# Some remarks on the comparison principle in Kirchhoff equations 

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#### Abstract

In this paper we study the validity of the comparison principle and the sub-supersolution method for Kirchhoff type equations. We show that these principles do not work when the Kirchhoff function is increasing, contradicting some previous results. We give an alternative sub-supersolution method and apply it to some models.


## 1. Introduction

In the last years the nonlinear elliptic Kirchhoff equation has attracted much attention, see for instance [12], [13], [15], [16], and references therein. The equation has the following general form:

$$
\begin{cases}-M\left(\|u\|^{2}\right) \Delta u=f(x, u) & \text { in } \Omega,  \tag{1.1}\\ u=0 & \text { on } \partial \Omega,\end{cases}
$$

where $\Omega \subset \mathbb{R}^{N}, N \geq 1$, is a bounded and regular domain,

$$
\|u\|^{2}:=\int_{\Omega}|\nabla u|^{2} d x
$$

where $M$ is a continuous function verifying

$$
\begin{align*}
& M:[0,+\infty) \mapsto[0,+\infty)  \tag{0}\\
& \text { and } \exists m_{0}>0 \text { such that } M(t) \geq m_{0}>0 \forall t \in[0,+\infty),
\end{align*}
$$

and where $f \in C(\bar{\Omega} \times \mathbb{R})$. We assume $\left(M_{0}\right)$ along the paper.
Problem (1.1) models small vertical vibrations of an elastic string with fixed ends when the density of the material is homogeneous and there is a external force, see [9] for a explication of the model. To study this problem different methods

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have been used, mainly variational methods and fixed point arguments, and also bifurcation and sub-supersolution.

In this note, we have two main objectives. On the one hand, we present some examples demonstrating that some comparison results and those based on the sub-supersolution method appearing in the literature are not correct. On the other hand, we prove a sub-supersolution method that includes the above ones, specifically those in [3], [4], and [14].

An outline of the paper is as follows: in Section 2 we recall the previous results related to comparison and sub-supersolution method, and we present our main result. In Section 3 we give some counterexamples showing that some comparison results are not correct. Section 4 is devoted to prove our main result, and in Section 5 we apply our result to some specific examples.

## 2. Previous and main results

To our knowledge, there are basically three results concerning the comparison and sub-supersolution results related to (1.1). Let us recall them. In [3] (Theorems 2 and 3) the following result was proved:

Theorem 2.1. Assume that:
$\left(M_{1}\right) M$ is non-increasing in $[0,+\infty)$.
$(H)$ Define the function

$$
H(t):=M\left(t^{2}\right) t
$$

and assume that $H$ is increasing and $H(\mathbb{R})=\mathbb{R}$.
Then:
a) If there exist two non-negative functions $\underline{u}, \bar{u} \in C^{2}(\bar{\Omega})$ such that $\underline{u}=\bar{u}=0$ on $\partial \Omega$ and

$$
\begin{equation*}
-M\left(\|\underline{u}\|^{2}\right) \Delta \underline{u} \leq-M\left(\|\bar{u}\|^{2}\right) \Delta \bar{u} \quad \text { in } \Omega \tag{2.1}
\end{equation*}
$$

then (comparison principle)

$$
\underline{u} \leq \bar{u} \quad \text { in } \bar{\Omega} .
$$

b) If
$\left(f_{1}\right) f$ is increasing in the variable $u$ for each $x \in \Omega$ fixed, and there exist two regular functions $0 \leq \underline{u} \leq \bar{u}$ in $\Omega, \underline{u}=\bar{u}=0$ on $\partial \Omega$ satisfying

$$
\begin{equation*}
-M\left(\|\bar{u}\|^{2}\right) \Delta \bar{u} \geq f(x, \bar{u}), \quad-M\left(\|\underline{u}\|^{2}\right) \Delta \underline{u} \leq f(x, \underline{u}), \quad \text { in } \Omega . \tag{2.2}
\end{equation*}
$$

then (sub-supersolution method) there exists a solution $u$ of (1.1) such that $\underline{u} \leq u \leq \bar{u}$ in $\Omega$.

