

Finite time singularities for the free boundary incompressible Euler equations

Angel Castro, Diego Córdoba, Charles Fefferman,
Francisco Gancedo and Javier Gómez-Serrano

October 2, 2012

Abstract

In this paper, we prove the existence of smooth initial data for the 2D free boundary incompressible Euler equations (also known for some particular scenarios as the water wave problem), for which the smoothness of the interface breaks down in finite time into a splash singularity or a splat singularity.

Keywords: Euler, incompressible, blow-up, water waves, splash, splat.

Contents

I	Introduction	2
I.A	Statement of the Problem	2
I.B	Elementary Potential Theory	5
I.C	Main Results	7
I.D	Further Results	13
II	Splash curves: transformation to the tilde domain and back	13
III	Proof of real-analytic short-time existence in tilde domain	21
IV	Proof of short-time existence in Sobolev spaces in the tilde domain	29
IV.A	The Rayleigh-Taylor function in the tilde domain	29
IV.B	Definition of c in the tilde domain	32
IV.C	Time evolution of the function φ in the tilde domain	33
IV.D	Definition and a priori estimates of the energy in the tilde domain	35
IV.D.1	Estimates for BR	35
IV.D.2	Estimates for z_t	36
IV.D.3	Estimates for ω_t	36
IV.D.4	Estimates for ω	36
IV.D.5	Estimates for BR_t	37
IV.D.6	Estimates for the Rayleigh-Taylor function σ	37
IV.D.7	Estimates for σ_t	37
IV.D.8	Energy estimates on the curve	38
IV.D.9	Energy estimates for ω	42

IV.D.10 Finding the Rayleigh-Taylor function in the equation for $\partial_\alpha \varphi_t$	43
IV.D.11 Higher order derivatives of σ	54
IV.D.12 Energy estimates for φ	59
IV.D.13 Energy estimates for $\frac{ z_\alpha ^2}{m(Q^2\sigma)(t)} + \sum_{l=0}^4 \frac{1}{m(q^l)(t)}$	61
IV.E Proof of short-time existence (Theorem I.7)	61

I Introduction

I.A Statement of the Problem

In this paper, we prove that water waves in two space dimensions can form a singularity in finite time by either of two simple, natural scenarios, which we call a “splash” and a “splat”.

The water wave equations (or 2D incompressible free boundary Euler equations) describe a system consisting of a water region $\Omega(t) \subset \mathbb{R}^2$ and a vacuum region $\mathbb{R}^2 \setminus \Omega(t)$, evolving as a function of time t , and separated by a smooth interface

$$\partial\Omega(t) = \{z(\alpha, t) : \alpha \in \mathbb{R}\}.$$

We write $\Omega^1(t) = \mathbb{R}^2 \setminus \Omega(t)$, $\Omega^2(t) = \Omega(t)$. The fluid velocity $v(x, y, t) \in \mathbb{R}^2$ and the pressure $p(x, y, t) \in \mathbb{R}$ are defined for $(x, y) \in \Omega(t)$. The fluid is assumed to be incompressible and irrotational

$$\nabla \cdot v = 0, \quad \text{curl } v = 0 \quad \text{in } \Omega(t), \tag{I.1}$$

and to satisfy the 2D Euler equation

$$[\partial_t + (v \cdot \nabla_x)]v(x, y, t) = -\nabla p(x, y, t) - (0, g) \quad \text{in } \Omega(t), \tag{I.2}$$

where $g > 0$ is a constant, and the term $(0, g)$ takes gravity into account.

Neglecting surface tension, we assume that the pressure satisfies

$$p = p^*(t) \quad \text{at } \partial\Omega(t), \text{ where } p^*(t) \text{ is a function of } t \text{ alone.} \tag{I.3}$$

Finally, we assume that the interface moves with the fluid, i.e.,

$$\partial_t z(\alpha, t) = v(z(\alpha, t), t) + c^\#(\alpha, t)\partial_\alpha z(\alpha, t), \tag{I.4}$$

where $c^\#(\alpha, t)$ is an arbitrary smooth function of α, t (the choice of $c^\#$ affects only the parametrization of $\partial\Omega(t)$) and $z(\alpha, t) = (z_1(\alpha, t), z_2(\alpha, t))$.

At an initial time t_0 , we specify the fluid region $\Omega(t_0)$ and the velocity $v(x, y, t_0)$ ($(x, y) \in \Omega(t_0)$), subject to the constraint (I.1). We then solve equations (I.1-I.4) with the given initial conditions, and we ask whether a singularity can form in finite time from an initially smooth velocity $v(\cdot, t_0)$ and fluid interface $\partial\Omega(t_0)$.

The water wave problem comes in three flavors:

- Asymptotically Flat: We may demand that $z(\alpha, t) - (\alpha, 0) \rightarrow 0$ as $\alpha \rightarrow \pm\infty$.

- **Periodic:** We may instead demand that $z(\alpha, t) - (\alpha, 0)$ is a 2π -periodic function of α .
- **Compact:** Finally, we may demand that $z(\alpha, t)$ is a 2π -periodic function of α .

To obtain physically meaningful solutions in the Asymptotically Flat and Periodic flavors, we demand that

$$p(x, y, t) + gy = O(1) \quad \text{in } \Omega(t)$$

and that

$$\int_{\Omega(t)} |v(x, y, t)|^2 dx dy < \infty \quad (\text{finite energy}),$$

where we regard $\Omega(t)$ as a subset of $\mathbb{T} \times \mathbb{R}$, $\mathbb{T} = \mathbb{R}/2\pi\mathbb{Z}$, in the Periodic case.

In this paper, we restrict attention to periodic water waves, although our arguments can be easily modified to apply to the other flavors. (See Remark I.5 below).

Let us summarize some of the previous work on water waves. We discuss the real-analytic case later in this introduction. The existence and Sobolev regularity of water waves for short time is due to S. Wu [30]. Her proof applies to smooth interfaces that need not be graphs of functions, but [30] assumes the arc-chord condition

$$|z(\alpha, t) - z(\beta, t)| \geq c_{AC} |\alpha - \beta|, \quad \text{all } \alpha, \beta \in \mathbb{R}.$$

The constant $c_{AC} > 0$ is called the arc-chord constant, which may vary with time.

The issue of long-time existence has been treated in Alvarez-Lannes [3], where well-posedness over large time scales is shown, and several asymptotic regimes are justified. By taking advantage of the dispersive properties of the water-wave system, Wu [32] proved exponentially large time of existence for small initial data.

In three space dimensions, Wu [31] proved short-time existence; and Germain et al [19], [20] and Wu [33] proved existence for all time in the case of small initial data.

There are several important variants of the water wave problem. One can drop the assumption that the fluid is irrotational. See Christodoulou-Lindblad [12], Lindblad [23], Coutand-Shkoller [16], Shatah-Zeng [28], Zhang-Zhang [35]. Lannes [21] considered the case in which water is moving over a fixed bottom. Ambrose-Masmoudi [4] considered the case where the equations include surface tension, and the limit where the coefficient of surface tension tends to zero. Lannes [22] discussed the problem of two fluids separated by an interface with small non-zero surface tension. Alazard et al. [1] took advantage of the dispersive properties of the equations to lower the regularity of the initial data.

See also the papers of Córdoba et al. [13] and Alazard-Metivier [2].

In the case of large data for the two-dimensional problem (I.1-I.4), Castro et al. in [10], [9] showed that there exist initial data for which the interface is the graph of a function, but after a finite time the water wave “turns over” and the interface is no longer a graph. For previous numerical simulations showing this turning phenomenon, see Baker et al. [5] and Beale et al. [6].

Next, we describe a singularity that can form in water waves. We start by presenting what we believe based on numerical simulations; then, we explain what we can prove.

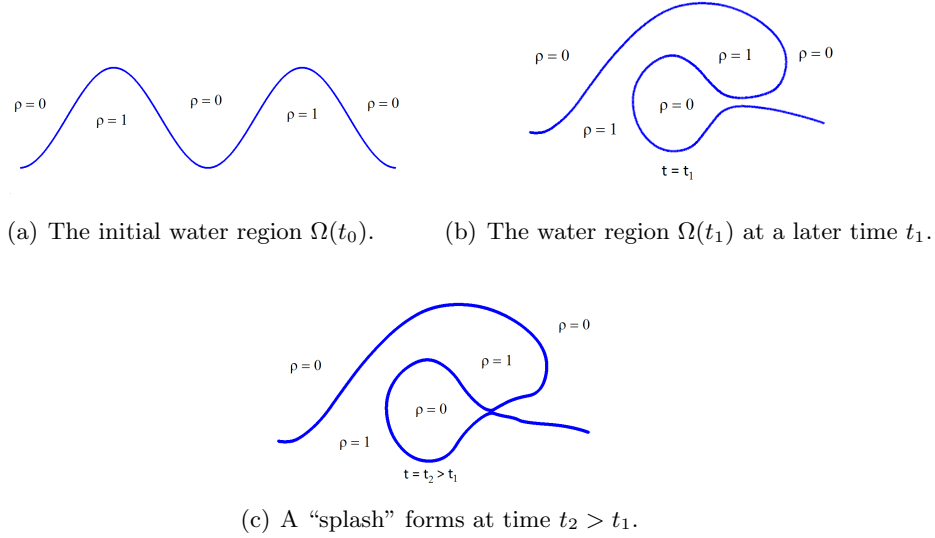


Figure 1: Evolution of a “splash” singularity.

Our simulations show an initially smooth water wave, for which the fluid interface is a graph as in Figure 1(a). At a later time t_1 , the water wave has “turned over” as described in [10], [9], i.e., the interface is no longer a graph. Finally, in Figure 1(c), the fluid interface self-intersects at a single point¹, but is otherwise smooth. We call this scenario a “splash”, and we call the single point at which the interface self-intersects, the “splash point”. Beyond the time t_2 pictured in Figure 1(c), there is no physically meaningful solution of (I.1-I.4).

Note that the arc-chord condition holds for times $t < t_2$, but the arc-chord constant tends to zero as t tends to t_2 .

The numerics that led us to Figures 1(a), 1(b) and 1(c) were performed using the method of Beale-Hou-Lowengrub [7], with special modifications to maintain accuracy up to the splash. In this paper, we use the numerics only as motivation for conjectures, so we omit a detailed discussion of the algorithms used. Actual results from our simulations are shown in Figures 3, 4 and 5. Figures 1 and 2 are cartoons.

Now let us explain what we can prove regarding the splash scenario. Recall that [10], [9] already proved that a water wave may start as in Figure 1(a) and later evolve to look like Figure 1(b). In this paper, we prove that a water wave may start as in Figure 1(b), and later form a splash, as in Figure 1(c).

We would like to prove that an initially smooth water wave may start as in Figure 1(a), then turn over as in Figure 1(b), and finally produce a splash as in Figure 1(c). To do so, our plan is to use interval arithmetic [24] to produce a rigorous computer-assisted proof that, close to the approximate solution arising from our numerics, there exists an exact solution of (I.1-I.4) that ends in a splash. The stability result announced in [8, Theorem 4.1] is a

¹Here, we regard the fluid interface as sitting inside $\mathbb{T} \times \mathbb{R}$; recall that our water waves are 2π -periodic under horizontal translation.

first step in this direction. We are grateful to R. de la Llave for introducing us to interval arithmetic and demonstrating its power.

A variant of the splash singularity is shown in Figures 2(a) and 2(b).

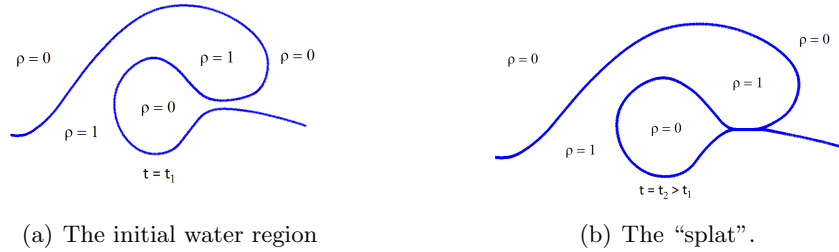


Figure 2: Evolution of a “splat” singularity.

The water wave starts out smooth, as in Figure 2(a), although the interface is not a graph. At a later time, the interface self-intersects along an arc, but is otherwise smooth. Again, no physically meaningful solution of (I.1-I.4) exists after the time depicted in Figure 2(b). We call this scenario a “splat”. In this paper, we prove that water waves can form a splat.

The stability theorem announced in [8] shows that a sufficiently small perturbation of initial conditions that lead to the splash will again lead to a splash. We expect that the analogous statement for a splat is not true.

We make no claim that the splash and the splat are the only singularities that can arise in solutions of the water wave equation.

I.B Elementary Potential Theory

To formulate precisely our main results, and to explain some ideas from their proofs, we recall some elementary potential theory for irrotational divergence-free vector fields $v(x, y, t)$ defined on a region $\Omega(t) \subset \mathbb{R}^2$ with a smooth periodic boundary $\{z(\alpha, t) : \alpha \in \mathbb{R}\}$ for fixed t . We assume that v is smooth up to the boundary and 2π -periodic with respect to horizontal translations. We suppose that v has finite energy.

Such a velocity field v may be represented in several ways:

- We may write $v = \nabla\phi$ for a velocity potential $\phi(x, y, t)$ defined on $\Omega(t)$ and smooth up to the boundary.
- We may also write $v = \nabla^\perp\psi = (-\partial_y\psi, \partial_x\psi)$ for a stream function ψ , defined on $\Omega(t)$ and smooth up to the boundary.
- The normal component of v at the boundary, given by

$$u_{normal}(\alpha, t) = v(z(\alpha, t), t) \cdot \frac{(\partial_\alpha z(\alpha, t))^\perp}{|\partial_\alpha z(\alpha, t)|}$$

uniquely specifies v on $\Omega(t)$. Here, $u^\perp = (-u_2, u_1)$ for $u = (u_1, u_2) \in \mathbb{R}^2$, and we always orient $\partial\Omega(t)$ so that the normal vector $(\partial_\alpha z(\alpha, t))^\perp$ points into the vacuum region $\mathbb{R}^2 \setminus \Omega(t)$.

The function $u_{normal}(\alpha, t)$ satisfies

$$\int_{\mathbb{T}} u_{normal}(\alpha, t) |\partial_\alpha z(\alpha, t)| d\alpha = 0,$$

but is otherwise arbitrary.

Note that, because v has finite energy, ϕ and ψ are 2π -periodic with respect to horizontal translations. (Without the assumption of finite energy, ϕ and ψ could be “periodic plus linear”). The functions ϕ and ψ are conjugate harmonic functions.

- There is another way to specify v , namely

$$v(x, y, t) = \frac{1}{2\pi} PV \int_{\mathbb{R}} \frac{(x - z_1(\beta, t), y - z_2(\beta, t))^\perp}{|(x - z_1(\beta, t), y - z_2(\beta, t))|^2} \omega(\beta, t) d\beta, \quad ((x, y) \in \Omega(t)) \quad (\text{I.5})$$

for a 2π -periodic function $\omega(\beta, t)$ called the “vorticity amplitude”. See [5].

Formula (I.5) holds only in the interior of $\Omega(t)$. Taking the limit as $(x, y) \rightarrow (z_1(\alpha, t), z_2(\alpha, t)) \in \partial\Omega(t)$ from the interior, we find that

$$v(z(\alpha, t), t) = BR(z, \omega)(\alpha, t) + \frac{1}{2} \omega(\alpha, t) \frac{\partial_\alpha z(\alpha, t)}{|\partial_\alpha z(\alpha, t)|^2}, \quad (\text{I.6})$$

where BR denotes the Birkhoff-Rott integral

$$BR(z, \omega)(\alpha, t) = \frac{1}{2\pi} P.V. \int_{\mathbb{R}} \frac{(z_1(\alpha, t) - z_1(\beta, t), z_2(\alpha, t) - z_2(\beta, t))^\perp}{|(z_1(\alpha, t) - z_1(\beta, t), z_2(\alpha, t) - z_2(\beta, t))|^2} \omega(\beta, t) d\beta. \quad (\text{I.7})$$

To see that v may be represented as in (I.5), (I.6), one applies the Biot-Savart law to a discontinuous extension of v from its initial domain $\Omega(t)$ to all of \mathbb{R}^2 ; to make the extension, one solves a Neumann problem in $\mathbb{R}^2 \setminus \Omega(t)$.

