítulo 4 se centra en la clasificación de los llamados datos funcionales híbridos, es decir, datos que están formados por variables funcionales y estáticas (constantes a lo largo del tiempo). El objetivo es seleccionar las variables, funcionales o estáticas, que mejor clasifiquen. Para ello, se define un kernel no isotrópico que asocia un parámetro ancho de banda escalar a cada una de las variables. De forma análoga a como se ha hecho en los capítulos anteriores, se propone un algoritmo alternante para resolver el problema de optimización binivel, que permite resolver los parámetros del kernel.

El problema de selección de variables presentado en el Capítulo 2 se generaliza al campo de la regresión en el Capítulo 5. El método de resolución combina la técnica denominada SVR (Support Vector Regression) con la minimización de la suma de los cuadrados de los residuos entre la verdadera variable respuesta y la prevista.

Todos los algoritmos propuestos a lo largo de esta tesis han sido aplicados a bases de datos sintéticas y reales, quedando probada su efectividad.

## Summary

The goal of this PhD dissertation is to develop new approaches for supervised classification and regression in Functional Data Analysis. Particularly, the Mathematical Optimization tools analyzed in this thesis exploit the functional nature of the data, leading to novel strategies which may outperform the standard methodologies and link mathematics with real-life applications.

Chapter 1 presents the main ideas, challenges and the notation used in this thesis.

Chapter 2 addresses the problem of selecting a finite set of time instants which best classify multivariate functional data into two predefined classes. Using, not only the information provided by the function itself but also its high-order derivatives will be crucial to improve the accuracy. To do this, a continuous bilevel optimization problem is solved. Such problem combines the resolution of the well-known technique SVM (Support Vector Machine) with the maximization of the correlation between the class label and the score.

Chapter 3 also focuses on the binary classification problem using SVM. However, instead of finding the most important time instants, here we define a functional bandwidth in the so-called kernel function. In this way, accuracy may be improved and the most relevant intervals of the domain of the function, according to their classification ability, are identified, enhancing the interpretability. A bilevel optimization problem is formulated and solved by means of an alternating procedure.

Chapter 4 is focused on classifying the so-called hybrid functional data, i.e., data which are formed by functional and static (constant over time) covariates. The goal is to select the features, functional or static, which best classify. An anisotropic kernel which associates a scalar bandwidth to each feature is defined. As in previous chapters, an alternating approach is proposed to solve a bilevel optimization problem.

Chapter 5 generalizes the variable selection problem presented in Chapter 2 to regression. The solution approach combines the SVR (Support Vector Regression) problem with the minimization of sum of the squared residuals between the actual and predicted responses. An alternating heuristic is developed to handle such model.

All the methodologies presented along this dissertation are tested in synthetic and real data sets, showing their applicability.

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# Chapter 1

# Introduction

Functional Data Analysis (FDA), [Ferraty and Vieu, 2006; Ramsay and Silverman, 2002, 2005], is concerned with the analysis of infinite-dimensional data, instead of the usual finite-dimensional vectors. A common example of functional data in a real-life application is given by the *growth* curves. More precisely, Figure 1.1(a) depicts the 93 observations of the Berkeley growth study data set [Tuddenham and Snyder, 1954] which consists of the height in centimeters of 39 boys (solid blue line) and 54 girls (dashed red line) recorded along the time interval ranging from 1 to 18 years. Another popular example is the *tecator* data set, [Borggaard and Thodberg, 1992], where the absorbance spectra of a sample of 215 finely chopped meat have been recorded in the wavelength range 850 – 1050 nanometers (Figure 1.1(b)).

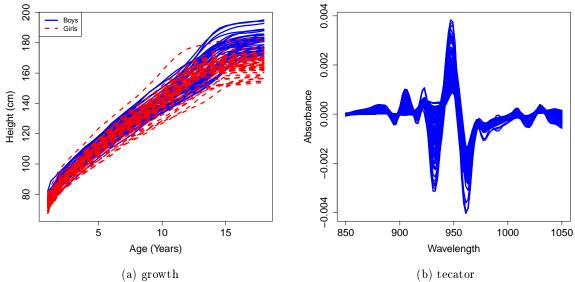


Figure 1.1: Two examples of functional data in real-life applications

Since the dimension of the functional data is infinite, FDA can be rightfully situated within the Big Data revolution area, [Al-Jarrah et al., 2015; Baesens, 2014; Chen et al., 2014; Chen and Zhang, 2014; Sangalli, 2018; Singh and Reddy, 2014; Torrecilla and Romo, 2018]. Indeed, several works in the literature link FDA and Big Data, e.g., [Chen et al., 2011, 2017; Giraldo et al., 2018; Vieu, 2018]. The proper treatment of such data is crucial to extract meaningful information and enhance decision making.

Two main challenges in FDA are classification and regression. The works of [Biau et al., 2005; Cuevas et al., 2007; Preda et al., 2007; Rossi and Villa, 2006, 2008] should be highlighted in the former case, whereas for references on the latter, the reader is referred to [Ferraty and Vieu, 2004; Hernández et al., 2007; James et al., 2009; Kneip et al., 2016]. Section 1.2 is devoted to present the main concepts of these two topics.

The aim of this thesis is to develop new strategies for classification and regression in Functional Data Analysis. The use of Mathematical Optimization strategies will define new algorithms which improve the benchmark methodologies, as our numerical experience shows.

#### 1.1 Functional Data Analysis

FDA studies infinite-dimensional data. [Ramsay and Silverman, 2005] (first edition in 1997) coined the term functional data. Thanks to the technological advances witnessed in recent years, functional data have increasingly arisen in many real-world applications, e.g., speech recognition, [Rossi and Villa, 2008], spectrometry, [Martín-Barragán et al., 2014], meteorology, [Besse et al., 2000], client segmentation, [Laukaitis and Račkauskas, 2005], temporal gene expression data, [Leng and Müller, 2006], physical, [Muñoz and González, 2010; Tuddenham and Snyder, 1954], and chemical processes, [Blanquero et al., 2016a,b].

Regarding the techniques used in FDA, it must be mentioned that, theoretically, functional data are assumed to be infinite-dimensional. However, in practice processes cannot be monitored continuously and instead, measurements on a grid are given. In other words, data are usually presented as high-dimensional (but finite-dimensional) data. Therefore, methodologies managing high-dimensional data can be applied, as done for instance in [Hastie et al., 1995], where a penalized linear discriminant analysis method is described to handle problems with many highly correlated predictors, such as those obtained by discretizing a function. In general, the direct use of standard multivariate analysis techniques for functional data may have dramatic consequences. It yields ill-posed problems since the strong relationship between the measurements in two consecutive time instants is not taken into account, and serious drawbacks, such as the curse of dimensionality, may appear, see Section 2 of [Vieu, 2018]. The work of [Horváth and Kokoszka, 2012] includes some examples in the literature, showing that functional data problems need to be handled with different tools from those used in multivariate analysis, in order to take advantage of the functional nature of the data. For instance, [Borggaard and Thodberg, 1992] claims that functional regression yields better predictions than multivariate linear regression because of the high-dimensionality of the data. The spectra analyzed in [Kirkpatrick and Heckman, 1989], as well as the growth curves in [Griswold et al., 2008] are better represented within a functional framework. The work of [Febrero et al., 2007] analyzes curves of nitrogen oxide pollutants. It is observed that the critical pollution peaks are situated in the early morning hours as well as in the evening, which coincides with the time points at which people usually go to work and come back home. Hence, the shape of the functions plays here a very important role. If such functional data were studied from a multivariate perspective, it would be hard to obtain such a suitable interpretation. Finally, with respect to the dimensionality reduction, benchmark methods such as Principal Component Analysis (PCA) do not take into account some intrinsic characteristics of the functional data, e.g., continuity or smoothness. Multivariate PCA and the functional counterpart (FPCA) are thus different, [Ramsay and Silverman, 2005].

Although a full review of all the FDA techniques exceeds the aim of this dissertation, some references on this topic are highlighted. The monograph [Ramsay and Silverman, 2005] outlines the first definitions and problems related to functional data. The application of such ideas to real-world problems is treated in [Ramsay and Silverman, 2002]. From a non-parametric point of view, the books of [Ferraty and Vieu, 2006] and [Bosq and Blanke, 2007] address classification and forecasting problems, making emphasis on both theoretical and practical aspects. The paper of [Cuevas, 2014] provides a partial survey of the main concepts of the FDA theory from a statistical perspective. Recent advances can be found on the Special Issue introduced in [Goia and Vieu, 2016]. For further information on FDA, the reader is referred to the works of [Horváth and Kokoszka, 2012; Hsing and Eubank, 2015; González-Manteiga and Vieu, 2007; Müller, 2016; Wang et al., 2016].

Computational aspects of FDA are extensively discussed in the literature; the work of [Ramsay et al., 2009] presents a comprehensive study of the application of functional data in R, [Core Team, 2017], and Matlab, [Matlab, 2018] languages. Some of the main packages used in R are fda, [Ramsay et al., 2018], for classic functional data analysis, fda.usc, [Febrero-Bande and Oviedo de la Fuente, 2012] for non-parametric functional data strategies and advanced tools in the standard FDA, and rainbow, [Hyndman and Shang, 2010], for functional data representation. An extensive list of the available R packages can be found in [Scheipl, 2018]. The Matlab package PACE, [Yao et al., 2015] provides several implementations of FDA for Functional Principal Component Analysis (FPCA), and BFDA, [Yang and Ren, 2017], follows a Bayesian point of view.

Most of the above-mentioned FDA references focus on the univariate case, i.e., each observation is represented by just one single function. Two examples of univariate functional data are shown in Figure 1.1. Unfortunately, multivariate functional data have received less attention in the literature. Some applications of multivariate functional data in PCA and clustering can be found in [Berrendero et al., 2011; Chiou et al., 2014; Happ and Greven, 2017] and [Jacques and Preda, 2014; Kayano et al., 2010; Tokushige et al., 2007], respectively. Roughly speaking, a multivariate functional datum can be defined as a finite-dimensional vector where each component is a function. In other words, each individual is represented by a finite set of functions. More specifically, given a sample s of individuals, a functional datum  $X_i \in \mathcal{X} = \mathcal{F}^p$ ,  $i \in s$  is formed by a set of p functional features, i.e.,

$$X_i(t) = (X_{i1}(t), \dots, X_{ip}(t)),$$
 (1.1)

where  $X_{iv}: [0,T] \to \mathbb{R}$ ,  $v=1,\ldots,p$  are functions taking values on the time interval [0,T] and belonging to the functional space  $\mathcal{F}$ , whose choice will depend on the problem treated, and will be conveniently detailed along this thesis when needed. As an illus-

trative example, Figure 1.2 shows a sample of a synthetic 3—variate functional data set from Section 4.1 of [Wang and Yao, 2015]. The figure collects three chemical variables that have been recorded along a batch-type process.

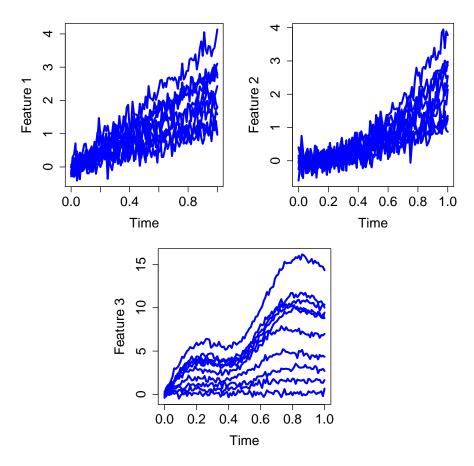


Figure 1.2: An example of multivariate functional data

The univariate functional data corresponds with the case, p=1, whereas p>1 yields multivariate functional data. It may occur that some of the p functions in  $X_i$  take a constant value along the interval [0,T]. For instance, in handwriting analysis, one can collect pure functional information, such as the x and y trajectories recorded while writing characters, or static values (i.e., constant over time), such as the force at which the characters are written. More information about this data set can be found in the Character Trajectories Dataset from the UCI Machine Learning repository [Dheeru and Karra Taniskidou, 2017]. Figure 1.3 depicts samples of curves of the infinite-dimensional data and a boxplot of the static variable. Despite its obvious application in many real-world contexts, this type of data has not been studied deeply in the literature. A few references are [Febrero-Bande et al., 2017] where the most informative variables in terms of prediction are selected, and Chapter 10 of [Ramsay and Silverman, 2005]. In these situations, the p-dimensional vector (1.1) can be divided into two parts, where the first

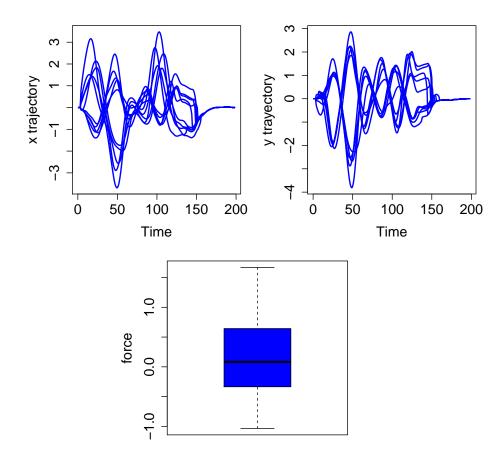


Figure 1.3: An example of hybrid functional data

 $p_1$  components are non-constant functions, and the remaining  $p_2$  covariates are static values, with  $p = p_1 + p_2$  and  $\mathcal{X} = \mathcal{F}^{p_1} \times \mathbb{R}^{p_2}$ . Such particular functional data are referred along this dissertation as hybrid functional data, and can be represented as

$$X_i(t) = (X_{i1}(t), \dots, X_{i p_1}(t), X_{i p_1+1}, \dots, X_{i p_1+p_2})$$
(1.2)

#### 1.2 Supervised Classification and Regression

In this section we introduce two of the most challenging problems in Supervised Learning, namely supervised classification and regression. Section 1.2.1 collects the main definitions and concepts regarding these topics. Section 1.2.2 describes a benchmark strategy for classification and regression, namely Support Vector Machine (SVM), for classification and its extension to regression, Support Vector Regression (SVR), respectively. Section 1.2.3 introduces the so-called kernel function used to map the data onto a higher-dimensional space, yielding better predictions. Finally, Section 1.2.4 outlines

the methods used in this dissertation to estimate accuracies.

#### 1.2.1 Supervised Learning

Supervised Learning is grounded in statistical learning theory, [Vapnik, 1995, 1998] and essentially, identifies properties of learning machines in order to generalize well to the forthcoming unobserved data. The set of observations used to learn is known as training sample. A simple example of Supervised Learning can be found in the medical field. Let us assume given an explanatory variable, X, e.g., medical results, and a response variable, Y, e.g., ill/healthy, or hemoglobin levels in the blood. The goal is to learn the main properties of the observed patients, in order to predict the response variable Y of new individuals, just using the information provided by the X variable.

Although some surveys develop Supervised Learning from a general perspective, [Schölkopf et al., 1999; Schölkopf and Smola, 2001], most of the recent monographs are particularly devoted to classification and regression problems. More details about the study of both topics are given in the next paragraphs.

A plethora of examples of supervised classification can be found in real-life applications, e.g., medicine, [Guyon et al., 2002; Furey et al., 2000], chemistry, [Ivanciuc, 2007] or fraud detection, [Fawcett and Provost, 1997], just to cite a few references. See also [Carrizosa et al., 2011; Carrizosa and Romero Morales, 2013; García-Borroto et al., 2014; Kotsiantis et al., 2007; Lemaire et al., 2014; Provost and Fawcett, 2013] for some surveys and monographs.

Supervised classification aims to find a classification rule, which assigns a class label Y belonging to a finite set of classes, just using the information provided by the covariate X in the training sample. In this dissertation, we will restrict ourselves to the case of binary classification, and thus the response variable Y will belong to the label set  $\{-1, +1\}$ . The multiclass counterpart can be easily reduced to the binary case, for instance, by comparing one class versus the rest. In order to get the classification rule, some classifiers involve the use of a *score function*  $\hat{Y}(X)$ , and the classification is carried out then by comparing its value with a threshold.

The simplest classifiers are obtained when the score functions are linear, i.e.,  $\hat{Y}(X)$  is a linear combination of the variables X. The pioneering work of [Fisher, 1936] has been generalized by the Linear Discriminant Analysis (LDA), [Friedman et al., 2001b]. The logistic regression [Friedman et al., 2001b] is another popular classifier which builds maximum likelihood estimates by solving nonlinear optimization problems. One of the benchmark techniques in (linear) supervised classification is Support Vector Machine (SVM) [Carrizosa and Romero Morales, 2013; Cortes and Vapnik, 1995; Cristianini and Shawe-Taylor, 2000; Vapnik, 1995, 1998], described in detail in Section 1.2.2.

Other supervised methods are quite popular and powerful. Nearest-neighbor is based on a dissimilarity measure and the classification rule groups together those elements which may share the same class label. The basic method is known as the k-nearest neighbor, [Cover and Hart, 1967; Dasarathy, 1991] and associates to a given X, the label which is most frequent among the closest k objects. The classification trees, [Breiman et al., 1984], are tree-based classifiers based on if-then rules. They are very appealing because of their easy interpretability. For other benchmark techniques in supervised classification, such as random forest or neural networks, the reader is referred to [Biau and Scornet, 2016; Breiman, 2001; Genuer et al., 2017; Gurney, 2014; Schmidhuber, 2015].

Broadly speaking, these classification methods can be applied to both multivariate data and functional data classification. Some differences should be, however, pointed out. First, the covariance operator is non-invertible when infinite-dimensional or highly autocorrelated data appear. For this reason, any technique requiring such inversion, e.g., LDA, cannot be directly applied in FDA. To overcome this issue different strategies which take into account the functional nature of the data, such as [James and Hastie, 2001], have been applied. Regardless of the classification rules, some differences occur between the finite and infinite-dimensional field. Particularly, [Delaigle and Hall, 2012a] shows that the near perfect classification phenomenon holds in the functional setting. Indeed there exist non-trivial FDA problems where no error in the classification is obtained. This fact cannot happen in the finite-dimensional field, except when degenerated problems are treated. A survey of different classification methods in functional data can be found in [Baíllo et al., 2011].

The idea of the standard multivariate (supervised) regression is to predict, through a score function  $\hat{Y}(X)$ , a real-valued response variable, by making use of the explanatory variables in X. The linear regression, i.e., the case in which the score is a linear combination of the covariates, is one of the most popular strategies in the literature, enhanced with some approaches, such as Lasso, [Tibshirani, 1996], ridge regression, [Drapper and Smith, 1998; Miller, 2002], Least Angle Regression, [Efron et al., 2004] or Elastic Net, [Zou and Hastie, 2005]. Section 1.2.2 is devoted to a deep analysis of a benchmark nonlinear method, namely, Support Vector Regression (SVR), [Smola and Schölkopf, 2004].

The use of functional regression is growing more and more since the former monograph (first edition in 1997) of [Ramsay and Silverman, 2002]. Some applications can be found in [Müller and Stadtmüller, 2005], and the reader is referred to [Morris, 2015] for a recent survey. Under the umbrella of functional regression, one finds methods involving either functional predictors, functional responses or both functional predictors and responses. Along this dissertation, we will just focus on functional predictor regression. Some references to study the remaining cases are [Fan and Zhang, 2000; Faraway, 1997; Lin and Ying, 2001; Reiss and Ogden, 2010; Staicu et al., 2010; Yao et al., 2005; Zhou et al., 2010]. Functional predictor regression involves the regression of a scalar response

Y by means of a set of functional predictor variables X. The linear version was first introduced by [Ramsay and Dalzell, 1991], and [Ramsay and Silverman, 2005] discussed the results obtained with this model where different basis functions have been introduced. The interpretability is addressed in some cases through Lasso approaches [Zhu and Cox, 2009], or just allowing sparsity in the model, [James et al., 2009]. Nonlinear models have also been studied in the literature. Particularly, [Yao and Müller, 2010] proposed a quadratic model and a functional generalized additive model for noise-free functions is considered in [McLean et al., 2012]. [Ferraty and Vieu, 2004, 2006] applied nonparametric models and [Hernández et al., 2007; Hernández et al., 2009] adapted the SVR method to the functional context.

# 1.2.2 Support Vector Machine (SVM) and Support Vector Regression (SVR)

Support Vector Machine (SVM) and Support Vector Regression are powerful tools for classification and regression, respectively. The aim of this section is to describe both of them.

With respect to classification, assume given a sample s of individuals, where each instance  $i \in s$  is associated to the pair  $(X_i, Y_i)$ . The datum  $X_i \in \mathcal{X}$  is the predictor variable, whilst  $Y_i \in \{-1, +1\}$  denotes the class label. Moreover, the space  $\mathcal{X}$  could be either multivariate or functional, depending on the framework considered. When the instances in the training sample are linearly separable, SVM [Cortes and Vapnik, 1995] provides an optimal hyperplane  $\langle \mathbf{w}, X_i \rangle + b$ , separating both classes, where  $\mathbf{w} \in \mathcal{X}$ ,  $b \in \mathbb{R}$  and  $\langle \cdot, \cdot \rangle$  denotes the inner product in the space  $\mathcal{X}$ . Such hyperplane is obtained by maximizing the so-called margin, i.e., the distance to the closest positive and negative training data, [Vapnik, 1995, 1998]. The maximal margin is provided by the element  $\mathbf{w}$  with minimum norm such that  $Y_i(\langle \mathbf{w}, X_i \rangle + b) \geq 1$ ,  $\forall i \in s$ . The so-called hard-margin problem is formulated as the following convex quadratic problem with linear constraints:

$$\begin{cases}
\min_{\mathbf{w},b} & \langle \mathbf{w}, \mathbf{w} \rangle \\
\text{s.t.} & Y_i (\langle \mathbf{w}, X_i \rangle + b) \ge 1, i \in s
\end{cases}$$
(1.3)

Since perfect classification of the training sample is quite unusual, some classification errors are allowed via the artificial variables  $\xi_i$  introduced for all  $i \in s$ . In that case, the optimal solution of the linear SVM is obtained by solving the following optimization problem, called soft-margin:

$$\begin{cases}
\min_{\mathbf{w},b,\xi} & \langle \mathbf{w}, \mathbf{w} \rangle + C \sum_{i \in s} \xi_i \\
\text{s.t.} & Y_i \left( \langle \mathbf{w}, X_i \rangle + b \right) \ge 1 - \xi_i, i \in s, \\
\xi_i \ge 0, \quad i \in s
\end{cases} \tag{1.4}$$

The parameter C is a regularization parameter to be tuned, that penalizes the existence of misclassified observations in the training sample [Hastie et al., 2004; Vapnik, 1998]. Larger values of C yield smaller-margin hyperplanes, whilst smaller values of C result in larger-margin hyperplanes, even if they misclassify more data in the training sample.

The procedures above define a linear classification rule: given  $\mathbf{w}$ , optimal solution of (1.3) or (1.4), a score  $\hat{Y}(X)$  given in (1.5) is associated to each data X, and thus X is classified in class +1 if and only if  $\hat{Y}(X) > \beta$ , where  $\beta$  is a prefixed threshold value.

$$\hat{Y}(X) = \langle \mathbf{w}, X \rangle \tag{1.5}$$

The resolution of Problem (1.4) can be significantly enhanced by solving its dual problem. Apart from other computational issues, using the dual formulation, we may avoid infinite-dimensional optimization, which would be the case of  $\mathbf{w}$  if  $\mathcal{X}$  were a functional space. More specifically, building the Lagrangian function and imposing the Karush-Kuhn-Tucker (KKT) optimality conditions, Problem (1.4) turns out to be equivalent to the concave quadratic maximization problem with linear constraints in (1.6), easily solved by standard local search routines or specific tools, as in [Ferris and Munson, 2004; Richtárik and Takáč, 2016]:

$$\begin{cases}
\max_{\alpha} & \sum_{i \in s} \alpha_i - \frac{1}{2} \sum_{i,j \in s} \alpha_i \alpha_j Y_i Y_j \langle X_i, X_j \rangle \\
\text{s.t.} & \sum_{i \in s} \alpha_i Y_i = 0 \\
& \alpha_i \in [0, C], i \in s
\end{cases}$$
(1.6)

In addition, the primal optimal solution  $\mathbf{w}$  can be recovered from the dual optimal solution,  $\alpha$ , yielding the expression:

$$\mathbf{w} = \sum_{i \in s} \alpha_i Y_i X_i \tag{1.7}$$

and therefore,  $\mathbf{w}$  is generated from a combination of the objects  $X_i$ . Those individuals  $i \in s$  such that  $\alpha_i$  is strictly positive are called support vectors. The support vectors lie exactly on the lines parallel to the hyperplane which are separated by a fixed distance defined by the margin. For any X, the score  $\hat{Y}(X)$  is obtained as given by  $\hat{Y}(X) = \langle \mathbf{w}, X \rangle = \sum_{i \in s} \alpha_i Y_i \langle X_i, X \rangle$ .