In [14] (Theorems 3.2 and 3.3), se also [8], the authors proved a similar result to Theorem 2.1 in the case that $M$ is increasing.

Theorem 2.2. Assume that
$\left(M_{2}\right) M$ is increasing.
Then, the comparison principle holds. Moreover, if $f$ satisfies $\left(f_{1}\right)$, the subsupersolution method also works.

Finally, in [4] the following result is shown:
Theorem 2.3. Assume that $M$ satisfies $\left(M_{2}\right)$ and
$\left(f_{2}\right) f$ is a positive function.
If there exist $\bar{u} \in W^{1, \infty}(\Omega), \bar{u} \geq 0$ on $\partial \Omega$, and a family $\left(\underline{u}_{\delta}\right) \subset W_{0}^{1, \infty}(\Omega)$ such that

$$
\begin{equation*}
-m_{0} \Delta \bar{u} \geq f(x, \bar{u}) \tag{2.3}
\end{equation*}
$$

$\left\|\underline{u}_{\delta}\right\|_{1, \infty} \rightarrow 0$ as $\delta \rightarrow 0, \underline{u}_{\delta} \leq \bar{u}$ in $\Omega$ for $\delta$ small enough, and given $\alpha>0$, there is $\delta_{0}$ such that

$$
\begin{equation*}
-\Delta \underline{u}_{\delta} \leq \frac{1}{\alpha} f\left(x, \underline{u}_{\delta}\right), \quad \text { for } \delta \leq \delta_{0} \tag{2.4}
\end{equation*}
$$

then there is a small enough $\delta>0$ such that there exists a solution $u$ of (1.1) such that $\underline{u}_{\delta} \leq u \leq \bar{u}$ in $\Omega$.

Of course, the above inequalities (2.3) and (2.4) are considered in the weak sense.

Our main result reads as follows:
Theorem 2.4. Assume $\left(M_{0}\right)$ and
$\left(M_{3}\right) G(t):=M(t) t$ is invertible and denote by $R(t):=G^{-1}(t)$
Define now the non-local operator

$$
\mathcal{R}(w):=R\left(\int_{\Omega} f(x, w) w d x\right) .
$$

If there exist $\underline{u}, \bar{u} \in H^{1}(\Omega) \cap L^{\infty}(\Omega)$ such that $\underline{u} \leq \bar{u}$ in $\Omega, \underline{u} \leq 0 \leq \bar{u}$ on $\partial \Omega$ satisfying

$$
\begin{equation*}
-M(\mathcal{R}(w)) \Delta \bar{u} \geq f(x, \bar{u}), \quad-M(\mathcal{R}(w)) \Delta \underline{u} \leq f(x, \underline{u}), \quad \forall w \in[\underline{u}, \bar{u}] \tag{2.5}
\end{equation*}
$$

then there exists a solution $u$ of (1.1) such that $\underline{u} \leq u \leq \bar{u}$ in $\Omega$.
Remark 2.5. (1) We would like to remark that Theorem 2.4 does not assume $\left(f_{1}\right)$.
(2) Observe that condition (2.5) involves all the functions $w$ in the interval $[\underline{u}, \bar{u}]$. So, in order to verify for instance the first inequality in (2.5), we have to take into account the sign of $-\Delta \bar{u}$ and the monotonicity of the map $w \mapsto M(\mathcal{R}(w))$. See Section 5 for applications of this result.

In Section 3, we show that Theorem 2.2 is not correct. Now, we deduce Theorems 2.1 b ) and 2.3 from Theorem 2.4.

Corollary 2.6. Assume that $M$ is smooth, $\left(M_{1}\right),(H),\left(f_{1}\right)$ and that there exist a sub-supersolution in the sense of Theorem 2.1. Then, there exists a solution $u$ of (1.1) such that $\underline{u} \leq u \leq \bar{u}$ in $\Omega$.
Proof. Observe that if $M$ is non-increasing and $H$ is increasing, then $G$ is increasing. Indeed, using that $M^{\prime} \leq 0$ we get that

$$
G^{\prime}(t)=M^{\prime}(t) t+M(t) \geq 2 t M^{\prime}(t)+M(t)=H^{\prime}\left(t^{1 / 2}\right)>0, \quad t>0
$$