Thus, our velocity field v admits multiple descriptions. Note that the description in terms of ω is significantly different from the descriptions in terms of ϕ , ψ and u_{normal} , because we bring in the Neumann problem on $\mathbb{R}^2 \setminus \Omega(t)$ to justify (I.5) and (I.6). When $\partial\Omega(t)$ is a “splash curve” as in Figure 1(c), there is no problem defining ϕ and it is smooth up to the boundary, except that it can take two different values at the splash point, for obvious reasons. The same is true of ψ . Similarly, $u_{normal}(\alpha, t)$ continues to behave well.

However, there is no reason to believe that $\omega(\alpha, t)$ will be well-defined and smooth for a splash curve, since $\mathbb{R}^2 \setminus \Omega(t)$ is a somewhat pathological domain. Our numerics suggest that $\max_\alpha |\omega(\alpha, t)| \sim \frac{C}{t_s - t}$, where t_s is the time of the splash.

Let us apply the above potential theory to the water wave problem. A standard formulation of the problem [5] takes $z(\alpha, t)$ and $\omega(\alpha, t)$ as unknowns. This has the advantage that at least we know where our unknown functions are supposed to be defined, which is more than

we can say for ϕ , ψ and u . Standard computations (see e.g. [13, Section 2]) show that the water wave problem is equivalent to the following equations

$$\partial_t z(\alpha, t) = BR(z, \omega)(\alpha, t) + \bar{c}(\alpha, t) \partial_\alpha z(\alpha, t) \quad (\text{I.8})$$

and

$$\begin{aligned} \partial_t \omega(\alpha, t) = & -2 \partial_\alpha z(\alpha, t) \cdot \partial_t BR(z, \omega)(\alpha, t) \\ & - \partial_\alpha \left(\frac{|\omega|^2}{4 |\partial_\alpha z|^2} \right) (\alpha, t) + \partial_\alpha (\bar{c}(\alpha, t) \omega(\alpha, t)) \\ & + 2 \bar{c}(\alpha, t) \partial_\alpha z(\alpha, t) \cdot \partial_\alpha BR(z, \omega)(\alpha, t) - 2g \partial_\alpha z_2(\alpha, t). \end{aligned} \quad (\text{I.9})$$

Here, $\bar{c}(\alpha, t)$ is a function that we may pick arbitrarily, since it influences only the parametrization of $\partial\Omega(t)$. For future reference, we write down several standard equations that follow from (I.1-I.4) by routine computation and elementary potential theory.

$$\Delta_x \phi(x, y, t) = \Delta_x \psi(x, y, t) = 0 \quad \text{in } \Omega(t); \quad \phi \text{ and } \psi \text{ are harmonic conjugates.}$$

$$p(x, y, t) = -\partial_t \phi(x, y, t) - \frac{1}{2} |\nabla \phi(x, y, t)|^2 - gy$$

$$\partial_n \psi|_{z(\alpha, t)} = -\frac{\partial_\alpha \Phi(\alpha, t)}{|\partial_\alpha z(\alpha, t)|}, \quad \text{where } \Phi(\alpha, t) = \phi(z(\alpha, t), t)$$

and n is the outward-pointing unit normal to $\partial\Omega(t)$.

$$\psi(x + 2\pi, y, t) = \psi(x, y, t) \text{ and } \phi(x + 2\pi, y, t) = \phi(x, y, t)$$

$$\psi(x, y, t) = O(1) \text{ as } y \rightarrow -\infty$$

$$v = \nabla^\perp \psi \text{ in } \Omega(t)$$

$$\partial_t z(\alpha, t) = v(z(\alpha, t), t) + c(\alpha, t) \partial_\alpha z(\alpha, t)$$

$$\partial_t \Phi(\alpha, t) = \frac{1}{2} |v(z(\alpha, t), t)|^2 + c(\alpha, t) v(z(\alpha, t), t) \cdot \partial_\alpha z(\alpha, t) - gy(\alpha, t) + p^*(t). \quad (\text{I.10})$$

We may write $u(\alpha, t)$ to denote $v(z(\alpha, t), t)$.

I.C Main Results

Our main result is the following theorem. For the definition of a splash curve see Definition II.1 in Section II. The interface shown in Figure 1(c) is an example of a splash curve.

Theorem I.1 *Let $z^0(\alpha)$ be a splash curve, where the splash point is given by $z^0(\alpha_1) = z^0(\alpha_2)$, $\alpha_1 \neq \alpha_2$. Let $u_{normal}^0(\alpha)$ be a scalar function in $H^4(\mathbb{T})$, satisfying*

$$\int_{\mathbb{T}} u_{normal}^0(\alpha) |\partial_\alpha z^0(\alpha)| d\alpha = 0 \quad (\text{I.11})$$

and

$$u_{normal}^0(\alpha_1), u_{normal}^0(\alpha_2) < 0. \quad (\text{I.12})$$

Then there exist a time $T > 0$; a time-varying domain $\Omega(t)$ defined for $t \in [0, T]$ and a velocity field $v(x, y, t)$ defined for $(x, y) \in \Omega(t)$, $t \in [0, T]$ such that the following hold:

$$\Omega(t) \text{ and } v(x, y, t) \text{ solve the water wave equations (I.1-I.4) for all } t \in [0, T]. \quad (\text{I.13})$$

$$\begin{aligned} \partial\Omega(t) \text{ is given as a parametrized curve } \{z(\alpha, t) : \alpha \in \mathbb{R}\}, \\ \text{with } z(\alpha, t) - (\alpha, 0) \text{ } 2\pi\text{-periodic in } \alpha \text{ for fixed } t. \end{aligned} \quad (\text{I.14})$$

$$z(\alpha, t) - (\alpha, 0) \in C([0, T], H^4(\mathbb{T})) \text{ and } v(z(\alpha, t), t) \in C([0, T], H^3(\mathbb{T})) \quad (\text{I.15})$$

$$z(\alpha, 0) = z^0(\alpha) \text{ and } u_{normal}(\alpha, 0) = u_{normal}^0(\alpha) \text{ for all } \alpha \in \mathbb{R}. \quad (\text{I.16})$$

$$\begin{aligned} \text{For each } t \in [0, T], \text{ the curve } \partial\Omega(t) \text{ satisfies the arc-chord condition,} \\ \text{but the arc-chord constant tends to zero as } t \rightarrow 0. \end{aligned} \quad (\text{I.17})$$

This result was announced in [8].

To prove that ‘‘splash singularities’’ can form, we note that the water wave equations are invariant under time reversal. Therefore, it is enough to exhibit a solution of the water wave equations that starts as a splash at time zero, but satisfies the arc-chord condition for each small positive time. Theorem I.1 provides such solutions.

Since the curve touches itself it is not clear if the vorticity amplitude is well defined, although the velocity potential remains nonsingular. In order to get around this issue we will apply a transformation from the original coordinates to new ones which we will denote with a tilde. The purpose of this transformation is to be able to deal with the failure of the arc-chord condition. Let us consider the scenario in the periodic setting and then the transformation defined by $\tilde{z}(\alpha, t) \equiv P(z(\alpha, t))$ where P is a conformal map that will be given as:

$$P(z) = \left(\tan \left(\frac{z}{2} \right) \right)^{1/2}$$

and the branch of the root will be taken in such a way that it separates the self-intersecting points of the interface. We will also need that the interface passes below the points $(\pm\pi, 0)$ (or, equivalently, that those points belong to the vacuum region) in order for the tilde region to lie inside a closed curve and the vacuum region to lie on the outer part. See Figures 3 and 4. Here $P(z)$ will refer to a 2 dimensional vector whose components are the real and imaginary parts of $P(z_1 + iz_2)$. Its inverse is given by

$$P^{-1}(w) = i \log \left(\frac{1 - iw^2}{1 + iw^2} \right) = 2 \arctan(w^2) \text{ for } w \in \mathbb{C}.$$

In this setting, $P^{-1}(z)$ will be well defined modulo multiples of 2π .

Remark I.2 Note that $P(z)$ is periodic such that $P(z + 2k\pi) = P(z)$. Moreover, $P(z)$ is one-to-one in the water region and single-valued except at the splash point.

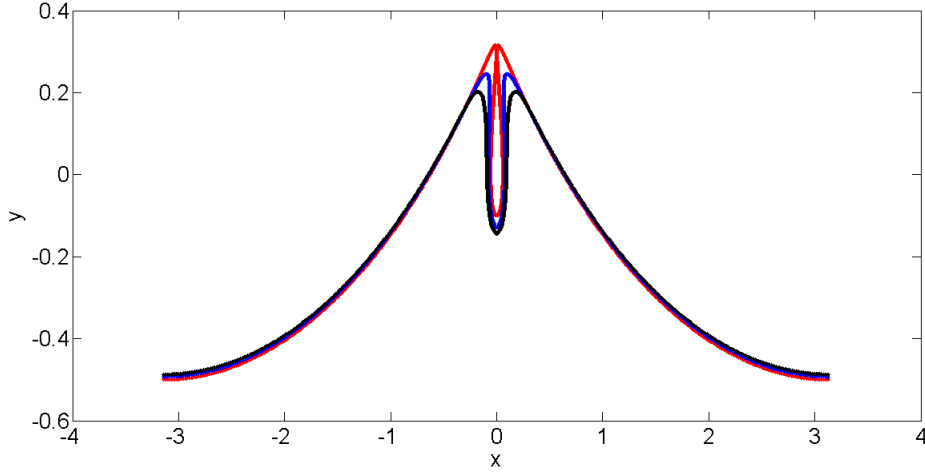


Figure 3: Splash singularity at times $t = 0$ (Red - splash), $t = 4 \cdot 10^{-3}$ (Blue - turning) and $t = 7 \cdot 10^{-3}$ (Black - graph).

Remark I.3 *Although the transformation to the tilde domain is convenient, the real reason for Theorem I.1 is that the potential theory inside the water region does not go bad as we approach the splash even though it goes bad in the vacuum region.*

We define the following quantities:

$$\begin{aligned} \tilde{\psi}(\tilde{x}, \tilde{y}, t) &\equiv \psi(P^{-1}(\tilde{x}, \tilde{y}), t), & \tilde{\phi}(\tilde{x}, \tilde{y}, t) &\equiv \phi(P^{-1}(\tilde{x}, \tilde{y}), t), & \tilde{v}(\tilde{x}, \tilde{y}, t) &\equiv \nabla \tilde{\phi}(\tilde{x}, \tilde{y}, t), \\ \tilde{\Phi}(\alpha, t) &= \tilde{\phi}(\tilde{z}(\alpha, t), t), & \tilde{\Psi}(\alpha, t) &= \tilde{\psi}(\tilde{z}(\alpha, t), t). \end{aligned}$$

Also we define $\tilde{\Omega}(t) = P(\Omega(t))$. Let us note that since ψ and ϕ are 2π periodic, the resulting $\tilde{\psi}$ and $\tilde{\phi}$ are well defined. We do not have problems with the harmonicity of $\tilde{\psi}$ or $\tilde{\phi}$ at the point which is mapped from minus infinity times i (which belongs to the water region) by P since ϕ and ψ tend to finite limits at minus infinity times i . Also, the periodicity of ϕ and ψ causes $\tilde{\phi}$ and $\tilde{\psi}$ to be continuous (and harmonic) at the interior of $P(\Omega^2(t))$.

Let us assume that there exists a solution of (I.10) and that we take $u_{normal} = \frac{\Psi_\alpha}{|z_\alpha|}$ such that $u_{normal}(\alpha_1), u_{normal}(\alpha_2) < 0$ for all $0 < t < T$, with T small enough, thus $z(\alpha, t)$ satisfies the arc-chord condition and does not touch the removed branch from $P(w)$.

The system (I.10) in the new coordinates reads

$$\begin{aligned}
\Delta \tilde{\psi}(\tilde{x}, \tilde{y}, t) &= 0 \quad \text{in } P(\Omega^2(t)) \\
\partial_n \tilde{\psi} \Big|_{\tilde{z}(\alpha, t)} &= -\frac{\tilde{\Phi}_\alpha(\alpha, t)}{|\tilde{z}_\alpha(\alpha, t)|} \\
\tilde{v} &\equiv \nabla^\perp \tilde{\psi} \quad \text{in } P(\Omega^2(t)) \\
\tilde{z}_t(\alpha, t) &= Q^2(\alpha, t) \tilde{u}(\alpha, t) + c(\alpha, t) \tilde{z}_\alpha(\alpha, t) \\
\tilde{\Phi}_t(\alpha, t) &= \frac{1}{2} Q^2(\alpha, t) |\tilde{u}(\alpha, t)|^2 + c(\alpha, t) \tilde{u}(\alpha, t) \cdot \tilde{z}_\alpha(\alpha, t) - g P_2^{-1}(\tilde{z}(\alpha, t)) \\
\tilde{z}(\alpha, 0) &= \tilde{z}^0(\alpha) \\
\tilde{\Phi}_\alpha(\alpha, 0) &= \tilde{\Phi}_\alpha^0(\alpha) = \Phi_\alpha^0(\alpha),
\end{aligned} \tag{I.18}$$

where \tilde{u} is the limit of the velocity coming from the fluid region in the tilde domain and

$$Q^2(\tilde{z}(\alpha, t), t) = \left| \frac{dP}{dw}(P^{-1}(\tilde{z}(\alpha, t))) \right|^2, \quad Q^2(\alpha, t) = \left| \frac{dP}{dw}(z(\alpha, t)) \right|^2.$$

We can solve the Neumann problem in the complement of $\tilde{\Omega}(t)$. Therefore we can represent the velocity field \tilde{v} in terms of a vorticity amplitude $\tilde{\omega}$.

We will see that \tilde{z} and $\tilde{\omega}$ satisfy the following equations

$$\tilde{z}_t(\alpha, t) = Q^2(\alpha, t) BR(\tilde{z}, \tilde{\omega})(\alpha, t) + \tilde{c}(\alpha, t) \tilde{z}_\alpha(\alpha, t). \tag{I.19}$$

$$\begin{aligned}
\tilde{\omega}_t(\alpha, t) &= -2 \partial_t BR(\tilde{z}, \tilde{\omega})(\alpha, t) \cdot \tilde{z}_\alpha(\alpha, t) - |BR(\tilde{z}, \tilde{\omega})|^2 \partial_\alpha Q^2(\alpha, t) \\
&\quad - \partial_\alpha \left(\frac{Q^2(\alpha, t)}{4} \frac{\tilde{\omega}(\alpha, t)^2}{|\tilde{z}_\alpha(\alpha, t)|^2} \right) + 2 \tilde{c}(\alpha, t) \partial_\alpha BR(\tilde{z}, \tilde{\omega}) \cdot \tilde{z}_\alpha(\alpha, t) \\
&\quad + \partial_\alpha (\tilde{c}(\alpha, t) \tilde{\omega}(\alpha, t)) - 2g \partial_\alpha (P_2^{-1}(\tilde{z}(\alpha, t))).
\end{aligned} \tag{I.20}$$

Remark I.4 *Equations (I.19-I.20) are analogous to (I.8-I.9). In fact, if we set $Q \equiv 1$ in (I.19-I.20) we recover (I.8-I.9).*

Our strategy will be the following: we will consider the evolution of the solutions in the tilde domain and then see that everything works fine in the original domain.

We will have to obtain the normal velocity once given the tangential velocity, and vice-versa. To do this, we just have to notice that

$$\tilde{\Phi}_\alpha(\alpha, t) = \tilde{u}(\alpha, t) \cdot \tilde{z}_\alpha(\alpha, t) = BR(\tilde{z}, \tilde{\omega}) \cdot \tilde{z}_\alpha(\alpha, t) + \frac{\tilde{\omega}(\alpha, t)}{2}.$$

From that, we can invert the equation (see [13]) and get $\tilde{\omega}$. Equation (I.6) in the tilde domain then tells us \tilde{v} on the boundary $\partial \tilde{\Omega}(t)$.

We now note that a solution of the system (I.18) in the tilde domain gives rise to a solution of the system (I.10) in the non-tilde domain, by inverting the map P . In fact, this will be the implication used in Theorem I.1 (finding a solution in the tilde domain, and therefore in the non-tilde).

Remark I.5 *It is likely that a similar argument works for the other two settings (closed contour and asymptotic to horizontal) by choosing an appropriate $P(w)$ that separates the singularity. For example, for the closed contour we could consider $P_{clo}(z) = \sqrt{z}$, taking the branch so that it separates the singularity, and for the asymptotic to horizontal scenario, it is enough to move the interface such that the water region is entirely contained in the lower halfplane (and the point $-i$ belongs to the vacuum region) and apply the relation $\frac{\tilde{z}+i}{\tilde{z}-i} = \sqrt{\frac{z+i}{z-i}}$.*

We now state the local existence results that lead to the proof of the existence of a splash singularity (Theorem I.1). To avoid the failure of the arc-chord condition, we will prove the local existence in the tilde domain. This can be done in two different settings, namely in the space of analytic functions and the Sobolev space H^s .