The problem statement detailed in the previous lines for classification can be generalized to regression. Indeed, for a given set of observations  $\{(X_i, Y_i)\}_{i \in s}$ , where  $X_i$  belongs to the multivariate or functional space  $\mathcal{X}$  and  $Y_i \in \mathbb{R}$ , for all  $i \in s$ . The main goal is to find a rule able to predict the response  $Y \in \mathbb{R}$  from the information of the data  $X \in \mathcal{X}$ . In its simplest version, SVR [Smola and Schölkopf, 2004] finds a linear score function  $\hat{Y}: \mathcal{X} \to \mathbb{R}$ , in such a way that, for  $X \in \mathcal{X}$ ,  $\hat{Y}(X)$  differs at most  $\varepsilon$  from

the obtained response  $Y \in \mathbb{R}$ . The score function  $\hat{Y}$  can be expressed as

$$\hat{Y}(X) = \langle \mathbf{w}, X \rangle + b, \tag{1.8}$$

where  $b \in \mathbb{R}$ , and  $\mathbf{w} \in \mathcal{X}$  are the optimal solution of the hard-margin problem in (1.9):

$$\begin{cases}
\min_{\mathbf{w},b} & \langle \mathbf{w}, \mathbf{w} \rangle \\
\text{s.t.} & Y_i - \langle \mathbf{w}, X_i \rangle - b \leq \varepsilon, \ i \in s, \\
& \langle \mathbf{w}, X_i \rangle + b - Y_i \leq \varepsilon, \ i \in s
\end{cases}$$
(1.9)

Problem (1.9) implicitly assumes that all the pairs  $(X_i, Y_i)$  are well predicted with  $\varepsilon$  precision. This is not always the case, and some errors may be allowed. As done in the classification problem, we introduce artificial variables  $\xi_i, \xi_i^*$ , yielding, for a fixed regularization parameter C, the soft-margin problem in (1.10):

$$\begin{cases}
\min_{\mathbf{w},b,\xi,\xi^*} & \langle \mathbf{w}, \mathbf{w} \rangle + C \sum_{i \in s} (\xi_i + \xi_i^*) \\
\text{s.t.} & Y_i - \langle \mathbf{w}, X_i \rangle - b \le \varepsilon + \xi_i, i \in s, \\
& \langle \mathbf{w}, X_i \rangle + b - Y_i \le \varepsilon + \xi_i^*, i \in s \\
& \xi_i, \xi_i^* \ge 0
\end{cases} (1.10)$$

Problem (1.10) is usually more easily solved in its dual formulation. Thanks to the Lagrangian function and the KKT conditions, Problem (1.10) can be rewritten as a concave maximization problem with linear contraints:

$$\begin{cases}
\max_{\alpha,\alpha^*} & -\frac{1}{2} \sum_{i,j \in s} (\alpha_i - \alpha_i^*)(\alpha_j - \alpha_j^*) \langle X_i, X_j \rangle - \varepsilon \sum_{i \in s} (\alpha_i + \alpha_i^*) + \sum_{i \in s} Y_i(\alpha_i - \alpha_i^*) \\
\text{s.t.} & \sum_{i \in s} (\alpha_i - \alpha_i^*) = 0 \\
& \alpha_i, \alpha_i^* \in [0, C], i \in s
\end{cases}$$
(1.11)

and therefore the primal variables  $\mathbf{w}$  can be written as a linear combination of the training objects,  $X_i$ :

$$\mathbf{w} = \sum_{i \in s} (\alpha_i - \alpha_i^*) X_i \tag{1.12}$$

Along this dissertation, we consider in (1.13) an equivalent SVR dual problem, by making the change of variables  $\nu_i = \alpha_i/C$  and  $\nu_i^* = \alpha_i^*/C$ ,  $i \in s$ :

$$\begin{cases} \max_{\nu,\nu^*} & -\frac{1}{2} \sum_{i,j \in s} (\nu_i - \nu_i^*)(\nu_j - \nu_j^*) C\langle X_i, X_j \rangle - \varepsilon \sum_{i \in s} (\nu_i + \nu_i^*) + \sum_{i \in s} Y_i (\nu_i - \nu_i^*) \\ \text{s.t.} & \sum_{i \in s} (\nu_i - \nu_i^*) = 0 \\ & \nu_i, \nu_i^* \in [0, 1], \ i \in s \end{cases}$$

$$(1.13)$$

#### 1.2.3 Kernels Definition

Section 1.2.2 was devoted to linear SVM and SVR problems. In this section, a nonlinear extension obtained by means of the so-called *kernel trick*, is discussed.

Nonlinear Support Vector based problems are obtained by means of a feature map  $\phi: \mathcal{X} \to \overline{\mathcal{X}}$  which embeds the original data X in a higher-dimensional space  $\overline{\mathcal{X}}$ , containing an inner-product. The aim of this nonlinear map  $\phi$  is to translate the original data  $X_i$  to a space in which data are linearly separable, and therefore all the procedures explained in Section 1.2.2 can be applied. In this way, the inner product  $\langle X_i, X_j \rangle$  that appears in the objective functions of the optimization problems (1.6) and (1.13), and also in their corresponding score functions (1.5) and (1.8), turns out to be  $\langle \phi(X_i), \phi(X_j) \rangle$ . The explicit expressions of the higher-dimensional space  $\overline{\mathcal{X}}$  and  $\phi$  are not needed, since all the calculations are done through the inner product  $\langle \phi(X_i), \phi(X_j) \rangle$ . Hence, one can just provide the so-called kernel function  $K: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ , [Cristianini and Shawe-Taylor, 2000; Hofmann et al., 2008; Schölkopf and Smola, 2001], defined by:

$$K(X_i, X_j) = \langle \phi(X_i), \phi(X_j) \rangle \tag{1.14}$$

and therefore, the classification problem (1.6) is reformulated as follows:

$$\begin{cases} \max_{\alpha} & \sum_{i \in s} \alpha_i - \frac{1}{2} \sum_{i,j \in s} \alpha_i \alpha_j Y_i Y_j K(X_i, X_j) \\ \text{s.t.} & \sum_{i \in s} \alpha_i Y_i = 0 \\ & \alpha_i \in [0, C], \ i \in s, \end{cases}$$

$$(1.15)$$

yielding a nonlinear classification rule: given  $\alpha$ , optimal solution of (1.15), a score  $\hat{Y}(X)$  in (1.16) is associated with each functional data X,

$$\hat{Y}(X) = \sum_{i \in s} \alpha_i Y_i K(X, X_i), \quad X \in \mathcal{X}, \tag{1.16}$$

and thus X is classified in class +1 if and only  $\hat{Y}(X) > \beta$ .

In an analogous manner, the regression problem (1.13) is rewritten in the following way:

$$\begin{cases}
\max_{\nu,\nu^*} & -\frac{1}{2} \sum_{i,j \in s} (\nu_i - \nu_i^*)(\nu_j - \nu_j^*) CK(X_i, X_j) - \varepsilon \sum_{i \in s} (\nu_i + \nu_i^*) + \sum_{i \in s} Y_i(\nu_i - \nu_i^*) \\
\text{s.t.} & \sum_{i \in s} (\nu_i - \nu_i^*) = 0 \\
& \nu_i, \nu_i^* \in [0, 1], i \in s,
\end{cases}$$
(1.17)

transforming the score function in (1.8) into:

$$\hat{Y}(X) = \sum_{i \in s} (\alpha_i - \alpha_i^*) K(X_i, X) + b, \quad X \in \mathcal{X},$$
(1.18)

A function must satisfy some conditions to be a kernel. More precisely, a kernel K is a positive definite function with satisfies the conditions provided by the Mercer's theorem [Mercer, 1909]. [Smola and Schölkopf, 2004] clarifies that such result just means that a kernel function can always be written as an inner product in some feature space, and consequently, some closure properties are derived. They include the integrals of kernels and the positive linear combinations of kernels, applied for Multiple Kernel Learning in [Carrizosa et al., 2014] and the references therein. Moreover, the product property holds, i.e., if  $K_1$  and  $K_2$  are two kernels, then the function defined in (1.19)

$$K(X_i, X_j) = K_1(X_i, X_j) K_2(X_i, X_j)$$
(1.19)

is also a kernel.

More closure properties and details of the proof of these results can be found in [Shawe-Taylor et al., 2004; Smola and Schölkopf, 2004].

A wide variety of kernels, mostly in finite-dimensional spaces, are proposed in the literature. We can mention for instance the linear kernel, [Carrizosa and Romero Morales, 2013; Cristianini and Shawe-Taylor, 2000; Hofmann et al., 2008], in (1.20),

$$K(X_i, X_j) = \langle X_i, X_j \rangle \tag{1.20}$$

which will lead the simplest Support Vector problems (1.6) and (1.13).

As stated in [Vapnik, 1995], polynomial functions of type (1.21)

$$K(X_i, X_j) = (1 + \langle X_i, X_j \rangle)^D \tag{1.21}$$

are kernels too.

The Gaussian (RBF) kernel, defined with a bandwidth parameter  $\omega$  in (1.22), is the most popular kernel, mainly due to its excellent empirical behavior, [Carrizosa et al., 2014; Cristianini and Shawe-Taylor, 2000; Keerthi and Lin, 2003]. Along this dissertation, we will just focus on the RBF kernel, even though the applications proposed in this thesis can be easily extended to other kernels.

$$K(X_i, X_j) = \exp(-\omega \langle X_i - X_j, X_i - X_j \rangle) \tag{1.22}$$

So far, the reasonings made through Sections 1.2.2 and 1.2.3 are valid either for finite or infinite-dimensional spaces. By contrast, in the following lines, we restrict ourselves

to the case in which the data are functional with the aim of clearly define the different kernels which will be analyzed in the next chapters of the dissertation.

Formally speaking, let  $X_i, X_j : [0, T] \to \mathbb{R}$  belonging to the Hilbert functional space  $\mathcal{X} = \mathcal{F}$ . The simplest way to deduce the functional version of the finite-dimensional Gaussian kernel, is just to define the inner product as:

$$\langle X_i, X_j \rangle = \int_0^T X_i(t) X_j(t) dt, \quad X_i, X_j \in \mathcal{F}$$
 (1.23)

which combined with (1.22), for a given bandwidth  $\omega$ , yields:

$$K(X_i, X_j, \omega) = \exp\left(-\omega \int_0^T (X_i(t) - X_j(t))^2 dt\right), \quad X_i, X_j \in \mathcal{F}$$
 (1.24)

When data are multivariate, i.e.,  $\mathcal{X} = \mathcal{F}^p$ , the product property defined in (1.19) will be used. Particularly, the following Gaussian kernel with a fixed bandwidth  $\boldsymbol{\omega} = (\omega_1, \dots, \omega_p)$ , is produced:

$$K(X_i, X_j, \boldsymbol{\omega}) = \exp\left(-\sum_{v=1}^p \omega_v \int_0^T (X_{iv}(t) - X_{jv}(t))^2 dt\right), \quad X_i, X_j \in \mathcal{F}^p$$
 (1.25)

For hybrid functional data as in (1.2), the last  $p_2$  integral terms in (1.25) can be substituted by ordinary squared sums as follows:

$$K(X_{i}, X_{j}, \boldsymbol{\omega}) = \exp\left(-\sum_{v=1}^{p_{1}} \omega_{v} \int_{0}^{T} (X_{iv}(t) - X_{jv}(t))^{2} dt - \sum_{v=p_{1}+1}^{p_{2}} \omega_{v} (X_{iv} - X_{jv})^{2}\right), \quad X_{i}, X_{j} \in \mathcal{F}^{p_{1}} \times \mathbb{R}^{p_{2}}$$
(1.26)

Finally, since in practice, functional data are only measured in a finite grid of points, let say  $\mathbf{t} = (t_1, \dots, t_H)$ , the integrals of Equation (1.25) can be approximated by sums, in which the evaluation of the functional data in the vector  $\mathbf{t}$  is performed, yielding:

$$K(X_i, X_j, \boldsymbol{\omega}, \mathbf{t}) = \exp\left(-\sum_{v=1}^p \sum_{h=1}^H \omega_v (X_{iv}(t_h) - X_{jv}(t_h))^2 dt\right), \quad X_i, X_j \in \mathcal{F}^p \quad (1.27)$$

The expressions of the kernels given by (1.24), (1.26) and (1.27) will be studied in detail along this dissertation.

#### 1.2.4 Performance Estimation

If the whole data set is used to train the supervised model, overfitting may appear. See Chapter 7 of [Friedman et al., 2001b] for more details. The performance measures may then be overoptimistic. To avoid this issue, the usual methodology is to divide the whole data set into three independent parts, namely training, validation, and testing.

Particularly, the training sample is used to build a model for a fixed combination of parameters, the validation sample is utilized to tune such parameters, and finally, the efficiency of the model is estimated in the testing sample. For instance, when building a classifier with the SVM problem (1.6), the optimization problem is run in the same training sample for different values of C. Then, the parameter C associated to the largest classification accuracy, measured on the validation sample, is kept. Finally, the chosen classifier is used to estimate the accuracy on the testing sample.

Since the results obtained with the above-mentioned tool may highly depend on the division made, it is useful to apply the so-called k-fold cross-validation method, [Kohavi, 1995]. To be more precise, k-fold cross-validation splits the whole data set into k folds. Then, the model is trained and validated on k-1 parts, and the remaining one is used to test the assessment. In this way, a series of k accuracy measures on the testing samples is given. As a final result, the averaged accuracy on the k testing samples is proposed as an estimate of the goodness of fit.

The number of folds k frequently depends on the cardinality of the databases. If insufficient data are available, then the so-called leave-one-out is applied, i.e., k coincides with the number of observations. Therefore, the model is run each time with all the individuals except one, which will be used to test the results.

#### 1.3 Feature Selection

The analysis of (high-dimensional) data entails some difficulties associated with the high computational costs, and the introduction of redundancy and noise from measurement errors, which are usually associated with lower performance measures. Hence, to avoid these issues, it is useful to apply feature selection strategies.

Feature selection is a key preprocessing step in data mining due to several reasons. First, interpretability may be enhanced and monitoring costs may be reduced if just a few number of features capable of making good predictions is considered instead of the original and usually large set of features. Second, to select the most important features makes sense in real-world problems, since as shown in e.g., the gene expression work [Golub et al., 1999], the relevant information may be summarized in just some points. Last but not least, the redundant information introduced by the original data can be surmounted by means of feature selection tools, yielding equivalent or even better performance values.

A plethora of works have been published on feature selection. [Blum and Langley, 1997] was one of the first papers published on this topic. Here feature selection was performed on data sets containing approximately 40 features. The survey of [Guyon and Elisseeff, 2003] goes further and introduces several feature selection approaches with hundreds or even thousands of variables. The overview [Fan and Lv, 2010] summa-

rizes the most important methods from a statistical point of view, and [Chandrashekar and Sahin, 2014] makes a survey, focusing on the differences of the well-known filter, wrapper, and embedded methods.

In classification and regression for multivariate data, we should emphasize the works [Benítez-Peña et al., 2018; Bertolazzi et al., 2016; Carrizosa et al., 2011; Maldonado and Weber, 2009; Maldonado et al., 2011; Rakotomamonjy, 2003] in the former case, and [Andersen and Bro, 2010; Mehmood et al., 2012; Mitchell and Beauchamp, 1988; Smith and Kohn, 1996; Yang and Ong, 2011; Zhang, 2009] in the latter.

For functional data, different perspectives have been addressed to deal with the feature selection problem. Dimensionality reduction, for instance, is based on the projection of the functional data on lower-dimensional spaces. These include, among others, FPCA [Górecki and Krzyśko, 2012; Hall et al., 2001; Li et al., 2013; Lin et al., 2015; Locantore et al., 1999], Partial Least Squares (PLS) [Aguilera et al., 2016; Delaigle and Hall, 2012b; Preda et al., 2007; Wang and Huang, 2016, and B-splines functions [James and Hastie, 2002; Wang et al., 2007]. For other dimensionality reduction techniques in functional data, see [Ferraty and Vieu, 2002; Hsing and Ren, 2009; Li and Hsing, 2010; Zhang et al., 2013]. It is also very common to use sparsity techniques to handle situations in which feature selection is involved. [James et al., 2009] seeks the non-zero ranges of the coefficient function for a functional linear regression model, by using a regularized least-squared method. In a non-supervised classification context, papers such as [Chamroukhi, 2016; Chamroukhi and Nguyen, 2018; Hébrail et al., 2010; Samé et al., 2011 work with functional data with regime changes, i.e., they assume that the functions are formed by successive shifting domains, where some of them may be zero-weighted. A different feature selection methodology in FDA is known as variable selection. Variable selection aims to find a subset of relevant time instants which represent well the function, and yield acceptable performance values, as well. Regarding functional regression, some references such as [Kneip et al., 2016; McKeague and Sen, 2010] should be highlighted. In [Kneip et al., 2016] a method is proposed to detect the most important points of impact among a predefined set of time instants in which the functional data are measured, i.e., it is assumed that the impact points only belong to the set of timestamps where the functions are monitored, which is not always the case. Moreover, [Kneip et al., 2016] is a generalization of the model proposed in [McKeague and Sen, 2010 where the identifiability and estimation of just one time instant is sought. The work of [Aneiros and Vieu, 2014] directly applies standard multivariate procedures to discretized functional data. Thus, the functional nature of the data is disregarded and not exploited. The optimal selection of the time instants in functional nonparametric regression models has been studied too. For example, on the works of [Aneiros and Vieu, 2016; Ferraty et al., 2010, the most influential design points are sought among a given (large) set, usually hard to obtain, while the methodologies of [Berrendero et al., 2018; Ferraty et al., 2010] based on a greedy approach, in which the time instants are sequentially located. On functional classification, we should highlight for example, [Lindquist and McKeague, 2009], where one single time instant is sought, and, as admitted in the paper, it is not possible to generalize their methodology to search for a set of more time instants. We also emphasize the recent works of [Berrendero et al., 2016a,b, 2017; Torrecilla and Suárez, 2016; Torrecilla Noguerales, 2015], where greedy approaches, yielding local optima, are used. These papers follow a combinatorial approach: such time instants are assumed to belong to the finite set of instants at which actual measurements exist.

Unfortunately, the vast literature mentioned above is restricted on univariate functional data. Feature selection methods on multivariate (hybrid) functional data have been rarely studied. Indeed we can only make reference to some PCA-based approaches, e.g., [Berrendero et al., 2011; Jacques and Preda, 2014] where the dimension is reduced.

#### 1.4 Contributions of this Thesis

The goal of this thesis is to solve new Supervised Learning problems in Functional Data by means of Mathematical Optimization tools. The functional nature of the data is taking into account in all these models, which successfully improve the current benchmark prediction results. This section briefly describes the problems addressed, as well as the challenges involved regarding the Supervised Learning field.

Chapter 2 is based on the work [Blanquero et al., 2017]. We address the problem of selecting the most informative time instants in binary classification with multivariate functional data. Selecting a finite set of time instants may lead to an improvement in the predictive ability of the estimated model, in addition to reducing the model complexity. Our proposal is not restricted to multivariate functional data. Indeed, our approach allows one to classify univariate functional data in the very same way by using high-order information of the data, e.g., monotonicity or convexity through the derivatives. The aforementioned optimization problem is a Global Optimization problem in continuous variables: the time instants are to be selected to maximize the correlation between the class label and the SVM score used for classification. A nested heuristic is defined to enhance the algorithmic performance in which the suboptimal solution obtained in the simplest cases is considered as the initial solution in the more difficult models. The effectiveness of the proposal is shown in univariate and multivariate data sets from the literature.

Chapter 3 is based on the work [Blanquero et al., 2018a]. A new functional bandwidth kernel is proposed to solve the SVM problem for functional data, which improves the accuracy obtained with the usual scalar bandwidth parameter. Our approach is able to optimally select different ranges in the domain of the function according to

their classification ability. Both the kernel and the SVM parameters are tuned with a surrogate of the accuracy, namely, the correlation between the actual class and the SVM score. Such parameter tuning yields a continuous optimization problem, allowing us to use gradient methods, known to be more efficient than the optimization methods available for piecewise constant performance measures, such as the misclassification rate. Moreover, the proposed method is enhanced by defining a hierarchy of kernel bandwidths models of increasing complexity, inspired by the nested model previously proposed for Multiple Kernel Learning. By using this hierarchy will provide wide flexibility since complex parameterizations of the functional bandwidth can be efficiently optimized from more simple ones. Our experiments with benchmark data sets show the advantages of using functional parameters and the effectiveness of our approach.

Chapter 4 is based on the work [Jiménez-Cordero and Maldonado, 2018], where a feature selection problem for hybrid functional data is treated. Our aim is to select the most important covariates, either functional or static, in order to achieve good classification predictions. In this chapter, an embedded feature selection approach for SVM classification is proposed, where the isotropic Gaussian kernel is modified by associating a bandwidth to each feature, which automatically weighs the importance of the different variables (functional or static). The bandwidths are jointly optimized with the SVM parameters, yielding an alternating optimization approach. The drastic improvements in the classification rates, as well as the robustness of our methodology, were tested on benchmark data sets.

The results provided in Chapter 2 can be extended to regression. In fact, Chapter 5, based on [Blanquero et al., 2018b], outlines the problem of selecting a small set of time instants able to capture the information needed to predict a scalar response variable from multivariate functional data. More precisely, selecting from the full monitoring interval a few time instants without damaging prediction accuracy would definitely lead to a much better understanding of the data, enhancing quicker predictions and easing decision making. Replacing the whole interval by a low-dimensional vector of time instants can be seen as a variable selection procedure from an infinite set of features. The regression tool used in this chapter is SVR, and a continuous optimization algorithm is proposed to fit the parameters and select the time instants as well. We illustrate the usefulness of our proposal in some benchmark data sets.

# Chapter 2

# Variable Selection in Functional Data Classification with SVM

2.1. Introduction 23

## 2.1 Introduction

Functional data classification entails some difficulties associated with the high computational costs, and the introduction of redundancy and noise from measurement errors, which may deteriorate the correct classification performance. Since functional data are intrinsically infinite-dimensional data, it is thus useful to select the time instants providing the most relevant information of the data, i.e., to perform variable selection.

In this chapter, we address the problem of classifying multivariate functional data into two prefixed classes by using the information provided by a training sample. More precisely, our goal is to select the most informative time instants in order to obtain good classification rates. Classifiers will be based on the benchmark supervised classification tool SVM, detailed in Section 1.2.2.

Variable selection for multivariate functional data has been scarcely analyzed in the literature yet, as Section 1.3 outlines. Therefore, the main contribution of this chapter is to provide a new strategy able to find the most informative time instants to achieve good classification rates in multivariate functional data. Contrary to the usual trend in the literature, [Berrendero et al., 2016a,b, 2017; Torrecilla and Suárez, 2016; Torrecilla Noguerales, 2015], we consider the time as a continuous variable, and we search for an optimal SVM-classifier using a surrogate of the rate of misclassified data, namely the correlation between the SVM score and the actual class. Finding such optimal time instants amounts to solving a continuous smooth optimization problem. Moreover, our algorithmic strategy is improved thanks to the definition of nested models of increasing complexity, following the idea in [Carrizosa et al., 2014].

Finally, our framework can accommodate from one to several functions, allowing one to address in the very same way univariate and multivariate functional data. In particular, one can easily include in the model higher-order information (monotonicity, convexity, ...) by replacing each univariate functional datum by a multivariate one, corresponding to the functional datum itself and its derivatives. The information provided by the derivatives has been utilized in the clustering context, [Ieva et al., 2013; Meng et al., 2018], with outstanding results.

The remainder of this chapter is structured as follows. In Section 2.2 we present the variable selection problem, including the management of the functional data derivatives. In addition, the problem formulation, as well as the solving strategy are detailed. Section 2.3 is focused on the numerical experiments, and finally Section 2.4 presents some conclusions and extensions.

# 2.2 A Global Optimization Approach to the Variable Selection Problem

In this section, the mathematical formulation of the variable selection problem in SVM classification with functional data is outlined. Section 2.2.1 briefly presents the variable selection problem and details how the higher-order information can be included in the multivariate data structure. Section 2.2.2 is devoted to the problem formulation and the solving strategy, whereas a nested heuristic is proposed in Section 2.2.3, in which we take advantage of the fact that the different time instants  $\mathbf{t} = (t_1, \ldots, t_H)$  can be easily embedded in a nested structure of models. Section 2.2.4 addresses the problem of determining the number H of time instants.

## 2.2.1 Variable Selection with Functional SVM

We assume given a sample s of individuals, where each instance  $i \in s$  is associated with the pair  $(X_i, Y_i)$ . The datum  $X_i \in \mathcal{X} = \mathcal{F}^p$  is composed by p functional features, i.e.,  $X_i = (X_{i1}(t), \ldots, X_{ip}(t))$ , as sketched in (1.1). The functional space  $\mathcal{F}$  represents the class of d-times continuously differentiable functions on the time interval [0, T]. Furthermore,  $Y_i \in \{-1, +1\}$  denotes the class label of the observation  $i \in s$ . Our aim is to find a classification rule which allows us to infer the class Y of a new functional observation  $X \in \mathcal{X}$ . To do this, an SVM-classifier, obtained from the resolution of Problem (1.15) will be used. Since our objective is to select the finite set of H time instants that provide the most relevant information for discriminating between two groups, the functional kernel given in (1.27) was chosen. Hence, two types of parameters need to be tuned: the vector of time instants,  $\mathbf{t} = (t_1, \ldots, t_H)$ , such that

$$0 \le t_1 \le \dots \le t_H \le T \tag{2.1}$$

and the parameters associated with the SVM problem (1.15), i.e., the regularization parameter C and the bandwidth  $\omega$  of the kernel (1.27). Extra constraints over the parameters can be easily incorporated into the optimization problem, such as imposing a fixed separation between the time instants. Details about the resulting optimization problem and the solving strategy are given in Section 2.2.2.

It is worth mentioning that our methodology is not only restricted to pure multivariate functional data. Indeed, the approach here proposed can be directly applied to univariate functional data,  $X(t) \in \mathcal{F}$ . More specifically, apart from the straightforward case in which one just considers p = 1, a preprocessing stage can be carried out in order to transform the univariate data into multivariate ones by taking advantage of the higher-order information throughout the usage of the derivatives of X. This process yields data of the form:

$$(X(t), X'(t), \dots, X^{d)}(t)),$$
 (2.2)

where  $X^{(d)}(t)$  denotes the d-th derivative of X(t). Moreover, the information provided by the derivatives can also be added to the pure multivariate functional case, yielding

$$(X_1(t), \dots, X_p(t), X_1'(t), \dots, X_p'(t), \dots, X_1^{d)}(t), \dots, X_p^{d)}(t)).$$
 (2.3)

The numerical experience in Section 2.3 shows that the higher-order information will be crucial in the classifier performance.

We also recall that, in practice, the original functional data  $X_i$  may be only available throughout a grid of time instants. Therefore, interpolation techniques, such as cubic splines, [De Boor, 1978; Friedman et al., 2001b], should be used as a preprocessing step so that the functional data can be properly rebuilt. It is important to remark that the interpolation step recovers the smoothness of the data with respect to  $\mathbf{t}$ .

Furthermore, if we want to take advantage of the higher-order information of the data, it is necessary to get, as preprocessing, the derivatives from the data X(t). One possible choice would be to compute the derivatives of the smoothed data. Nevertheless, in order to avoid the propagation of numerical errors from the interpolation, we suggest using the finite-increments as an approximation of the derivatives. For instance, the first derivative of X(t) in a point  $t_h$  admits the following approximation:

$$X'(t_h) = \frac{X(t_h) - X(t_{h-1})}{t_h - t_{h-1}}$$
(2.4)

Note that in (2.4),  $t_h$ ,  $\forall h$ , indicate the time instants where the functional data are discretized. The formula in (2.4) should be reproduced for all the time points of the discretization, and extended to any derivative's order. After obtaining the discretized derivatives, they should be smoothed with an interpolation technique, as explained before.

## 2.2.2 The Bilevel Optimization Problem

As previously mentioned, two different types of decision variables are involved in the variable selection problem for classification of functional data with SVM. First, the H time instants  $\mathbf{t} = (t_1, \ldots, t_H)$  satisfying (2.1), and second, the parameters C and  $\boldsymbol{\omega}$  involved in the SVM problem (1.15), and in the Gaussian kernel (1.27), respectively.

Different strategies are proposed here to find the optimal values of  $C, \omega$  and  $\mathbf{t}$ . C is obtained by using a standard grid search, while a bilevel optimization problem is defined to tune the parameters  $\omega$  and  $\mathbf{t}$ . In such bilevel problem we propose to maximize the Pearson correlation coefficient between the class label  $Y_i$  of the observation  $i \in s$ , and the score  $\hat{Y}(X_i(\mathbf{t}), \omega, \alpha)$  in (1.16). Other references in the literature, such as [Székely et

al., 2007; Torrecilla Noguerales, 2015], have previously used similar performance measures, with excellent results. Despite the fact that, when using the Pearson correlation coefficient as a surrogate of accuracy, a linear relationship between the binary label,  $Y \in \{-1, +1\}$ , and the real-valued score,  $\hat{Y} \in \mathbb{R}$ , is implicitly assumed, such coefficient is very fast to compute and even more important, it yields a smooth optimization problem, in which gradient information can be used to speed up the convergence. This last issue means a significant advantage over the use of other performance measures, such as those based on the confusion matrix, which usually lead to mixed-integer optimization problems hard to solve for realistic data sizes.