and then, $w \mapsto \mathcal{R}(w)$ is increasing because $f$ is also increasing.
Consider now that $\underline{u}, \bar{u}$ is a sub-supersolution in the sense of Theorem 2.1. We are going to show that it is also sub-supersolution in the sense of Theorem 2.4. We show this fact for $\underline{u}$; for $\bar{u}$ we can apply an analogous reasoning. Since $f$ is increasing and $0 \leq \underline{u} \leq \bar{u}$, we have that

$$
M\left(\|\underline{u}\|^{2}\right)\|\underline{u}\|^{2} \leq \int_{\Omega} f(x, \underline{u}) \underline{u} \leq \int_{\Omega} f(x, w) w \quad \forall w \in[\underline{u}, \bar{u}],
$$

and so,

$$
\|\underline{u}\|^{2} \leq \mathcal{R}(w) \Longrightarrow M\left(\|\underline{u}\|^{2}\right) \geq M(\mathcal{R}(w)) \quad \forall w \in[\underline{u}, \bar{u}] .
$$

Hence,

$$
-\Delta \underline{u} \leq \frac{f(x, \underline{u})}{M\left(\|\underline{u}\|^{2}\right)} \leq \frac{f(x, \underline{u})}{M(\mathcal{R}(w))} \quad \forall w \in[\underline{u}, \bar{u}] .
$$

Then, $(\underline{u}, \bar{u})$ satisfies the hypotheses of Theorem 2.4 and we can conclude the existence of a solution $u$ of (1.1) and $u \in[\underline{u}, \bar{u}]$.

Corollary 2.7. Assume $\left(M_{2}\right),(H),\left(f_{2}\right)$ and that there exists a sub-supersolution in the sense of Theorem 2.3. Then, there exists a solution $u$ of (1.1) such that $\underline{u} \leq u \leq \bar{u}$ in $\Omega$.

Proof. Observe that if $M$ is increasing, then $G$ is increasing. Assume now the existence of a supersolution $\bar{u}$ and family of sub-solution $\underline{u}_{\delta}$ in the sense of Theorem 2.3. Then,

$$
-\Delta \bar{u} \geq \frac{f(x, \bar{u})}{m_{0}} \geq \frac{f(x, \bar{u})}{M(\mathcal{R}(w))} \quad \forall w \in[\underline{u}, \bar{u}] .
$$

Consider now

$$
\alpha=\max _{0 \leq w \leq \bar{u}} M(\mathcal{R}(w))
$$

and take $\underline{u}=\underline{u}_{\delta}$ for some $\delta \leq \delta_{0}$ given by Theorem 2.3. Then, using that $f \geq 0$,

$$
-\Delta \underline{u} \leq \frac{1}{\alpha} f(x, \underline{u}) \leq \frac{1}{M(\mathcal{R}(w))} f(x, \underline{u}) \quad \forall w \in[\underline{u}, \bar{u}]
$$

and so, $\underline{u}, \bar{u}$ is sub-supersolution in the sense of Theorem 2.4. Theorem 2.4 concludes the result.

## 3. Counterexamples

In this section we have two objectives: to show that when $M$ satisfies only $\left(M_{2}\right)$, or $M$ satisfies only $\left(M_{1}\right)$ (Cases 1 and 2 below, respectively), the comparison principle and the sub-supersolutions fail.

For that consider

$$
\Omega=(0, \pi), \quad u_{1}:=\sin (x), \quad u_{2}:=x(\pi-x),
$$

and

$$
\begin{equation*}
M(t):=a+b(t+c)^{p}, \quad c \geq 0, a, b>0, p \in \mathbb{R} . \tag{3.1}
\end{equation*}
$$

Observe that

$$
-\Delta u_{1}=u_{1}, \quad-\Delta u_{2}=2, \quad\left\|u_{1}\right\|^{2}=\frac{\pi}{2}, \quad\left\|u_{2}\right\|^{2}=\frac{\pi^{3}}{3}
$$

and

$$
\max _{x \in[0, \pi]} \frac{u_{1}(x)}{u_{2}(x)}=\max _{x \in[0, \pi]} \frac{\sin (x)}{x(\pi-x)}=\frac{4}{\pi^{2}}:=\rho^{*} \simeq 0.4083
$$