For the analytic version we define

$$S_r = \{\alpha + i\eta, |\eta| < r\},$$

$$\|f\|_{L^2(\partial S_r)}^2 = \sum_{\pm} \int_{-\pi}^{\pi} |f(\alpha \pm ir)|^2 d\alpha,$$

$$\|f\|_r^2 = \|f\|_{L^2(\partial S_r)}^2 + \|\partial_{\alpha}^3 f\|_{L^2(\partial S_r)}^2,$$

we consider the space

$$H^3(\partial S_r) = \{f \text{ analytic in } S_r, \|f\|_r^2 < \infty, f \text{ } 2\pi\text{-periodic}\}$$

and we take $(z_1 - \alpha, z_2, \Phi) \in (H^3(\partial S_r))^3 \equiv X_r$.

The first results concerning the Cauchy problem for small data in Sobolev spaces near the equilibrium point are due to Craig [18], Nalimov [25] and Yosihara [34]. Beale et al. [7] considered the Cauchy problem in the linearized version. For local existence with small analytic data see Sulem-Sulem [29]. Our main results regarding local existence in the tilde domain are the following theorems:

Theorem I.6 (Local existence for analytic initial data in the tilde domain) *Let $z^0(\alpha)$ be a splash curve and let $u^0 \cdot \frac{z_{\alpha}^0}{|z_{\alpha}^0|}(\alpha) = \frac{\Phi_{\alpha}^0}{|z_{\alpha}^0|}(\alpha)$ be the initial tangential velocity such that*

$$(z_1^0(\alpha) - \alpha, z_2^0(\alpha), \Phi^0(\alpha)) \in X_{r_0},$$

for some $r_0 > 0$, and satisfying:

1. $u_{normal}^0(\alpha_1) = u_{normal}(\alpha_1, 0) < 0, \quad u_{normal}^0(\alpha_2) = u_{normal}(\alpha_2, 0) < 0$
2. $\int_{\mathbb{T}} u_{normal}^0(\alpha) |\partial_{\alpha} z^0(\alpha)| d\alpha = 0.$

Then there exist a finite time $T > 0$, $0 < r < r_0$, a time-varying curve $\tilde{z}(\alpha, t)$ and a function $\tilde{\Phi}(\alpha, t)$ satisfying:

1. $P^{-1}(\tilde{z}_1(\alpha, t)) - \alpha, P^{-1}(\tilde{z}_2(\alpha, t))$ are 2π -periodic,
2. $P^{-1}(\tilde{z}(\alpha, t))$ satisfies the arc-chord condition for all $t \in (0, T]$,

and $\tilde{u}(\alpha, t)$ with

$$(\tilde{z}_1(\alpha, t), \tilde{z}_2(\alpha, t), \tilde{\Phi}(\alpha, t)) \in C([0, T], X_r)$$

which provides a solution of the water wave equations (I.18) with $\tilde{z}^0(\alpha) = P(z^0(\alpha))$ and $\tilde{u}(\alpha, 0) \cdot (\tilde{z}_\alpha)^\perp(\alpha, 0) = \tilde{u}^0(\alpha) \cdot (\tilde{z}^0)_\alpha^\perp(\alpha)$.

The main tool in the proof is an abstract Cauchy-Kowalewski theorem from [26] and [27]. For more details see [11].

For the proof of local existence in Sobolev spaces we will take the following $\tilde{c}(\alpha, t)$:

$$\begin{aligned} \tilde{c}(\alpha, t) &= \frac{\alpha + \pi}{2\pi} \int_{-\pi}^{\pi} (Q^2 BR(\tilde{z}, \tilde{\omega}))_\beta(\beta, t) \cdot \frac{\tilde{z}_\beta(\beta, t)}{|\tilde{z}_\beta(\beta, t)|^2} d\beta \\ &\quad - \int_{-\pi}^{\alpha} (Q^2 BR(\tilde{z}, \tilde{\omega}))_\beta(\beta, t) \cdot \frac{\tilde{z}_\beta(\beta, t)}{|\tilde{z}_\beta(\beta, t)|^2} d\beta. \end{aligned}$$

This choice of \tilde{c} will ensure that $|\tilde{z}(\alpha, t)|$ depends only on t . We will also define an auxiliary function $\tilde{\varphi}(\alpha, t)$ analogous to the one introduced in [7] (for the linear case) and [4] (nonlinear case) which helps us to bound several of the terms that appear:

$$\tilde{\varphi}(\alpha, t) = \frac{Q^2(\alpha, t)\tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|} - \tilde{c}(\alpha, t)|\tilde{z}_\alpha(\alpha, t)|. \quad (\text{I.21})$$

Then, we can prove the following theorem:

Theorem I.7 (Local existence for initial data in Sobolev spaces in the tilde domain)

In the setting of Section I.B, let $\tilde{z}^0(\alpha)$ be the image of a splash curve by the map P parametrized in such a way that $|\partial_\alpha \tilde{z}^0(\alpha)|$ does not depend on α , and such that $\tilde{z}_1^0(\alpha), \tilde{z}_2^0(\alpha) \in H^4(\mathbb{T})$. Let $\tilde{\varphi}(\alpha, 0) \in H^{3+\frac{1}{2}}(\mathbb{T})$ be as in (I.21) and let $\tilde{\omega}(\alpha, 0) \in H^2(\mathbb{T})$. Then there exist a finite time $T > 0$, a time-varying curve $\tilde{z}(\alpha, t) \in C([0, T]; H^4)$, and functions $\tilde{\omega}(\alpha, t) \in C([0, T]; H^2)$ and $\tilde{\varphi} \in C([0, T]; H^{3+\frac{1}{2}})$ providing a solution of the water wave equations (I.19 - I.20).

The proof is based on the adaptation of the local existence proof in [13] to the tilde domain.

Some of the relevant estimates from [13] obviously hold here as well, with essentially unchanged proofs. We state such results in Lemmas IV.2 and Lemmas IV.5, ..., IV.9 below; and refer the reader to the relevant sections of [13] for the proofs.

However, [13] contains several ‘‘miracles’’, i.e., complicated calculations and estimates that lead to simple favorable results for no apparent reason. To see that analogous ‘‘miracles’’ occur in our present setting, we have to go through the arguments in detail; see Lemmas IV.10 and IV.12, ..., IV.15 below.

We have tried to make it possible to check the correctness of our arguments without extreme effort, and without undue repetitions from [13].

It would be very interesting to understand a-priori why the “miracles” in this paper and in [4], [13] occur. Presumably there is a simple, conceptual explanation, which at present we do not know.

At the end of Section II we will define the notion of a “splat curve”. The curve depicted in Figure 2(b) is an example of a splat curve.

In the statement of Theorem I.7, we may take $\tilde{z}_0(\alpha)$ to be the image of a splat curve under P rather than the image of a splash curve.

The proof of Theorem I.7 goes through for this case with trivial changes. Consequently, we obtain an analogue of Theorem I.6, with hypothesis 1 replaced by

Hypothesis 1': $u_{normal}^0 = u_{normal}(\alpha, 0)$ is negative for all $\alpha \in I_1 \cup I_2$, where I_1, I_2 are the intervals appearing in the definition of a splat curve in Section II.

Just as Theorem I.6 implies the formation of splash singularities for water waves, the above analogue of Theorem I.6 for splat curves implies

Corollary I.8 (Splat singularity) *There exist solutions of the water wave system that collapse along an arc in finite time, but remain otherwise smooth.*

I.D Further Results

Here we mention some immediate consequences of our results which are relevant:

1. (Splash and Splat singularities for 3D water waves) It is possible to extend our results to the periodic three dimensional setting by considering scenarios invariant under translation in one of the coordinate directions. While preparing the final revisions of this manuscript, we noticed that in a very recent arXiv posting [17], Coutand-Shkoller consider additional 3D splash singularities.
2. (No gravity) The existence of a splash singularity can also be proved in the case where the gravity constant g is equal to zero, as long as the Rayleigh-Taylor condition holds.

II Splash curves: transformation to the tilde domain and back

In this section we will rewrite the equations by applying a transformation from the original coordinates to new ones which we will denote by tilde. The purpose of this transformation is to be able to deal with the failure of the arc-chord condition.

For initial data we are interested in considering a self-intersecting curve in one point. More precisely, we will use as initial data *splash curves* which are defined this way:

Definition II.1 *We say that $z(\alpha) = (z_1(\alpha), z_2(\alpha))$ is a splash curve if*

1. $z_1(\alpha) - \alpha, z_2(\alpha)$ are smooth functions and 2π -periodic.

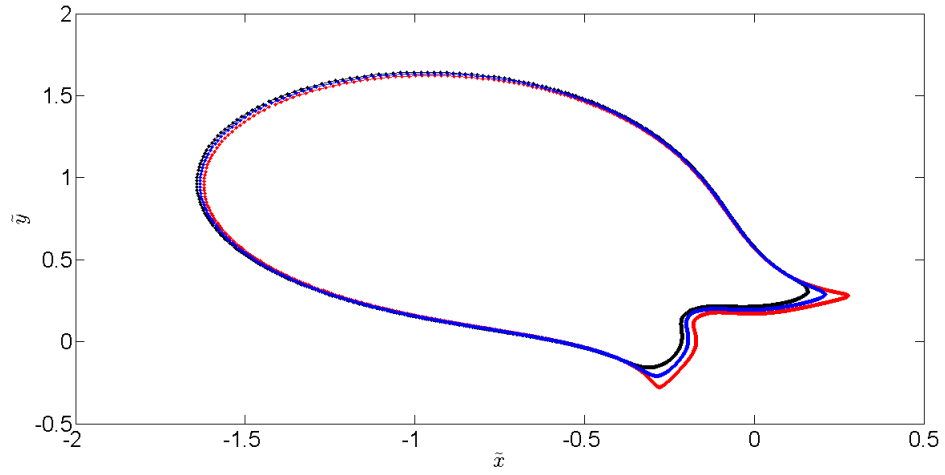


Figure 4: Tilde domain at times $t = 0$ (Red - splash), $t = 4 \cdot 10^{-3}$ (Blue - turning) and $t = 7 \cdot 10^{-3}$ (Black - graph).

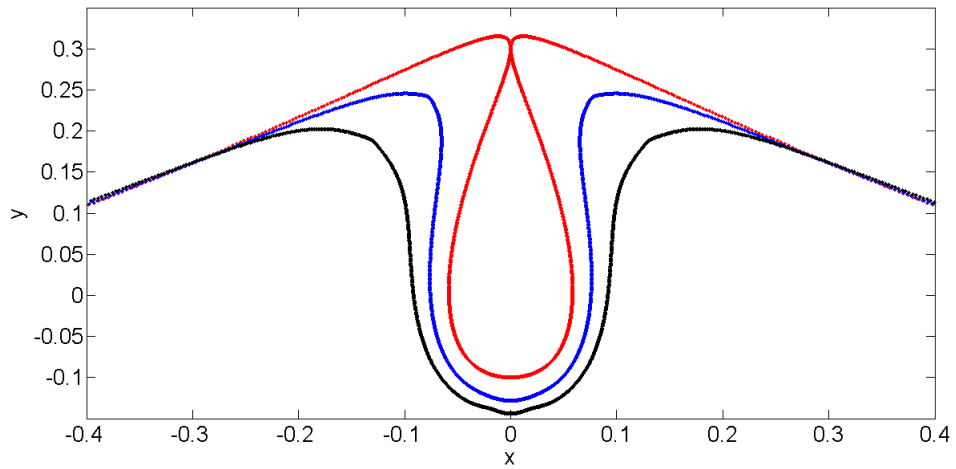


Figure 5: Zoom of the splash singularity at times $t = 0$ (Red - splash), $t = 4 \cdot 10^{-3}$ (Blue - turning) and $t = 7 \cdot 10^{-3}$ (Black - graph).

2. $z(\alpha)$ satisfies the arc-chord condition at every point except at α_1 and α_2 , with $\alpha_1 < \alpha_2$ where $z(\alpha_1) = z(\alpha_2)$ and $|z_\alpha(\alpha_1)|, |z_\alpha(\alpha_2)| > 0$. This means $z(\alpha_1) = z(\alpha_2)$, but if we remove either a neighborhood of α_1 or a neighborhood of α_2 in parameter space, then the arc-chord condition holds.
3. The curve $z(\alpha)$ separates the complex plane into two regions; a connected water region and a vacuum region (not necessarily connected). The water region contains each point $x+iy$ for which y is large negative. We choose the parametrization such that the normal vector $n = \frac{(-\partial_\alpha z_2(\alpha), \partial_\alpha z_1(\alpha))}{|\partial_\alpha z(\alpha)|}$ points to the vacuum region. We regard the interface to be part of the water region.
4. We can choose a branch of the function P on the water region such that the curve $\tilde{z}(\alpha) = (\tilde{z}_1(\alpha), \tilde{z}_2(\alpha)) = P(z(\alpha))$ satisfies:
 - (a) $\tilde{z}_1(\alpha)$ and $\tilde{z}_2(\alpha)$ are smooth and 2π -periodic.
 - (b) \tilde{z} is a closed contour.
 - (c) \tilde{z} satisfies the arc-chord condition.

We will choose the branch of the root that produces that

$$\lim_{y \rightarrow -\infty} P(x + iy) = -e^{-i\pi/4}$$

independently of x .

5. $P(w)$ is analytic at w and $\frac{dP}{dw}(w) \neq 0$ if w belongs to the interior of the water region. Furthermore, $(\pm\pi, 0)$ and $(0, 0)$ belong to the vacuum region.
6. $\tilde{z}(\alpha) \neq q^l$ for $l = 0, \dots, 4$, where

$$q^0 = (0, 0), \quad q^1 = \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right), \quad q^2 = \left(\frac{-1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right), \quad q^3 = \left(\frac{-1}{\sqrt{2}}, \frac{-1}{\sqrt{2}}\right), \quad q^4 = \left(\frac{1}{\sqrt{2}}, \frac{-1}{\sqrt{2}}\right). \quad (\text{II.1})$$

From now on, we will always work with splash curves as initial data unless we say otherwise. Condition 6 will be used in the local existence theorems and can be proved to hold for short enough time as long as the initial condition satisfies it. It is also immediate to check that the previous choice of P transforms any periodic interface into a closed curve. Here are two examples of curves which are not splash curves (see Figure 6).

Now we will show a careful deduction of the equations in the tilde domain. From the definition of \tilde{z} we have that

$$\tilde{z}_\alpha(\alpha, t) = \nabla P(z(\alpha, t)) \cdot z_\alpha(\alpha, t) \quad (\text{II.2})$$

and

$$\begin{aligned} \tilde{z}_t(\alpha, t) &= \nabla P(z(\alpha, t)) \cdot z_t(\alpha, t) = \nabla P(z(\alpha, t)) \cdot (u(\alpha, t) + c(\alpha, t)z_\alpha(\alpha, t)) \\ &= \nabla P(z(\alpha, t)) \cdot u(\alpha, t) + c\tilde{z}_\alpha(\alpha, t). \end{aligned} \quad (\text{II.3})$$

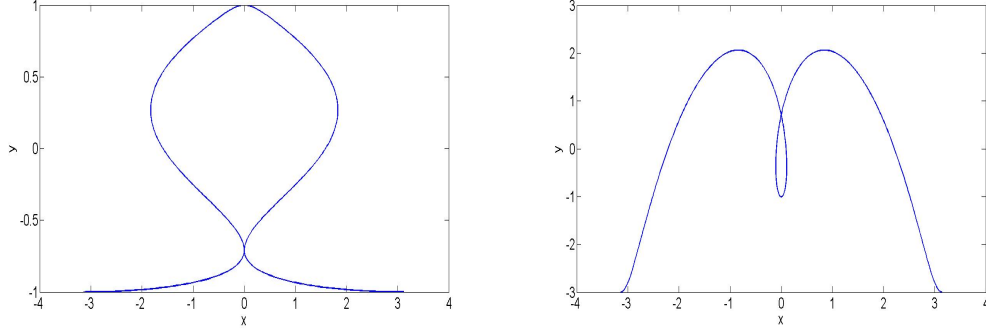


Figure 6: Two examples of non splash curves.