In this chapter, the parameters and time instants sought, as well as the performance estimates of the classifier, are obtained as follows: the database is split into k folds, as detailed in Section 1.2.4. Then, k-1 folds are chosen to be again divided into three parts, yielding the samples  $s_1$ ,  $s_2$  and  $s_3$ . Finally, the remaining fold constitutes the fourth independent sample  $s_4$ . Samples  $s_1$  and  $s_2$  act as training samples, while  $s_3$  and  $s_4$  are the validation and testing samples, respectively. This division process is repeated one time per fold.

Regarding the role of each sample in the optimization strategy, sample  $s_1$  is used to obtain the SVM dual variables,  $\alpha$ , solving Problem (1.15) for fixed  $\omega$ ,  $\mathbf{t}$  and C. Sample  $s_2$  is employed to compute  $R((Y_i, \hat{Y}(X_i(\mathbf{t}, \omega, \alpha)))_{i \in s_2})$ , i.e., the correlation coefficient between the class labels and the scores defined in (1.16). Sample  $s_3$  is used to tune the regularization parameter C, by evaluating the accuracy for all the values of C in a grid, and keeping the one with the largest value. Finally, the accuracy obtained with the optimal parameters is estimated on the independent sample  $s_4$ .

To sum up, for a fixed C, the resulting bilevel optimization problem is given in (2.5)

$$\begin{cases}
\max_{\alpha, \boldsymbol{\omega}, \mathbf{t}} & R((Y_i, \hat{Y}(X_i(\mathbf{t}), \boldsymbol{\omega}, \alpha))_{i \in s_2}) \\
\text{s.t.} & \alpha \text{ solves } (1.15) \text{ in } s_1, \\
\omega_v \ge 0, v = 1, \dots, p \\
0 \le t_1 \le \dots \le t_H \le T
\end{cases} \tag{2.5}$$

Note also that we have emphasized the dependence of the score  $\hat{Y}$  on the time instants in  $\mathbf{t}$ , on the bandwidth  $\boldsymbol{\omega}$ , and on the classification coefficients  $\alpha$  in the notation. When such values are clear, they will be omitted in the notation for the sake of simplicity.

Problem (2.5) is a nonlinear problem which can be solved with the techniques described in e.g., [Colson et al., 2007]. For instance, we may mention branch-and-bound schemes in which the problem is reformulated under some convexity assumptions using the KKT conditions. Even with these reductions, the so-obtained problem is difficult to solve due to the nonconvexities in the complementary and Lagrangian constraints. Penalty function methods can also be used to solve bilevel problems, but convergence

is to stationary points.

Instead of the above-mentioned resolution methods, we propose to address the bilevel problem (2.5) for each C by a procedure consisting in two alternating steps: the SVM step, in which for  $\omega$  and  $\mathbf{t}$  fixed, we solve Problem (1.15) to obtain the optimal SVM variables  $\alpha$ ; and the max-corr step, where for  $\alpha$  fixed, one maximizes the Pearson correlation coefficient R in (2.6) to obtain the optimal bandwidth  $\omega$  and the time instants  $\mathbf{t}$ . This correlation maximization problem can be expressed as:

$$\begin{cases}
\max_{\boldsymbol{\omega}, \mathbf{t}} & R((Y_i, \hat{Y}(X_i(\mathbf{t}), \boldsymbol{\omega}))_{i \in s_2}) \\
\text{s.t.} & \omega_v \ge 0, \ v = 1, \dots, p \\
& 0 \le t_1 \le \dots \le t_H \le T
\end{cases}$$
(2.6)

Different strategies are used to solve Problems (1.15) and (2.6). The standard local search routines, specified in Section 1.2.2, can be applied for the SVM Problem (1.15). On the other hand, Problem (2.6) is a continuous optimization problem, where classic local searches are combined with a multi-start approach to avoid getting stuck at local optima. The initial values of  $\omega$  and  $\mathbf{t}$  in the first iteration of the alternating approach are randomly selected in their corresponding domains of definition.

The alternating procedure is run until some stopping criteria, such as the number of evaluations or the maximum time allowed is reached, yielding certain values of  $\omega$ ,  $\mathbf{t}$  and  $\alpha$ , for a fixed C. The value of C is chosen by applying a grid search, i.e., for each value of C in a grid, the accuracy obtained with the classification rule obtained after solving Problem (2.5), is measured in sample  $s_3$ . The parameter C with the best accuracy will be kept. Finally, we test our approach by measuring the accuracy in a fourth sample,  $s_4$ .

Calculating the gradient of the objective function in (2.6) will reduce the computational effort, since numerical differentiation is avoided. Just applying the chain rule and taking into account (2.7), i.e., the derivative of the kernel function in (1.27) with respect to the parameters in  $\omega$  and  $\mathbf{t}$ , we can easily obtain an explicit expression for the gradient of the objective function in (2.6):

$$\frac{\partial K(X_{i}, X_{j}, \boldsymbol{\omega}, \mathbf{t})}{\partial \omega_{v}} = K(X_{i}, X_{j}, \boldsymbol{\omega}, \mathbf{t}) \left( -\sum_{h=1}^{H} (X_{iv}(t_{h}) - X_{jv}(t_{h}))^{2} \right) v = 1, \dots, p$$

$$\frac{\partial K(X_{i}, X_{j}, \boldsymbol{\omega}, \mathbf{t})}{\partial t_{h}} = -2K(X_{i}, X_{j}, \boldsymbol{\omega}, \mathbf{t}) \sum_{v=1}^{p} (\omega_{v}(X_{iv}(t_{h}) - X_{jv}(t_{h}))) \times \left( \frac{\partial X_{iv}(t)}{\partial t} \Big|_{t=t_{h}} - \frac{\partial X_{jv}(t)}{\partial t} \Big|_{t=t_{h}} \right), h = 1, \dots, H$$
(2.7)

The pseudocode of our approach is outlined in Algorithm 1, and an extension of it

based on a nested heuristic is detailed in Section 2.2.3.

## Algorithm 1 Heuristic for variable selection

#### Input: H

- Randomly split the sample s into  $s_1$ ,  $s_2$ ,  $s_3$  and  $s_4$ .
- Compute the derivatives of the functional data.
- Smooth the data with some interpolation technique.

for C in the grid do

## Alternating Procedure

### repeat

- 1. Fixed  $\omega$ ,  $\mathbf{t}$ , calculate the parameters  $\alpha$  of the SVM clasiffier by solving Problem (1.15) using  $s_1$ .
- 2. Fixed  $\alpha$ , compute  $\omega$ ,  $\mathbf{t}$  by solving Problem (2.6) over  $s_2$ .

until stopping criteria

• Evaluate the accuracy using the sample  $s_3$  for the C fixed in the grid.

#### end for

• The optimal value of C is the one with best accuracy in  $s_3$ , and the optimal values of  $\alpha$ ,  $\omega$  and  $\mathbf{t}$  are the parameters associated to the optimal C.

**Output:** Optimal parameters  $\omega$ , t, C,  $\alpha$ , and the accuracy estimated from  $s_4$ .

## 2.2.3 A Nested Heuristic

In this section we enhance the basic heuristic detailed in Algorithm 1. Adopting the idea of [Carrizosa et al., 2014], we propose to define a series of nested models of increasing complexity, where the optimal solution of the elementary case is used as a starting solution in the following more complex model.

The idea is that, in order to find the vector  $\mathbf{t}^{h+1}$  of h+1 time instants, one can use as starting solution a perturbation of  $\mathbf{t}^h$ , the solution obtained when only h time instants are sought. Therefore, if we want to find the H time instants which best discriminate between two groups, we apply successively the Alternating Procedure of Algorithm 1 for h=1 to H, but considering the easy-to-tune structure of the simple models as a simplification of the complex cases, in such a way that the (suboptimal) solution  $K(X_i, X_j, \boldsymbol{\omega}^h, \mathbf{t}^h)$  is used as an initial solution for kernel  $K(X_i, X_j, \boldsymbol{\omega}^{h+1}, \mathbf{t}^{h+1})$ . More precisely, in order to build the initial solution for the h+1 time instants in  $\mathbf{t}^{h+1}$ , we first select a random value  $\tau \in [0, T]$ , and then we include it in the appropriate position of the optimal solution of the level h,  $\mathbf{t}^h_{opt}$ , in such a way that  $\mathbf{t}^{h+1}$  satisfies the conditions in (2.1), i.e.,  $\mathbf{t}^{h+1} := \sigma(\tau, \mathbf{t}^h_{opt})$ , where  $\sigma$  is the function that sorts in increasing order the time instants  $\mathbf{t}^h_{opt}$  and  $\tau$ .

One of the advantages of our nested heuristic is that it allows us to obtain a trajectory of the accuracy in terms of the number of time instants chosen. This is a crucial issue, since, in practice, the number H of time instants to consider may not be fixed, and thus a list of classifiers, with different complexity (H) and accuracy, can be provided.

Note that the solution of the level h will be used just as a starting point of level h+1, in order to speed up the algorithm, but still allows the algorithm to yield a solution that is very different from the level h solution. In this way, our proposal clearly differs from [Torrecilla Noguerales, 2015], where greedy schemes are proposed.

The pseudocode of the nested heuristic is shown in Algorithm 2.

## Algorithm 2 Nested heuristic for variable selection

Input: H, nested kernels  $K(X_i, X_j, \boldsymbol{\omega}^1, \mathbf{t}^1) \prec \ldots \prec K^H(X_i, X_j, \boldsymbol{\omega}^H, \mathbf{t}^H)$ .

- Randomly split the sample s into  $s_1$ ,  $s_2$ ,  $s_3$  and  $s_4$ .
- Compute the derivatives of the functional data.
- Smooth the data with some interpolation technique.

for C in the grid do

## Initialization:

- h := 1.
- Randomly select an initial solution  $\widetilde{\boldsymbol{\omega}}^1 \in [0, +\infty)^p$  and  $\tilde{\mathbf{t}}^1 := t_1 \in [0, T]$ .
- Set  $(\boldsymbol{\omega}, \mathbf{t}) := (\widetilde{\boldsymbol{\omega}}^1, \widetilde{\mathbf{t}}^1)$ .

## while $h \leq H$ do

- 1. Run the Alternating Procedure of Algorithm 1 for  $K(X_i, X_j, \boldsymbol{\omega}^h, \mathbf{t}^h)$ , starting from  $(\boldsymbol{\omega}, \mathbf{t})$  and yielding  $(\boldsymbol{\omega}_{opt}^h, \mathbf{t}_{opt}^h)$  as solution, using samples  $s_1$  and  $s_2$ .
- 2. Randomly generate  $\tau \in [0, T]$ .
- 3. Set  $\boldsymbol{\omega}^{h+1} := \boldsymbol{\omega}_{opt}^{h}$ ,  $\mathbf{t}^{h+1} := \sigma(\tau, \mathbf{t}_{opt}^{h})$ ,  $(\boldsymbol{\omega}, \mathbf{t}) := (\boldsymbol{\omega}^{h+1}, \mathbf{t}^{h+1})$  and h := h + 1.
- 4. Evaluate the accuracy over the sample  $s_3$  with C fixed.

## end while

## end for

• For h fixed, the optimal value of C is the one with the best accuracy in  $s_3$ . The optimal values of  $\alpha$ ,  $\omega$  and  $\mathbf{t}$  are the parameters associated to the optimal C.

**Output:** Optimal parameters  $\omega_{opt}^h$ ,  $\mathbf{t}_{opt}^h$ ,  $\forall h$ , the associated coefficients  $C, \alpha$ , and the accuracy estimated from  $s_4$ .

## 2.2.4 Choice of the Number of Variables, H

The choice of the optimal number of time instants, H, is a critical issue. The larger is H, the better is the classification accuracy expected to be obtained, although the risk of overfitting increases. However, the smaller the value of H, the easier the interpretation of the results obtained.

In this chapter, we propose to follow the common strategy carried out in the literature, [Berrendero et al., 2016a,b, 2017; Torrecilla and Suárez, 2016; Torrecilla Noguerales, 2015], and choose the value of H by estimating the accuracy on the validation sample  $s_3$  with k-fold cross-validation. The value of H with the largest accuracy will be kept.

## 2.3 Numerical Experiments

This section details the computational results of our approach, in which we provide the accuracy obtained when only some selected time instants, instead of the whole functional interval [0,T], are considered. Section 2.3.1 describes the settings of the computational experience, and in Section 2.3.2 the description of the data sets is given. The results obtained for the different databases are presented in Section 2.3.3.

## 2.3.1 Description of the Experiments

Our proposal has been applied to both univariate and multivariate functional data. On top of comparing the performance of the SVM based on the full time interval against the SVM classifier for data measured at just H time instants, we have also analyzed the improvements in performance obtained when, instead of the functional data alone, up to d derivatives of the functional data are also included in the input. For this reason, we have also run Algorithm 2 for three different values of d, namely d = 0, 1, 2, which correspond respectively to the cases in which just the information of the functional data, or also its monotonicity, or both monotonicity and convexity, are considered.

In order to obtain stable results, k-fold cross-validation is performed. The number of folds, k, will be 10 in the databases with more than 100 individuals, or it will coincide with the number of individuals of the database in the remaining data sets. The cardinality of each database is shown in Table 2.1. Algorithm 2 is run k times, one per fold. Each time, the data set is divided into four samples  $s_1 - s_4$  as explained in Section 2.2.2. To test our results we provide the average of the accuracy across the folds, measured on  $s_4$ . The number of iterations of the multi-start is five, the number of iterations of the Alternating Procedure in Algorithm 1 is ten, and the (maximum) number of time instants to be selected, i.e., the number of nested kernels, is H = 19. Finally, the parameter C takes values in the set  $\{2^{-10}, \ldots, 2^{10}\}$  in logarithmic scale.

Apart from the experiments explained above, we have also tuned the optimal number of time instants, H by performing cross-validation on sample  $s_3$ , as explained in Section 2.2.4.

The whole computational experience is executed on a cluster with 2 terabytes of RAM memory at 6.2 TFlops, running CentOS Linux 7.3, and it is coded in R, [Core Team, 2017].

## 2.3.2 Description of the Data Sets

Three univariate (growth,  $phoneme\_large$  and tecator) and three multivariate (batch,  $batch\_noise$  and trigonometric) functional databases have been considered to check the performance of our approach. Samples of ten individuals of each data set are plotted in Figure 2.1 (univariate data) and 2.2 (multivariate data). The records in class -1

are depicted with a solid blue line, whereas the records in class +1 are plotted in red dashed line.

Table 2.1 shows the number of records of each database, the number of time instants in which the records are measured, the number of records of each class and the number of components of the functional data vector. A detailed description of each database follows.

	# records	#time instants	#records label -1	# records label +1	#components
$\overline{\hspace{1cm}}$ growth	93	31	54	39	1
$phoneme\_large$	1717	256	1022	695	1
tecator	215	100	77	138	1
batch	100	101	50	50	3
${\it batch\_noise}$	100	101	50	50	3
${ m trigonometric}$	400	1001	200	200	2

Table 2.1: Data description summary

#### Growth Data Set

This data set was first introduced in [Tuddenham and Snyder, 1954], and has been studied in several works, e.g., [Cuevas et al., 2007; Muñoz and González, 2010; Torrecilla Noguerales, 2015]. It is available in the fda library of R. The data set contains the height in centimeters of an amount of 93 individuals ranging from the age of 1 to 18 years measured on 31 non-equally spaced time instants. More specifically, the heights of 39 boys and 54 girls are given. The aim is to determine if a new individual is a boy or a girl, just with the information provided by the height curve.

## Phoneme large Data Set

This database was originally presented in [Hastie et al., 1995] and can be obtained from [Friedman et al., 2001a]. The original data set contains 4509 functions with the log-periodograms, monitored at 256 equally spaced points, of individuals pronouncing the following five phonemes: "sh" as in "she", "dcl" as in "dark", "iy" as the vowel in "she", "aa" as the vowel in "dark", and "ao" as the first vowel in "water". The five-class classification problem has been adapted to our binary classification framework as done in [Delaigle and Hall, 2012a; Torrecilla Noguerales, 2015], yielding a total of 1717 observations, 1022 from the phoneme "ao" and 695 from "aa". Therefore, the goal is to build a classification rule, which differentiates both phonemes. Apart from the papers just cited, this data set has also been applied in [Berrendero et al., 2016c; Friedman et al., 2001b] among others.

#### Tecator Data Set

This data set deals with the near-infrared absorbance spectra of 215 samples of finely chopped pork, recorded at 100 equally spaced points from 850 to 1050 nanometers. It has associated the values of the fat content, and according to [Ferraty and Vieu, 2006], the database can be divided into two classes depending if the fat content is smaller or larger than 20%. Moreover, the curves of tecator are usually smoothed, e.g.: [Ferraty and Vieu, 2006; Porro et al., 2009; Torrecilla Noguerales, 2015], in order to work with the second derivatives instead of the raw data. This reduction is also made in this dissertation. The data can be obtained from the fda.usc library of R, and have been analyzed in works such as [Martín-Barragán et al., 2014; Rossi and Villa, 2006].

## Batch Data Set

This is a synthetic data set. The three covariates of this first multivariate data set, batch, come from Section 4.1 of [Wang and Yao, 2015]. In this data set, each instance is described by three functions  $X_v$ , v = 1, 2, 3 with very different shapes: linear, quadratic and sinusoidal, respectively. Although Wang and Yao consider that the upper bound for the time interval in which the functions are measured follows an uniform distribution on [0.9, 1.1], we assume, for the sake of simplicity, that  $X_v : [0, 1] \to \mathbb{R}$ , v = 1, 2, 3. Formally:

$$X_{i1}(t) = a_i \cdot t + \gamma_i(t)$$

$$X_{i2}(t) = a_i \cdot t^2 + \gamma_i(t)$$

$$X_{i3}(t) = b_i (4\sin(t) + 0.5\sin(\nu_0 \cdot t))$$
(2.8)

for  $t \in [0, 1]$ , where each  $(a_i, b_i)$  follows a bivariate Gaussian distribution with mean vector (2.5, 2.5) and covariance matrix diag(2.5, 2.5).

For each  $t \in [0, 1]$ , the measurements errors  $\gamma_i(t)$  are i.i.d. Gaussian noise with mean 0 and standard deviation 0.2. The individuals  $X_i$  with label  $Y_i = +1$  have  $\nu_0 = 10$ , whereas those with  $Y_i = -1$  are associated with  $\nu_0 = 11$ .

## Batch noise Data Set

This multivariate synthetic data set comes from Section 4.2 of [Wang and Yao, 2015] and the three covariates have the same structure as in (2.8). In this case, the coefficients  $(a_i, b_i)$  still follows a bivariate Gaussian distribution with mean vector (2.5, 2.5) and covariance matrix diag(2.5, 2.5). Nevertheless, the parameter  $\nu_0 = 10$  for all the individuals, and the standard deviation of the Gaussian noise  $\gamma_i(t)$  is equal to 0.2 in the individuals with label  $Y_i = +1$ , and equal to 0.3 in the observations with  $Y_i = -1$ .

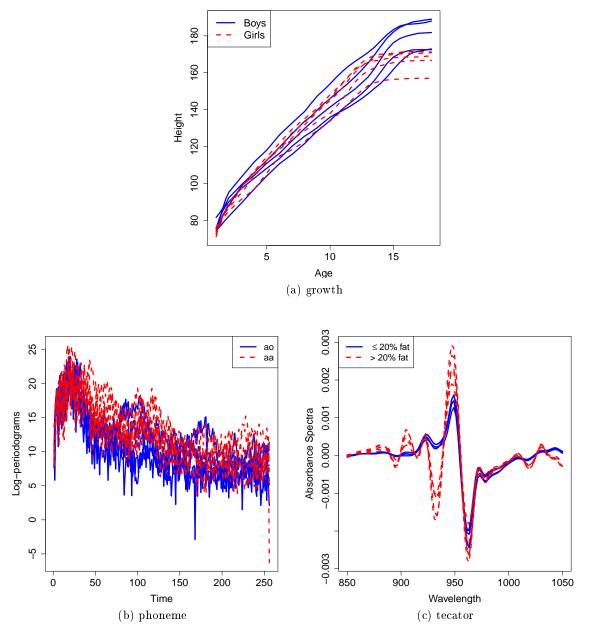


Figure 2.1: Sample of functional data in the univariate data sets analyzed

## Trigonometric Data Set

The trigonometric database is a synthetic data set formed by two functional features. Functional components  $X_{iv}:[1,21]\longrightarrow \mathbb{R},\ v=1,2$  are based on the data generated in Section 5.2.2 of [Jacques and Preda, 2014] and have the form:

$$X_{i1}(t) = -\frac{21}{2} + t + \nu_0 U_1 \cos\left(\nu_0 \frac{t}{10}\right) + \nu_0 U_1 \sin\left(\nu_0 + \frac{t}{10}\right) + \gamma_i(t)$$

$$X_{i2}(t) = -\frac{21}{2} + t + \nu_0 U_1 \sin\left(\nu_0 \frac{t}{10}\right) + \nu_0 U_2 \cos\left(\nu_0 + \frac{t}{10}\right) + \nu_0 U_3 \left(\left(\frac{t}{10}\right)^2 + \frac{t}{10} + 1\right) + \gamma_i(t)$$

$$(2.9)$$

where  $t \in [1, 21]$ ,  $U_1, U_2, U_3 \sim \mathcal{N}(1, 1)$  are independent Gaussian variables and  $\gamma_i(t)$  is a white noise of unit variance. The value of  $\nu_0$  is dependent on the class label. More specifically, the individuals with label  $Y_i = 1$  have  $\nu_0 = 1$ , while the observations corresponding to  $Y_i = -1$  have  $\nu_0 = 2$ .

Note that the *trigonometric* data set is used in [Jacques and Preda, 2014] for clustering purposes with three and five groups. Nevertheless, in this chapter, since binary classification is studied, we only consider two groups.

#### 2.3.3 Results

In this section, we detail the computational results obtained on the univariate and multivariate functional data described in Section 2.3.2. Moreover, we present the numerical experience for the optimal choice of the number of time instants to be considered, H.

#### Results on Univariate Functional Data

Table 2.2 reports the average accuracy on the testing sample of the data sets growth,  $phoneme\_large$  and tecator provided by Algorithm 2 with the information given by the raw data (d=0), the first derivative (d=1), and the first two derivatives (d=2). Leave-one-out is performed on the growth data set, whereas 10-fold cross-validation is done in  $phoneme\_large$  and tecator. Our results are compared with  $acc\ max$  and  $acc\ min$ , respectively the best and worst accuracy results obtained with the state-of-the-art methods, as reported in Tables 2 and 3 of [Berrendero et al., 2016c].

Information shown in Table 2.2 is also depicted in Figure 2.3. Particularly, the solid red-circled, blue-triangled and green-crossed lines indicates the average accuracy obtained with d = 0, 1, 2, respectively. The horizontal black solid line and pink dashed lines give the values of  $acc\ max$  and  $acc\ min$ , respectively.

Two main conclusions are obtained from our analysis. First, our results are competitive against the state-of-the-art. Moreover, the use of higher-order information deeply affects the classification performance. This fact is extremely noticeable in the tecator data set. Furthermore, in such database we are very close to the value acc max with just H = 2 time instants and d = 2. If we focus on the growth data set, we realize that with H = 3, 5, 10, 13, 14, and d = 2 we achieve the same accuracy as the value acc max.

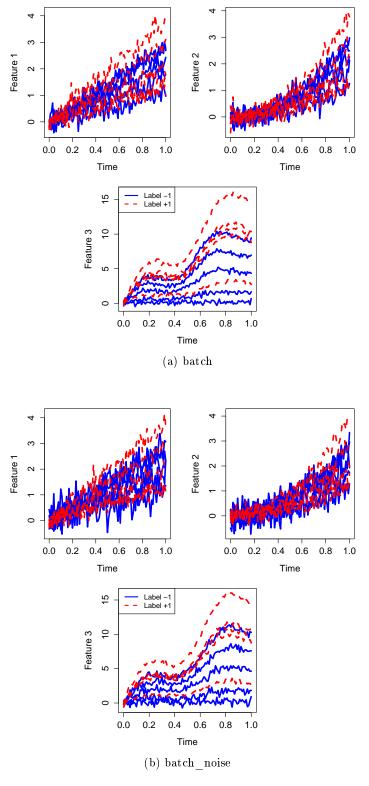


Figure 2.2: Sample of functional data in the multivariate data sets analyzed

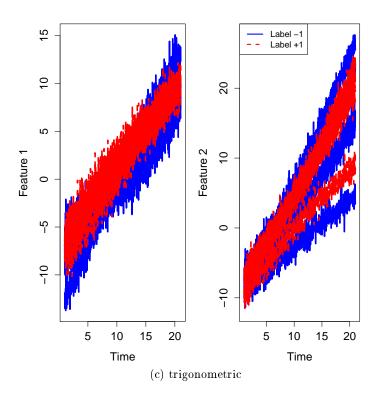


Figure 2.2: Sample of functional data in the multivariate data sets analyzed (cont.)

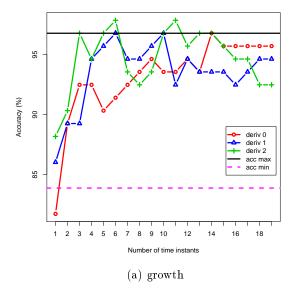
This also happens with H = 6 or H = 10, and d = 1. Furthermore, our methodology is capable of improving the value  $acc\ max$  if H = 6 or H = 11 time instants and d = 2 derivatives are considered.

#### Results on Multivariate Functional Data

In this section we collect the results obtained in the multivariate databases batch,  $batch\_noise$  and trigonometric. Since, there is no standard methodology in the literature which handles the variable selection problem in classification with multivariate functional data, in this section, we compare our results with the standard SVM-classification in which the whole time domain and just the information of the functional data are considered, i.e., d = 0. More specifically, we run the SVM problem (1.15) for the C values in  $\{2^{-10}, \ldots, 2^{10}\}$ , and  $\omega_v \in \{2^{-5}, \ldots, 2^{5}\}$ , for  $v = 1, \ldots, p$ , to keep then the best accuracy as reference value. Both standard SVM and Algorithm 2 have been run using 10—fold cross-validation in all the data sets.

Table 2.3 and Figure 2.4 give the accuracy values of our method for d=0,1,2, plotted in solid red-circled, blue-triangled and green-crossed lines, respectively. Furthermore, the classification accuracy with all the time instants is depicted using a horizontal solid black line.