In order to prove that the comparison principle fails, we take $\bar{u}=\rho u_{2}, \rho>0$ and $\underline{u}=u_{1}$. So,

$$
-M\left(\|\underline{u}\|^{2}\right) \Delta \underline{u} \leq-M\left(\|\bar{u}\|^{2}\right) \Delta \bar{u} \quad \text { for all } x \in(0, \pi)
$$

if and only if

$$
\begin{equation*}
M(\pi / 2) \leq 2 \rho M\left(\rho^{2} \frac{\pi^{3}}{3}\right) \tag{3.2}
\end{equation*}
$$

Hence, if

$$
\begin{equation*}
\rho<\rho^{*} \quad \text { and } \quad M(\pi / 2) \leq 2 \rho M\left(\rho^{2} \frac{\pi^{3}}{3}\right) \tag{3.3}
\end{equation*}
$$

then the comparison principle fails.
To prove that the sub-supersolutions method fails, we consider the problem

$$
\begin{cases}-M\left(\|u\|^{2}\right) \Delta u=f(x)=\sin (x) & \text { in } \Omega,  \tag{3.4}\\ u=0 & \text { on } \partial \Omega .\end{cases}
$$

Observe that the solutions of (3.4) are

$$
u_{0}=k \sin (x),
$$

with $k$ satisfying

$$
\begin{equation*}
k M\left(k^{2} \frac{\pi}{2}\right)=1 \tag{3.5}
\end{equation*}
$$

Consider the pair $(\bar{u}, \underline{u})=\left(\rho u_{2}, 0\right)$. Then there is a pair of sub-supersolution of (3.4) in the sense of Theorem 2.2 provided that

$$
\begin{equation*}
2 \rho M\left(\rho^{2} \frac{\pi}{2}\right) \geq 1 \tag{3.6}
\end{equation*}
$$

Then, if the method is applicable, then there exists a solution $u_{0}$ of (3.4) such that

$$
0 \leq u_{0} \leq \bar{u}=\rho u_{2} \quad \text { in } \Omega
$$

Hence, if

$$
\begin{equation*}
\rho<k \rho^{*} \quad \text { and } \quad 2 \rho M\left(\rho^{2} \frac{\pi}{2}\right) \geq 1 \tag{3.7}
\end{equation*}
$$

where $k$ satisfies (3.5), then the sub-supersolution method fails.
Case 1. $M$ is increasing. Consider in this case $c=0, a>0$ and $p>0$ in (3.1). Then, (3.3) is equivalent to

$$
a+b\left(\frac{\pi}{2}\right)^{p} \leq 2 \rho\left(a+b\left(\rho^{2} \frac{\pi^{3}}{3}\right)^{p}\right) \quad \text { and } \quad \rho<\rho^{*}
$$

Taking $b$ large, we need that for some $\rho<\rho^{*}$,

$$
\frac{1}{2} \frac{1}{\left(\pi^{2} \frac{2}{3}\right)^{p}}<\rho^{1+2 p}
$$

By continuity, it is enough that the above inequality holds for $\rho=\rho^{*}$, that is,

$$
\frac{1}{2} \frac{1}{\left(\pi^{2} \frac{2}{3}\right)^{p}}<\left(\frac{4}{\pi^{2}}\right)^{1+2 p} \Longleftrightarrow 1<\frac{8}{\pi^{2}}\left(\frac{32}{3 \pi^{2}}\right)^{p}
$$

which is true for $p$ large.
Now, we analyze the sub-supersolution method. First, observe that since $M$ is increasing, (3.4) possesses a unique solution, $u_{0}=k \sin (x)$, where $k$ satisfies

$$
\begin{equation*}
k\left(a+b\left(k^{2} \frac{\pi}{2}\right)^{p}\right)=1 \tag{3.8}
\end{equation*}
$$

Observe that if $a \rightarrow 0$, then

$$
k(a) \rightarrow\left(\frac{1}{b}\right)^{1 /(2 p+1)}\left(\frac{2}{\pi}\right)^{p /(2 p+1)}
$$