Since $\phi = \tilde{\phi} \circ P$ and $v = \nabla\phi = \nabla(\tilde{\phi} \circ P)$, we obtain

$$v_i = \partial_i\phi = \partial_i(\tilde{\phi} \circ P) = \sum_j (\partial_j\tilde{\phi} \circ P) \frac{\partial P_j}{\partial x_i} = \sum_j (\tilde{v}_j \circ P) \partial_i P_j. \quad (\text{II.4})$$

This implies that

$$u(\alpha, t) = \nabla P(z(\alpha, t))^T \tilde{u}(\alpha, t). \quad (\text{II.5})$$

Plugging this into (II.3) we get

$$\tilde{z}_t(\alpha, t) = \nabla P(z(\alpha, t)) \cdot \nabla P(z(\alpha, t))^T \cdot \tilde{u}(\alpha, t) + c\tilde{z}_\alpha(\alpha, t). \quad (\text{II.6})$$

From the Cauchy-Riemann equations

$$\nabla P(z(\alpha, t)) \cdot \nabla P(z(\alpha, t))^T = Q^2(\alpha, t) \cdot Id_2, \quad Q^2(\alpha, t) = \left| \frac{dP(z)}{dz} \right|^2. \quad (\text{II.7})$$

In this particular case, this means that

$$Q^2(\alpha, t) = \left| \frac{1 + \tilde{z}(\alpha, t)^4}{4\tilde{z}(\alpha, t)} \right|^2, \quad \tilde{z}(\alpha, t) = \tilde{z}_1(\alpha, t) + i\tilde{z}_2(\alpha, t).$$

Recall that $\tilde{\Phi}$ is the restriction of $\tilde{\phi}$ to the interface, i.e. $\tilde{\Phi}(\alpha, t) = \tilde{\phi}(\tilde{z}(\alpha, t), t)$. Then

$$\tilde{\Phi}(\alpha, t) = \tilde{\phi}(\tilde{z}(\alpha, t), t) = \phi(P^{-1}(\tilde{z}(\alpha, t)), t) = \phi(z(\alpha, t), t) = \Phi(\alpha, t) \quad (\text{II.8})$$

Thus, $\tilde{\Phi}$ satisfies

$$\begin{aligned} \frac{\partial \tilde{\Phi}}{\partial t} &= \frac{1}{2} |u(\alpha, t)|^2 + c(\alpha, t) u(\alpha, t) \cdot z_\alpha(\alpha, t) - g z_2(\alpha, t) \\ &= \frac{1}{2} |\nabla P(z(\alpha, t))^T \cdot \tilde{u}(\alpha, t)|^2 + c(\alpha, t) \tilde{u}(\alpha, t) \cdot \tilde{z}_\alpha(\alpha, t) - g P_2^{-1}(\tilde{z}(\alpha, t)), \end{aligned} \quad (\text{II.9})$$

where the subscript in the gravity term of the last line denotes the second component. Thus the system (I.10) in the new coordinates reads

$$\begin{aligned}
\Delta\tilde{\psi}(x, y, t) &= 0 \quad \text{in } P(\Omega^2(t)) \\
\partial_n\tilde{\psi}\Big|_{\tilde{z}(\alpha, t)} &= -\frac{\tilde{\Phi}_\alpha(\alpha, t)}{|\tilde{z}_\alpha(\alpha, t)|} \\
\tilde{v} &\equiv \nabla^\perp\tilde{\psi} \quad \text{in } P(\Omega^2(t)) \\
\tilde{z}_t(\alpha, t) &= Q^2(\alpha, t)\tilde{u}(\alpha, t) + c(\alpha, t)\tilde{z}_\alpha(\alpha, t) \\
\tilde{\Phi}_t(\alpha, t) &= \frac{1}{2}Q^2(\alpha, t)|\tilde{u}(\alpha, t)|^2 + c(\alpha, t)\tilde{u}(\alpha, t) \cdot \tilde{z}_\alpha(\alpha, t) - gP_2^{-1}(\tilde{z}(\alpha, t)) + p^*(t) \\
\tilde{z}(\alpha, 0) &= \tilde{z}^0(\alpha) \\
\tilde{\Phi}_\alpha(\alpha, 0) &= \tilde{\Phi}_\alpha^0(\alpha) = \Phi_\alpha^0(\alpha).
\end{aligned} \tag{II.10}$$

We have seen that \tilde{v} can be represented in the form

$$\tilde{v}(\tilde{x}, \tilde{y}, t) = \nabla^\perp\tilde{\psi}(\tilde{x}, \tilde{y}, t) = \frac{1}{2\pi}P.V \int_{-\pi}^{\pi} \frac{(\tilde{x} - \tilde{z}_1(\alpha, t), \tilde{y} - \tilde{z}_2(\alpha, t))^\perp}{|(\tilde{x} - \tilde{z}_1(\alpha, t), \tilde{y} - \tilde{z}_2(\alpha, t))|^2} \tilde{\omega}(\alpha, t) d\alpha.$$

Taking limits from the fluid region we obtain

$$\tilde{u}(\alpha, t) = BR(\tilde{z}, \tilde{\omega}) + \frac{\tilde{\omega}}{2|\tilde{z}_\alpha|^2} \tilde{z}_\alpha.$$

The evolution of $\tilde{\omega}$ is calculated in the following way. First, let us recall the equations

$$\begin{aligned}
\tilde{z}_t(\alpha, t) &= Q^2(\alpha, t)\tilde{u}(\alpha, t) + c(\alpha, t)\tilde{z}_\alpha(\alpha, t) \\
\tilde{\Phi}_t(\alpha, t) &= \frac{1}{2}Q^2(\alpha, t)|\tilde{u}(\alpha, t)|^2 + c(\alpha, t)\tilde{u}(\alpha, t) \cdot \tilde{z}_\alpha(\alpha, t) - gP_2^{-1}(\tilde{z}(\alpha, t)) \\
\tilde{\Phi}_\alpha(\alpha, t) &= \tilde{u}(\alpha, t) \cdot \tilde{z}_\alpha(\alpha, t) \\
\tilde{z}(\alpha, 0) &= \tilde{z}^0(\alpha) \\
\tilde{\Phi}_\alpha(\alpha, 0) &= \tilde{\Phi}_\alpha^0(\alpha) = \Phi_\alpha^0(\alpha).
\end{aligned} \tag{II.11}$$

Substituting the expression for $\tilde{u}(\alpha, t)$ and performing the change $\tilde{c}(\alpha, t) = c(\alpha, t) + \frac{1}{2}Q^2(\alpha, t)\frac{\tilde{\omega}(\alpha, t)}{|\tilde{z}_\alpha(\alpha, t)|^2}$ we obtain

$$\begin{aligned}
\tilde{z}_t(\alpha, t) &= Q^2(\alpha, t)BR(\tilde{z}, \tilde{\omega})(\alpha, t) + \tilde{c}(\alpha, t)\tilde{z}_\alpha(\alpha, t) \\
\tilde{\Phi}_\alpha(\alpha, t) &= BR(\tilde{z}, \tilde{\omega})(\alpha, t) \cdot \tilde{z}_\alpha(\alpha, t) + \frac{1}{2}\tilde{\omega}(\alpha, t) \\
\tilde{\Phi}_t(\alpha, t) &= \frac{1}{2}Q^2(\alpha, t)|\tilde{u}(\alpha, t)|^2 + c(\alpha, t)\tilde{u}(\alpha, t) \cdot \tilde{z}_\alpha(\alpha, t) - gP_2^{-1}(\tilde{z}(\alpha, t)) \\
&= \frac{1}{2}Q^2(\alpha, t)|BR(\tilde{z}, \tilde{\omega})(\alpha, t)|^2 - \frac{Q^2(\alpha, t)}{8} \frac{\tilde{\omega}(\alpha, t)^2}{|\tilde{z}_\alpha(\alpha, t)|^2} \\
&\quad + \tilde{c}(\alpha, t)BR(\tilde{z}, \tilde{\omega}) \cdot \tilde{z}_\alpha(\alpha, t) + \frac{1}{2}\tilde{c}(\alpha, t)\tilde{\omega}(\alpha, t) - gP_2^{-1}(\tilde{z}(\alpha, t)).
\end{aligned} \tag{II.12}$$

On the one hand, by taking derivatives with respect to t in the second equation follows

$$\begin{aligned}
\tilde{\Phi}_{\alpha t}(\alpha, t) &= \partial_t BR(\tilde{z}, \tilde{\omega})(\alpha, t) \cdot \tilde{z}_\alpha(\alpha, t) + BR(\tilde{z}, \tilde{\omega})(\alpha, t) \cdot \tilde{z}_{\alpha t}(\alpha, t) + \frac{\tilde{\omega}_t(\alpha, t)}{2} \\
&= \partial_t BR(\tilde{z}, \tilde{\omega}) \cdot \tilde{z}_\alpha(\alpha, t) + |BR(\tilde{z}, \tilde{\omega})|^2 \partial_\alpha Q^2(\alpha, t) \\
&+ Q^2(\alpha, t) BR(\tilde{z}, \tilde{\omega}) \cdot \partial_\alpha BR(\tilde{z}, \tilde{\omega}) + \tilde{c}_\alpha(\alpha, t) BR(\tilde{z}, \tilde{\omega}) \cdot \tilde{z}_\alpha(\alpha, t) \\
&+ \tilde{c}(\alpha, t) BR(\tilde{z}, \tilde{\omega}) \cdot \tilde{z}_{\alpha\alpha}(\alpha, t) + \frac{\tilde{\omega}_t(\alpha, t)}{2}. \tag{II.13}
\end{aligned}$$

On the other, taking derivatives with respect to α in the third equation in (II.12) yields

$$\begin{aligned}
\tilde{\Phi}_{\alpha t}(\alpha, t) &= \frac{1}{2} |BR(\tilde{z}, \tilde{\omega})|^2 \partial_\alpha Q^2(\alpha, t) + Q^2(\alpha, t) BR(\tilde{z}, \tilde{\omega}) \cdot \partial_\alpha BR(\tilde{z}, \tilde{\omega}) \\
&- \frac{1}{2} \partial_\alpha \left(\frac{Q^2(\alpha, t)}{4} \frac{\tilde{\omega}(\alpha, t)^2}{|\tilde{z}_\alpha(\alpha, t)|^2} \right) + \tilde{c}_\alpha(\alpha, t) BR(\tilde{z}, \tilde{\omega}) \cdot \tilde{z}_\alpha(\alpha, t) \\
&+ \tilde{c}(\alpha, t) \partial_\alpha BR(\tilde{z}, \tilde{\omega}) \cdot \tilde{z}_\alpha(\alpha, t) + \tilde{c}(\alpha, t) BR(\tilde{z}, \tilde{\omega}) \cdot \tilde{z}_{\alpha\alpha}(\alpha, t) \\
&+ \frac{1}{2} \partial_\alpha (\tilde{c}(\alpha, t) \tilde{\omega}(\alpha, t)) - \partial_\alpha (gP_2^{-1}(\tilde{z}(\alpha, t))). \tag{II.14}
\end{aligned}$$

Combining both equations, we find that

$$\begin{aligned}
\tilde{\omega}_t(\alpha, t) &= -2\partial_t BR(\tilde{z}, \tilde{\omega})(\alpha, t) \cdot \tilde{z}_\alpha(\alpha, t) - |BR(\tilde{z}, \tilde{\omega})|^2 \partial_\alpha Q^2(\alpha, t) \\
&- \partial_\alpha \left(\frac{Q^2(\alpha, t)}{4} \frac{\tilde{\omega}(\alpha, t)^2}{|\tilde{z}_\alpha(\alpha, t)|^2} \right) + 2\tilde{c}(\alpha, t) \partial_\alpha BR(\tilde{z}, \tilde{\omega}) \cdot \tilde{z}_\alpha(\alpha, t) \\
&+ \partial_\alpha (\tilde{c}(\alpha, t) \tilde{\omega}(\alpha, t)) - 2\partial_\alpha (gP_2^{-1}(\tilde{z}(\alpha, t))). \tag{II.15}
\end{aligned}$$

We will proceed in the following way: we will consider the evolution of the solutions in the tilde domain and see that everything works fine in the original domain. For example, the sign condition on the normal vectors in the non-tilde domain has an equivalent form in the tilde domain (i.e. the two normal components have negative sign).

In the non-tilde domain, this implies that the interface moves away from the branch removed from the square root, and therefore the interface touches neither the branch cut nor the conflictive points q^l (see Condition 6 in Definition II.1). Hence P and P^{-1} will be well defined and one-to-one. (See Figure 9).

Let us note that getting $\phi = \tilde{\phi} \circ P$ is not a problem since ϕ is bounded and harmonic. Moreover, as $\tilde{v} = \nabla^\perp \tilde{\psi}$ and

$$v = \nabla P^T(\tilde{v} \circ P)$$

and ∇P has exponential decay at infinity, the velocity v belongs to $L^2(\Omega^2(t)) \cap [-\pi, \pi] \times \mathbb{R}$.

Remark II.2 Ψ, Φ, u and z have easy transformations to the tilde domain but ω has not.

We would like to discuss what happens to the amplitude of the vorticity ω in the non-tilde domain as the curve approaches the splash.

If the vorticity belongs to $C([0, T_{splash}], C^\delta(\mathbb{T}))$, then the normal velocity should be continuous at the splash point and therefore the normal component of the restriction of the

velocity to the curve from the water region cannot have the same sign at $z(\alpha_1)$ and $z(\alpha_2)$ (see Theorem I.1). This means that the C^δ -norm of the amplitude of the vorticity becomes unbounded at the time of the splash.

We illustrate this phenomenon by plotting $1/\max|\omega|$ (see Figure 7), where the blue curve is the calculated ω and the red curve is a potential fitting to the data as numerical instabilities don't allow us to compute ω with enough precision when we are in the regime which is close to the splash. Time has been reversed so that the splash occurs at time $t = 0$ and the interface separates from itself at $t > 0$.

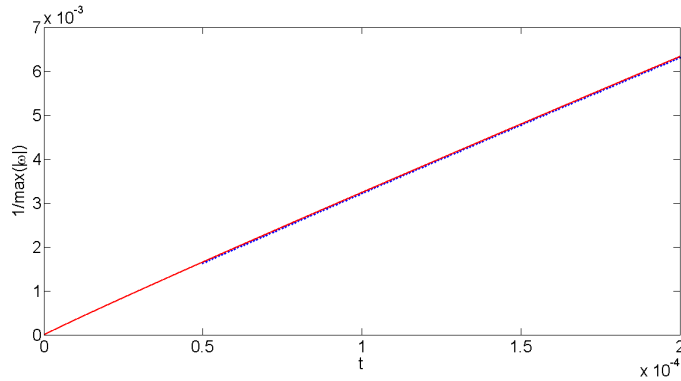


Figure 7: Vorticity amplitude in the nontilde domain. The vorticity reaches infinity at a rate of approximately $\frac{1}{(T_{splash}-t)^{0.966}} \approx \frac{1}{(T_{splash}-t)}$. The fit is given by $F = 23.72 \cdot t^{0.966} - 1.476 \cdot 10^{-6}$.

We also have performed numerical simulations in order to get a blowup rate for the arc-chord condition. As in Figure 7, we plot the inverse of the arc-chord constant. The blue curve is made by the calculated points and the red curve is the interpolating one. We see a very good fitting. Time follows the same convention as before and the numerical evidence indicates a blowup of the arc-chord as $\frac{1}{T_{splash}-t}$. The results can be seen in Figure 8.

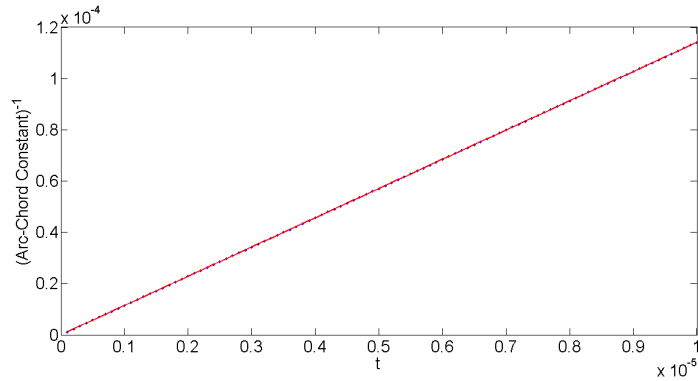


Figure 8: Arc-chord condition in the non-tilde domain. The arc-chord reaches infinity at a rate of approximately $\frac{1}{(T_{splash}-t)}$. The fit is given by $F = 11.41 \cdot t + 5.104 \cdot 10^{-9}$.