As in the analysis of univariate functional data, using derivatives turns out to be



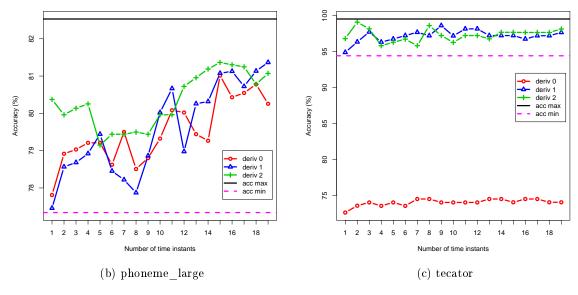
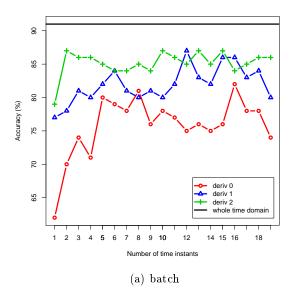


Figure 2.3: Average accuracy in the univariate data sets analyzed

crucial to enhance classification rates. Moreover, classifying using the information of the whole time interval yields worse accuracy than using only carefully selected time instants. This can be seen, for instance, in the  $batch\_noise$  data set, where for H=7 and d=0, accuracy is improved in around two points, or even better with H=8, and d=2, where the difference is about ten points. Particularly, when d=2 derivatives are considered, the accuracy values here obtained are always much better than when the whole time domain is taken into account. Focusing on the trigonometric data set, the accuracy values are better when more than H=2 time points are chosen than when

the whole time interval is considered.



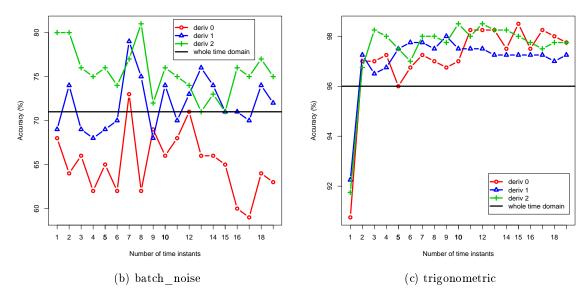


Figure 2.4: Average accuracy in the multivariate data sets analyzed

## Results on the optimal choice of the time instants, H

In order to obtain the best number of time instants, H, we performed cross-validation on the validation sample  $s_3$ , as detailed in Section 2.2.4. Table 2.4 shows the average optimal number of time instants over all the folds in the univariate and multivariate databases when H is varied. Moreover, in Figures 2.5 and 2.6 the resulting boxplots

are depicted. In the x-axis, the maximum number of time instants considered when running our heuristic is given, whereas the y-axis indicates the optimal number of time instants obtained across the different runs. Boxplots in red, blue and green show the results when the information of the derivative d = 0, d = 1 or d = 2 is used, respectively.

We can observe that, although the experiments are run until H=19, the optimal number of time instants to be selected is lower in almost all databases. Indeed, most of the data sets need between 1 and 8 time instants. It implies that data information is summarized on a small finite set of time points, which may improve the interpretability of the results.

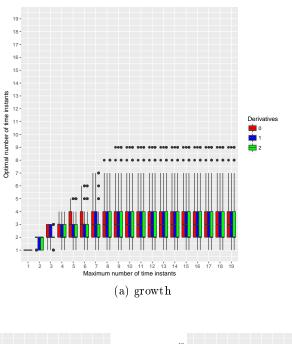
## 2.4 Conclusions and Extensions

We have proposed in this chapter a new approach to optimally select the most informative time instants in multivariate functional data classification. Furthermore, our methodology, by its nature, allows the easy usage of high-order information, e.g., monotonicity, or convexity by means of the derivatives. The numerical experience reported has shown that the information provided by the derivatives has valuable consequences in the classification performance, yielding competitive results when are compared against the state-of-the-art in the literature. We have worked under the assumption that time is a continuous parameter, and continuous optimization tools are then used to achieve an optimal choice of the parameters.

The nested structure of the problem is exploited to enhance running times by using the optimal solutions obtained in simpler models as starting solutions in more complex models.

In our analysis, for the sake of simplicity, we have considered the Pearson correlation coefficient as the performance measure to be optimized. Nevertheless, other measurements such as the Mutual Information Criterion [Cover and Thomas, 2006; Gómez-Verdejo et al., 2009], the Fisher-Correlation Criteria, [Ding and Peng, 2005], the distance covariance [Berrendero et al., 2016b; Székely et al., 2007; Torrecilla Noguerales, 2015], or the distance correlation in [Torrecilla Noguerales, 2015] can be used.

We have restricted ourselves to the pure multivariate functional data case. The problem of time instants selection in multivariate hybrid functional data [Jiménez-Cordero and Maldonado, 2018] is also worth being analyzed. Here, we have just employed the information provided by the first and second derivatives. Thanks to kernel definition, it is very easy to extend our proposal, in order to include the derivatives of higher order.



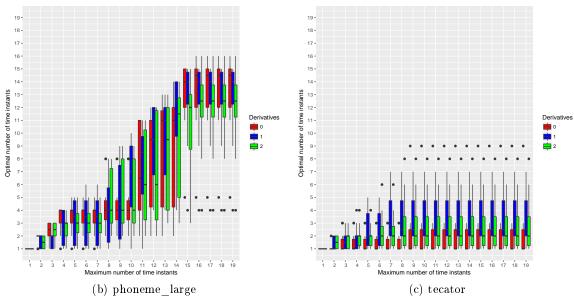


Figure 2.5: Boxplots of the optimal number of time instants in the univariate data sets

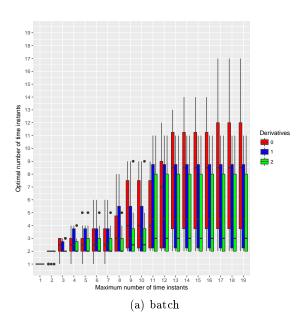
										_					
	19	95.69	94.62	92.47		19	80.25	81.36	81.07			19	74.06	99.76	98.13
	18	95.69	94.62	92.47		18	80.77	81.13	80.78			18	74.06	97.20	99.76
	17	95.69	93.54	94.62		17	80.54	80.72	81.24			17	74.52	97.20	99.76
	16	95.69	92.47	94.62		16	80.43	81.12	81.30			16	74.52	96.75	99.76
	15	95.69	93.54	95.69		15	81.01	81.07	81.36			15	74.06	97.22	89.76
	14	22.96	93.54	22.96		14	79.26	80.31	81.18			14	74.52	97.22	89.76
	13	93.54	93.54	22.96		13	79.44	80.25	80.95			13	74.52	97.22	22.96
	12	94.62	94.62	95.69		12	80.02	78.97	80.72			12	74.04	98.16	97.22
	11	93.54	92.47	97.84		11	80.08	99.08	96.62			11	74.04	98.16	97.22
H	10	93.54	60.77	22.96	Н	10	79.32	80.02	96.62		Н	10	74.04	97.18	96.27
	6	92.96	95.69	93.54		6	78.80	78.86	79.44			6	74.04	98.61	97.22
	8	93.54	94.62	92.47		8	78.50	78.77	79.49			∞	74.52	97.20	98.61
	2	96.52	94.62	93.54		2	79.03	78.21	79.44			2	73.57	89.76	95.82
	9	91.39	60.77	97.84		9	78.97	78.45	79.44			9	73.57	97.22	96.73
	2	90.32	95.69	22.96		5	79.20	79.44	79.14			ಬ	74.04	96.75	96.29
	4	92.47	94.62	94.62		4	79.20	78.92	80.25			4	73.57	96.32	95.82
	3	92.47	89.24	22.96		3	79.03	78.68	80.13			33	74.04	97.72	98.16
	2	89.24	89.24	90.32		2	78.91	78.56	96.62			2	73.59	96.34	60.66
	1	81.72	86.02	88.17		1	77.81	77.45	80.37			1	72.64	94.89	62.96
	p	0	$\vdash$	2		p	0	$\vdash$	2	]		q	0	$\vdash$	2
growth	acc min acc max	22.96			$phoneme\_large$	acc min acc max	82.53				tecator	acc min acc max	99.53		
g.	acc mi	83.87			phone	acc mi	77.34				$t\epsilon$	acc mi	94.42		

Table 2.2: Accuracy results on univariate data sets

96.00	whole time domain	trigonometric			71.00	whole time domain	$batch\_noise$			83.87	whole time domain	batch
2 1 0	d		2	_	0	d		2	1	0	d	_
90.75 91.25 91.75	<u>-</u>		80.00	69.00	68.00	1		79.00	77.00	62.00	1	
97.00 97.25 96.75	2		80.00	74.00	64.00	2		87.00	78.00	70.00	2	
97.00 96.5 98.25	သ		76.00	69.00	66.00	3		86.00	81.00	74.00	3	
97.25 96.75 98.00	4		75.00	68.00	62.00	4		86.00	80.00	71.00	4	
96.00 97.50 97.50	υ <sub>1</sub>		76.00	69.00	65.00	57		85.00	82.00	80.00	υī	
96.75 97.75 97.00	6		74.00	70.00	62.00	6		84.00	84.00	79.00	6	
97.25 97.75 98.00	7		77.00	79.00	73.00	7		84.00	81.00	78.00	7	
97.00 97.50 98.00	∞		81.00	75.00	62.00	8		85.00	80.00	81.00	∞	
96.75 98.00 97.75	9		72.00	68.00	69.00	9		84.00	81.00	76.00	9	
97.00 97.50 98.50	10	Н	76.00	74.00	66.00	10	Н	87.00	80.00	78.00	10	H
98.25 97.50 98.00	11		75.00	70.00	68.00	11		86.00	82.00	77.00	11	
98.25 97.50 98.50	12		74.00	73.00	71.00	12		85.00	87.00	75.00	12	
98.25 97.25 98.25	13		71.00	76.00	66.00	13		87.00	83.00	76.00	13	
97.50 97.25 98.25	14		73.00	74.00	66.00	14		85.00	82.00	75.00	14	
98.50 97.25 98.00	15		71.00	71.00	65.00	15		87.00	86.00	76.00	15	
97.50 97.25 97.75	16		76.00	71.00	60.00	16		84.00	86.00	82.00	16	
98.25 97.25 97.50	17		75.00	70.00	59.00	17		85.00	83.00	78.00	17	
98.00 97.00 97.75	18		77.00	74.00	64.00	18		86.00	84.00	78.00	18	
97.75 97.25 97.75	19		75.00	72.00	63.00	19		86.00	80.00	74.00	19	

Table 2.3: Accuracy results on multivariate data sets

Table 2.4: Average results of the optimal number of time instants on univariate and multivariate databases



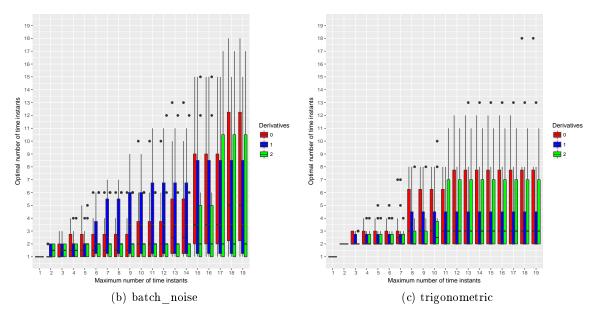


Figure 2.6: Boxplots of the optimal number of time instants in the multivariate data sets

## Chapter 3

Bandwidth Selection in SVM with Functional Data

3.1. Introduction 47

## 3.1 Introduction

In this chapter, we address, as in Chapter 2, binary classification using SVM for functional data. While Chapter 2 was focused on finding the most relevant time instants, here we address the problem of using a functional bandwidth parameter. In this way, accuracy may be improved and relevant time intervals are identified.

To the best of our knowledge, no strategy has been presented in the literature in which different ranges in the domain of the functions are optimally selected by means of a functional weight in the kernel used in an SVM algorithm. Therefore, the main contribution of this chapter is to define a new functional kernel, that optimally identifies time subintervals. Similar ideas have been used in references such as [Bugeau and Pérez, 2007; Chen et al., 2000; Duong et al., 2008; Sain, 2002] for kernel density estimation purposes, and in [Cai et al., 2000; Wu et al., 1998] for functional regression.

Instead of using a performance measure based on the confusion matrix, as usual, both the kernel and the SVM parameters are sought by optimizing a surrogate of the classification rate or the margin, namely, the correlation between the actual observation label and the SVM score. See [Berrendero et al., 2016c; Székely et al., 2007; Torrecilla Noguerales, 2015] for more details on surrogate measures for the accuracy. Tuning such parameters leads to solve an optimization problem, where continuous optimization techniques are applied.

The remainder of the chapter is structured as follows. In Section 3.2 we present the SVM classification model for functional data and motivate the use of a functional bandwidth kernel. Section 3.3 describes the optimization method used to tune the bandwidth parameters. Section 3.4 is devoted to present the numerical experiments, showing that our approach outperforms benchmark methods in the literature. Finally, some conclusions and extensions are described in Section 3.5.

## 3.2 Functional Bandwidth

We follow the notation of the preceding chapters. We have a sample s of observations; each observation  $i \in s$  has associated a pair  $(X_i, Y_i)$ , where each  $X_i : [0, T] \to \mathbb{R}$  belongs to the set  $\mathcal{X} = \mathcal{F}$  of Riemann integrable functions in the time interval [0, T], and  $Y_i \in \{-1, +1\}$  denotes the class label for the observation  $i, i \in s$ . The goal is to build an SVM classification rule which allows us to infer the class Y of a new functional observation  $X \in \mathcal{X}$ .

The usual choice for the kernel function in the functional SVM setup is the Gaussian kernel in (1.24), as done, for instance, in [Kadri et al., 2010; Wang and Yao, 2015]. Nevertheless, in these papers, the associated bandwidth is considered to be a scalar value. In our proposal we extend the fixed scalar bandwidth parameter  $\omega$  in an RBF

kernel to a functional bandwidth,  $\omega(t)$ , that varies along the range of the functional data:

$$K(X_i, X_j) = \exp\left(-\int_0^T (X_i(t) - X_j(t))^2 \omega(t) dt\right)$$
 (3.1)

Throughout this chapter, we assume that  $\omega$  in (3.1) is a non-negative Riemann integrable function in [0, T], and thus K is well-defined.

Considering  $\omega(t)$  as a constant function yields the traditional kernel. However, we consider such bandwidth as a function which adapts to the structure and shape of the data and may lead to better insight and classification rates. More specifically, making  $\omega$  dependent on t allows us to identify those subintervals in [0,T] which are critical for classification, namely, those for which  $\omega(t)$  takes highest values.

Example 3.2.1. As an illustration, let us study the regions data set e.g., [Martín-Barragán et al., 2014], in which the daily temperature has been measured along a year in 35 Canadian weather stations. Two groups can be distinguished: Atlantic climate (label -1), with 15 records, versus the rest of climates (label +1), with 20 records. Figure 3.1 depicts the 15 curves in the interval [1, 365] corresponding to the Atlantic climate, in solid blue line, and the 20 curves corresponding to the rest of climates, in dashed red line, with the data measured every single day. Using SVM with a constant  $\omega(t)$  as in (3.2)

$$\omega(t) = \omega, \quad \forall t \in [0, T] \quad \text{with } T = 365, \tag{3.2}$$

leads to a classifier with the out-of-sample confusion matrix shown in Table 3.1.

Now, let us consider the very same RBF model with a functional bandwidth  $\omega(t)$  of the form

$$\omega(t) = \begin{cases} \omega_1, & \text{if } 0 \le t \le \tau_1 \\ \omega_2, & \text{if } \tau_1 < t \le 365, \end{cases}$$
 (3.3)

Label -1

Label 1

where  $\omega_1, \omega_2, \tau_1$  are parameters to be tuned using the techniques described in this chapter. In other words, with the bandwidth in (3.3) we split into two pieces the interval [0, T] into two pieces, giving different weights to each time interval. The SVM classifier obtained this way leads to the out-of-sample confusion matrix in Table 3.2. Comparing Tables

	Label -1	Label 1
Label -1	51.42%	5.71%
Label 1	11.42%	31.42%

Table 3.1: Confusion matrix with  $\omega$  as in (3.2)

Table 3.2: Confusion matrix with  $\omega$  as in (3.3)

Label -1

54.28%

8.57%

Label 1

2.85% 34.28%

3.1 and 3.2 we can see that the traditional SVM yields an accuracy of 82.84%. On the

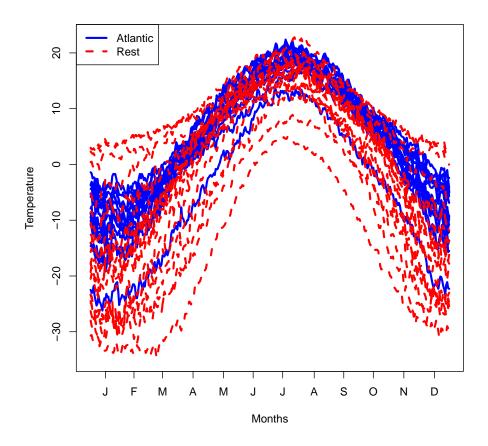


Figure 3.1: regions data set

other hand, our SVM with the very same RBF kernel but using a functional parameter of the form (3.3) yields an accuracy of 88.56% instead.

Regarding the interpretability of the results, Figures 3.2 and 3.3 show the boxplots of the values of the bandwidth  $\omega$  as in (3.2), and the values of  $\omega_1, \omega_2$  and  $\tau_1$ , as in (3.3). The single-bandwidth approach gives the same importance to all the months of the year with the majority of the bandwidth values between 50 and 150. In contrast, our functional bandwidth methodology with two different pieces proposed to divide the whole year into two parts, before and after summer (months of June and July), see Figure 3.3. Moreover, according to the values of  $\omega_1$  and  $\omega_2$ , in order to get good classification predictions, we should focus on the second half-year and give more importance to the second part, i.e., the autumn and first months of winter, which coincide to the time instants when the temperature begins to decrease.

The previous illustrative example demonstrates that even a simple functional bandwidth such as (3.3) may yield important improvements in accuracy. Such improvement is a consequence of the adequate choice of the parameters  $\tau_1$ ,  $\omega_1$  and  $\omega_2$  allowing us

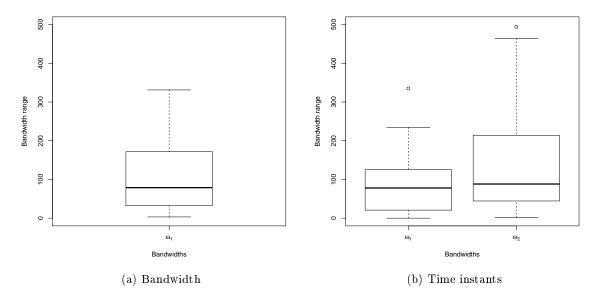


Figure 3.2: (a) and (b) show the bandwidth values for the *regions* data set when  $\omega$  has the form of (3.2) and (3.3), respectively

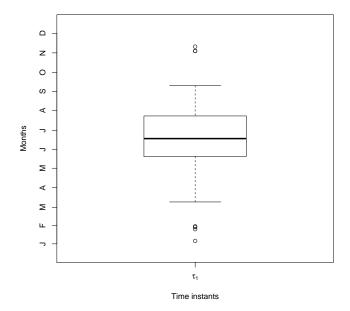


Figure 3.3: Time instant results for the regions data set with  $\omega$  as in (3.3)

to know which are the most suitable intervals for classification. Using a functional bandwidth parameter  $\omega(t)$  gives more flexibility. For instance, it may be chosen in the class of piecewise constant non-negative functions in [0,T] with H pieces, i.e., one can

naturally assume that  $\omega(t)$  has the form (3.4)

$$\omega(t) = \begin{cases} \omega_1, & \text{if } 0 \le t \le \tau_1 \\ \omega_2, & \text{if } \tau_1 < t \le \tau_2 \\ \cdots \\ \omega_h, & \text{if } \tau_{h-1} < t \le \tau_h \\ \cdots \\ \omega_H, & \text{if } \tau_{H-1} < t \le T \end{cases}$$

$$(3.4)$$

where  $\omega_1, \ldots, \omega_H \geq 0$  and  $0 \leq \tau_1 \leq \ldots \leq \tau_{H-1} \leq T$  are parameters to be tuned. Instead of piecewise constant functions, one could consider  $\omega(t)$  belonging to the class of polynomials of degree H which are non-negative in [0, T], the class of piecewise polynomial functions non-negative in [0, T], or the non-negative splines, [De Boor, 1978; Friedman et al., 2001b].

The use of functional parameters in the kernel may lead to significant improvements in the accuracy, as demonstrated in our numerical experiments. The price to pay for obtaining such gains in the accuracy is the fact that tuning the functional parameters requires the use of using more sophisticated optimization procedures. In Section 3.3 we detail how the underlying optimization problem for tuning  $\omega(t)$  is solved.

## 3.3 Optimal Selection of the Functional Bandwidth

Parameter tuning in the classification of functional data with SVM implies the optimal choice of two very different elements: the scalar regularization parameter C in (1.15), and the kernel K in (3.1) through  $\omega(t)$ . The problem of finding the best function  $\omega(t)$  in (3.1) is not tractable as a rule in its full generality. Hence, we restrict our attention to certain classes of functions parameterized by a vector  $\theta$  belonging to a certain set  $\Theta$ , i.e.,  $\omega$  is expressed as  $\omega(t,\theta)$ , and the choice of the function  $\omega$  is equivalent to choosing the parameters  $\theta$ .

**Example 3.3.1.** For the bandwidth given in (3.4), one would have that  $\theta = (\omega_1, \ldots, \omega_H, \tau_1, \ldots, \tau_{H-1})$ , and  $\Theta = \{(\omega_1, \ldots, \omega_H, \tau_1, \ldots, \tau_{H-1}) : \omega_h \geq 0, \forall h, \tau_h \in [0, T], h = 1, \ldots, H - 1, \tau_1 \leq \ldots \leq \tau_{H-1}\}$ . For convenience, we consider  $\tau_0 = 0$  and  $\tau_H = T$ .

In this chapter, parameter tuning is done following the approach proposed in Chapter 2. First, the data set is divided into k folds. Second, k-1 folds are again split into three samples named  $s_1$ ,  $s_2$ , and  $s_3$ , while the remaining fold is denoted by  $s_4$ . Samples  $s_1$  and  $s_2$  play the role of training samples, whereas  $s_3$  and  $s_4$  formed the validation and testing sets, respectively.

The first independent sample  $s_1$  is employed for the resolution of Problem (1.15), that is the classic SVM formulation, to obtain a classification rule by means of  $\alpha$ , for fixed parameters  $\theta$  and C. The second independent sample  $s_2$  is used to measure

the quality of parameters  $\theta$ , i.e., it is used to calculate  $R((Y_i, \hat{Y}(X_i, \theta, \alpha))_{i \in s_2})$ , the correlation between the class labels and the scores. To find the regularization parameter C, we measure the accuracy in the sample  $s_3$  for all the different possible values of C in the grid, and we keep the C providing the largest accuracy. Finally, the accuracy is measured in the independent sample  $s_4$  is reported.

After all these considerations, for fixed C, we formulate bilevel optimization problem, that can be expressed as:

$$\begin{cases}
\max_{\theta,\alpha} & R((Y_i, \hat{Y}(X_i, \theta, \alpha))_{i \in s_2}) \\
\text{s.t.} & \alpha \text{ solves } (1.15) \text{ in } s_1 \\
& \theta \in \Theta
\end{cases}$$
(3.5)

We next propose an alternating approach for which only a few iterations will be carried out. Firstly, in the first step of our alternating approach, for fixed parameters  $\theta$  and C, a classification rule is obtained solving Problem (1.15), that is, the classic SVM. Problem (1.15) is a concave quadratic maximization problem, which can be solved by standard local search optimizers, as specified in Section 1.2.2. Secondly, in the second step, for fixed  $\alpha$  and C,  $\theta$  is chosen by solving:

$$\max_{\theta \in \Theta} R((Y_i, \hat{Y}(X_i, \theta))_{i \in s_2}) \tag{3.6}$$

Problem (3.6) is a continuous optimization problem which is solved by using standard local search techniques with multi-start. The alternating procedure will alternate these two steps until some stopping criterion is met. Suitable values for  $\theta$  and  $\alpha$  will be obtained by this procedure for a specific value of the regularization parameter C.

The value of C will be chosen by a grid search, as commonly done in standard SVM. This means that, for every value of C in a given grid, we measure the accuracy in  $s_3$  of the classification rule obtained with the best  $\theta$  and  $\alpha$  found as solutions of Problem (3.6). The C with the largest accuracy in  $s_3$  will be chosen. Finally, we estimate the correct classification rate using the fourth independent sample,  $s_4$ .

The pseudocode of the heuristic that have just been presented is outlined in Algorithm 3.

As in Chapter 2, the above-explained methodology is embedded in a nested heuristic. More precisely, given a family of kernel functions, we construct a series of nested kernel models with their associated parameters, or equivalently, a series of H nested functional bandwidths  $\omega_{(1)}(t,\theta_{(1)}) \prec \ldots \prec \omega_{(H)}(t,\theta_{(H)})$ . By  $\omega_{(h)}(t,\theta_{(h)}) \prec \omega_{(h+1)}(t,\theta_{(h+1)})$  we denote that the bandwidth  $\omega_{(h)}(t,\theta_{(h)})$  has parameters which are part of the parameters of the bandwidth  $\omega_{(h+1)}(t,\theta_{(h+1)})$ . When solving Problem (3.5) for  $\omega_{(H)}(t,\theta_{(H)})$  we will use a sequential approach where the (suboptimal) solution obtained when using  $\omega_{(h)}(t,\theta_{(h)})$ , will be used as an initial solution of Problem (3.5) with  $\omega_{(h+1)}(t,\theta_{(h+1)})$ .

## Algorithm 3 Heuristic for parameter tuning

## Input: H

• Randomly split the sample s into  $s_1$ ,  $s_2$ ,  $s_3$  and  $s_4$ .

for C in the grid do

## Alternating Procedure

## repeat

- 1. Fixed  $\theta$ , compute the parameters  $\alpha$  of the SVM classifier by solving Problem (1.15) in  $s_1$ .
- 2. Fixed  $\alpha$ , calculate  $\theta$  by solving Problem (3.6) in  $s_2$ .

until stopping criteria

• Evaluate the accuracy in the sample  $s_3$  with C fixed.

#### end for

• The optimal value of C is the one with the best accuracy in  $s_3$ . The optimal values of  $\alpha$  and  $\theta$  are the ones associated with the optimal parameter C.

**Output:** optimal parameters C and  $\theta$ , optimal classification coefficients  $\alpha$ , and the corresponding accuracy estimated from  $s_4$ .