Take

$$
p>\frac{\ln \left(\pi^{2} / 8\right)}{\ln \left(32 /\left(3 \pi^{2}\right)\right)}
$$

Then there exists $a_{0}>0$ such that for all $a \in\left(0, a_{0}\right)$ we have

$$
\begin{equation*}
\frac{a+b\left(\frac{16 k^{2}}{3 \pi}\right)^{p}}{a+b\left(\frac{k^{2} \pi}{2}\right)^{p}}>\frac{\pi^{2}}{8} \tag{3.9}
\end{equation*}
$$

Hence, $\bar{u}$ is supersolution if (see (3.6))

$$
2 \rho\left(a+b\left(\frac{\rho^{2} \pi^{3}}{3}\right)^{p}\right) \geq 1
$$

By continuity, (3.7) is verified for some $\rho<\rho^{*}$ if

$$
2 \frac{4}{\pi^{2}} k\left(a+b\left(\frac{\left(\frac{4}{\pi^{2}} k\right)^{2} \pi^{3}}{3}\right)^{p}\right)>1
$$

which is equivalent, using (3.8), to (3.9).
Case 2. $M$ is decreasing. Take in this case $a, c>0$ and $p<0$. In this case, (3.3) is equivalent to

$$
\begin{equation*}
a(1-2 \rho) \leq b\left(2 \rho\left(\rho^{2} \frac{\pi^{3}}{3}+c\right)^{p}-\left(\frac{\pi}{2}+c\right)^{p}\right) \quad \text { and } \quad \rho<\rho^{*} \tag{3.10}
\end{equation*}
$$

Take $\rho^{2}<\frac{3}{2 \pi^{2}}$. Then

$$
\begin{equation*}
\frac{\pi / 2+c}{\rho^{2} \pi^{3} / 3+c}>1 \tag{3.11}
\end{equation*}
$$

For this $\rho$ fixed, take $p$ such that

$$
\begin{equation*}
2 \rho>\left(\frac{\pi / 2+c}{\rho^{2} \pi^{3} / 3+c}\right)^{p} \tag{3.12}
\end{equation*}
$$

or equivalently,

$$
2 \rho\left(\rho^{2} \frac{\pi^{3}}{3}+c\right)^{p}>\left(\frac{\pi}{2}+c\right)^{p}
$$

Now, take $b$ large enough to have (3.10).
Now, we show that the sub-supersolution method does not work for $M$ only satisfying $\left(M_{1}\right)$. Take $\rho$ and $p$ such that (3.11) and (3.12) are satisfied. On the other hand, take $b$ such that $b(\pi / 2+c)^{p}>1$, and then for all $a>0$ we have

$$
\begin{equation*}
a+b\left(\frac{\pi}{2}+c\right)^{p}>1 \tag{3.13}
\end{equation*}
$$

Then, thanks to (3.13), there exists at least a positive solution of (3.5), that is,

$$
k\left(a+b\left(k^{2} \frac{\pi}{2}+c\right)^{p}\right)=1
$$

and then, there exists at least a positive solution of (3.4). Observe that in this case, we can not assure that (3.4) has a unique solution. On the other hand, since $p<0$, observe that

$$
\begin{equation*}
k \geq \frac{1}{a+b c^{p}} \tag{3.14}
\end{equation*}
$$

In order to verify (3.7) we need

$$
2 \rho\left(a+b\left(\rho^{2} \frac{\pi^{3}}{3}+c\right)^{p}\right) \geq 1 \quad \text { and } \quad \rho<k \frac{4}{\pi^{2}}
$$

Now, we prove that

$$
2 \rho\left(a+b\left(\rho^{2} \frac{\pi^{3}}{3}+c\right)^{p}\right)>a+b\left(\frac{\pi}{2}+c\right)^{p}
$$

whence we conclude the result from (3.13). This is equivalent to

$$
b\left[2 \rho\left(\rho^{2} \frac{\pi^{3}}{3}+c\right)^{p}-\left(\frac{\pi}{2}+c\right)^{p}\right]>a(1-2 \rho)
$$

which is true taking $a$ small and positive. Finally, we need to verify $\rho<4 k / \pi^{2}$. But, observe that by (3.14), we have that, for $a$ small, the above inequality is true.