We also kept track of the energy conservation. If we consider the following energy (not to be confused with the one in Section IV):

$$E_S(t) = \frac{1}{2} \int_{\Omega_f^2(t)} |v(x, y, t)|^2 dx dy + \frac{1}{2} \int_{-\pi}^{\pi} g(z_2(\alpha, t))^2 \partial_\alpha z_1(\alpha, t) d\alpha \equiv E_k(t) + E_p(t) \quad (\text{II.16})$$

where $z(\alpha, t) = (z_1(\alpha, t), z_2(\alpha, t))$, $u(\alpha, t) = v(z(\alpha, t), t)$, and $\Omega_f^2(t) = \Omega^2(t) \cap [-\pi, \pi] \times \mathbb{R}$ is a fundamental domain in the water region in a period, then we can see that the energy is conserved; this is a check of the accuracy of our numerics.

$$\begin{aligned} \frac{dE_k(t)}{dt} &= \int_{\Omega_f^2(t)} v(x, y, t) (v_t(x, y, t) + v(x, y, t) \cdot \nabla v(x, y, t)) dx dy \\ &= \int_{\Omega_f^2(t)} v(x, y, t) (-\nabla p(x, y, t) - g(0, 1)) dx dy \\ &= - \int_{\Omega_f^2(t)} v(x, y, t) (\nabla(p(x, y, t) + gy)) dx dy \\ &= - \int_{\partial(\Omega_f^2(t))} v(x, y, t) \cdot \vec{n} gy ds \\ &= - \int_{-\pi}^{\pi} g z_2(\alpha, t) u(\alpha, t) \cdot \partial_\alpha z^\perp(\alpha, t) d\alpha \end{aligned} \quad (\text{II.17})$$

where we have used the incompressibility of the fluid ($\nabla \cdot v = 0$) and the continuity of the pressure on the interface ($p^*(t)|_{\partial\Omega^2(t)} = 0$). Next

$$\begin{aligned} \frac{dE_p(t)}{dt} &= \int_{-\pi}^{\pi} g z_2(\alpha, t) \partial_t z_2(\alpha, t) \partial_\alpha z_1(\alpha, t) d\alpha + \frac{1}{2} \int_{-\pi}^{\pi} g (z_2(\alpha, t))^2 \partial_t \partial_\alpha z_1(\alpha, t) d\alpha \\ &= \int_{-\pi}^{\pi} g z_2(\alpha, t) \partial_t z_2(\alpha, t) \partial_\alpha z_1(\alpha, t) d\alpha - \int_{-\pi}^{\pi} g z_2(\alpha, t) \partial_\alpha z_2(\alpha, t) \partial_t z_1(\alpha, t) d\alpha \\ &= \int_{-\pi}^{\pi} g z_2(\alpha, t) u(\alpha, t) \cdot \partial_\alpha z^\perp(\alpha, t) d\alpha. \end{aligned} \quad (\text{II.18})$$

This proves that the energy is constant. Note that:

$$\begin{aligned} \int_{\Omega_f^2(t)} |v(x, y, t)|^2 dx dy &= \int_{\Omega_f^2(t)} |\nabla \phi(x, y, t)|^2 dx dy \\ &= - \int_{\Omega_f^2(t)} \phi(x, y, t) \Delta \phi(x, y, t) dx dy \\ &\quad + \int_{\partial(\Omega_f^2(t))} \phi(x, y, t) \nabla \phi(x, y, t) \cdot \vec{n} dx dy \\ &\stackrel{\Delta \phi = 0}{=} \int_{\partial(\Omega_f^2(t))} \phi(x, y, t) \nabla \phi(x, y, t) \cdot \vec{n} dx dy \end{aligned} \quad (\text{II.19})$$

so the numerical calculation is restricted to the values at the boundary. We observe that the energy of our system is conserved, as we have

$$E_S(t) \approx 38.3936, \quad \frac{\max_t E_S(t) - \min_t E_S(t)}{\min_t E_S(t)} \approx 6 \cdot 10^{-11}.$$

We now give the proof of Theorem I.1 using Theorem I.7.

Proof of Theorem I.1: Using the fact that there is local existence to the initial data in the tilde domain and applying P^{-1} to the solution obtained there, we can get a curve $z(\alpha, t)$ that solves the water wave equation in the non tilde domain. Details on the local existence in the tilde domain are shown below. Note that the sign condition (I.12) assumed in Theorem I.1 guarantees that for positive time t the curve in the nontilde domain will separate (as depicted in Figure 9(a)) instead of crossing itself (as depicted in Figure 9(b)). More precisely, we check that for small positive time t the curve $\alpha \mapsto z(\alpha, t) = (z_1(\alpha, t), z_2(\alpha, t)) = P^{-1}(\tilde{z}(\alpha, t)) \in \mathbb{R}/2\pi\mathbb{Z} \times \mathbb{R}$ is a simple closed curve, i.e. that $\alpha \mapsto z(\alpha, t)$ is one-to-one. Indeed, if not, there exist a sequence of positive times $t_\nu \rightarrow 0$ and points $\alpha'_\nu, \alpha''_\nu$ such that $\alpha'_\nu \neq \alpha''_\nu \pmod{2\pi\mathbb{Z}}$, but $z(\alpha'_\nu, t_\nu) = z(\alpha''_\nu, t_\nu)$. Since the initial splash curve $\alpha \mapsto z(\alpha, 0)$ satisfies the modified chord-arc condition described in Condition 2 of Definition II.1, we may assume without loss of generality that $\alpha'_\nu \rightarrow \alpha_1$ and $\alpha''_\nu \rightarrow \alpha_2$ (with α_1, α_2 as in Definition II.1). The sign condition (I.12) therefore guarantees that (for large ν), $\tilde{z}(\alpha'_\nu, t_\nu)$ and $\tilde{z}(\alpha''_\nu, t_\nu)$ lie in the image of the (open) time-zero water region under the map P . Moreover (for large ν), $\tilde{z}(\alpha'_\nu, t_\nu) \neq \tilde{z}(\alpha''_\nu, t_\nu)$ since $\tilde{z}(\alpha_1, 0) \neq \tilde{z}(\alpha_2, 0)$.

Since P^{-1} is one-to-one on the image of the open time-zero water region under P , it follows that (for large ν) we have $z(\alpha'_\nu, t_\nu) \neq z(\alpha''_\nu, t_\nu) \in \mathbb{R}/2\pi\mathbb{Z} \times \mathbb{R}$, with $z(\alpha, t) \equiv P^{-1}(\tilde{z}(\alpha, t))$. This contradicts the defining condition $z(\alpha'_\nu, t_\nu) = z(\alpha''_\nu, t_\nu)$, completing the proof that $\alpha \mapsto z(\alpha, t)$ is a simple closed curve for small positive t .

The proof of Theorem I.1 is complete. \square

We end this section by defining a “splat curve”, as promised in Section I. To do so, we simply modify our Definition II.1 for a splash curve, by replacing Condition 2 in that definition by the following

Condition 2': We are given two disjoint closed non-degenerate intervals $I_1, I_2 \subset [0, 2\pi)$ whose images under $\alpha \mapsto (z_1(\alpha), z_2(\alpha)) \in \mathbb{R}/2\pi\mathbb{Z} \times \mathbb{R}$ coincide.

The map $\alpha \mapsto (z_1(\alpha), z_2(\alpha)) \in \mathbb{R}/2\pi\mathbb{Z} \times \mathbb{R}$ satisfies the chord-arc condition when restricted to the complement of any open interval J such that $J \supset I_1$ or $J \supset I_2$.

As promised, the curve depicted in Figure 2(b) is a splat curve. Observe that the curve in Figure 2(b) cannot be real-analytic.

III Proof of real-analytic short-time existence in tilde domain

The main goal of this section is to prove Theorem I.6. In order to accomplish this task we will prove local well-posedness for the system (III.1) below. In this section, we will drop the

tildes from the notation. The system arises from (II.11) taking $c = 0$:

$$\left\{ \begin{array}{l} z_t = \left| \frac{dP}{dw}(P^{-1}(z)) \right|^2 u \\ \Phi_t = \frac{1}{2} \left| \frac{dP}{dw}(P^{-1}(z)) \right|^2 |u|^2 - gP_2^{-1}(z) \\ u = BR(z, \omega) + \frac{\omega}{2|z_\alpha|^2} z_\alpha \\ \Phi_\alpha = \frac{\omega}{2} + BR(z, \omega) \cdot z_\alpha \\ \left| \frac{dP}{dw}(P^{-1}(z(\alpha, t))) \right|^2 = \frac{1}{16} \left| \frac{1+(z_1(\alpha, t)+iz_2(\alpha, t))^4}{z_1(\alpha, t)+iz_2(\alpha, t)} \right|^2 \\ P_2^{-1}(z(\alpha, t)) = \log \left| \frac{i+(z_1(\alpha, t)+iz_2(\alpha, t))^2}{i-(z_1(\alpha, t)+iz_2(\alpha, t))^2} \right|. \end{array} \right. \quad (\text{III.1})$$

We demand that $z^0(\alpha) \neq (0, 0)$ to find the function $\frac{dP}{dw}(P^{-1}(z(\alpha, t)))$ well defined. This condition is going to remain true for short time. We also consider $z^0(\alpha) \neq q_l$, $l = 1, \dots, 4$ in (II.1) to get $P_2^{-1}(z(\alpha, t))$ well defined. Again this is going to remain true for short time.

The main tool in this section is a Cauchy-Kowalewski theorem (see [10, Section 5] for more details). We recall the following definitions

$$S_r = \{\alpha + i\eta, |\eta| < r\},$$

$$\|f\|_{L^2(\partial S_r)}^2 = \sum_{\pm} \int_{-\pi}^{\pi} |f(\alpha \pm ir)|^2 d\alpha,$$

$$\|f\|_r^2 = \|f\|_{L^2(\partial S_r)}^2 + \|\partial_\alpha^3 f\|_{L^2(\partial S_r)}^2,$$

the space

$$H^3(\partial S_r) = \{f \text{ analytic in } S_r, \|f\|_r < \infty, f \text{ } 2\pi\text{-periodic}\}$$

and we now take $(z_1, z_2, \Phi) \in (H^3(\partial S_r))^3 \equiv X_r$. We have the following theorem:

Theorem III.1 *Let $z^0(\alpha)$ be a curve satisfying the arc-chord condition*

$$\frac{|z^0(\alpha) - z^0(\alpha - \beta)|^2}{|\beta|^2} > \frac{1}{M^2}$$

which doesn't touch the points q_l , $l = 0, \dots, 4$ in (II.1), and $(z^0, \Phi^0) \in X_{r_0}$ for some $r_0 > 0$. Then, there exist a time $T > 0$ and $0 < r < r_0$ such that there is a unique solution to the system (III.1) in $C([0, T], X_r)$ with initial conditions $z(\alpha, 0) = z^0(\alpha)$, $\Phi(\alpha, 0) = \Phi^0(\alpha)$, for all $\alpha \in \mathbb{T}$.

Equation (III.1) can be extended for complex variables:

$$z_t(\alpha + i\xi, t) = F^1(z(\alpha + i\xi, t), \Phi(\alpha + i\xi, t)), \quad \Phi_t(\alpha + i\xi, t) = F^2(z(\alpha + i\xi, t), \Phi(\alpha + i\xi, t)).$$

Here

$$F^1(z, \Phi) = \left| \frac{dP}{dw}(P^{-1}(z)) \right|^2 u$$

where we abuse notation by writing

$$\left| \frac{dP}{dw}(P^{-1}(z(\alpha + i\xi, t))) \right|^2 = \frac{1}{16} \frac{\prod_{l=1}^4 [(z_1(\alpha + i\xi, t) - q_1^l)^2 + (z_2(\alpha + i\xi, t) - q_2^l)^2]}{(z_1(\alpha + i\xi, t))^2 + (z_2(\alpha + i\xi, t))^2}$$

and

$$u(\alpha + i\xi, t) = BR(z(\alpha + i\xi, t), \omega(\alpha + i\xi, t)) + \frac{1}{2} \left(\frac{\omega(\alpha + i\xi, t) \partial_\alpha z(\alpha + i\xi, t)}{(\partial_\alpha z_1(\alpha + i\xi, t))^2 + (\partial_\alpha z_2(\alpha + i\xi, t))^2} \right)$$

with

$$BR(z(\alpha + i\xi, t), \omega(\alpha + i\xi, t)) = \frac{1}{2\pi} PV \int_{\mathbb{T}} \frac{(z_2(\alpha + i\xi - \beta, t) - z_2(\alpha + i\xi, t), z_1(\alpha + i\xi, t) - z_1(\alpha + i\xi - \beta, t))}{(z_1(\alpha + i\xi, t) - z_1(\alpha + i\xi - \beta, t))^2 + (z_2(\alpha + i\xi, t) - z_2(\alpha + i\xi - \beta, t))^2} \omega(\alpha + i\xi - \beta, t) d\beta$$

and ω given implicitly by

$$\Phi_\alpha = \frac{\omega}{2} + BR(z, \omega) \cdot z_\alpha.$$

We will also abuse notation by writing $|u|^2$ for $u_1^2 + u_2^2$, even for complex $u = (u_1, u_2)$. The operator F^2 is given by

$$F^2(z, \Phi) = \frac{1}{2} \left| \frac{dP}{dw}(P^{-1}(z)) \right|^2 |u|^2 - gP_2^{-1}(z)$$

where

$$P_2^{-1}(z(\alpha + i\xi, t)) = \frac{1}{2} \sum_{l=1}^4 (-1)^l \log[(z_1(\alpha + i\xi, t) - q_1^l)^2 + (z_2(\alpha + i\xi, t) - q_2^l)^2].$$

Below we will use a strip of analyticity small enough so that the complex logarithm above is continuous. We use the following proposition:

Proposition III.2 *Consider $0 \leq r < r'$ and the open set $O \subset X_{r'}$ given by:*

$$O = \{(z, \Phi) \in X_{r'} : \|z_i\|_{r'}, \|\Phi\|_{r'} < R, \inf_{\alpha + i\xi \in S_r} |(z_1(\alpha + i\xi) - q_1^l)^2 + (z_2(\alpha + i\xi) - q_2^l)^2| > R^{-2}, \\ l = 0, \dots, 4, \inf_{\substack{\alpha + i\xi \in S_r \\ \beta \in [-\pi, \pi]}} G(z)(\alpha + i\xi, \beta) > R^{-2}\}$$

with

$$G(z)(\alpha + i\xi, \beta) = \left| \frac{(z_1(\alpha + i\xi) - z_1(\alpha + i\xi - \beta))^2 + (z_2(\alpha + i\xi) - z_2(\alpha + i\xi - \beta))^2}{\beta^2} \right|$$

then the function $F = (F^1, F^2)$ for $F : O \rightarrow X_r$ is a continuous mapping. In addition, there is a constant C_R (depending on R only) such that

$$\|F(z, \Phi)\|_r \leq \frac{C_R}{r' - r} \|(z, \Phi)\|_{r'} \quad (\text{III.2})$$

$$\|F(z^2, \Phi^2) - F(z^1, \Phi^1)\|_r \leq \frac{C_R}{r' - r} \|(z^2 - z^1, \Phi^2 - \Phi^1)\|_{r'} \quad (\text{III.3})$$

and

$$\sup_{\substack{\alpha + i\xi \in S_r \\ \beta \in [-\pi, \pi]}} |F^1(z, \Phi)(\alpha + i\xi) - F^1(z, \Phi)(\alpha + i\xi - \beta)| \leq C_R |\beta| \quad (\text{III.4})$$

for $z, z^j, \Phi, \Phi^j \in O$.