**Example 3.3.2.** Consider in (3.4) the family of piecewise constant functions with 3 pieces. We have that  $\omega_{(1)}(t,\theta_{(1)}) = \omega_1$ , with  $\theta_{(1)} = \omega_1$ ,  $\omega_{(2)}(t,\theta_{(2)}) = \omega_1 I_{[0,\tau_1]} + \omega_2 I_{(\tau_1,T]}$ , with  $\theta_{(2)} = (\omega_1,\omega_2,\tau_1)$ , and finally  $\omega_{(3)}(t,\theta_{(3)}) = \omega_1 I_{[0,\tau_1]} + \omega_2 I_{(\tau_1,\tau_2]} + \omega_3 I_{(\tau_2,T]}$ , with  $\theta_{(3)} = (\omega_1,\omega_2,\omega_3,\tau_1,\tau_2)$ . Here  $I_{[r,r']}$  denotes the indicator function, i.e., the function which is equal to 1 in the interval [r,r'] and 0 otherwise.

Once we have obtained the (suboptimal) solution of  $\omega_{(h)}(t,\theta_{(h)})$  by  $\theta_{(h)}^{opt} = (\omega_1^{opt},\ldots,\omega_h^{opt},\tau_1^{opt},\ldots,\tau_{h-1}^{opt})$ , then, we randomly select an interval  $[\tau_{\ell-1},\tau_{\ell})$  and split it into two pieces by its midpoint, assigning the same bandwidth value to such two new pieces. In other words, the initial point of the parameters in the level h+1 turns out to be

$$\theta_{(h+1)} = \left(\omega_1^{opt}, \dots, \omega_{\ell-1}^{opt}, \omega_\ell^{opt}, \omega_\ell^{opt}, \omega_{\ell+1}^{opt}, \dots, \omega_h^{opt}, \tau_1^{opt}, \dots, \tau_{\ell-1}^{opt}, \frac{\tau_\ell^{opt} + \tau_{\ell-1}^{opt}}{2}, \tau_\ell^{opt}, \dots, \tau_h^{opt}\right).$$

The pseudocode of the nested algorithm is shown in Algorithm 4.

## 3.4 Numerical Experiments

This section details the experiments performed (Section 3.4.1) and the main characteristics of the databases here considered (Section 3.4.2). Finally, Section 3.4.3 presents the computational results obtained.

## 3.4.1 Description of the Experiments

In this section, a detailed description of the experiments carried out to test our methodology is made. To obtain stable estimates, k-fold cross-validation has been used to evaluate the performance of the algorithm on different data sets, as detailed in Section

## Algorithm 4 Nested heuristic for parameter tuning

**Input:** H, nested functional bandwidths  $\omega_{(1)}(t,\theta_{(1)}) \prec \ldots \prec \omega_{(H)}(t,\theta_{(H)})$ .

• Randomly split the sample s into  $s_1, s_2, s_3$  and  $s_4$ .

for C in the grid do

## Initialization:

- h := 1.
- Randomly select an initial solution  $\theta_{(h)} \in \Theta_{(h)}$ .
- Set  $\theta := \theta_{(h)}$

## while $h \leq H$ do

1. Using samples  $s_1$  and  $s_2$ , run the Alternating Procedure of Algorithm 3 for  $\omega(t, \theta_{(h)})$ , starting from  $\theta$  and yielding

$$\theta_{(h)}^{opt} = \left(\omega_1^{opt}, \dots, \omega_h^{opt}, \tau_1^{opt}, \dots, \tau_{h-1}^{opt}\right) \text{ as solution.}$$
2. Randomly select  $\ell \in \{1, 2, \dots, h\}$ .

- $\theta := \left(\omega_1^{opt}, \dots, \omega_{\ell-1}^{opt}, \omega_\ell^{opt}, \omega_\ell^{opt}, \omega_{\ell+1}^{opt}, \dots, \omega_h^{opt}, \tau_1^{opt}, \dots, \tau_{\ell-1}^{opt}, \frac{\tau_\ell^{opt} + \tau_{\ell-1}^{opt}}{2}, \tau_\ell^{opt}, \dots, \tau_{h-1}^{opt}\right)$
- 4. Evaluate the accuracy in the sample  $s_3$  with C fixed.

#### end while

#### end for

• For h fixed, the optimal value of C is the one with the best accuracy in  $s_3$ . The optimal values of  $\alpha$  and  $\theta_{(h)}$  are the ones associated to the optimal parameter C.

**Output:** optimal parameters C,  $\theta_{(h)}^{opt}$ ,  $\forall h$ , the associated classification coefficients  $\alpha$ , and the accuracy estimated from  $s_4$ .

1.2.4. As in the previous chapter, the number k of folds varies depending on the size of the database. For small databases, k is equal to the number of observations, i.e., we performed leave-one-out, whilst for large databases, we take k=10. A database is considered small here if and only if it has less than 100 observations. See Table 3.3 for details.

Algorithm 4 is run k times, one per fold, as done in Chapter 2. Each time, the division into four independent samples  $s_1, s_2, s_3$ , and  $s_4$  is done as explained in Section 3.3. The number of runs of the multi-start local search optimization method is set to five. The algorithm is run until the maximum number of iterations reaches ten, or when the difference between the objective values in two consecutive iterations is less than  $10^{-5}$ . The functional bandwidth  $\omega(t,\theta)$  is the piecewise constant function in (3.4) with H=8. The regularization parameter C varies in the set  $\{2^{-10},\ldots,2^{10}\}$ . The parameters  $\theta_{(h)}$  are in the set  $\Theta_{(h)} = \{(\omega_1, \ldots, \omega_h, \tau_1, \ldots, \tau_{h-1}) : \omega_\ell \geq 2^{-4}, \ell = 1\}$  $1, \ldots, h, 0 \le \tau_1 \le \ldots \le \tau_{h-1} \le T$ ,  $\forall h = 1, \ldots, 8$ .

For comparison purposes, apart from the standard SVM, i.e., our approach with H=1, we have run three supervised classification methods for functional data, available at the fda.usc library of R, [Febrero-Bande and Oviedo de la Fuente, 2012], namely classif.depth, classif.kernel, classif.knn with the default parameters. In order to obtain a fair comparison, the accuracy obtained is estimated on the very same testing sample  $s_4$  used in our approach.

The algorithm presented in this chapter was coded in R and was executed on a cluster with 2Tb of RAM memory at 6.2 TFlops, running CentOS Linux 7.3.

## 3.4.2 Description of the Data Sets

Our methodology has been tested in 12 benchmark data sets, widely used in the functional data classification literature, namely, ECG, growth, gun, MCO, phoneme,  $phoneme\_large$ , rain, regions,  $synthetic\_magnitude$ , tecator, wine, and yoga. A summary of all the data sets here used can be seen in Table 3.3. Since the data sets growth,  $phoneme\_large$ , and tecator have been previously described in Section 2.3.2, we will give only a complete description of the remaining ones. Moreover, a sample of ten individuals of growth,  $phoneme\_large$ , and tecator is shown in Figure 2.1, whereas the remaining sets are plotted in Figure 3.4. The solid blue and dashed red lines represent the observations with class -1 and +1, respectively.

#### ECG Data Set

The ECG data set can be found in [Bagnall et al., 2016; Chen et al., 2015]. It contains 96 measurements of cardiac electrical activity (electrocardiogram). A label of normal or abnormal has been associated to each individual. Particularly, this database is formed by 133 observations identified as normal (class + 1) and 67 abnormal observations (class -1). This data set has also been used in [Olszewski, 2001; Xing et al., 2009]. The goal is to detect if the cardiac activity of a new patient is normal or not.

#### Gun Data Set

Gun data set comes from [Bagnall et al., 2016; Chen et al., 2015]. It reproduces the hand gestures of 200 actors measured on 96 time points, reproducing two different gun movements, namely draw and point. Each class is formed by 100 individuals. An example of a paper where it has been used is [Xing et al., 2009]. Our goal is to distinguish between the two motions.

## MCO Data Set

The original experiment of the *MCO* database comes from [Ruiz-Meana et al., 2003], and can be extracted from the R library, fda.usc. In this experiment, the mitochondrial calcium overload (MCO) of two groups, namely control and treatment, of isolated mouse cardiac cells have been measured every ten seconds ranging from second 0 to 3,590. The aim is to know if a new cardiac cell comes from a control or treatment mouse, based on

the MCO levels. This data set has been used in [Baíllo et al., 2011; Cuevas et al., 2006] and Online companion of [Carrizosa et al., 2014].

#### Phoneme Data Set

As the *phoneme\_large* data set from Section 2.3.2, the *phoneme* database was first used in [Hastie et al., 1995]. Here, in the *phoneme* data set, we use 200 functions, 100 of each class, corresponding to the phonemes "aa" and "ao" as appear in the R library fda.usc, measured in 150 time points. The objective is to discriminate between the two phonemes. Some references where this data set has been studied are [Ferraty and Vieu, 2006; Muñoz and González, 2010; Rossi and Villa, 2006; Torrecilla Noguerales, 2015].

## Rain Data Set

The *rain* data set can be found e.g., in [Martín-Barragán et al., 2014] and contains the daily temperature measured along a year in 35 Canadian weather stations. Two classes are distinguished, namely rainy and dry stations, depending if the yearly total amount of precipitations are below or above 600. The aim is to know if a Canadian station is dry or not.

## Regions Data Set

The regions data set can also be found in e.g., [Martín-Barragán et al., 2014] and has been already briefly explained in Example 3.2.1. The objective is to discriminate between the Atlantic and the rest of climates.

## Synthetic\_magnitude Data Set

The *synthetic\_magnitude* data set has been simulated from the information detailed in the Model 3 of [López-Pintado and Romo, 2009]. Particularly, the data have been recorded on 100 equally-spaced points on the interval [0, 1]. The individuals belonging to the class +1 have the form:

$$X_i(t) = 4t + \gamma_i(t), \tag{3.7}$$

where  $\gamma_i(t)$  is a stochastic Gaussian process with zero mean and covariance function  $c(s,t) = \exp(-|t-s|)$ . On the other hand, the observations with label -1 are defined as follows:

$$X_i(t) = \begin{cases} 4t + a_i b_i \nu, & \text{if } t \ge T_i \\ 4t, & \text{if } t < T_i \end{cases}$$
 (3.8)

where  $a_i$  follows a Bernoulli distribution with probability 0.1,  $b_i$  is a random variable independent of  $a_i$  taking values +1 and -1 with probability 1/2,  $\nu$  is equal to 25, and  $T_i$  follows a uniform distribution on [0,1]. The goal is to distinguish between both classes, -1 and +1.

#### Wine Data Set

The *wine* data set can be found in [Bagnall et al., 2016; Chen et al., 2015]. It contains 111 spectrograph curves measured in 234 time points. The goal is to classify between two different types of grapes.

## Yoga Data Set

The yoga database can be found in [Wei, 2006], and has been applied in papers such as [Wei and Keogh, 2006]. In this data set, the transitions between several yoga poses have been captured in 150 men and 156 women. The images have been converted into functional data, yielding curves measured in 426 time points. The goal is to know if the yoga pose is performed by a man or a woman.

#### 3.4.3 Results

We provide the boxplots of the accuracy measured on  $s_4$  from H = 1 to H = 8 for the different folds in the k-fold accuracy estimation procedure.

Boxplots are not very informative for small data sets, for which leave-one-out is performed. Indeed, for each fold either one obtains an accuracy of 0% or 100%, since either the testing observation is wrongly or correctly classified. For this reason, only the boxplots of the largest data sets, i.e., ECG, gun, phoneme, phoneme\_large, synhetic\_magnitude, tecator, wine and yoga, are depicted in Figure 3.6. Moreover, the exact values of the average accuracy in all the data sets, as well as the corresponding values for the three fda.usc library methods considered in Section 3.4.1, are also presented in Table 3.4 for the sake of comparison. The first four columns correspond to the four methods we are comparing with, denoted as depth, kernel, knn and classic SVM. Finally, last column of Table 3.4 gives the best number of pieces chosen.

In general, our method for h = 2, ..., 8 is better than the four comparative approaches in the data sets growth, MCO, phoneme, phoneme\_large, and regions. This improvement may be produced by the shape of the curves. The different class labels seem to be easy to identify depending on the time subinterval, and therefore our strategy makes easier such separation. Observe for instance, the growth data set, in which the two classes have a different pattern around the time instant 15. Moreover, it is seen in Table 3.4 that the improvement in the accuracy strongly depends on the data set considered. Indeed, no improvement is seen for the databases gun, rain, and tecator when comparing our

methodology with H=1 and  $H\geq 2$ . However, for some of the values  $H\geq 2$  the accuracy obtained in gun is better than that provided by depth. The results of our approach in the database rain are always better than the ones provided of the three fda.usc methods. In contrast, such three methods should be applied if the tecator data set is studied. In the databases ECG, growth, phoneme large and yoga there is a minor improvement (about a 0.5 points) when comparing the classic SVM with our approach for  $H \geq 2$ . Such improvement also holds in the ECG data set when comparing with the depth method. The accuracy value obtained in phoneme large with our approach when H=4 pieces are chosen is better than all the three fda.usc methods. Analogous conclusions are obtained in the yoqa data set. A considerably larger accuracy is obtained in databases MCO, phoneme, regions, synthetic magnitude, and wine when solving the problem with  $H \geq 2$  than when solving with H = 1, i.e., the classic SVM. In some cases such improvement yields around a ten percentage points of difference in accuracy. Such a large accuracy also occurs when comparing our approach with the three fda.usc methods in the databases MCO, regions and wine. The improvement is not so evident in the phoneme data set. In the data set synthetic magnitude, our results are comparable to those provided by depth and knn, but much better than the ones in kernel.

Apart from the improvements in the accuracy, our approach enables us to identify subintervals of special interest. This fact would be impossible if the standard scalar bandwidth, which treats equally all time instants, were considered. We highlight, for instance, the case of the wine data set, whose curves are almost identical except around the time instants at which peaks occur. Figure 3.5 shows the boxplots of the values of  $\omega_1, \omega_2, \omega_3, \tau_1$  and  $\tau_2$  obtained when a functional bandwidth with H = 3 pieces is sought. We observe that the time instants which distinguish one piece from another are around 50 and 125, which coincides with the points of some of the peaks. Furthermore, the associated weight is greater in the third part, where the biggest peak is located.

Regarding the trajectory of the accuracy versus the number of pieces, we observe that there is not a clear pattern. For instance, in the MCO data set, we have worse results with H=2 pieces than with the classic SVM (H=1). However, a difference of six points is obtained when comparing H=6 with H=1.

In contrast, in the *regions* data set, the accuracies with  $H \geq 2$  are significantly better than with H = 1, reaching the maximum value with H = 6. Similar conclusions can be drawn in the remaining data sets.

This fact shows that a good choice of the value of H is necessary. Since the value of the parameter H depends on the division of the data set, we show in the last column of Table 3.4 the average value of the best H parameter estimated on sample  $s_3$ .

-	#records	#points measurements	#records label -1	#records label $+1$
ECG	200	96	67	133
$\operatorname{growth}$	93	31	54	39
$\operatorname{gun}$	200	96	100	100
MCO	89	360	44	45
${ m phoneme}$	200	150	100	100
${ m phoneme\_large}$	1717	256	1022	695
$\operatorname{rain}$	35	365	15	20
$\operatorname{regions}$	35	365	20	15
$\operatorname{synthetic} \_\operatorname{magnitude}$	150	100	75	75
${ m tecator}$	215	100	77	138
wine	111	234	54	57
yoga	306	426	150	156

Table 3.3: Data description summary

#### 3.5 Conclusions and Extensions

In this chapter, we have shown how SVM for functional data can be improved if a functional bandwidth, to be tuned via a nested heuristic, is used. By using very simple functional parameters, together with our tuning procedure, we obtained better accuracy in the test sets than with the traditional scalar parameter model. The methodology here proposed is able to identify the critical points in which a change in the behavior of the functions is produced, yielding the most relevant intervals in terms of the classification rate.

The difficulties associated to the tuning of more complex structures are mitigated by the use of a heuristic that exploits the nested structure of the functional parameter, by using the (suboptimal) solution of one level as an initial solution for the next level. Our tuning procedure takes advantage of the functional nature of the data by expressing the tuning problem as a bilevel optimization problem in continuous variables. In contrast to the usual approach, where the misclassification rate is minimized, here the correlation between labels and scores are optimized, allowing us to use gradient-based local search algorithms.

In our approach, the number of pieces of the functional bandwidth, H, is fixed from the beginning, and the trajectory of the classification rates for the different number of pieces is shown. However, since the results depend on H, we also choose the value of H yielding the best accuracy, estimated on the validation sample.

The analysis performed here, using piecewise constant functions as bandwidths, can be easily extended to other expressions such as polynomials, or piecewise polynomials, including splines [De Boor, 1978; Friedman et al., 2001b]. Apart from the Pearson correlation coefficient, different types of association measures can be applied, [Székely et al., 2007; Torrecilla Noguerales, 2015].

The functional data here considered are univariate functions. The case of multivariate (hybrid) functional data, [Jiménez-Cordero and Maldonado, 2018] can also be addressed with our proposal, after the convenient modification of the kernel function.

The standard hinge loss function has been used in the SVM formulation of this chapter. Our approach might also be adapted to other loss functions, such as the so-called ramp loss, [Brooks, 2011], by replacing (1.15) with the corresponding SVM problem. The same happens if the SVM in (1.15) is replaced by other related methods such as the least-squares SVM, e.g., [Cruz-Cano et al., 2010].

Our approach is limited here to classification problems. If instead, functional regression is pursued, [Sood et al., 2009], our methodology can be adapted to this context, replacing SVM by Support Vector Regression (SVR).

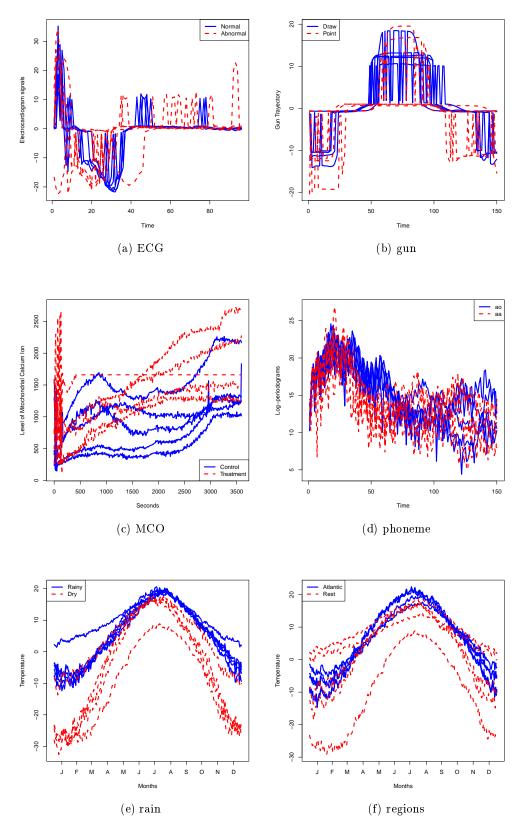


Figure 3.4: Sample of functional data in the data sets analyzed

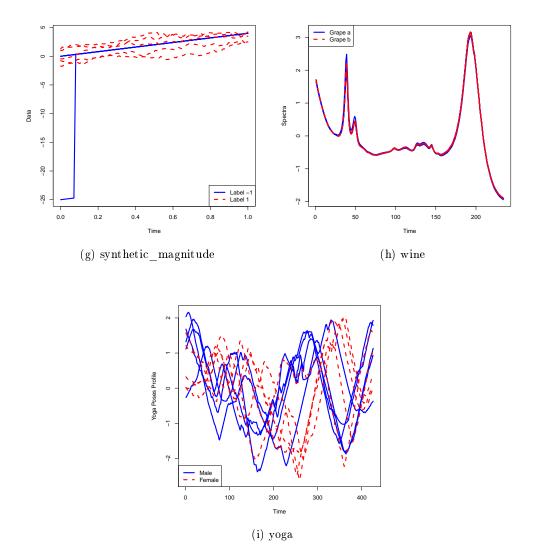


Figure 3.4: Sample of functional data in the real data sets analyzed (cont.)

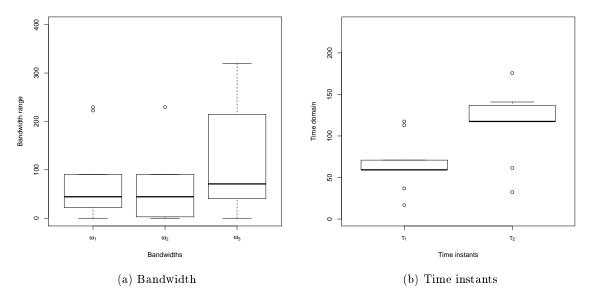


Figure 3.5: Bandwidth and time instants results for the wine data set

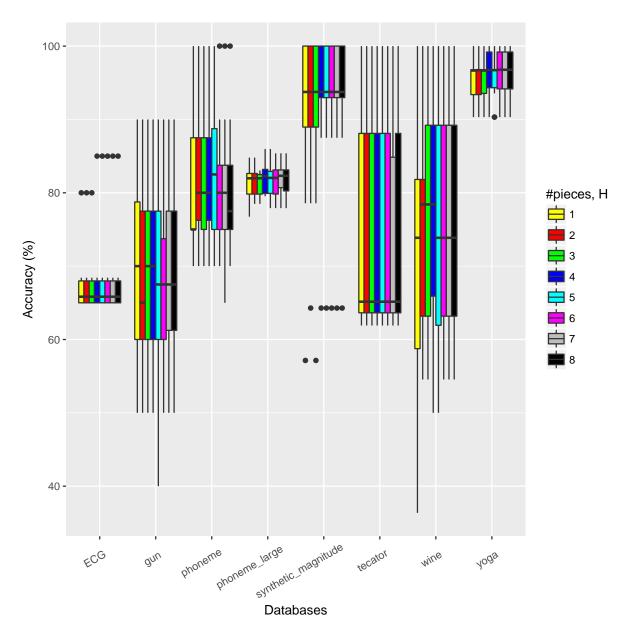


Figure 3.6: Accuracy boxplots in the analyzed larger data sets depending on the number of pieces, H. Since the boxplots are rather informative for the small data sets, i.e., growth, MCO, rain and regions, only the accuracy values of the remaining databases are depicted

	Jonth	donth bound bun	Jenn				H					Boot U
	aepun	kerner	KIIII	1 (classic SVM)	2	3	4	ಬ	9	7	$\infty$	Dest u
ECG	67.51	74.41	83.92	67.51	67.51	67.51	68.01	68.01	68.01	68.01	68.01	1.70
growth	78.49	94.62	92.47	94.62	94.62	94.62	94.62	93.54	93.54 95.69	94.62	94.62	1.30
gun	52.50	73.50	78.00	69.50	68.00		69.50 69.50	67.50 $67.00$	67.00	69.00	69.50	3.00
MCO	67.41	78.65	79.77	80.89	78.65	83.14	82.02	83.14	86.51	83.14	83.14	4.15
phoneme	76.00	80.00	73.50	80.50	81.50	81.00	81.50	82.00 81.00	81.00	80.50	80.50	4.00
phoneme_large	71.69	65.46	78.91	81.24	81.47	81.24 82.00		81.65	81.59	81.83	81.65	2.10
rain	82.85	80.00	77.14	82.85	80.00	80.00	82.85	80.00	80.00	77.14	77.14	1.91
regions	77.14	85.71	77.14	82.84	88.56	88.57	88.57	85.71	91.42	91.42	88.57	1.77
synthetic_magnitude	99.37	55.97	96.54	90.40	91.11	90.40	92.54	92.54	92.54	92.54	92.54	1.90
tecator	94.87	98.13	98.11	74.04	74.04	74.04	74.04	74.04	74.04	73.59	74.04	1.80
wine	61.87	91.93	92.03	71.27	75.77	77.59	77.59	75.68	89.92	89.92	89.92	2.60
yoga	84.13	96.08	96.73	95.11	95.45	95.76	96.44	95.78	60.96	60.96	60.96	3.60

(depth, kernel and knn) and running our approach from H = 1 to H = 8. Last column presents the average value of the best parameter HTable 3.4: Average of the accuracy estimated on sample  $s_4$  for all the data sets after running the three methods available at fda.usc

### Chapter 4

# SVM-Classification of Hybrid Functional Data

4.1. Introduction 69

#### 4.1 Introduction

In this chapter, we are interested in classifying hybrid functional data, i.e., data with functional and static (constant over time) covariates, into two predefined classes, using SVM. Feature selection plays a very important role in data mining. Hence, it is crucial to design a methodology that selects the most important features yielding good classification performance. Some references of feature selection and particularly, on feature selection in univariate functional data are given in Section 1.3. Nevertheless, regarding feature selection in multivariate functional data and, more specifically, in hybrid functional data, the literature is very scarce.

In this chapter, we demonstrate that hybrid data sets cannot be learned properly with the current methodologies for SVM classification. We propose a modification of the standard SVM classification to handle functional hybrid data sets, and as a byproduct, to select the most informative features. The different components of the data, functional or static, are weighted by different scaling factors of a modified Gaussian kernel. The idea of considering different weights for different types of features is not new. Indeed, it has been applied in [Bugeau and Pérez, 2007; Chen et al., 2000; Duong et al., 2008; Sain, 2002] for kernel density estimation purposes and in [Maldonado et al., 2015] for clustering problems, among others.

The remainder of this chapter is structured as follows: in Section 4.2 we formally introduce the concepts used in our methodology and detail our approach. Section 4.3 is devoted to the computational experience, including a sensitivity analysis of the parameters involved in the model. Finally, some conclusions and possible future lines of research are described in Section 4.4.

#### 4.2 The Mathematical Model

This section details the problem formulation of feature selection in SVM classification with hybrid functional data, as well as the solving strategy.

Following the notation of previous chapters, let s be a sample of individuals with an associated pair  $(X_i, Y_i)$  for each individual  $i \in s$ . A hybrid functional datum  $X_i \in \mathcal{X}$ , with  $\mathcal{X} = \mathcal{F}^{p_1} \times \mathbb{R}^{p_2}$ , is defined as a vector of  $p_1$  functional features and  $p_2$  static features, as in Equation (1.2), for a Hilbert space  $\mathcal{F}$ . Moreover,  $Y_i \in \{-1, +1\}$  denotes the class label of the observation  $i \in s$ .

In this chapter we design a model which obtains, via SVM, good classification rates in order to determine the class Y of a new observation  $X \in \mathcal{X}$ , and at the same time it yields the most informative set of features  $\mathcal{V} \subset \{1, \ldots, p_1 + p_2\}$ .

To do this, we use the kernel function given in (1.26) in which a scalar bandwidth is associated to each feature, instead of the usual isotropic Gaussian kernel with a unique

bandwidth. Whereas the bandwidth in the isotropic kernel is just one single value, common to all the variables, the kernel in (1.26) has a bandwidth for each feature. This allows more flexibility in our model, weighting each covariate differently according to its contribution in the classification model.

The feature selection problem implies the tuning of two parameters: the regularization parameter C of the SVM problem (1.15), and the bandwidths  $\omega_v, v = 1, \ldots, p_1 + p_2$  associated with each feature of  $X \in \mathcal{X}$  through the kernel (1.26).