Remark 3.1. The above example shows that Theorem 3.3 in [14] (which assures that the sub-supersolution method and the comparison principle work), see also Theorem 2.3 in [11], seems not correct. Hence, the existence results of, for instance, [1], [2], [6], have been obtained using a method that fails.

## 4. Proof of Theorem 2.4

First, we are going to transform our equation (1.1) into another non-local elliptic equation. Indeed, multiplying (1.1) by $u$ and integrating, we get

$$
M\left(\|u\|^{2}\right)\|u\|^{2}=\int_{\Omega} f(x, u) u d x
$$

By $\left(H_{3}\right), G$ is invertible, and so

$$
\|u\|^{2}=R\left(\int_{\Omega} f(x, u) u d x\right)=\mathcal{R}(u)
$$

Then, (1.1) is equivalent to the problem

$$
\begin{cases}-\Delta u=\frac{f(x, u)}{M(\mathcal{R}(u))} & \text { in } \Omega  \tag{4.1}\\ u=0 & \text { on } \partial \Omega\end{cases}
$$

Observe that (4.1) is a non-local elliptic equation, without terms in $\|u\|$, and so it suffices to apply Theorem 3.2 in [7]. This completes the proof.

In the following result, we prove a specific comparison principle which is valid when $M$ only satisfies hypothesis $(H)$ and the second member of the equation is constant. Define $e$ to be the unique positive solution of the equation

$$
\begin{cases}-\Delta e=1 & \text { in } \Omega  \tag{4.2}\\ e=0 & \text { on } \partial \Omega\end{cases}
$$

Lemma 4.1. Assume that $M$ satisfies $(H)$ and let $u_{i} \in H_{0}^{1}(\Omega), i=1,2$, be functions such that

$$
-M\left(\left\|u_{i}\right\|^{2}\right) \Delta u_{i}=f_{i} \in \mathbb{R}_{+}
$$

and $f_{1} \leq f_{2}$. Then, $u_{1} \leq u_{2}$ in $\Omega$.
Proof. Observe that

$$
\begin{equation*}
M\left(\left\|u_{i}\right\|^{2}\right) u_{i}=f_{i} e \tag{4.3}
\end{equation*}
$$

and then $u_{1} \leq u_{2}$ if and only if

$$
\begin{equation*}
\frac{f_{1}}{M\left(\left\|u_{1}\right\|^{2}\right)} \leq \frac{f_{2}}{M\left(\left\|u_{2}\right\|^{2}\right)} . \tag{4.4}
\end{equation*}
$$

But observe that, from (4.3),

$$
f_{i}=\frac{M\left(\left\|u_{i}\right\|^{2}\right)\left\|u_{i}\right\|}{\|e\|}
$$

and then (4.4) is equivalent to

$$
\begin{equation*}
\left\|u_{1}\right\| \leq\left\|u_{2}\right\| . \tag{4.5}
\end{equation*}
$$

Since $M\left(\left\|u_{i}\right\|^{2}\right)\left\|u_{i}\right\|=f_{i}\|e\|$ and due to $(H)$, (4.5) follows.
Remark 4.2. We would like to emphasize that Lemma 4.1 is only true when $f_{i}$, $i=1,2$ are real numbers.

## 5. Applications

In this section we apply our result to some models. We only assume that $M$ satisfies $\left(M_{3}\right)$. Denote by $\lambda_{1}>0$ the principal eigenvalue of the Laplacian and $\varphi_{1}>0$ the eigenfunction associated to it with $\left\|\varphi_{1}\right\|_{\infty}=1$.