Proof: First we point out that ω is given in term of Φ_α and z by the implicit equation

$$\Phi_\alpha = \frac{\omega}{2} + BR(z, \omega) \cdot z_\alpha \equiv \frac{1}{2}(I + J)(\omega).$$

It is well known that the operator $(I + J)$ is invertible on L^2 for real functions with mean zero (see [13, Section 5] for more details). Writing

$$\omega(\alpha \pm ir) = 2\Phi_\alpha(\alpha \pm ir) - \frac{1}{2\pi} \int_{\mathbb{T}} \frac{(z(\alpha \pm ir) - z(\beta))^\perp \cdot z_\alpha(\alpha \pm ir)}{|z(\alpha \pm ir) - z(\beta)|^2} \omega(\beta) d\beta$$

one can find that

$$\|\omega\|_{L^2(\partial S_r)} \leq 2\|\Phi_\alpha\|_{L^2(\partial S_r)} + C_R \|\omega\|_{L^2(\partial S_0)}$$

(where C_R depends on R) for $(z, \Phi) \in O$. The bound of $(I + J)^{-1}$ for real functions yields

$$\|\omega\|_{L^2(\partial S_0)} \leq 2\|(I + J)^{-1}\|_{L^2 \rightarrow L^2} \|\Phi_\alpha\|_{L^2(\partial S_0)} \leq C_R \|\Phi_\alpha\|_{L^2(\partial S_r)}.$$

Thus

$$\|\omega\|_{L^2(\partial S_r)} \leq C_R \|\Phi_\alpha\|_{L^2(\partial S_r)}.$$

Analogously, one finds that

$$\|\partial_\alpha^2 \omega\|_{L^2(\partial S_r)} \leq C_R \|\Phi\|_r.$$

This allows us to assert that ω is at the same level as Φ_α in terms of derivatives:

$$\|\omega\|_{L^2(\partial S_r)} + \|\partial_\alpha^2 \omega\|_{L^2(\partial S_r)} \leq C_R \|\Phi\|_r \leq C_R \|\Phi\|_{r'}. \quad (\text{III.5})$$

Then, inequality (III.2) follows as in [10, Section 6.3]. We will see how to deal with the most singular terms. For the first term in the norm, it is easy to find that

$$\|F(z, \Phi)\|_{L^2(\partial S_r)} \leq C_R \|(z, \Phi)\|_r \leq C_R \|(z, \Phi)\|_{r'}. \quad (\text{III.6})$$

In order to control the second one, we will show how to deal with F^1 as F^2 is analogous. Here we point out that the functions

$$\left| \frac{dP}{dw}(P^{-1}(z(\alpha + i\xi, t))) \right|^2, \quad P_2^{-1}(z(\alpha + i\xi, t))$$

have no loss of derivatives and they are regular as long as $(z, \Phi) \in O$. Therefore, in $\partial_\alpha^3 F^1$ the most singular term is given by

$$\left| \frac{dP}{dw}(P^{-1}(z(\alpha + i\xi, t))) \right|^2 \partial_\alpha^3 u(\alpha + i\xi, t)$$

as the rest can be estimated in an easier manner (see [13, Section 6.1] as an example with more details). From the definition it is easy to bound $\left| \frac{dP}{dw}(P^{-1}(z)) \right|^2$ in L^∞ , it remains to control $\partial_\alpha^3 u$ in $L^2(\partial S_r)$. To simplify the exposition we ignore the time dependence of the functions, we denote $\gamma = \alpha \pm ir$,

$$\begin{aligned} (z_1(\gamma) - z_1(\gamma - \beta))^2 + (z_2(\gamma) - z_2(\gamma - \beta))^2 &\equiv |z(\gamma) - z(\gamma - \beta)|_*^2, \\ (\partial_\alpha z_1(\gamma))^2 + (\partial_\alpha z_2(\gamma))^2 &\equiv |z_\alpha(\gamma)|_*^2, \end{aligned}$$

and

$$(z_2(\gamma - \beta) - z_2(\gamma), z_1(\gamma) - z_1(\gamma - \beta)) \equiv (z(\gamma) - z(\gamma - \beta))^\perp.$$

Next, we split as follows

$$\partial_\alpha^3 u = I_1 + I_2 + I_3 + I_4 + I_5 + I_6 + \text{l.o.t.}$$

where l.o.t. denotes lower order terms which can be estimated in an easier manner. We have

$$\begin{aligned} I_1 &= \frac{1}{2\pi} PV \int_{-\pi}^{\pi} \frac{(\partial_\alpha^3 z(\gamma) - \partial_\alpha^3 z(\gamma - \beta))^\perp}{|z(\gamma) - z(\gamma - \beta)|_*^2} \omega(\gamma - \beta) d\beta, \\ I_2 &= \frac{-1}{\pi} PV \int_{-\pi}^{\pi} \frac{(z(\gamma) - z(\gamma - \beta))^\perp}{(|z(\gamma) - z(\gamma - \beta)|_*^2)^2} (z(\gamma) - z(\gamma - \beta)) \cdot (\partial_\alpha^3 z(\gamma) - \partial_\alpha^3 z(\gamma - \beta)) \omega(\gamma - \beta) d\beta, \\ I_3 &= \frac{1}{2\pi} PV \int_{-\pi}^{\pi} \frac{(z(\gamma) - z(\gamma - \beta))^\perp}{|z(\gamma) - z(\gamma - \beta)|_*^2} \partial_\alpha^3 \omega(\gamma - \beta) d\beta, \\ I_4 &= \frac{1}{2} \frac{\omega(\gamma) \partial_\alpha^4 z(\gamma)}{|z_\alpha(\gamma)|_*^2}, \\ I_5 &= -\frac{1}{2} \frac{\omega(\gamma) \partial_\alpha z(\gamma)}{(|z_\alpha(\gamma)|_*^2)^2} \partial_\alpha z(\gamma) \cdot \partial_\alpha^4 z(\gamma) \end{aligned}$$

and

$$I_6 = \frac{1}{2} \frac{\partial_\alpha^3 \omega(\gamma) \partial_\alpha z(\gamma)}{|z_\alpha(\gamma)|_*^2}.$$

For I_6 we find

$$\|I_6\|_{L^2(\partial S_r)} \leq \frac{1}{2} \|\partial_\alpha z\|_{L^\infty(S_r)} \left(\inf_{\substack{\gamma \in S_r \\ \beta \in [-\pi, \pi]}} G(z)(\gamma, \beta) \right)^{-1} \|\partial_\alpha^3 \omega\|_{L^2(\partial S_r)}$$

and since $(z, \Phi) \in O$ we get

$$\|I_6\|_{L^2(\partial S_r)} \leq C_R \|\partial_\alpha^3 \omega\|_{L^2(\partial S_r)}$$

by using Sobolev embedding. A simple application of the Cauchy formula gives

$$\|\partial_\alpha f\|_{L^2(\partial S_r)} \leq \frac{C}{r' - r} \|f\|_{L^2(\partial S_{r'})}$$

which allows us to find

$$\|I_6\|_{L^2(\partial S_r)} \leq \frac{C_R}{r' - r} \|\partial_\alpha^2 \omega\|_{L^2(\partial S_{r'})}.$$

The bound (III.5) gives finally

$$\|I_6\|_{L^2(\partial S_r)} \leq \frac{C_R}{r' - r} \|\Phi\|_{r'}.$$

In a similar way we obtain

$$\|I_4\|_{L^2(\partial S_r)} + \|I_5\|_{L^2(\partial S_r)} \leq C_R \|\partial_\alpha^4 z\|_{L^2(\partial S_r)} \leq \frac{C_R}{r' - r} \|z\|_{r'}.$$

In I_3 we decompose further: $I_3 = I_{3,1} + I_{3,2}$ where

$$I_{3,1} = \frac{1}{2\pi} PV \int_{-\pi}^{\pi} K(\gamma, \beta) \partial_\alpha^3 \omega(\gamma - \beta) d\beta, \quad I_{3,2} = \frac{1}{2} \frac{z_\alpha^\perp(\gamma)}{|z_\alpha(\gamma)|_*^2} H(\partial_\alpha^3 \omega)(\gamma),$$

where H denotes the Hilbert transform and the kernel K is given by

$$\frac{(z(\gamma) - z(\gamma - \beta))^\perp}{|z(\gamma) - z(\gamma - \beta)|_*^2} - \frac{z_\alpha^\perp(\gamma)}{|z_\alpha(\gamma)|_*^2} \frac{1}{2 \tan(\beta/2)}.$$

We can integrate by parts $\partial_\beta(-\partial_\alpha^2 \omega(\gamma - \beta))$ in $I_{3,1}$ to find

$$\|I_{3,1}\|_{L^2(\partial S_r)} \leq C_R \|\partial_\alpha^2 \omega\|_{L^2(\partial S_r)} \leq C_R \|\Phi\|_{r'}$$

(see [13, Section 3] for more details). The term $I_{3,2}$ can be estimated by

$$\|I_{3,2}\|_{L^2(\partial S_r)} \leq C_R \|H(\partial_\alpha^3 \omega)\|_{L^2(\partial S_r)} = C_R \|\partial_\alpha^3 \omega\|_{L^2(\partial S_r)} \leq \frac{C_R}{r' - r} \|\Phi\|_{r'}.$$

A similar splitting in $I_2 = I_{2,1} + I_{2,2}$ with

$$I_{2,1} = \frac{-1}{\pi} PV \int_{-\pi}^{\pi} L(\gamma, \beta) \cdot (\partial_\alpha^3 z(\gamma) - \partial_\alpha^3 z(\gamma - \beta)) d\beta,$$

$$I_{2,2} = -\frac{\omega(\gamma) z_\alpha^\perp(\gamma)}{(|z_\alpha(\gamma)|_*^2)^2} z_\alpha(\gamma) \cdot \Lambda(\partial_\alpha^3 z)(\gamma),$$

(where $\Lambda = H\partial_\alpha$) gives the kernel L as follows

$$\begin{aligned} L(\gamma, \beta) \cdot (\partial_\alpha^3 z(\gamma) - \partial_\alpha^3 z(\gamma - \beta)) &= -\frac{\omega(\gamma) z_\alpha^\perp(\gamma)}{(|z_\alpha(\gamma)|_*^2)^2} \frac{z_\alpha(\gamma) \cdot (\partial_\alpha^3 z(\gamma) - \partial_\alpha^3 z(\gamma - \beta))}{4 \sin^2(\beta/2)} \\ &+ \frac{\omega(\gamma - \beta) (z(\gamma) - z(\gamma - \beta))^\perp}{(|z(\gamma) - z(\gamma - \beta)|_*^2)^2} (z(\gamma) - z(\gamma - \beta)) \cdot (\partial_\alpha^3 z(\gamma) - \partial_\alpha^3 z(\gamma - \beta)). \end{aligned}$$

Heuristically, we regard this operator as no better or no worse than a Hilbert transform of $\partial_\alpha^3 z$. It is easy to prove that

$$\|I_{2,1}\|_{L^2(\partial S_r)} \leq C_R \|\partial_\alpha^3 z\|_{L^2(\partial S_r)} \leq C_R \|\Phi\|_{r'}$$

(see [13, Section 6.1] for more details). The term $I_{2,2}$ can be bounded as follows

$$\|I_{2,2}\|_{L^2(\partial S_r)} \leq C_R \|\Lambda(\partial_\alpha^3 z)\|_{L^2(\partial S_r)} = C_R \|\partial_\alpha^4 z\|_{L^2(\partial S_r)} \leq \frac{C_R}{r' - r} \|z\|_{r'}.$$

Analogously, for I_1 we find

$$\|I_1\|_{L^2(\partial S_r)} \leq \frac{C_R}{r' - r} \|z\|_{r'}.$$

This strategy allows us to deal with $\partial_\alpha^3 u$ and therefore with $\partial_\alpha^3 F^1$. The same applies to $\partial_\alpha^3 F^2$ and we can get finally (III.2).

To get (III.3) we write

$$\Phi_\alpha^1 = \frac{1}{2}(I + J_{z^1})(\omega^1), \quad \Phi_\alpha^2 = \frac{1}{2}(I + J_{z^2})(\omega^2)$$

where

$$J_{z^j}(\omega) = 2BR(z^j, \omega) \cdot z_\alpha^j$$

for $z^j \in O$ and $j = 1, 2$. This implies

$$\Phi_\alpha^2 - \Phi_\alpha^1 = \frac{\omega^2 - \omega^1}{2} + BR(z^2, \omega^2 - \omega^1) \cdot z_\alpha^2 + BR(z^2, \omega^1) \cdot z_\alpha^2 - BR(z^1, \omega^1) \cdot z_\alpha^1$$

which yields

$$(\omega^2 - \omega^1) = 2(I + J_{z^2})^{-1}(\Phi_\alpha^2 - \Phi_\alpha^1) - 2(I + J_{z^2})^{-1}(BR(z^2, \omega^1) \cdot z_\alpha^2 - BR(z^1, \omega^1) \cdot z_\alpha^1).$$

This helps us to find

$$\|\omega^2 - \omega^1\|_{L^2(\partial S_r)} + \|\partial_\alpha^2 \omega^2 - \partial_\alpha^2 \omega^1\|_{L^2(\partial S_r)} \leq C(R)(\|\Phi^2 - \Phi^1\|_r + \|z^2 - z^1\|_r).$$

We use a decomposition similar to the one used to prove (III.2) which allows us to get finally (III.3). Inequality (III.4) follows in an easier manner. \square

Proof of Theorem III.1: We apply the following result of Nirenberg [26] and Nishida [27].

Abstract Cauchy-Kowalewski Theorem:

Consider the equation

$$\frac{du(t)}{dt} = F(u(t)) \text{ for } |t| < \delta \tag{III.7}$$

with initial condition

$$u(0) = u^0 \in X_{r_0} \tag{III.8}$$

For some numbers $\hat{C}, \hat{R} > 0$, assume the following hypothesis:

For every pair of numbers r, r' such that $0 < r' < r < r_0$, F is a Lipschitz map from $\{u \in X_r : \|u - u^0\|_{X_r} < \hat{R}\}$ into $X_{r'}$, with Lipschitz constant at most $\frac{\hat{C}}{r - r'}$. Then the equation (III.7) with initial condition (III.8) has a solution $u(t)$ in $C([-\delta, \delta], X_r)$ for small enough $r, \delta > 0$.

The above Abstract Cauchy-Kowalewski Theorem is obviously equivalent to a special case of Nishida's Theorem [27], although our notation differs from that of [26]. In place of (III.7), Nirenberg and Nishida treat the more general equation $\frac{du(t)}{dt} = F(u(t), t)$.

The proof of the Abstract Cauchy-Kowalewski Theorem in [26] proceeds by showing that the obvious iteration scheme

$$u^{k+1}(t) = u^0 + \int_0^t F(u^k(s)) ds$$

converges in X_r for small enough r (depending on t).

Our system (III.1) has the form $\frac{du}{dt} = F(u)$ for $u = (z, \Phi)$. Proposition III.2 tells us that the hypothesis of the Abstract Cauchy-Kowalewski Theorem holds for the system (III.1). In particular, for $\hat{R} > 0$ small enough, we obtain the arc-chord condition for every $u = (z, \Phi)$ such that $\|(z, \Phi) - (z^0, \Phi^0)\|_{X_r} < \hat{R}$ for any (arbitrarily small) $r > 0$.

Hence, the conclusion of Theorem III.1 follows from the Abstract Cauchy-Kowalewski Theorem. □

Proof of Theorem I.6:

Applying Theorem III.1, we obtain a solution of the water wave equation, with the correct initial conditions, in the tilde domain. Passing from the tilde domain back to the original problem, we obtain a solution of the water wave equations as asserted in Theorem I.6.

We have to make sure that, for small positive time, the splash curve evolves as in Figure 9(a), rather than Figure 9(b).

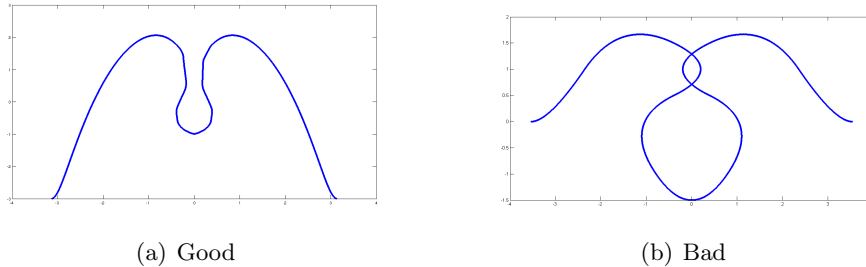


Figure 9: Two different evolutions of the interface.

This is guaranteed by the hypothesis of Theorem I.6 regarding the sign of the normal component of the initial velocity at the splash point. □

IV Proof of short-time existence in Sobolev spaces in the tilde domain

In this section we will show how to obtain a local existence theorem for the water wave equations in the tilde domain. The proof is based on energy estimates and uses the fact that the Rayleigh-Taylor function is positive.