In agreement with the methodologies of Chapters 2 and 3, we propose to combine a grid search to get the optimal value of C with a bilevel optimization to optimize the bandwidth  $\omega$ . When k-fold cross-validation is performed, k-1 folds constitute samples  $s_1$  and  $s_2$  (both training sets) and sample  $s_3$  (validation set), whilst the remaining fold, denoted as  $s_4$ , is the testing set. Sample  $s_1$  is utilized to solve the SVM problem (1.15), for fixed C and  $\omega$ , yielding the variables  $\alpha$ . The independent sample  $s_2$  is used to measure the goodness of fit via the Pearson correlation coefficient  $R((Y_i, \hat{Y}(X_i, \omega, \alpha))_{i \in s_2})$  for  $\alpha$  and C fixed. Sample  $s_3$  is employed to find the regularization parameter C, by computing the accuracy on  $s_3$  for the values of C in the grid, and keeping the one with the largest value. Finally, the output accuracy is estimated on sample  $s_4$ .

Therefore, for a fixed C, the bilevel optimization problem is stated as follows:

$$\begin{cases}
\max_{\boldsymbol{\omega},\alpha} & R((Y_i, \hat{Y}(X_i, \boldsymbol{\omega}, \alpha))_{i \in s_2}) \\
\text{s.t.} & \alpha \text{ solves } (1.15) \text{ in } s_1 \\
\omega_v \ge 0, \quad v = 1, \dots, p_1 + p_2,
\end{cases} \tag{4.1}$$

In order to solve Problem (4.1), we propose using an alternating approach, consisting of just few iterations of two steps. First, the optimal variables  $\alpha$  are obtained by solving Problem (1.15) for fixed  $\omega$  in sample  $s_1$ . Second, the optimal values of the parameter  $\omega$  are sought, for fixed  $\alpha$ , once Problem (4.2) is solved in sample  $s_2$ .

$$\begin{cases}
\max_{\boldsymbol{\omega}} & R((Y_i, \hat{Y}(X_i, \boldsymbol{\omega}))_{i \in s_2}) \\
\text{s.t.} & \omega_v \ge 0, \quad v = 1, \dots, p_1 + p_2,
\end{cases}$$
(4.2)

Problems (1.15) and (4.2) have different nature and, consequently, they should be solved with different strategies. Problem (1.15) is a quadratic maximization problem with linear constraints in which the strategies of Section 1.2.2 can be applied to easily attain the global optimum. In contrast, Problem (4.2) is a continuous optimization problem whose optimal solution is obtained by embedding classic local searches in a multi-start.

The alternating procedure is run, for a fixed C, until some stopping criterion is fulfilled. Since, apart from obtaining good classification rates, our goal is to select the most informative features, once the alternating approach is finished, we eliminate those covariates v whose associated bandwidths  $\omega_v$  are close enough to zero and repeat

the alternating algorithm with the remaining features. In other words, we keep those features satisfying  $\omega_v > \delta$ , where  $\delta > 0$  is a threshold value. This process is repeated until the selected features do not change in two consecutive iterations of the procedure that has just been described.

Once the alternating approach has provided good values for  $\alpha$ ,  $\omega$ , and therefore, the set  $\mathcal{V}$  of selected features, the value of C is chosen by computing the accuracy on  $s_3$  for all C values in the grid, and the one that leads to the largest accuracy is kept.

Finally, the effectiveness of our methodology is tested on an independent sample  $s_4$ , in which the classification accuracy is computed.

The pseudocode of our approach is given in Algorithm 5.

#### Algorithm 5 Heuristic for parameter tuning and feature selection

```
• Randomly split the sample s into s_1, s_2, s_3 and s_4.
```

for C in the grid do

Initialization:  $V = \{1, \dots, p_1 + p_2\}$ 

repeat

Alternating Procedure

repeat

- 1. For  $\omega$  fixed, obtain the variables  $\alpha$  of the SVM classifier by solving Problem (1.15) in  $s_1$ .
- 2. For a fixed  $\alpha$ , calculate  $\omega$  by solving Problem (4.2) in  $s_2$ .

until stopping criteria

• Delete the features, v, such that  $\omega_v \leq \delta$ , i.e.,  $\mathcal{V} = \{v : \omega_v > \delta\}$ 

until no new features are deleted

• Evaluate the accuracy in the sample  $s_3$  with C fixed.

#### end for

• Keep the value of C with the maximum accuracy in  $s_3$ , and the associated values of  $\alpha$ ,  $\omega$ , and the set  $\mathcal{V}$ .

**Output:** optimal parameters C and  $\omega$ , optimal classification coefficients  $\alpha$ , the selected features in  $\mathcal{V}$ , and the corresponding accuracy estimated from  $s_4$ .

### 4.3 Numerical Experiments

This section is devoted to the computational experience on the algorithm proposed in this chapter for classification and feature selection of hybrid functional data. Section 4.3.1 is devoted to the description of the experiments performed. In Section 4.3.2, the different databases are described. Section 4.3.3 presents several algorithms used to compare our proposed methodology. Finally, Section 4.3.4 outlines the details of the sensitivity analysis, and Section 4.3.5 gives the results of our proposal.

#### 4.3.1 Description of the Experiments

This section explains the details of the computational experiments carried out to show the efficiency of our approach. Algorithm 5 has been run on the databases described in Section 4.3.2. Each data set is split into four parts,  $s_1 - s_4$ , as explained in Section 4.2. Since the features of the hybrid functional data may have different scales, we have normalized them before applying our approach, as explained in e.g., [Wang and Yao, 2015].

When selecting the most informative covariates, we remove those features with  $\omega_v \leq 10^{-5}$ , i.e.,  $\delta = 10^{-5}$ . The stopping criterion is fulfilled when the number of iterations is equal to five. The parameter C ranges in the set  $\{2^{-7}, \ldots, 2^7\}$  on a logarithmic scale.

In order to have stable results, Algorithm 5 was run five times, and the boxplot of the accuracy computed on  $s_4$  is reported. To compare our methodology with others, we consider the approaches detailed in Section 4.3.3.

Furthermore, we executed a sensitivity analysis of the parameters involved in the algorithm. The details of this analysis are shown in Section 4.3.4.

All the experiments were coded in R, [Core Team, 2017], and carried out in a cluster with 2 terabytes of RAM memory at 6.2 TFlops, running CentOS Linux 7.3.

#### 4.3.2 Description of the Data Sets

Two simulated examples, namely *batch* and *trigonometric*, and two real databases, denoted here as *pen* and *retail*, were considered. A summarized description of the data sets, including the number of individuals in the sample, the number of elements of each class, and the number of static and functional covariates, is given in Table 4.1.

	#individuals	#functional	#static	#records	#records
		covariates	covariates	label -1	label +1
batch	1000	3	2	500	500
${ m trigonometric}$	1000	2	2	500	500
pen	296	2	1	171	125
retail	3602	5	1	1776	1826

Table 4.1: Data description summary

The functional covariates of batch and trigonometric data sets have already been explained in Section 2.3.2, more specifically on Equations (2.8) and (2.9), respectively. Therefore, in this section we will only provide the details of their static covariates. By contrast, a complete description of the databases pen and retail is given. Figures 4.1-4.4 show respectively a subset of ten functions of the four data sets. The functional features

are depicted in a standard x-y plot, where the solid blue lines and the dashed red lines indicate respectively the individuals with class -1 and +1. On the other hand, for the sake of visualization, static covariates are shown in boxplots (or barplots in the case of categorical features), with the individuals with classes -1 and +1 colored in blue and red respectively.

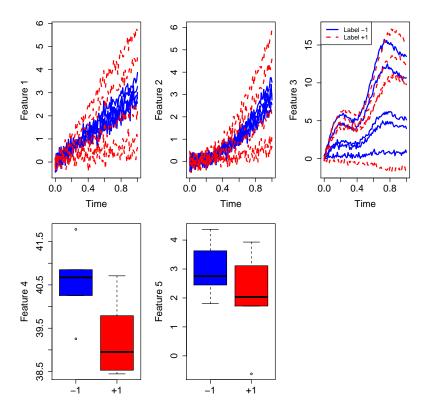


Figure 4.1: Sample of batch data set

#### Batch data set

The three functional covariates of the first data set, batch, are given in Equation (2.8). Note that the class label  $Y_i$  just depends on the value  $\nu_0$  in the definition of  $X_3$ . Therefore, the third covariate is the only relevant feature for classification, if just the functional components of the hybrid functional data is taken into account.

To complete the data set, we added two real variables,  $X_4$  and  $X_5$ , in agreement with (4.3) and (4.4) for all i = 1, ..., 1000:

$$X_{i4} \sim \begin{cases} \mathcal{N}(\mu = 39, \sigma^2 = 1), & \text{if } Y_i = +1 \\ \mathcal{N}(\mu = 40, \sigma^2 = 1), & \text{if } Y_i = -1 \end{cases}$$
(4.3)

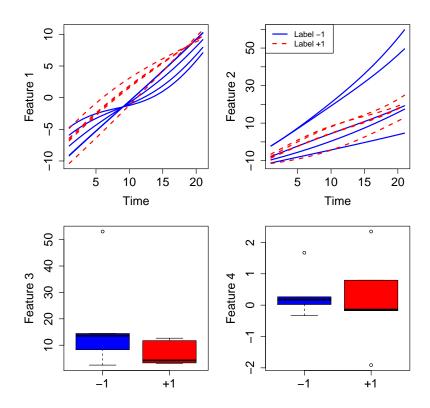


Figure 4.2: Sample of trigonometric data set

$$X_{i5} \sim \begin{cases} \mathcal{N}(\mu = 2, \sigma^2 = 1), & \text{if } Y_i = +1 \\ \mathcal{N}(\mu = 3, \sigma^2 = 1), & \text{if } Y_i = -1 \end{cases}$$
 (4.4)

where  $\mathcal{N}(\mu, \sigma^2)$  indicates a normal distribution of mean  $\mu$  and variance  $\sigma^2$ .

#### Trigonometric data set

The *trigonometric* database consists two functional features and two scalar covariates. Functional components are shown in Equation (2.9).

The remaining static variables  $X_3$  and  $X_4$  have been created according to (4.5) and (4.6)

$$X_{i3} \sim \begin{cases} \mathcal{N}(\mu = 0, \sigma^2 = 225), & \text{if } Y_i = +1\\ \mathcal{N}(\mu = 20, \sigma^2 = 400), & \text{if } Y_i = -1 \end{cases}$$
(4.5)

$$X_{i4} \sim \mathcal{N}(\mu = 0, \sigma^2 = 1), \quad \forall i$$
 (4.6)

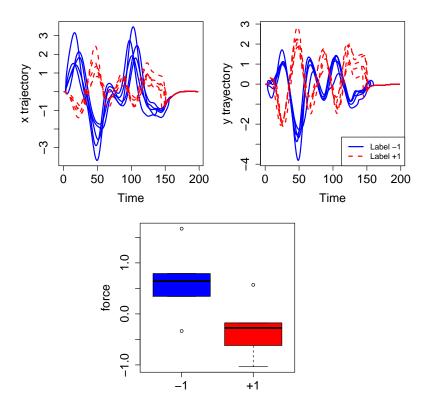


Figure 4.3: Sample of pen data set

#### Pen data set

The pen data set comes from the Character Trajectories Dataset of the UCI Machine Learning repository [Dheeru and Karra Taniskidou, 2017] and have been used in papers such as [Hubert et al., 2015, 2017]. It contains the x and y trajectories, and the force applied to write multiple characters.

The aim here is to discriminate between two selected characters, m and z. The two functional features here considered are the x and y trajectories, while the pen tip force is the static covariate.

#### Retail data set

The data set retail is extracted from the Online Retail Data Set of the UCI Machine Learning Repository [Dheeru and Karra Taniskidou, 2017], and has been studied in e.g., [Chen et al., 2012]. It contains the monthly transactions of the customers of a UK-registered non-store, online retail during the first 10 months out of the 13 months available. The aim is to predict whether customer will buy products in the last three months. Customers that only purchased items in the last three months were removed from the data set since no purchase history is available for constructing covariates,

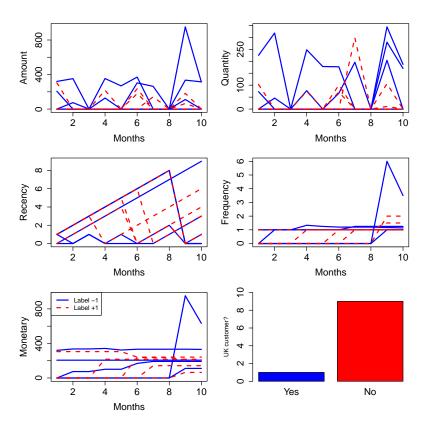


Figure 4.4: Sample of retail data set

yielding an amount of 3,602 individuals instead of the original number of 3,630. The first functional feature is the amount of money spent by the customers. The second functional variable denotes the quantity of products bought. The last three functional covariates are the variables Recency, Frequency, and Monetary, described in [Chen et al., 2012]. Finally, the scalar variable is a binary feature which indicates whether the customers come from the UK, or not.

#### 4.3.3 Comparative Algorithms

Since, to the best of our knowledge, no methodology has been reported in the literature of classification to deal with feature selection in hybrid functional data, we suggest some techniques with which to compare our proposal, described in what follows.

#### Functional SVM (FSVM)

The first alternative method corresponds to the SVM algorithm for functional data. In this case, the different types of features, i.e., functional or static, are not taken into account, and no variable selection is made.

A grid search is performed to obtain the scalar parameters C and  $\omega$  based on the

following set of values:  $\{2^{-7}, \dots, 2^7\}$  on a logarithmic scale. The SVM problem (1.15) is solved with an isotropic Gaussian kernel in (4.7):

$$K(X_i, X_j, \omega) = \exp\left(-\omega \left(\sum_{v=1}^{p_1} \int_0^T \left(X_{iv}(t) - X_{jv}(t)\right)^2 dt + \sum_{v=p_1+1}^{p_2} \left(X_{iv} - X_{jv}\right)^2\right)\right)$$
(4.7)

for  $X_i, X_j \in \mathcal{X}$ . The scalar parameters C and  $\omega$  yielding the best accuracy in the validation sample are kept. Finally, the accuracy for the selected parameters C and  $\omega$  is computed as a measure of performance.

#### Static SVM (SSVM)

The second alternative corresponds to the SVM problem when the functions of the hybrid functional data are summarized in scalar values.

We solved the SVM problem (1.15) on the training set, for each of the values of C and  $\omega$  belonging to the set  $\{2^{-7}, \ldots, 2^7\}$  in logarithmic scale. The best values of C and  $\omega$  are chosen by measuring the accuracy on the validation sample, and then, the final results are estimated with the optimal values for C and  $\omega$  on the testing sample.

In this case, the kernel function used in Problem (1.15) is the isotropic kernel in (1.22) for multivariate data,  $K(Z_i, Z_j)$ , in which a transformation of  $X_i$ , namely  $Z_i$ , is used. Two different transformations  $Z_i$  are here suggested. In the first one, each functional component  $X_{iv}(t)$ ,  $v = 1, \ldots, p_1$  is summarized in a 4-dimensional vector which includes the mean value, the standard deviation, the minimum and the maximum values. Moreover, we add the values of the static covariates  $X_{iv}$ ,  $v = p_1 + 1, \ldots, p_1 + p_2$ . Such transformation  $Z_i$  is given in (4.8):

$$Z_{i} = \left( \max(X_{i1}(t)), \operatorname{sd}(X_{i1}(t)), \min(X_{i1}(t)), \max(X_{i1}(t)), \ldots, \right.$$

$$\left. \operatorname{mean}(X_{ip}(t)), \operatorname{sd}(X_{ip}(t)), \min(X_{ip}(t)), \max(X_{ip}(t)), \right.$$

$$\left. X_{i p_{1}+1}, \ldots, X_{i p_{1}+p_{2}} \right)$$

$$(4.8)$$

The second transformation proposed consists of substituting each functional covariate by its value at the H discretization points,  $t_1, \ldots, t_H$ , where it has been recorded. We also add the values of the static covariates. In other words, the transformation  $Z_i$  turns out to be as in (4.9):

$$Z_{i} = \left(X_{i1}(t_{1}), \dots, X_{i1}(t_{H}), \dots, X_{ip_{1}}(t_{1}), \dots, X_{ip_{1}}(t_{H}), X_{ip_{1}+1}, \dots, X_{ip_{1}+p_{2}}\right) (4.9)$$

#### LiblineaR

The last comparative algorithm comes from the R library LiblineaR. Such library combines different types of loss functions and regularization schemes, yielding eight versions

for the classification problem, including the well-known Lasso-SVM approach. Here, we have compared our proposal with the eight possibilities by previously transforming the hybrid functional data into finite-dimensional vectors as in (4.9).

As in the previous algorithms, the scalar parameter C is sought in the set  $\{2^{-7}, \ldots, 2^7\}$  in logarithmic scale, and the value yielding the best accuracy on the validation sample is saved. Finally, the accuracy for the best value of C is given as result.

In all the above-explained algorithms the data set is divided into three parts, namely, training, validation, and testing. For the sake of comparison with our proposed approach, the division is made in such a way that the testing sample coincides exactly with the so-called sample  $s_4$  described in Section 4.2. Furthermore, all the comparative algorithms were run five times for each data set, as stated in Section 4.3.1. The accuracy over all the runs, measured on the testing sample, is used as a performance metric and is depicted in boxplots.

#### 4.3.4 Sensitivity Analysis

In order to study the robustness of our proposed algorithm with respect to the parameters involved, a sensitivity analysis has been performed. We tested how sensitive our methodology is to the regularization parameter C, the threshold at which the features are removed  $\delta$ , the maximum number of iterations of the alternating approach, and the bandwidths  $\omega_v$ ,  $v = 1, \ldots, p_1 + p_2$ .

First, we ran five times the alternating approach of Algorithm 5 to test the sensitivity of the algorithm with respect to the parameter C, computing the average accuracy over the k folds, measured on  $s_3$ .

Second, the sensitivity analysis for the elimination threshold  $\delta$  is performed by running Algorithm 5 five times for the values given in the set  $\{10^{-10}, \ldots, 10^{-5}\}$  in logarithmic scale. The average accuracy is estimated on  $s_3$ .

Third, Algorithm 5 was run five times with the maximum number of iterations in the set  $\{5, \ldots, 10\}$ . The average accuracy measured on the sample  $s_3$  was then computed.

Finally, we studied the convergence of the bandwidths. Note that, in this case, convergence does not mean that the bandwidths tend to the same value in all the runs, but that they are greater or smaller than  $\delta$ , and thus they yield the same features in most of the cases. For each of the five times that Algorithm 5 was run, the optimal values of the bandwidths were obtained. The goal is to assess the importance of the variables visually.

In all the sensitivity analyses carried out, the remaining parameters not considered in the study took the values given in Section 4.3.1. For instance, when the sensitivity with respect to C was analyzed, the elimination threshold was equal to  $10^{-5}$ , and the maximum number of iterations of the alternating approach was set to five.

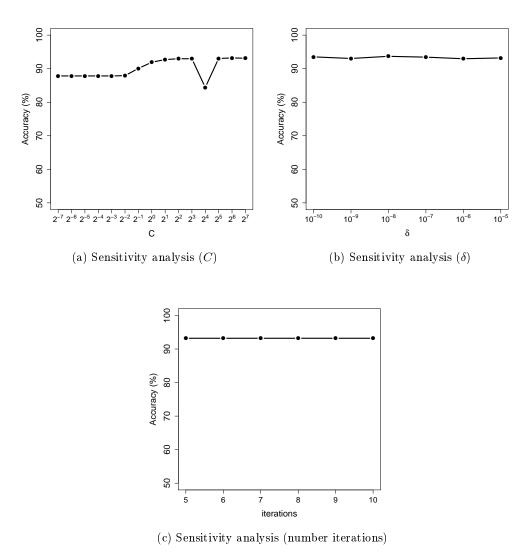


Figure 4.5: Results of the sensitivity analysis for the batch data set

#### 4.3.5 Results

Algorithm 5 and all the comparative methods of Section 4.3.3 have been run five times. Boxplots of the accuracy on the testing sample are given to test the efficiency of our proposal. Particularly, in the boxplots, our approach is denoted by *alt*, and the FSVM strategy of Section 4.3.3 is marked as f, the SSVM method for the finite-dimensional data in (4.8) and (4.9) are denoted by st and disc, respectively, finally, the accuracy results of the eight classification methodologies of LiblineaR in Section 4.3.3 are indicated by  $r_0, r_1, \ldots, r_7$ , since the parameter in the R function that states which out of the eight methods is used, goes from 0 to 7.

Plots of the results of sensitivity analysis explained in Section 4.3.4, are also depicted

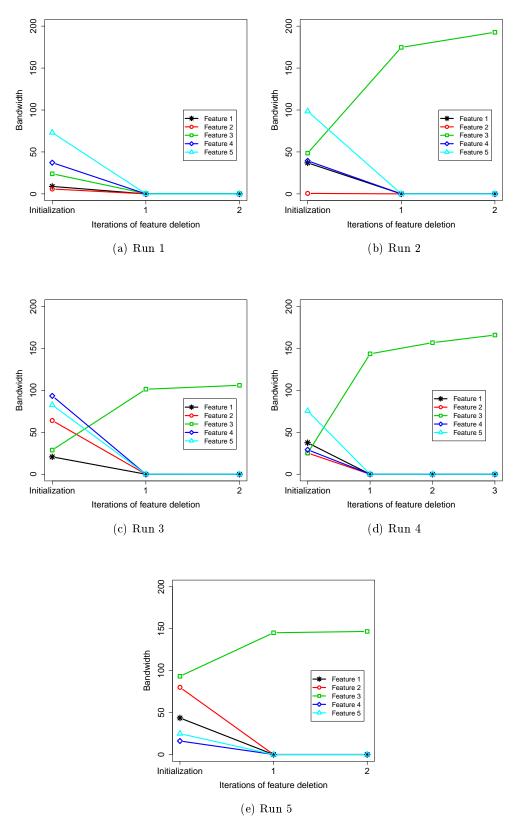


Figure 4.6: Convergence of the bandwidths for the batch data set

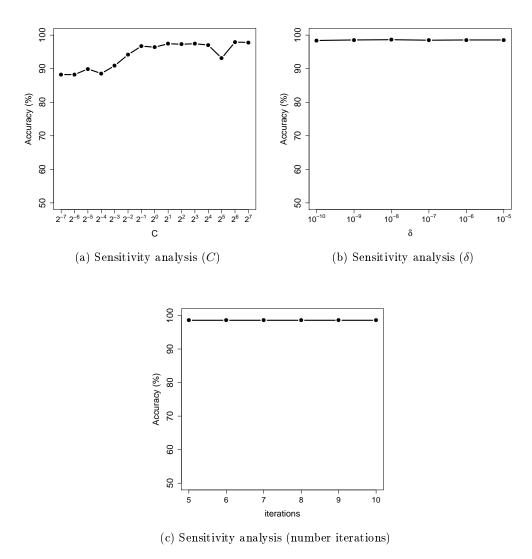


Figure 4.7: Results of the sensitivity analysis for the trigonometric data set

in Figures 4.5 - 4.12.

More details about the classification performance on the tested data sets are given in the following lines.

#### Batch data set

Figure 4.13 shows the boxplots of the accuracy when comparing our proposal and the remaining methods. It is quite apparent that the proposed methodology yields better accuracy and we are able to identify the most informative features as a byproduct. In fact, the third variable was selected to be important by our algorithm in all the five runs. Remember that this feature is the only functional covariate which is correlated with the target variable. In the third run, for instance, we obtain the following optimal

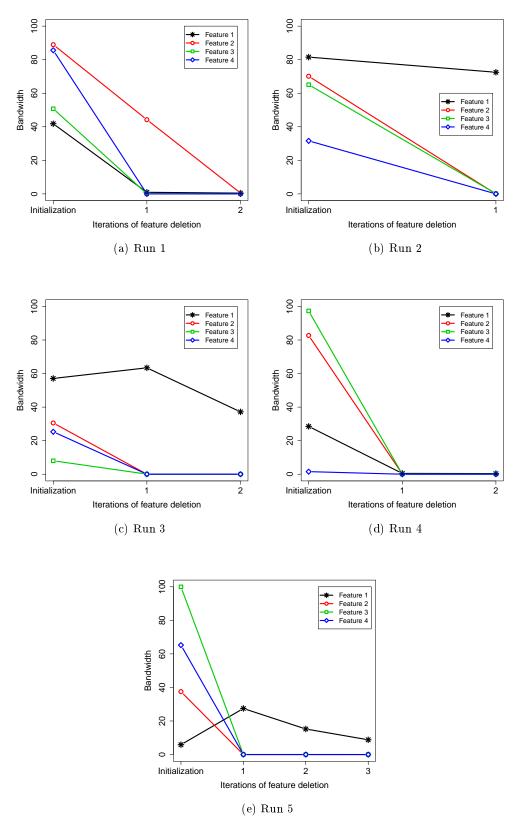


Figure 4.8: Convergence of the bandwidths for the trigonometric data set

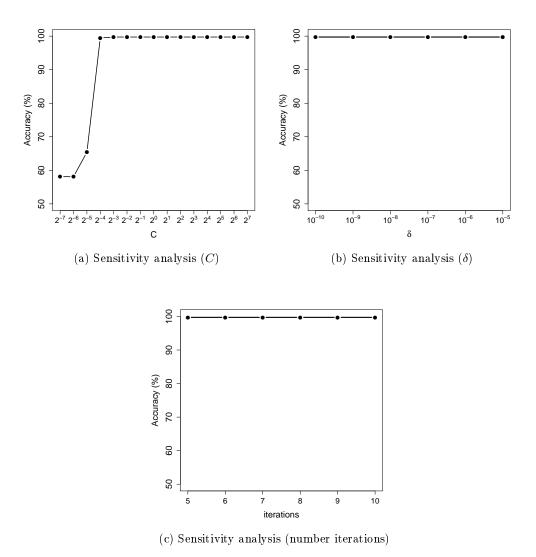


Figure 4.9: Results of the sensitivity analysis for the pen data set

bandwidth:  $\omega = (0, 0, 165.9076, 0.0703, 0)$ , i.e., the third and the fourth variables are identified as relevant. Notice that our methodology is not influenced by the static or functional nature of the covariates. In fact, in this example, one variable of each type is selected. Regarding the sensitivity analysis of the parameters, we observe that the value of C should be carefully chosen since, as can be seen in Figure 4.5(a), the resulting accuracy depends on the value of C. By contrast, our proposal is robust with respect to the elimination threshold  $\delta$  and the number of iterations of the alternating approach, as shown by the stable behavior in Figures 4.5(b) and 4.5(c), respectively.

Finally, in Figure 4.6 we can see how the optimal values of the bandwidths evolve in the five runs. We observe that, independently of the initial bandwidths selected, the bandwidth associated with the third variable tends toward a value greater than zero.