Example 1. Consider the equation

$$
\begin{cases}-M\left(\|u\|^{2}\right) \Delta u=\lambda u^{q} & \text { in } \Omega  \tag{5.1}\\ u=0 & \text { on } \partial \Omega\end{cases}
$$

where $\lambda \in \mathbb{R}$ and $0<q<1$. This problem was analyzed in [3] when $M$ satisfies $\left(M_{1}\right)$ and $(H)$. We are going to show that (5.1) possesses a positive solution if and only if $\lambda>0$. From the maximum principle, if $\lambda \leq 0$ problem (5.1) does not have any positive solution. Assume $\lambda>0$ and take as sub-supersolutions $\underline{u}=\varepsilon \varphi_{1}$ and $\bar{u}=K e$ with $\varepsilon, K>0$ to be chosen. Then, $\bar{u}$ is supersolution if

$$
K^{1-q} \geq \frac{1}{m_{0}} \lambda\|e\|_{\infty}^{q}
$$

Fix such $K$. Then, $\underline{u}$ is subsolution if

$$
M(\mathcal{R}(w)) \varepsilon^{1-q} \leq \frac{\lambda}{\lambda_{1}}, \quad \forall w \in[\underline{u}, \bar{u}] .
$$

It is enough to take $\varepsilon$ small such that the above inequality holds and that $\underline{u} \leq \bar{u}$.
Example 2. Consider the classical concave-convex equation

$$
\begin{cases}-M\left(\|u\|^{2}\right) \Delta u=\lambda u^{q}+u^{p} & \text { in } \Omega  \tag{5.2}\\ u=0 & \text { on } \partial \Omega\end{cases}
$$

where $\lambda \in \mathbb{R}$ and $0<q<1<p$. Again we assume only that $M$ satisfies $\left(M_{3}\right)$. We show that there exists at least a positive solution for $\lambda$ small and positive. For that, again take the same sub-supersolution of the above example. We can show that $\bar{u}=K e$ es supersolution provided that

$$
m_{0} K^{1-q} \geq \lambda\|e\|_{\infty}^{q}+K^{p-q}\|e\|_{\infty}^{p}
$$

Then there exists $\lambda_{0}>0$ such that, for $\lambda \in\left(0, \lambda_{0}\right)$, there exists $K_{0}$ such that $\bar{u}=K_{0} e$ is supersolution.

Now, $\underline{u}=\varepsilon \varphi_{1}$ is subsolution provided that

$$
M(\mathcal{R}(w)) \varepsilon^{1-q} \lambda_{1} \leq \lambda+\varepsilon^{p-q} \varphi_{1}^{p-q}, \quad \forall w \in[\underline{u}, \bar{u}] .
$$

It suffices again to take $\varepsilon$ small.
Example 3. Consider now the logistic equation

$$
\begin{cases}-M\left(\|u\|^{2}\right) \Delta u=\lambda u-u^{p} & \text { in } \Omega  \tag{5.3}\\ u=0 & \text { on } \partial \Omega\end{cases}
$$

where $\lambda \in \mathbb{R}$ and $1<p$. In this example we assume, in addition to $\left(M_{3}\right)$, that there exist two positive constants $m_{0}, m_{\infty}$ such that

$$
\begin{equation*}
m_{0} \leq M \leq m_{\infty} \tag{5.4}
\end{equation*}
$$

This equation was studied in [5] when $M=M(u)$ is a continuous function from $L^{p}(\Omega)$ into $\mathbb{R}$ that satisfies (5.4); however, they do not assume $\left(M_{3}\right)$. They used a fixed point argument and showed the existence of positive solution for $\lambda>\lambda_{1} m_{\infty}$ (Theorem 2.1 in [5]).

We obtain a similar result for the Kirchhoff equation (5.3) by the sub-supersolution method. Observe that in this case we can not apply Theorem 2.1. Take $\bar{u}=\lambda$. It is clear that $\bar{u}$ is supersolution. As subsolution, take $\underline{u}=\varepsilon \varphi_{1}$. Then we need that

$$
M(\mathcal{R}(w)) \lambda_{1}+\left(\varepsilon \varphi_{1}\right)^{p-1} \leq \lambda, \quad \forall w \in[\underline{u}, \bar{u}] .
$$

Then there exists at least a positive solution for $\lambda>\lambda_{1} m_{\infty}$.
Remark 5.1. After we have finished and revised the paper, we have known the paper [10], where the authors give some counterexamples showing that equation (1.1) does not enjoy the comparison principle nor the sub supersolutions method.

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