IV.A The Rayleigh-Taylor function in the tilde domain

We begin by recalling the function $\tilde{\varphi}(\alpha, t)$, which will be studied in detail in Section IV.C and in the definition of the Rayleigh-Taylor condition, by the expression

$$\tilde{\varphi}(\alpha, t) = \frac{Q^2 \tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|} - \tilde{c}|\tilde{z}_\alpha(\alpha, t)|. \quad (\text{IV.1})$$

Next we introduce the R-T function:

$$\begin{aligned} \sigma \equiv & \left(BR_t(\tilde{z}, \tilde{\omega}) + \frac{\tilde{\varphi}}{|\tilde{z}_\alpha|} BR_\alpha(\tilde{z}, \tilde{\omega}) \right) \cdot \tilde{z}_\alpha^\perp + \frac{\tilde{\omega}}{2|\tilde{z}_\alpha|^2} \left(\tilde{z}_{\alpha t} + \frac{\tilde{\varphi}}{|\tilde{z}_\alpha|} \tilde{z}_{\alpha\alpha} \right) \cdot \tilde{z}_\alpha^\perp \\ & + Q \left| BR(\tilde{z}, \tilde{\omega}) + \frac{\tilde{\omega}}{2|\tilde{z}_\alpha|^2} \tilde{z}_\alpha \right|^2 (\nabla Q)(\tilde{z}) \cdot \tilde{z}_\alpha^\perp + g(\nabla P_2^{-1})(\tilde{z}) \cdot \tilde{z}_\alpha^\perp. \end{aligned} \quad (\text{IV.2})$$

This function σ coincides with the expression $\tilde{z}^\perp(\alpha, t) \cdot \nabla \tilde{p}(\tilde{z}(\alpha, t), t)$, where $\tilde{p} = p \circ P^{-1}$. Indeed, it is easy to check that

$$\partial_t \tilde{\phi} + \frac{Q^2}{2} |\tilde{v}|^2 = -\tilde{p} - gP_2^{-1} + p^*(t). \quad (\text{IV.3})$$

And taking the gradient on the equation (IV.3) yields

$$\tilde{v}_t + \frac{1}{2} (\nabla Q^2) |\tilde{v}|^2 + Q^2 (\tilde{v} \cdot \nabla) \tilde{v} = -\nabla \tilde{p} - g\nabla P_2^{-1}. \quad (\text{IV.4})$$

In addition we know that

$$\tilde{v}(\tilde{z}(\alpha, t), t) = BR(\tilde{z}, \tilde{\omega})(\alpha, t) + \frac{\tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|^2} \tilde{z}_\alpha(\alpha, t) \quad (\text{IV.5})$$

and therefore

$$\frac{d}{dt} \tilde{v}(\tilde{z}(\alpha, t), t) = \partial_t BR(\tilde{z}, \tilde{\omega})(\alpha, t) + \partial_t \left(\frac{\tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|^2} \right) \tilde{z}_\alpha(\alpha, t) + \frac{\tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|^2} \partial_t \tilde{z}_\alpha(\alpha, t). \quad (\text{IV.6})$$

On the other hand, by using (IV.4) we have

$$\begin{aligned} \frac{d}{dt} \tilde{v}(\tilde{z}(\alpha, t), t) &= \partial_t \tilde{v}(\tilde{z}(\alpha, t), t) + (\partial_t \tilde{z}(\alpha, t) \cdot \nabla) \tilde{v}(\tilde{z}(\alpha, t), t) \\ &= -\frac{1}{2} (\nabla Q^2) |\tilde{v}(\tilde{z}(\alpha, t), t)|^2 - Q^2 (\tilde{v}(\tilde{z}(\alpha, t), t) \cdot \nabla) \tilde{v}(\tilde{z}(\alpha, t), t) \\ &\quad - \nabla \tilde{p}(\tilde{z}(\alpha, t), t) - g\nabla P_2^{-1}(\tilde{z}(\alpha, t)) + (\partial_t \tilde{z}(\alpha, t) \cdot \nabla) \tilde{v}(\tilde{z}(\alpha, t), t). \end{aligned} \quad (\text{IV.7})$$

Furthermore the equation (II.12) together with (IV.5) gives rise to

$$\begin{aligned}\partial_t \tilde{z}(\alpha, t) &= Q^2 \tilde{v}(\tilde{z}(\alpha, t), t) - \frac{Q^2 \tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|^2} \tilde{z}_\alpha(\alpha, t) + \tilde{c} \tilde{z}_\alpha(\alpha, t) \\ &= Q^2 \tilde{v}(\tilde{z}(\alpha, t), t) - \frac{1}{|\tilde{z}_\alpha(\alpha, t)|} \left(\frac{Q^2 \tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|} - \tilde{c} |\tilde{z}_\alpha(\alpha, t)| \right) \tilde{z}_\alpha(\alpha, t).\end{aligned}\quad (\text{IV.8})$$

Therefore by (IV.1), we obtain

$$\partial_t \tilde{z}(\alpha, t) = Q^2 \tilde{v}(\tilde{z}(\alpha, t), t) - \tilde{\varphi}(\alpha, t) \frac{\tilde{z}_\alpha(\alpha, t)}{|\tilde{z}_\alpha(\alpha, t)|}.\quad (\text{IV.9})$$

By introducing (IV.9) in (IV.7) we have

$$\begin{aligned}\frac{d}{dt} \tilde{v}(\tilde{z}(\alpha, t), t) &= -\frac{1}{2} (\nabla Q^2) |\tilde{v}(\tilde{z}(\alpha, t), t)|^2 - Q^2 (\tilde{v}(\tilde{z}(\alpha, t), t) \cdot \nabla) \tilde{v}(\tilde{z}(\alpha, t), t) \\ &\quad - \nabla \tilde{p}(\tilde{z}(\alpha, t), t) - g \nabla P_2^{-1}(\tilde{z}(\alpha, t)) \\ &\quad + Q^2 (\tilde{v}(\tilde{z}(\alpha, t), t) \cdot \nabla) \tilde{v}(\tilde{z}(\alpha, t), t) - \tilde{\varphi}(\alpha, t) \frac{\tilde{z}_\alpha(\alpha, t)}{|\tilde{z}_\alpha(\alpha, t)|} \cdot \nabla \tilde{v}(\tilde{z}(\alpha, t), t).\end{aligned}$$

Therefore

$$\begin{aligned}\frac{d}{dt} \tilde{v}(\tilde{z}(\alpha, t), t) &= -\frac{1}{2} (\nabla Q^2) |\tilde{v}(\tilde{z}(\alpha, t), t)|^2 - \tilde{\varphi}(\alpha, t) \frac{\partial_\alpha \tilde{v}(\tilde{z}(\alpha, t), t)}{|\tilde{z}_\alpha(\alpha, t)|} \\ &\quad - \nabla \tilde{p}(\tilde{z}(\alpha, t), t) - g \nabla P_2^{-1}(\tilde{z}(\alpha, t)).\end{aligned}\quad (\text{IV.10})$$

Next we take a derivative with respect to α in the equation (IV.5) to get

$$\partial_\alpha \tilde{v}(\tilde{z}(\alpha, t), t) = \partial_\alpha BR(\tilde{z}, \tilde{\omega})(\alpha, t) + \partial_\alpha \left(\frac{\tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|^2} \right) \tilde{z}_\alpha(\alpha, t) + \left(\frac{\tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|^2} \right) \tilde{z}_{\alpha\alpha}(\alpha, t).\quad (\text{IV.11})$$

Multiplying equation (IV.10) by $\tilde{z}_\alpha^\perp(\alpha, t)$ and using (IV.11) we learn

$$\begin{aligned}\left(\frac{d}{dt} \tilde{v}(\tilde{z}(\alpha, t), t) \right) \cdot \tilde{z}_\alpha^\perp(\alpha, t) &= -Q \nabla Q \cdot \tilde{z}_\alpha^\perp(\alpha, t) |\tilde{v}(\tilde{z}(\alpha, t), t)|^2 \\ &\quad - \frac{\tilde{\varphi}(\alpha, t)}{|\tilde{z}_\alpha(\alpha, t)|} \partial_\alpha BR(\tilde{z}, \tilde{\omega})(\alpha, t) \cdot \tilde{z}_\alpha^\perp(\alpha, t) \\ &\quad - \frac{\tilde{\varphi}(\alpha, t)}{|\tilde{z}_\alpha(\alpha, t)|} \left(\frac{\tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|^2} \right) \tilde{z}_{\alpha\alpha}(\alpha, t) \cdot \tilde{z}_\alpha^\perp(\alpha, t) \\ &\quad - \nabla \tilde{p}(\tilde{z}(\alpha, t), t) \cdot \tilde{z}_\alpha^\perp(\alpha, t) - g \nabla P_2^{-1}(\tilde{z}(\alpha, t)) \cdot \tilde{z}_\alpha^\perp(\alpha, t).\end{aligned}\quad (\text{IV.12})$$

On the other hand, by multiplying (IV.6) by $\tilde{z}_\alpha^\perp(\alpha, t)$ we have

$$\left(\frac{d}{dt} \tilde{v}(\tilde{z}(\alpha, t), t) \right) \cdot \tilde{z}_\alpha^\perp(\alpha, t) = \partial_t BR(\tilde{z}, \omega) \cdot \tilde{z}_\alpha^\perp(\alpha, t) + \frac{\tilde{\omega}}{2|\tilde{z}_\alpha(\alpha, t)|^2} \partial_t \tilde{z}_\alpha(\alpha, t) \cdot \tilde{z}_\alpha^\perp(\alpha, t).\quad (\text{IV.13})$$

From (IV.12) and (IV.13) we find

$$\begin{aligned}
& \partial_t BR(\tilde{z}, \omega) \cdot \tilde{z}_\alpha^\perp(\alpha, t) + \frac{\tilde{\omega}}{2|\tilde{z}_\alpha(\alpha, t)|^2} \partial_t \tilde{z}_\alpha(\alpha, t) \cdot \tilde{z}_\alpha^\perp(\alpha, t) \\
&= -Q \nabla Q \cdot \tilde{z}_\alpha^\perp(\alpha, t) |\tilde{v}(\tilde{z}(\alpha, t), t)|^2 - \frac{\tilde{\varphi}(\alpha, t)}{|\tilde{z}_\alpha(\alpha, t)|} \partial_\alpha BR(\tilde{z}, \tilde{\omega})(\alpha, t) \cdot \tilde{z}_\alpha^\perp(\alpha, t) \\
&\quad - \frac{\tilde{\varphi}(\alpha, t)}{|\tilde{z}_\alpha(\alpha, t)|} \left(\frac{\tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|^2} \right) \tilde{z}_{\alpha\alpha}(\alpha, t) \cdot \tilde{z}_\alpha^\perp(\alpha, t) \\
&\quad - \nabla \tilde{p}(\tilde{z}(\alpha, t), t) \cdot \tilde{z}_\alpha^\perp(\alpha, t) - g \nabla P_2^{-1}(\tilde{z}(\alpha, t)) \cdot \tilde{z}_\alpha^\perp(\alpha, t). \tag{IV.14}
\end{aligned}$$

Finally, rearranging the terms in (IV.14) yields

$$\begin{aligned}
& -\nabla \tilde{p}(\tilde{z}(\alpha, t), t) \cdot \tilde{z}_\alpha^\perp(\alpha, t) = \left(\partial_t BR(\tilde{z}, \tilde{\omega})(\alpha, t) + \frac{\tilde{\varphi}(\alpha, t)}{|\tilde{z}_\alpha(\alpha, t)|} \partial_\alpha BR(\tilde{z}, \tilde{\omega})(\alpha, t) \right) \cdot \tilde{z}_\alpha^\perp(\alpha, t) \\
&+ \frac{\tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|^2} \left(\partial_t \tilde{z}_\alpha(\alpha, t) + \frac{\tilde{\varphi}(\alpha, t)}{|\tilde{z}_\alpha(\alpha, t)|} \tilde{z}_{\alpha\alpha} \right) \cdot \tilde{z}_\alpha^\perp(\alpha, t) + g \nabla P_2^{-1} \cdot \tilde{z}_\alpha^\perp(\alpha, t) \\
&+ Q \left| BR(\tilde{z}, \tilde{\omega})(\alpha, t) + \frac{\tilde{\omega}(\alpha, t)}{2|\tilde{z}_\alpha(\alpha, t)|^2} \tilde{z}_{\alpha\alpha}(\alpha, t) \right|^2 \left(\nabla Q \cdot \tilde{z}_\alpha^\perp(\alpha, t) \right),
\end{aligned}$$

and then, comparing with (IV.2), we obtain the desired result

$$-\nabla \tilde{p}(\tilde{z}(\alpha, t), t) \cdot \tilde{z}_\alpha^\perp(\alpha, t) = \sigma(\alpha, t).$$

Note that for the tilde domain, the Rayleigh-Taylor condition is the same as in the first domain, i.e:

$$\nabla p(\alpha, t) \cdot z_\alpha^\perp(\alpha, t) = \nabla \tilde{p}(\alpha, t) \cdot \tilde{z}_\alpha^\perp(\alpha, t)$$

where $\tilde{p} = p \circ P^{-1}$ and

$$\tilde{z}_\alpha(\alpha, t) = \nabla P(z(\alpha, t)) \cdot z_\alpha(\alpha, t) \Rightarrow \tilde{z}_\alpha^\perp(\alpha, t) = (-J \nabla P(z(\alpha, t)) J) \cdot z_\alpha^\perp(\alpha, t)$$

where J is the rotation matrix $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$. Together with the Cauchy-Riemann equations this implies that

$$(-J \nabla P(z(\alpha, t)) J) = \nabla P(z(\alpha, t)).$$

Moreover

$$\nabla p(\alpha, t) = \nabla P(z(\alpha, t))^T \nabla \tilde{p}(\alpha, t).$$

Hence

$$\langle \nabla p(\alpha, t), z_\alpha^\perp(\alpha, t) \rangle = \langle \nabla P(z(\alpha, t))^T \nabla \tilde{p}(\alpha, t), (\nabla P(z(\alpha, t)))^{-1} \tilde{z}_\alpha^\perp(\alpha, t) \rangle \tag{IV.15}$$

$$= \langle \nabla \tilde{p}(\alpha, t), \tilde{z}_\alpha^\perp(\alpha, t) \rangle. \tag{IV.16}$$

By taking the divergence on the Euler equation (I.1-I.2) and because the flow is irrotational in the interior of the regions $\Omega^j(t)$ follows

$$-\Delta p = |\nabla v|^2 \geq 0$$

which, together with the fact that the pressure is zero on the interface and $p(x, y, t) + gy = O(1)$ when y tends to $-\infty$, then follows by Hopf's lemma in $\Omega^2(t)$ that

$$\sigma(\alpha, t) \equiv -|z_\alpha^\perp(\alpha, t)|\partial_n p(z(\alpha, t), t) > 0,$$

except in the case $v = 0$. This argument was suggested by Hou and Caffisch (see [31]), although the proof of the positivity of the Rayleigh-Taylor condition in the nontilde domain for all time was first introduced by Wu in [30].

The above proof shows that $\sigma > 0$ provided our domain $\tilde{\Omega}(t)$ arises by applying the map P to a domain $\Omega(t)$ with smooth boundary. Here, $\partial\Omega(t)$ may be a splash curve, but we cannot allow boundaries $\partial\tilde{\Omega}(t)$ whose inverse images under P look like figure 9(b).

Nevertheless, since $\sigma > 0$ for the image of P applied to a splash curve, we know that $\sigma > 0$ at time $t = 0$ in the context of Theorem I.7. Our estimates below will guarantee that the condition $\sigma > 0$ persists for a short time. Thus, in proving Theorem I.7, we may use the positivity of σ .

IV.B Definition of c in the tilde domain

From now on, we will drop the tildes from the notation for simplicity. We will choose the following tangential term:

$$c = \frac{\alpha + \pi}{2\pi} \int_{-\pi}^{\pi} (Q^2 BR)_\beta \cdot \frac{z_\beta}{|z_\beta|^2} d\beta - \int_{-\pi}^{\alpha} (Q^2 BR)_\beta \cdot \frac{z_\beta}{|z_\beta|^2} d\beta. \quad (\text{IV.17})$$

Here and in (II.12) we find

$$P_2^{-1} = P_2^{-1}(z(\alpha, t)) = \log \left(\left| \frac{i + (z_1(\alpha, t) + iz_2(\alpha, t))^2}{i - (z_1(\alpha, t) + iz_2(\alpha, t))^2} \right| \right)$$

and

$$Q = Q(z(\alpha, t)) = \frac{1}{4} \left| \frac{1 + (z_1(\alpha, t) + iz_2(\alpha, t))^4}{z_1(\alpha, t) + iz_2(\alpha, t)} \right|.$$

These functions are regular as long as $z(\alpha, t) \neq q^l$. We deal with initial data which satisfy the above condition and we will show that it's going to remain true for short time. In order to measure it we define

$$m(q^l)(t) = \min_{\alpha \in \mathbb{T}} |z(\alpha, t) - q^l|$$

for $l = 0, \dots, 4$.