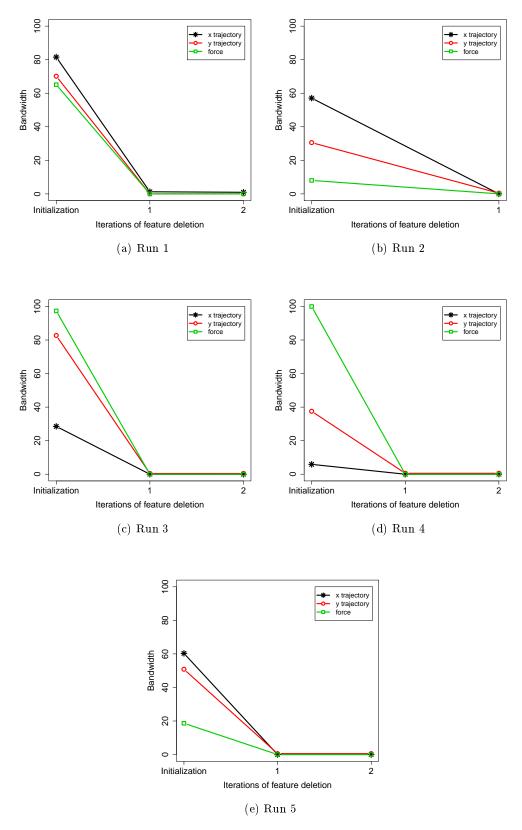


Figure 4.10: Convergence of the bandwidths for the pen data set

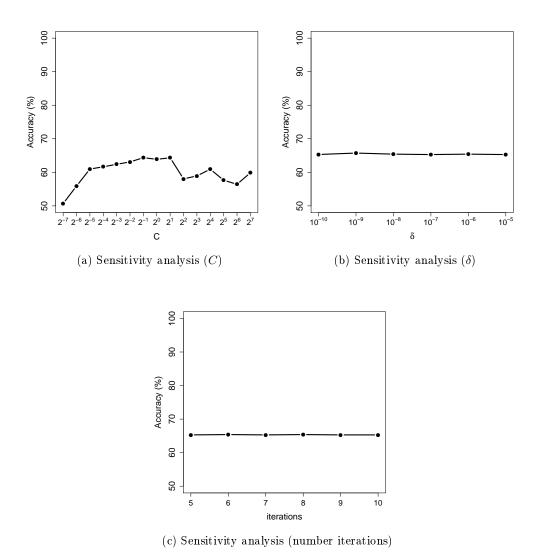


Figure 4.11: Results of the sensitivity analysis for the retail data set

#### Trigonometric data set

Figure 4.14 shows that our proposal improves the performance of the comparative algorithms.

With respect to the feature selection output, features one and three are selected in the five runs, and variable two in three out of five. Indeed, the fourth run gives  $\omega = (0.3758, 0.1281, 0.0929, 0)$  as optimal solution.

Focusing on the sensitivity analysis with respect to  $\delta$  and the number of iterations, stability in the results is obtained. Nevertheless, the value of C has an important role in the accuracy values, as seen in Figure 4.7.

The evolution of the values of the bandwidths in all the five runs is depicted in

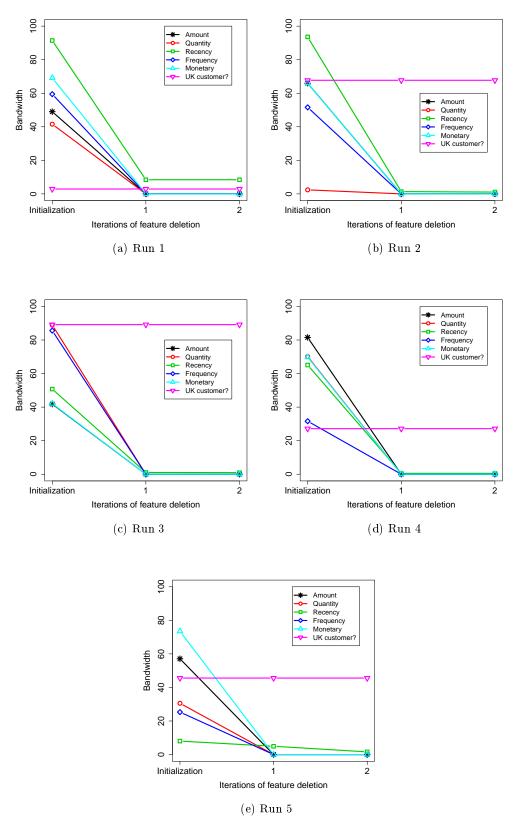


Figure 4.12: Convergence of the bandwidths for the retail data set

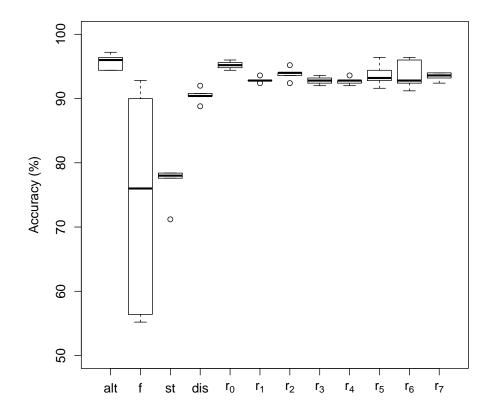


Figure 4.13: Accuracy of batch data set in all the algorithms performed

Figure 4.8.

#### Pen data set

We conclude from Figure 4.15 that our methodology is comparable with the remaining strategies. Moreover, we select just one variable out of three in two of the five runs. The evolution of the bandwidths values can be seen in Figure 4.10.

In this example, the value of C is critical, as can be observed in Figure 4.9(a), since the difference between the best and the worst case is around 40 points. However, our method is robust with respect to  $\delta$  and the number of iterations, as shown in Figures 4.9(b) and 4.9(c).

#### Retail data set

Figure 4.16 presents the accuracy boxplots of all the algorithms tested. We observe that our proposal yields comparable results with the remaining methodologies. Moreover,

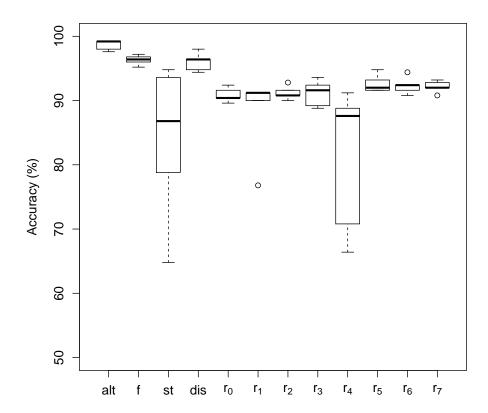


Figure 4.14: Accuracy of trigonometric data set in all the algorithms performed

the selected variables are the third and sixth in four of five runs. As an illustration, the optimal bandwidth in one of these runs is  $\omega = (0,0,1.5887,0,0,45.5919)$ . Feature 3 and Feature 6 correspond to Recency (number of months since the last purchase) computed for each of the 10 months, and UK Customer (a binary variable that indicates whether the customer comes from the UK). Since our objective is to predict whether a customer will buy products or not in the last three months, it seems that it is important to know the elapsed number of months since the last purchase. In addition, we observe that the customer origin plays an important role; customers in the UK tend to buy less than foreign customers.

Similar conclusions to the ones shown in the rest of the examples can be stated with respect to the sensitivity analysis.

In this example, it is even more clear that the choice of the parameter C is a crucial issue for obtaining good accuracy, as seen in Figure 4.11(a).

Figures 4.11(b) and 4.11(c) show again that the elimination threshold  $\delta$  and the number of iterations do not affect the effectiveness of our approach.

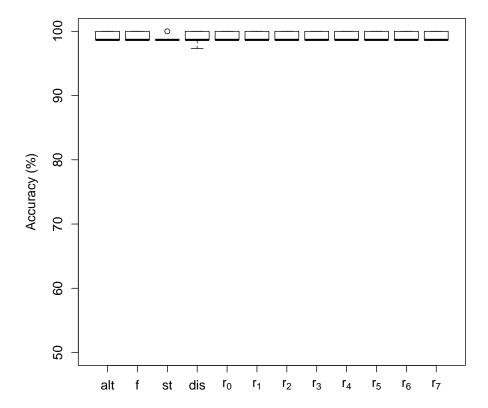


Figure 4.15: Accuracy of pen data set in all the algorithms performed

In Figure 4.12 we can observe the evolution of the values of the different bandwidths, converging in a small number of iterations.

#### 4.4 Conclusions and Extensions

In this chapter, we have shown how a feature selection strategy can be embedded in the well-known SVM technique to get the most informative covariates of hybrid functional data.

To do this, we have modified the standard Gaussian kernel by associating a bandwidth to each variable. Such bandwidths and the rest of the SVM parameters are sought via a bilevel optimization problem solved with an alternating approach. Instead of minimizing the misclassification rate, we propose to maximize the Pearson correlation coefficient between the class label and the score. Other measures such as the correlation in [Torrecilla Noguerales, 2015] can also be applied.

A sensitivity analysis of the setting parameters involved in our approach was made

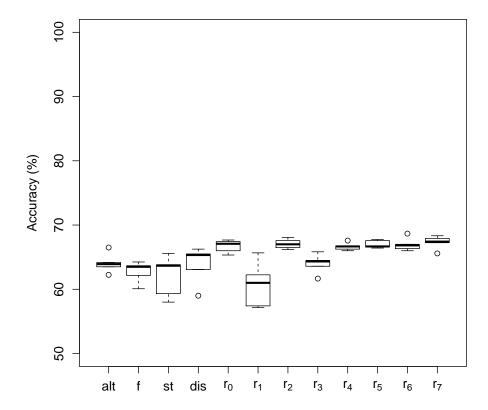


Figure 4.16: Accuracy of retail data set in all the algorithms performed

to show its robustness. We observe that the choice of the parameter C is critical to yield good classification rates. Some standard cross-validation methods may be used to get a good value of C. In contrast, the elimination threshold and the maximum number of iterations allowed in the alternating approach do not affect the accuracy obtained. Moreover, the values of the bandwidths associated with the features converge in few iterations to their final value.

In our proposal, we use standard optimization techniques to solve Problems (1.15) and (4.2). As a future research line, we could develop more efficient optimization strategies compatible with the world of Big Data, e.g., methodologies applied to Problem (1.15) which do not need the computation of the whole kernel matrix, or the use of stochastic gradients to iterate in the bandwidth parameters of Problem (4.2).

We have restricted ourselves to binary classification. The extension to related fields, such as multiclass classification or regression, deserves further study.

## Chapter 5

# SVR with Functional Data

5.1. Introduction 93

#### 5.1 Introduction

In contrast to what is analyzed in previous chapters, in this chapter we focus on functional regression, [Ferraty et al., 2010; Hernández et al., 2007; James et al., 2009; Kneip et al., 2016; Müller and Stadtmüller, 2005], one of the most challenging problems in FDA. Particularly, we are interested in the prediction of a scalar response, based on the information provided by multivariate functional data.

Predictor-response relationships are harder to be found and interpret as the dimension of the data becomes larger, or even infinite, as in our case. Selecting from the whole time interval a finite and small set of time instants can be understood as a variable selection strategy from an infinite set of features, which may lead to better predictions.

Several works in the literature have addressed the problem of variable selection in univariate functional data, as is outlined in Section 1.3. However, with respect to the variable selection in multivariate regression with functional data, scarce methodologies has been reported in the literature. We can just highlight the work in [Blanquero et al., 2017] for classification problems, based on Chapter 2 of this dissertation.

Hence, the problem of optimal selection of time instants in (multivariate) functional regression, as addressed in this chapter, is new in the literature. More precisely, we focus on SVR, a renowned methodology for regression problems, that allows us to capture nonlinearities. We stress the importance of developing a methodology able to handle multivariate functional data; first of all, on top of making the approach applicable to many more contexts, one can always associate with each functional data the function itself, as well as the functional data of its derivatives, allowing to use information on the data values as well as information related to monotonicity or convexity, for instance, as done in Chapter 2. Taking advantage of the functional behavior of the data, the selected features act as continuous decision variables in the optimization model. Therefore, the so-obtained optimization problem may be solved by means of continuous optimization techniques. If instead, the data were treated as multivariate finite-dimensional data, combinatorial problems, very hard to solve due to the exponential number of candidate solutions, would have been obtained. Furthermore, following the scheme of Chapter 2, our proposal handles in the very same way univariate and multivariate functions.

The remainder of this chapter is structured as follows. In Section 5.2, we detail the formulation and the solution approach, as well as the way to choose the best number of time points. Section 5.3 describes the numerical results obtained with our approach and we finish in Section 5.4 with some conclusions.

#### 5.2 The Variable Selection Problem

Section 5.2.1 is devoted to introduce the main concepts and notation used in the time instant selection problem. In Section 5.2.2 the problem of variable selection in SVR with functional data is formulated, and a resolution strategy is proposed.

#### 5.2.1 Preliminaries

As denoted along this dissertation, let s be a sample of individuals  $\{(X_i, Y_i)\}_{i \in s}$ , where  $Y_i \in \mathbb{R}$  and  $X_i \in \mathcal{X} = \mathcal{F}^p$  is formed by p functional components, as in Equation (1.1) with  $X_{iv} : [0,T] \to \mathbb{R}$  belonging to the class  $\mathcal{F}$  of d-times continuously differentiable functions on the time interval [0,T]. The goal is to find a rule able to predict the response  $Y \in \mathbb{R}$  from the information provided by the multivariate functional data  $X \in \mathcal{X}$ .

Our proposal can be applied to pure multivariate functional data, but also on univariate functional data,  $X(t) \in \mathcal{F}$ . The simplest way to do that would be just to consider p = 1. However, a more sophisticated form is applied, in which univariate data can be converted to multivariate by means of their derivatives, as done in Equation (2.2). Using the very same strategy, the high-order information provided by the derivatives can be also included in the pure multivariate functional data,  $X(t) \in \mathcal{F}^p$ , yielding data of the form (2.3).

In many real-life applications, the original functional data  $X_i$  are only known in some time instants. Hence, smoothing techniques, e.g., [De Boor, 1978; Friedman et al., 2001b], should be applied as a preprocessing step in those cases, so that an approximation to the original function  $X_i$  can be obtained from the observed time instants.

Moreover, if the higher-order information is taken into account, one can first compute the finite increments, and then smooth the sequence of increments. An example of the first derivative of X(t) in the discretization point  $t_h$  is given in (2.4). This process should be repeated for all the instants  $t_h$  in the discretized function and for any higher-order derivative. Such discretized derivatives will be then smoothed with some of the previously mentioned interpolation techniques.

#### 5.2.2 Problem Formulation

The aim of this chapter is to find time instants  $t_1, \ldots, t_H$  in such a way that the relationship between the functional predictor X and the scalar response Y, obtained via the SVR problem in (1.17), is as good as possible, in some sense to be specified.

Two very different types of parameters can be found in the variable selection problem. First, the H time instants  $\mathbf{t} = (t_1, \dots, t_H)$  satisfying that  $0 \le t_1 \le \dots \le t_H \le T$ , and second, the parameters  $\varepsilon$ , C,  $\omega$  involved in the SVR problem (1.17), and in the Gaussian kernel (1.27), respectively.

Following the strategy of Chapters 2, 3 and 4, we propose to find the optimal parameters  $\varepsilon$ , C,  $\omega$ ,  $\mathbf{t}$ , by combining a grid search for the parameter  $\varepsilon$ , and the resolution of a bilevel optimization problem for the remaining parameters. This bilevel optimization problem aims at minimizing the performance measure given by the sum of the squared residuals (SSR) between the real response value  $Y_i$  and the score  $\hat{Y}(X_i(\mathbf{t}), C, \omega, \nu, \nu^*)$  in (1.18).

In order to obtain more stable results and avoid overfitting, we proceed as in previous chapters, and we divide the sample s into four independent samples,  $s_1$ ,  $s_2$ ,  $s_3$  and  $s_4$  as follows. We first divide the sample into k folds. Then, k-1 folds are randomly selected and divided into three parts, yielding samples  $s_1$ ,  $s_2$  and  $s_3$ . The remaining fold forms sample  $s_4$ . Samples  $s_1$  and  $s_2$  play the role of training samples, whilst  $s_3$  and  $s_4$  are the validation and testing samples, respectively. Particularly, the independent sample  $s_1$  is used to obtain the optimal values of  $\nu$  and  $\nu^*$  by solving Problem (1.17) for fixed C,  $\omega$ ,  $\mathbf{t}$  and  $\varepsilon$ . Sample  $s_2$  is employed to compute the residuals between the response  $Y_i$  and the score  $\hat{Y}(X_i(\mathbf{t}), C, \omega, \nu, \nu^*)$ . Sample  $s_3$  is utilized to tune the parameter  $\varepsilon$  by evaluating the performance measure SSR for all the values in the grid, and keeping the parameter yielding the smallest residual. Finally, sample  $s_4$  is used to estimate the SSR and test the final results.

Hence, for a given  $\varepsilon$ , the bilevel optimization problem is stated as follows:

$$\begin{cases}
\min_{C, \boldsymbol{\omega}, \mathbf{t}, \nu, \nu^*} & \sum_{i \in s_2} (Y_i - \hat{Y}(X_i(\mathbf{t}), C, \boldsymbol{\omega}, \nu, \nu^*))^2 \\
\text{s.t.} & \nu, \nu^* \text{ solves } (1.17) \text{ in } s_1, \\
C \ge 0, & \\
\omega_v \ge 0, v = 1, \dots, p \\
0 \le t_1 \le \dots \le t_H \le T
\end{cases} \tag{5.1}$$

Problem (5.1) can be handled with an alternating algorithm, as also done in Chapters 2, 3 and 4. In the first step of our alternating procedure, Problem (1.17) is solved in sample  $s_1$  for given  $C, \omega$  and  $\mathbf{t}$ , obtaining the optimal SVR variables  $\nu$  and  $\nu^*$ . Problem (1.17) is a quadratic concave maximization problem with linear constraints. Hence, classic local search routines may be applied to find the global optimum. In the second step, for  $\nu$  and  $\nu^*$  fixed, we get the optimal  $C, \omega$  and  $\mathbf{t}$  solving Problem (5.2) in sample  $s_2$ . Problem (5.2) is a continuous optimization problem which is solved by combining standard local searches with a multi-start strategy to avoid getting stuck at bad local optima.

$$\begin{cases}
\min_{C, \boldsymbol{\omega}, \mathbf{t}} & \sum_{i \in s_2} (Y_i - \hat{Y}(X_i(\mathbf{t}), C, \boldsymbol{\omega}))^2 \\
\text{s.t.} & C \ge 0, \\
& \omega_v \ge 0, \ v = 1, \dots, p \\
& 0 \le t_1 \le \dots \le t_H \le T
\end{cases}$$
(5.2)

The alternating approach is run, for a fixed  $\varepsilon$ , until some stopping criteria is met, yielding good values of  $C, \omega, \mathbf{t}, \nu$  and  $\nu^*$ . The value of  $\varepsilon$  is obtained with a grid search, i.e., computing, for each  $\varepsilon$  in the grid, the performance measure SSR on the sample  $s_3$ , and keeping the one with the smallest value.

Finally, to test the efficiency of our approach, we calculate the SSR in a fourth independent sample  $s_4$ .

The pseudocode of our proposal can be seen in Algorithm 6.

#### Algorithm 6 Heuristic for variable selection

#### Input: H.

- Randomly split the sample s into  $s_1, s_2, s_3$  and  $s_4$ .
- Compute the derivatives of the functional data.
- Smooth the data with some interpolation technique.

for  $\varepsilon$  in the grid do

#### Alternating Procedure

#### repeat

- 1. For  $C, \omega, \mathbf{t}$  fixed, calculate the parameters  $\nu, \nu^*$  of the SVR problem (1.17) using the sample  $s_1$ .
- 2. Fixed  $\nu$  and  $\nu^*$  fixed, compute  $C, \omega, \mathbf{t}$  by solving Problem (5.2) sample  $s_2$ .

#### until stopping criteria

• Evaluate the performance measure SSR using the sample  $s_3$  for the  $\varepsilon$  fixed in the grid.

#### end for

• The optimal value of  $\varepsilon$  is the one with minimum performance measure SSR in  $s_3$ , and the optimal values of  $\nu$ ,  $\nu^*$ , C,  $\omega$  and  $\mathbf{t}$  are the parameters associated to the optimal  $\varepsilon$ .

**Output:** Optimal parameters  $\varepsilon, C, \omega, \mathbf{t}, \nu, \nu^*$ , and the performance measure SSR estimated on  $s_4$ .

In order to enhance the performance of the heuristic, we propose to define, as in Chapters 2 and 3, a series of nested models of increasing complexity, in which the optimal solution of a simple model is employed as initial solution in a more complex case. In other words, when seeking the h + 1 time instants in  $\mathbf{t}^{h+1}$ , one considers as initial solution a perturbation of  $\mathbf{t}^h$ , i.e., the optimal solution obtained when only h time instants are sought. Therefore, if we want to find the H time instants that best predict, we consider the easy-to-tune structure of the simple cases as a simplification of the complex models, in such a way that the (suboptimal) solution  $K(X_i, X_j, \boldsymbol{\omega}^h, \mathbf{t}^h)$ 

is used as initial solution for kernel  $K(X_i, X_j, \boldsymbol{\omega}^{h+1}, \mathbf{t}^{h+1})$ . More specifically, the initial solution of the parameters C and  $\boldsymbol{\omega}$  in the level h+1 are set as the optimal values of such parameters in the level h,  $\boldsymbol{\omega}^h_{opt}$  and  $C^h_{opt}$ , respectively. Moreover, the choice of the initial solution of the h+1 time instants in  $\mathbf{t}^{h+1}$  is made by selecting a random value  $\tau \in [0,T]$ , and including it in the appropriate position of the optimal solution of the level h,  $\mathbf{t}^h_{opt}$ . In other words,  $\mathbf{t}^{h+1}_{opt} = \sigma(\tau, \mathbf{t}^h_{opt})$ , where  $\sigma$  is a function that sorts in increasing order the time instants  $\mathbf{t}^h_{opt}$  and  $\tau$ .

The pseudocode of the nested heuristic is outlined in Algorithm 7.

Observe that our proposed heuristic differs from a greedy approach [Berrendero et al., 2018; Ferraty et al., 2010], since our proposal utilizes the optimal solution of level h just as starting solution of the level h + 1, allowing a very different solution for level h + 1 than the one obtained in the previous level, h. Consequently, our approach gives more flexibility to the model.

Moreover, when the exact number of selected time instants, H, is unknown, our algorithm has the advantage of allowing us to build a trajectory of the performance measure SSR in terms of the number of time instants. It may be very useful when a list of models with different complexity is needed.

#### 5.3 Numerical Experiments

This section is devoted to the computational experience on the proposed models. In Section 5.3.1 we describe the experiments performed. Section 5.3.2 details the data sets used to test our methodology, and Section 5.3.3 analyses the numerical results.

#### 5.3.1 Description of the Experiments

Algorithm 7 is run to show the usefulness of our approach, i.e., to test whether the predictions obtained when H time instants are carefully chosen are comparable, or even better, to the residuals achieved when the full time interval is considered.

To get stable results, k-fold cross-validation is accomplished. The number k of folds is dependent on the data set. More precisely, if a database is big, then k = 10 is chosen. By contrast, in the small data sets leave-one-out is performed, i.e., k coincides with the number of observations. Here, we consider that a database is big if it has more than 100 observations. More details about the cardinality of the databases can be seen in Table 5.1. Algorithm 7 is run k times, one per fold. In each run, the data set is split into four parts,  $s_1 - s_4$ , as described in Section 5.2.2. As the output of our methodology, we provide the average SSR estimated on the test sample  $s_4$  over all the folds.

The number of runs in the multi-start is five. The Alternating Procedure is stopped either when ten iterations are executed or when the difference between the objective values of two consecutive iterations is lower than  $10^{-5}$ . The maximum num-

#### Algorithm 7 Nested heuristic for variable selection

Input: H, nested kernels  $K(X_i, X_j, \boldsymbol{\omega}^1, \mathbf{t}^1) \prec \ldots \prec K(X_i, X_j, \boldsymbol{\omega}^H, \mathbf{t}^H)$ .

- Randomly split the sample s into  $s_1$ ,  $s_2$ ,  $s_3$  and  $s_4$ .
- Compute the derivatives of the functional data.
- Smooth the data with some interpolation technique.

#### for $\varepsilon$ in the grid do

#### Initialization:

- h := 1.
- Randomly select an initial solution  $\tilde{C}^1 \in [0, +\infty)$ ,  $\tilde{\omega}^1 \in [0, +\infty)^p$  and  $\tilde{\mathbf{t}}^1 := t_1 \in [0, T].$
- Set  $(C, \boldsymbol{\omega}, \mathbf{t}) := (\tilde{C}^1, \tilde{\boldsymbol{\omega}}^1, \tilde{\mathbf{t}}^1)$ .

#### while $h \leq H$ do

- 1. Run the Alternating Procedure of Algorithm 6 for  $K(X_i, X_j, \boldsymbol{\omega}^h, \mathbf{t}^h)$ , starting from  $(C, \boldsymbol{\omega}, \mathbf{t})$  and yielding  $(C_{opt}^h, \boldsymbol{\omega}_{opt}^h, \mathbf{t}_{opt}^h)$  as solution, using samples  $s_1$  and  $s_2$ .
- $\begin{array}{l} \text{2. Randomly generate } \tau \in [0,T]. \\ \text{3. Set } C^{h+1} := C^h_{opt}, \, \boldsymbol{\omega}^{h+1} := \boldsymbol{\omega}^h_{opt}, \, \mathbf{t}^{h+1} := \sigma(\tau,\mathbf{t}^h_{opt}), \\ (C,\boldsymbol{\omega},\mathbf{t}) := (C^{h+1},\boldsymbol{\omega}^{h+1},\mathbf{t}^{h+1}) \text{ and } h := h+1. \end{array}$
- 4. Evaluate the performance measure SSR over the sample  $s_3$  with  $\varepsilon$  fixed.

#### end while

#### end for

• For each h, the optimal value of  $\varepsilon$  is the one with the minimum performance measure SSR in  $s_3$ . The optimal values of  $\nu$ ,  $\nu^*$ , C,  $\omega$  and  $\mathbf{t}$  are the parameters associated to the optimal  $\varepsilon$ .

**Output:** Optimal parameters  $C^h_{opt}$ ,  $\boldsymbol{\omega}^h_{opt}$ ,  $\mathbf{t}^h_{opt}$ ,  $\forall h$ , the associated coefficients  $\varepsilon, \nu, \nu^*$ , and the performance measure SSR estimated from  $s_4$ .

ber of time instants to be sought is H=20, and the parameter  $\varepsilon$  moves in the set  $\{10^{-4}, 10^{-3}, 10^{-2}, 10^{-1}\}.$ 

All the experiments were carried out on a cluster with 2 Tb of RAM memory at 6.2 TFlops, running CentOS Linux 7.3, and it is coded in R, [Core Team, 2017].

#### 5.3.2Description of the Data Sets

We have tested our proposal on six univariate and two multivariate databases, widely used in the literature on functional regression. The univariate databases are denoted as canadian, [Goldsmith and Scheipl, 2014; James et al., 2009], cookie, [Goldsmith and Scheipl, 2014, DTI, [Goldsmith and Scheipl, 2014], simulated, [Ferraty et al., 2010], sugar, [Aneiros and Vieu, 2014], and tecator, [Ferraty et al., 2010; Goldsmith and Scheipl, 2014; Picheny et al., 2018. Multivariate databases are named as synthetic 1 and synthetic 2 and come from [Matsui and Konishi, 2011]; both of them have the same independent variables and only differ in the response variable. A sample of ten individuals of all the univariate databases is given in Figure 5.1. A sample of the observations of the dataset synthetic 1 (and synthetic 2) is depicted in Figure 5.2. Table 5.1 gives a summarized description of the data sets, including the number of records, the number of time instants where data are discretized, and the number of covariates.

	# records	#time instants	#components
canadian	35	365	1
cookie	72	700	1
DTI	334	93	1
$_{ m simulated}$	1500	100	1
sugar	268	571	1
$synthetic_1$	300	101	3
$synthetic_2$	300	101	3
tecator	215	100	1

Table 5.1: Data description summary

Details about each data set are presented in the following lines.

#### Canadian Data Set

The canadian data set have been studied in e.g., [Goldsmith and Scheipl, 2014; James et al., 2009]. The explanatory variables are formed by the daily temperature along one year measured on 35 Canadian weather stations, as in the rain and regions data set of Section 2.3.2. However, in this chapter the goal is to predict the logarithm of the total annual rainfall.

#### Cookie Data Set

This database can be found in [Goldsmith and Scheipl, 2014] and measures the 72 spectra of cookie dough samples every two nanometers (nm) from 1,100 to 2,498 nm with the aim of predict the percentage of sucrose content.

#### DTI Data Set

The *DTI* data set, [Goldsmith and Scheipl, 2014], consists of 334 observations that measure in 93 points the white matter in the corpus callosum to predict the cognitive performance in order to study multiple sclerosis lesions.

#### Simulated Data Set

According to the example of Section 3.2 of [Ferraty et al., 2010] we have generated 1,500 curves discretized in 100 equispaced points in the interval  $[0, 2\pi]$  following this

structure:

$$X_i(t) = \sum_{\ell=1}^{3} U_{i\ell} \cos\{(3+\ell)t\} + \sum_{\ell=1}^{3} V_{i\ell} \sin\{(4+\ell)t\} + W_i(t-\pi)^2, \quad i = 1, \dots, 1, 500$$

where  $U_{i\ell}$ ,  $V_{i\ell}$ ,  $W_i$ ,  $\ell = 1, 2$ ,  $\forall i$  are uniformly distributed in [0, 1], whereas  $U_{i3}$  and  $V_{i3}$  follow a normal distribution  $\mathcal{N}(0, 0.25)$ , where the second parameter denotes its variance.

For  $i=1,\ldots,1,500$ , the values of the response variable are obtained from the model  $Y_i=r(X_i)+\gamma_i$ , based on the time instants  $t\in\left\{\frac{48\pi}{99},\frac{58\pi}{99},\frac{128\pi}{99}\right\}$  with

$$r(X_i) = X_i \left(\frac{48\pi}{99}\right) + 2X_i \left(\frac{58\pi}{99}\right) X_i \left(\frac{128\pi}{99}\right),$$
 (5.3)

and  $\gamma_i$  independent and identically distributed as  $\mathcal{N}(0, \sigma_{\gamma}^2)$ , with  $\sigma_{\gamma}^2 = 5\% var\{r(X_i)\}$ .

#### Sugar Data Set

The goal of this data set from [Aneiros and Vieu, 2014] is to predict the percentage of ash content from the fluorescence spectra, measured on 571 points of 268 samples of sugar.

#### Tecator Data Set

This data set deals with the near-infrared absorbance spectra of 215 samples of finely chopped pork, measured at 100 equally spaced points from 850 to 1,050 nanometers. It has been previously used in Sections 2.3.2 and 3.4.2. Nevertheless, in this chapter, the response variable represents the fat content. More details can be found in [Ferraty et al., 2010; Goldsmith and Scheipl, 2014; Picheny et al., 2018].

#### Synthetic 1 and Synthetic 2 Data Sets

In this section we have dealt with 300 observations of two data sets, namely  $synthetic\_1$  and  $synthetic\_2$ , generated as in [Matsui and Konishi, 2011]. The three predictor variables are built as follows, for  $t \in [-1, 1]$ :

$$X_v(t) = U_v(t) + \gamma_v, \quad v = 1, 2, 3,$$
 (5.4)

where  $\gamma_v \sim \mathcal{N}(0, 0.025 \cdot (r_v)^2)$  and  $r_v = \max_t(U_v(t)) - \min_t(U_v(t))$ . Furthermore,

$$\begin{split} &U_1(t) = \cos(2\pi(t-a_1)) + a_2t; & a_1 \sim \mathcal{N}(-5, 3^2); & a_2 \sim \mathcal{N}(7, 1) \\ &U_2(t) = b_1 \sin(2t) + b_2; & b_1 \sim \mathcal{U}(3, 7); & b_2 \sim \mathcal{N}(0, 1) \\ &U_3(t) = c_1 t^3 + c_2 t^2 + c_3 t + c_4; & c_1 \sim \mathcal{N}(-3, 1.2^2); & c_2 \sim \mathcal{N}(2, 0.5^2); & c_3 \sim \mathcal{N}(-2, 1); & c_4 \sim \mathcal{N}(2, 1.5^2) \end{split}$$

The response variable Y is given by:

$$Y = g(U) + \nu_0 \tag{5.5}$$

with

$$g(U) = \sum_{v=1}^{3} \int_{-1}^{1} U_{v}(t)\varphi_{v}(t)dt; \quad \nu_{0} \sim \mathcal{N}(0, (c \cdot s)^{2}); \quad s = \max(g(U)) - \min(g(U))$$

$$\varphi_{1}(t) = \sin(2\pi t); \qquad \qquad \varphi_{2}(t) = \sin(\pi t); \qquad \qquad \varphi_{3}(t) = 0$$
(5.6)

The value c of the parameter  $\nu_0$  in (5.6) depends on the multivariate data set. More precisely, c = 0.05 in the database  $synthetic_1$  and c = 0.1 in  $synthetic_2$ .

#### 5.3.3 Results

Figure 5.3 shows the trajectory of the SSR obtained when H time instants are sought, ranging from H = 1 to H = 20. We depict in dotted-red, triangled-blue and crossed-green solid lines the results when d = 0, 1, 2 derivatives are considered, respectively.

To test the performance of our methodology, we use the maximum and minimum SSR values from a set of benchmark procedures in the literature. We indicate the reference SSR values in the cases where they are available, i.e., in data sets simulated, sugar and tecator by depicting them in solid black line (maximum residual), and dashed pink line (minimum residual). More precisely, the benchmark values come from [Ferraty et al., 2010 in simulated and tecator; and from [Aneiros and Vieu, 2014] in sugar. Moreover, in the cases where such reference values are not available, we compare our proposal with the SSR obtained when the full time domain is taking into account. Indeed, we have run Algorithm 7 with the same settings of Section 5.3.1, i.e., number of iterations, stopping criterion, and values of the parameter  $\varepsilon$ , to get the variables  $\nu, \nu^*, C$  and  $\omega$  of Problem (5.1) together with the average of performance measure SSR across folds on exactly the same testing sample  $s_4$ , where variable selection is performed. The results of Algorithm 7 when no variable selection is performed, i.e., the full (time) domain is taken into account, are plotted on dotted red, blue or green line depending if the degree of the derivatives is d=0,1 or 2, respectively. In addition, some parts of the output figures of the databases simulated, synthetic 1 and tecator are zoomed in order to improve the visualization.

On top of that, we will show that high-order information is crucial to achieving good residual values. Hence, Algorithm 7 is run for three different values of the derivatives d=0,1,2, which include, respectively, the situations where just the information of the raw functional data, or their monotonicity, or both their monotonicity and convexity are considered. The exact values of all the SSR are given in Tables 5.2 and 5.3 for comparison purposes.

In addition to the variable selection experiments, we also provide the best number H of time instants, applying the same strategy as in Chapters 2 and 3.

As a general conclusion, looking at Figure 5.3 and Tables 5.2 and 5.3, we state that the high-order information provided by the derivatives is crucial to get good predictions since most of the SSR obtained when monotonicity or both monotonicity and convexity are taken into account are better than the values obtained just using the information of the functional data alone. Moreover, when we compare our approach with the benchmarks in the literature, we conclude that SSR are improved with our method.

With respect to the best number of time instants, H, Figure 5.4 shows the boxplots of the best time instants chosen when the number of time instants to be selected ranges from H = 1 to H = 20.

On top of the overall conclusions given so far, more precise information on each data set is given in the following lines.

#### Canadian Data Set

Figure 5.3(a) and Table 5.2 show the results obtained forn this data set applying our methodology. Although there is not a clear pattern, possibly due to the small size of the data set, we observe that, the larger the number of time instants used, the lower the SSR, yielding in some cases better values when choosing appropriate time points than when using the full domain information, e.g., d = 1 and H = 5.

Regarding the interpretability of the results, [James et al., 2009] affirms that the temperatures in the spring and fall months do have a noticeable effect when predicting the annual rainfall. More specifically, Figure 4 of [James et al., 2009] shows that such an effect is produced around the months of April and November. Figure 5.5 shows the density histogram of the time instant values when H=7 time points are sought using our methodology. We clearly observe that the majority of values are located around the months of April and November independently of the value given to the parameter  $d \in \{0,1,2\}$  exactly as is stated in [James et al., 2009]. Similar results are obtained when  $H \neq 7$ , and therefore no more histogram figures are plotted.

#### Cookie Data Set

It is clear from Figure 5.3(b) and Table 5.2 that the derivative information plays a very important role when seeking the most informative time instants, since the highest SSR are obtained when only the raw data, and not the derivatives are used, i.e., when d = 0. Furthermore, using only a few time instants yields better residuals than using the full time interval, as can be seen, for instance for d = 1 and H = 4.

#### DTI Data Set

If we observe Figure 5.3(c) and Table 5.2, similar results were achieved with d = 0 and H = 6 than when comparing with the full time domain and d = 0.

#### Simulated Data Set

Since the median of the SSR values is given as reference in [Ferraty et al., 2010], in this example we give as output the median values instead of the mean, as the y-axis label of Figure 5.3(d) indicates. Table 5.2 also shows the median values for this database.

On top of that, the response variable is constructed using the evaluation of the predictor variable in three fixed time instants, namely  $\frac{48\pi}{99}$ ,  $\frac{58\pi}{99}$  and  $\frac{128\pi}{99}$ , as expressed in (5.3). Because of this, we have also run Algorithm 7 with the settings given in Section 5.3.1, and fixing such three time instants. The results are depicted in red, blue and green dashed-dotted line for the d = 0, 1, 2 degrees derivatives, respectively.

In the zoomed plot of Figure 5.3(d), it is observed that similar results are obtained with our methodology than with the minimum reference residual (pink dashed line) or even better if the values with d = 0 are inspected.

#### Sugar Data Set

Figure 5.3(e) and Table 5.2 show that noticeable improvements in terms of SSR are obtained with our approach, either compared with the SSR values reported in the literature or with the model in which the full time interval is considered and no feature selection is made. See the example of d = 2 and H = 3, for instance.

#### Tecator Data Set

Figure 5.3(h) and Table 5.2 show that our approach is able to improve the literature reference values in [Ferraty et al., 2010], and is comparable to the results given when the full interval is used and no feature selection is performed, especially if we compare with d = 2.

#### Synthetic 1 and Synthetic 2 Data Sets

We see in Figure 5.3(f), 5.3(g), and Table 5.3 that similar results in terms of prediction ability have been obtained with and without feature selection. An example of this fact is observed in the set *synthetic* 2 when d = 2, and H = 2.

#### 5.4 Conclusions and Extensions

In this chapter, we have proposed an approach based on continuous optimization to select time instants in regression problems with (multivariate) functional data.

The heuristic here proposed is enhanced with the definition of a nested structure which takes advantage of the optimal solutions in the simple models to reach better predictions. Furthermore, our proposal allows, in the very same manner, to take advantage of higher-order information provided by the derivatives of the (multivariate) functional data. Such information is crucial, as has been shown in the numerical experience.

Some extensions of the present work are possible. Here we have just considered pure (multivariate) functional data. Our proposal can be easily extended to the hybrid multivariate case with a simple modification of the kernel function, as in Chapter 4.

In this chapter, we have restricted ourselves to the time instant selection problem. A possible extension would be to optimally select H time intervals, instead of H time instants. Figure 5.6 shows the histograms of the extreme points when H=2 time intervals are sought in the *canadian* data set. We observe again that the most important domains are around the months of April and November.

Another challenging extension of our approach consists of working with spatiotemporal data, in which one seeks the most relevant time instants and locations, or to extend our proposal to other Data Science problems, such as clustering.

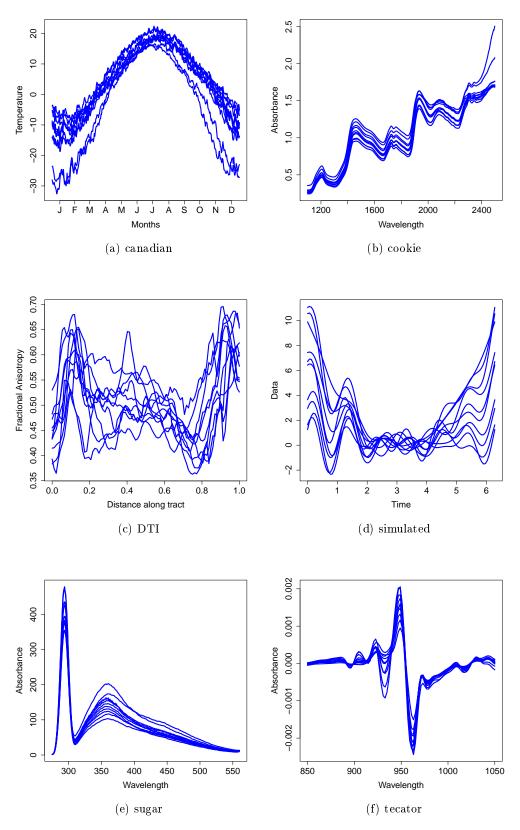


Figure 5.1: Sample of functional data in the univariate data sets analyzed

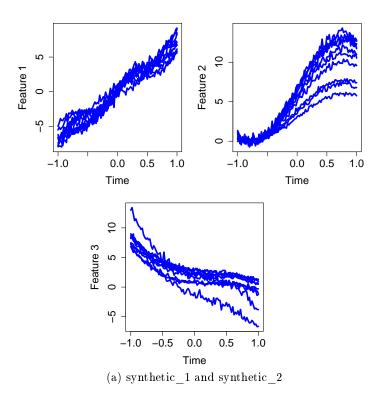


Figure 5.2: Sample of functional data in the univariate data sets analyzed

																	20	0.11	0.19	0.26
																	16	Ι.		0.26
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	19	1.4(	1.7.	1.8			19	0.0	0.04	0.0
	18	1.47	1.77	1.82			18	0.05	0.04	0.05
	17	1.56	1.78	1.83			17	0.04	0.04	0.04
	16	1.54	1.76	1.83			16	0.03	0.04	0.03
	15	1.55	1.74	1.84			15	0.05	0.03	0.03
	14	1.57	1.71	1.83			14	0.05	0.04	0.05
	13	1.72	1.74	1.86			13	0.06	0.04 0.04 0.03 0.04 0.04 0.04	0.04
	12	1.71	1.75	1.79			12	0.09	0.05	0.04
	11	1.69	1.62	1.88			11	0.08	0.05	90.0
H	10	1.87	1.92	1.90		H	10	0.09	90.0	90.0
	6	1.56	5.06	1.77			6	0.09	0.05	90.0
	$\infty$	1.43	1.75	1.89			$\infty$	0.11	0.06	0.06
	2	1.51	1.94	1.82		7	0.09	0.05	0.05	
	3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19	1.65	2.05	1.85			9	0.12	0.05	0.04
	ಬ	1.85	2.02	1.73			ಬ	0.10	0.07	0.05
	4	1.79	1.95	1.86			4	0.14	0.10	0.07
	3	1.99	2.05	1.61			က	0.16	0.12	0.13
	2	2.13	2.17	2.00			2	0.19	0.23	0.16
	_	2.57	2.31	2.12				0.80	$0.51 \ 0.23 \ 0.12 \ 0.10 \ 0.07 \ 0.05 \ 0.05 \ 0.06 \ 0.05 \ 0.06 \ 0.05 \ 0.05$	0.54
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Table 5.2: Performance results on univariate data sets

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1.86	2.46	2.83	2		0.88	1.26	1.67	2	
2.24	2.40	2.31	ಬ		0.80	1.05	1.09	3	
2.09	2.03	2.20	4		0.80	0.99	0.99	4	
2.08	2.38	2.09	Ů		0.85	0.96	1.09	5 6	
2.14	2.39	2.34	6		0.91	0.93	1.15	6	
2.29	2.26	2.38	7		0.86	1.02	1.11	7	
2.23	2.22	2.35	$\infty$		0.88	0.99	1.01	8	
2.05	2.19	2.27	9 10		0.85	1.04	1.00	9	
2.04	2.19	2.27	10	I	0.85	0.91	1.02	9 10	1
2.01	2.08	2.33	11	H	0.84	0.87	1.06	11	E
2.06	2.04	2.31	12		0.82	0.89	1.01	12	
2.12	2.02	2.30	12 13 14		$1.37 \ 0.88 \ 0.80 \ 0.80 \ 0.85 \ 0.91 \ 0.86 \ 0.88 \ 0.85 \ 0.85 \ 0.84 \ 0.82 \ 0.82 \ 0.83$	0.90	$2.78 \ 1.07 \ 1.09 \ 1.09 \ 1.05 \ 1.11 \ 1.11 \ 1.01 \ 1.02 \ 1.06 \ 1.01 \ 1.08 \ 1.07$	13	
2.20	2.00	2.22	14		0.83	0.89	1.07	14	
							1.08	15	
2.13 2.12 2.09 2.09 2.09 2.13	1.98 1.97 1.98 1.99 2.01 2.00	2.27 2.22 2.20 2.23 2.21 2.22	15 16 17 18 19 20		0.82 0.81 0.81 0.80 0.80 0.80	$0.87\ 0.86\ 0.85\ 0.84\ 0.84$	1.07 1.06 1.07 1.03 1.00	16	
2.09	1.98	2.20	17		0.81	0.85	1.06	17	
2.09	1.99	2.23	18		0.80	0.84	1.07	16 17 18 19 20	
2.09	2.01	2.21	19		0.80	0.84	1.03	19	
2.13	2.00	2.22	20		0.80	0.83	1.00	20	

Table 5.3: Performance results on multivariate data sets

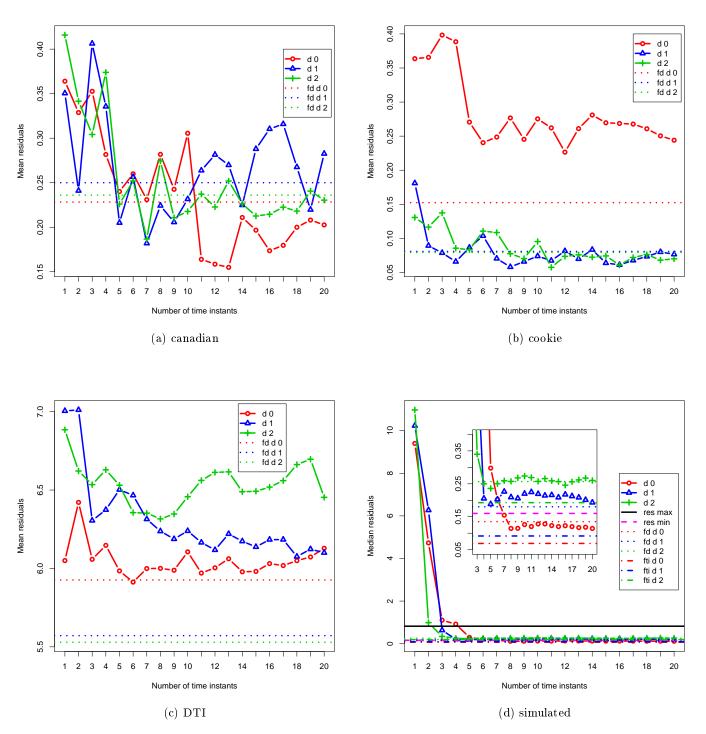


Figure 5.3: Variable selection results on databases canadian, cookie, DTI and simulated

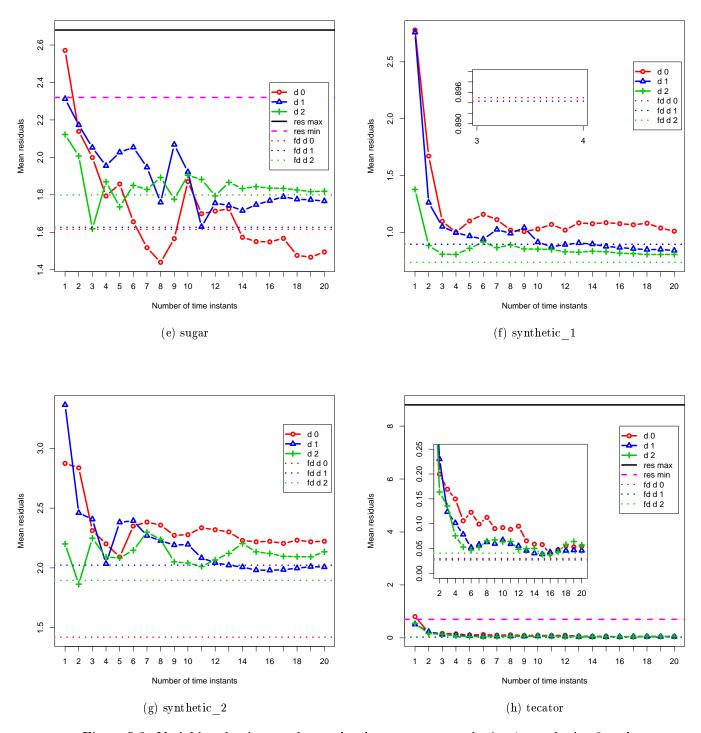


Figure 5.3: Variable selection results on databases sugar,  $synthetic\_1$ ,  $synthetic\_2$  and tecator (cont.)

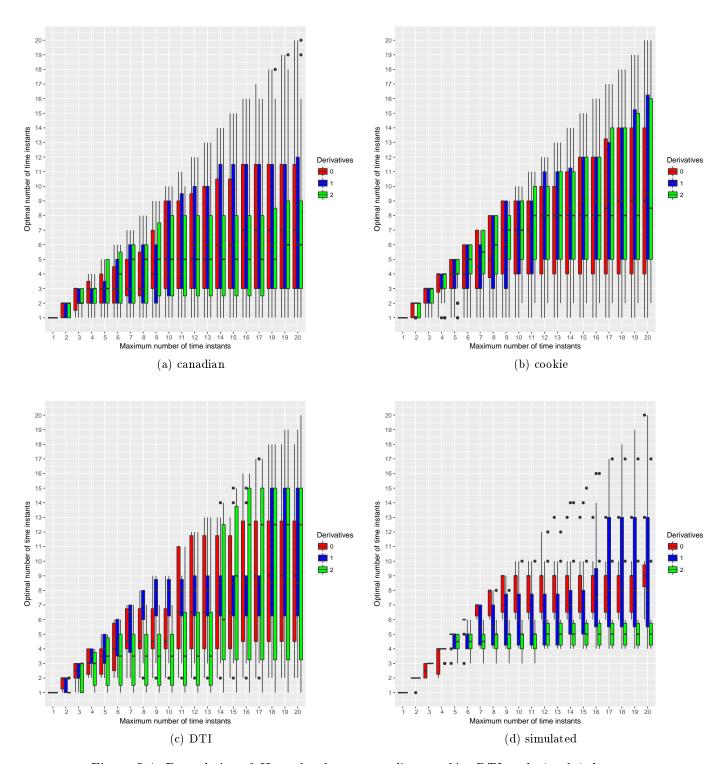


Figure 5.4: Best choice of H on databases canadian, cookie, DTI and simulated

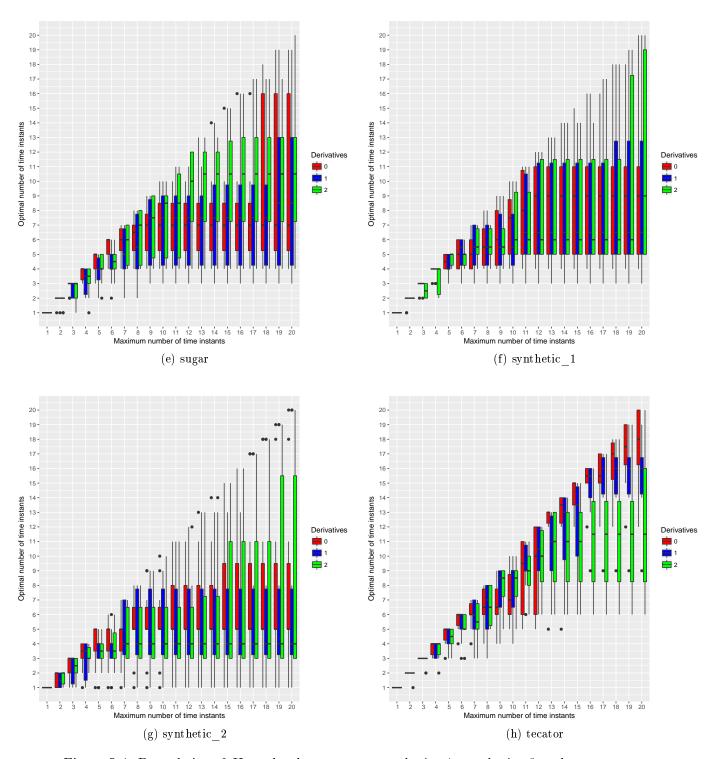


Figure 5.4: Best choice of H on databases sugar,  $synthetic_1$ ,  $synthetic_2$  and tecator (cont.)

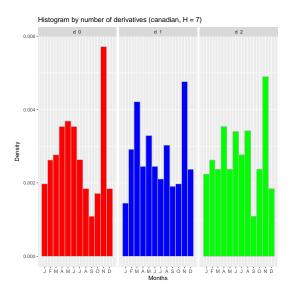


Figure 5.5: Histogram of the time instants values in canadian data set when H=7 time instants are sought

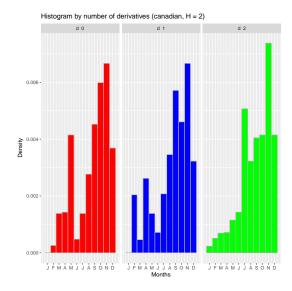


Figure 5.6: Histogram of the extreme points in canadian data set when H=2 time intervals are sought

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