We also point out that, because of our choice of $c(\alpha, t)$, solutions of (I.19 - I.20) satisfy that

$$|z_\alpha(\alpha, t)|^2 = A(t) \quad \text{for any } \alpha \in \mathbb{T}$$

as in [14, Equations (2.2 - 2.5)].

IV.C Time evolution of the function φ in the tilde domain

Recall that we have defined an auxiliary function $\varphi(\alpha, t)$ adapted to the tilde domain, which helps us to bound several of the terms that appear:

$$\varphi(\alpha, t) = \frac{Q^2(\alpha, t)\omega(\alpha, t)}{2|z_\alpha(\alpha, t)|} - c(\alpha, t)|z_\alpha(\alpha, t)|. \quad (\text{IV.18})$$

We will show how to find the evolution equation for φ_t . We have

$$\varphi = \frac{Q^2\omega}{2|z_\alpha|} - c|z_\alpha|$$

and therefore

$$\frac{\varphi^2}{Q^2} = \frac{Q^2\omega^2}{4|z_\alpha|^2} + \frac{c^2|z_\alpha|^2}{Q^2} - c\omega$$

that yields

$$-\partial_\alpha \left(\frac{\varphi^2}{Q^2} \right) = -\partial_\alpha \left(\frac{Q^2\omega^2}{4|z_\alpha|^2} \right) - \partial_\alpha \left(\frac{c^2|z_\alpha|^2}{Q^2} \right) + \partial_\alpha(c\omega).$$

The equation for ω_t reads:

$$\omega_t = -2BR_t \cdot z_\alpha - 2QQ_\alpha|BR|^2 + \underbrace{2cBR_\alpha \cdot z_\alpha}_{(1a)} - \partial_\alpha \left(\frac{\varphi^2}{Q^2} \right) + \underbrace{\partial_\alpha \left(\frac{c^2|z_\alpha|^2}{Q^2} \right)}_{(1b)} - 2\partial_\alpha(gP_2^{-1}). \quad (\text{IV.19})$$

For the quantity (1) = (1a) + (1b) we write

$$\begin{aligned} (1) &= (1a) + (1b) = 2cBR_\alpha \cdot z_\alpha + \partial_\alpha \left(\frac{c^2|z_\alpha|^2}{Q^2} \right) = 2c(BR_\alpha \cdot z_\alpha + \frac{c_\alpha|z_\alpha|^2}{Q^2} - \frac{c|z_\alpha|^2Q_\alpha}{Q^3}) \\ &= 2c[BR_\alpha \cdot z_\alpha + \frac{|z_\alpha|^2}{2\pi Q^2} \int_{-\pi}^{\pi} (Q^2BR)_\beta \cdot \frac{z_\beta}{|z_\beta|^2} d\beta - \frac{(Q^2BR)_\alpha \cdot z_\alpha}{Q^2} - \frac{c|z_\alpha|^2Q_\alpha}{Q^3}] \\ &= 2c[\frac{|z_\alpha|^2}{2\pi Q^2} \int_{-\pi}^{\pi} (Q^2BR)_\beta \cdot \frac{z_\beta}{|z_\beta|^2} d\beta - \frac{2Q_\alpha BR \cdot z_\alpha}{Q} - \frac{c|z_\alpha|^2Q_\alpha}{Q^3}] \end{aligned}$$

and then (IV.19) becomes

$$\begin{aligned} \omega_t &= -2BR_t \cdot z_\alpha - 2QQ_\alpha|BR|^2 - \partial_\alpha \left(\frac{\varphi^2}{Q^2} \right) \\ &\quad + \frac{c|z_\alpha|^2}{\pi Q^2} \int_{-\pi}^{\pi} (Q^2BR)_\beta \cdot \frac{z_\beta}{|z_\beta|^2} d\beta - \frac{4cQ_\alpha BR \cdot z_\alpha}{Q} - \frac{2c^2|z_\alpha|^2Q_\alpha}{Q^3} - 2\partial_\alpha(gP_2^{-1}). \end{aligned} \quad (\text{IV.20})$$

Furthermore

$$\begin{aligned}
\varphi_t &= QQ_t \frac{\omega}{|z_\alpha|} - \frac{Q^2 \omega}{2|z_\alpha|^3} z_\alpha \cdot z_{\alpha t} + \frac{Q^2 \omega_t}{2|z_\alpha|} - \partial_t(c|z_\alpha|) \\
&= QQ_t \frac{\omega}{|z_\alpha|} - \frac{Q^2 \omega}{2|z_\alpha|} \frac{1}{2\pi} \int_{-\pi}^{\pi} (Q^2 BR)_\beta \cdot \frac{z_\beta}{|z_\beta|^2} d\beta \\
&\quad + \frac{Q^2}{2|z_\alpha|} \left[-2BR_t \cdot z_\alpha - 2QQ_\alpha |BR|^2 - \partial_\alpha \left(\frac{\varphi^2}{Q^2} \right) \right. \\
&\quad \left. + \frac{c|z_\alpha|^2}{\pi Q^2} \int_{-\pi}^{\pi} (Q^2 BR)_\beta \cdot \frac{z_\beta}{|z_\beta|^2} d\beta - \frac{4cQ_\alpha BR \cdot z_\alpha}{Q} - \frac{2c^2|z_\alpha|^2 Q_\alpha}{Q^3} - 2\partial_\alpha (gP_2^{-1}) \right] - \partial_t(c|z_\alpha|).
\end{aligned}$$

We should remark that we have used that

$$z_\alpha \cdot z_{\alpha t} = \frac{1}{2\pi} \int_{-\pi}^{\pi} (Q^2 BR)_\beta \cdot z_\beta d\beta.$$

For simplicity, we denote

$$B(t) = \frac{1}{2\pi} \int_{-\pi}^{\pi} (Q^2 BR)_\beta \cdot \frac{z_\beta}{|z_\beta|^2} d\beta. \quad (\text{IV.21})$$

Computing

$$\begin{aligned}
\varphi_t &= QQ_t \frac{\omega}{|z_\alpha|} - \underbrace{\frac{Q^2 \omega}{2|z_\alpha|} B(t)}_{(2a)} - \frac{Q^2}{|z_\alpha|} BR_t \cdot z_\alpha - \frac{Q^3 Q_\alpha}{|z_\alpha|} |BR|^2 - \frac{Q^2}{2|z_\alpha|} \partial_\alpha \left(\frac{\varphi^2}{Q^2} \right) \\
&\quad + \underbrace{c|z_\alpha| B(t)}_{(2b)} - \frac{2cQQ_\alpha}{|z_\alpha|} BR \cdot z_\alpha - \frac{c^2|z_\alpha| Q_\alpha}{Q} - \frac{Q^2}{|z_\alpha|} \partial_\alpha (gP_2^{-1}) - \partial_t(c|z_\alpha|)
\end{aligned}$$

We can write

$$(2) = (2a) + (2b) = -B(t)\varphi,$$

and it yields

$$\begin{aligned}
\varphi_t &= -\varphi B(t) - \frac{Q^2}{2|z_\alpha|} \partial_\alpha \left(\frac{\varphi^2}{Q^2} \right) - Q^2 \left(BR_t \cdot \frac{z_\alpha}{|z_\alpha|} + \frac{\partial_\alpha (gP_2^{-1})}{|z_\alpha|} \right) \\
&\quad + QQ_t \frac{\omega}{|z_\alpha|} - 2cBR \cdot \frac{z_\alpha}{|z_\alpha|} QQ_\alpha - \frac{Q_\alpha}{Q} c^2 |z_\alpha| - \frac{Q^3}{|z_\alpha|} Q_\alpha |BR|^2 - \partial_t(c|z_\alpha|).
\end{aligned} \quad (\text{IV.22})$$

We will use the equation above to perform energy estimates.

IV.D Definition and a priori estimates of the energy in the tilde domain

Let us consider for $k \geq 4$ the following definition of energy $E(t)$:

$$\begin{aligned} E(t) = & 1 + \|z\|_{H^{k-1}}^2(t) + \int_{-\pi}^{\pi} \frac{Q^2(z)\sigma}{|z_\alpha|^2} |\partial_\alpha^k z|^2 d\alpha + \|\mathcal{F}(z)\|_{L^\infty}^2(t) \\ & + \|\omega\|_{H^{k-2}}^2(t) + \|\varphi\|_{H^{k-\frac{1}{2}}}^2(t) + \frac{|z_\alpha|^2}{m(Q^2\sigma)(t)} + \sum_{l=0}^4 \frac{1}{m(q^l)(t)}, \end{aligned} \quad (\text{IV.23})$$

where

$$\mathcal{F}(z) = \frac{|\beta|}{|z(\alpha) - z(\alpha - \beta)|}, \quad \alpha, \beta \in [-\pi, \pi],$$

and $m(Q^2\sigma) = \min_{\alpha \in \mathbb{T}} \{Q^2(z(\alpha, t))\sigma(\alpha, t)\}$. In the next section we shall show a proof of the following lemma.

Lemma IV.1 *Let $z(\alpha, t)$ and $\omega(\alpha, t)$ be a solution of (I.19-I.20). Then, the following a priori estimate holds:*

$$\frac{d}{dt} E(t) \leq C E^p(t), \quad (\text{IV.24})$$

for $k \geq 4$ and C and p constants depending only on k .

The following subsections are devoted to proving Lemma IV.1 by showing the regularity of the different elements involved in the problem: the Birkhoff-Rott integral, $z_t(\alpha, t)$, $\omega_t(\alpha, t)$, $\omega(\alpha, t)$; $BR_t(\alpha, t)$, the R-T function $\sigma(\alpha, t)$ and its time derivative $\sigma_t(\alpha, t)$.

IV.D.1 Estimates for BR

In this section we show that the Birkhoff-Rott integral is as regular as $\partial_\alpha z$.

Lemma IV.2 *The following estimate holds*

$$\|BR(z, \omega)\|_{H^k} \leq C(\|\mathcal{F}(z)\|_{L^\infty}^2 + \|z\|_{H^{k+1}}^2 + \|\omega\|_{H^k}^2)^j, \quad (\text{IV.25})$$

for $k \geq 2$, where C and j are constants independent of z and ω .

Remark IV.3 *Using this estimate for $k = 2$ we find easily that*

$$\|\partial_\alpha BR(z, \omega)\|_{L^\infty} \leq C(\|\mathcal{F}(z)\|_{L^\infty}^2 + \|z\|_{H^3}^2 + \|\omega\|_{H^2}^2)^j, \quad (\text{IV.26})$$

which shall be used throughout the paper, where C and j are universal constants.

Proof: The proof can be done as in [13, Section 6.1] since the definition for the Birkhoff-Rott operator is independent of the domain. \square

IV.D.2 Estimates for z_t

In this section we show that z_t is as regular as $\partial_\alpha z$.

Lemma IV.4 *The following estimate holds*

$$\|z_t\|_{H^k} \leq C \left(\|\mathcal{F}(z)\|_{L^\infty}^2 + \|z\|_{H^{k+1}}^2 + \|\omega\|_{H^k}^2 + \sum_{l=0}^4 \frac{1}{m(q^l)(t)} \right)^j, \quad (\text{IV.27})$$

for $k \geq 2$, where C and j are constants that depend only on k .

Proof: It follows from [13, Section 6.2]. The only additional thing we need to control is an L^∞ norm of Q^2 , which we can easily bound by the $m(q^l)$ terms which control the distance from the curve to the q^l points, more precisely, the one that controls the distance from the origin. \square

IV.D.3 Estimates for ω_t

This section is devoted to showing that ω_t is as regular as $\partial_\alpha \omega$.

Lemma IV.5 *The following estimate holds*

$$\|\omega_t\|_{H^k} \leq C \left(\|\mathcal{F}(z)\|_{L^\infty}^2 + \|z\|_{H^{k+2}}^2 + \|\omega\|_{H^{k+1}}^2 + \|\varphi\|_{H^{k+1}}^2 + \sum_{l=0}^4 \frac{1}{m(q^l)(t)} \right)^j, \quad (\text{IV.28})$$

for $k \geq 1$, where C and j are constants that depend only on k .

Proof: We use formula (IV.20) and proceed as in [13, Section 6.3]. Note that in [13] an exponential growth appears in the bound of the estimates for the nonlocal operator acting on ω_t (see equation (IV.20)). However, in a recent paper [15] the authors get a polynomial growth for the operator in both 2 and 3 dimensions. Note that even the exponential growth is still good enough to prove Theorem I.7. \square

IV.D.4 Estimates for ω

In this section we show that the amplitude of the vorticity ω lies at the same level as $\partial_\alpha z$. We shall consider $z \in H^k(\mathbb{T})$, $\varphi \in H^{k-\frac{1}{2}}(\mathbb{T})$ and $\omega \in H^{k-2}(\mathbb{T})$ as part of the energy estimates. The inequality below yields $\omega \in H^{k-1}(\mathbb{T})$.

Lemma IV.6 *The following estimate holds*

$$\|\omega\|_{H^{k-1}} \leq C \left(\|\mathcal{F}(z)\|_{L^\infty}^2 + \|z\|_{H^k}^2 + \|\omega\|_{H^{k-2}}^2 + \|\varphi\|_{H^{k-1}}^2 + \sum_{l=0}^4 \frac{1}{m(q^l)(t)} \right)^j, \quad (\text{IV.29})$$

for $k \geq 3$, where C and j are constants that depend only on k .

Proof: We can apply the same techniques as in [13, Section 6.4] since the most singular terms are treated there and the other terms are harmless and can be easily estimated. The impact of Q is now taken into account by the $m(q^l)$ terms (which now cover all of the points q^0, \dots, q^4). \square

IV.D.5 Estimates for BR_t .

Here we prove that the time derivative of the Birkhoff-Rott integral is at the same level as $\partial_\alpha^2 z$.

Lemma IV.7 *The following estimate holds*

$$\|BR_t\|_{H^k} \leq C \left(\|\mathcal{F}(z)\|_{L^\infty}^2 + \|z\|_{H^{k+2}}^2 + \|\omega\|_{H^{k+1}}^2 + \|\varphi\|_{H^{k+1}}^2 + \sum_{l=0}^4 \frac{1}{m(q^l)(t)} \right)^j, \quad (\text{IV.30})$$

for $k \geq 2$, where C and j are constants that depend only on k .

Proof: We proceed as in [13, Section 6.5], where BR_t appears in the formula (IV.2). We use (IV.27) and (IV.28) to bound z_t and ω_t in BR_t respectively. \square

IV.D.6 Estimates for the Rayleigh-Taylor function σ

Here we prove that the Rayleigh-Taylor function is at the same level as $\partial_\alpha^2 z$.

Lemma IV.8 *The following estimate holds*

$$\|\sigma\|_{H^k} \leq C \left(\|\mathcal{F}(z)\|_{L^\infty}^2 + \|z\|_{H^{k+2}}^2 + \|\omega\|_{H^{k+1}}^2 + \|\varphi\|_{H^{k+1}}^2 + \sum_{l=0}^4 \frac{1}{m(q^l)(t)} \right)^j, \quad (\text{IV.31})$$

for $k \geq 2$, where C and j are constants that depend only on k .

Proof: We proceed as in [13, Section 6.5] using formula (IV.2). There is a new term in the definition of σ , namely $Q \left| BR(z, \omega) + \frac{\omega}{|z_\alpha|^2} z_\alpha \right|^2 (\nabla Q)(z) \cdot z_\alpha^\perp$, but this term is less singular than $BR_t(z, \omega) \cdot z_\alpha^\perp$. Hence, the new term causes no trouble. \square

IV.D.7 Estimates for σ_t

In this section we obtain an upper bound for the L^∞ norm of σ_t that will be used in the energy inequalities and in the treatment of the Rayleigh-Taylor condition.

Lemma IV.9 *The following estimate holds*

$$\|\sigma_t\|_{L^\infty} \leq C \left(\|\mathcal{F}(z)\|_{L^\infty}^2 + \|z\|_{H^4}^2 + \|\omega\|_{H^3}^2 + \|\varphi\|_{H^3}^2 + \sum_{l=0}^4 \frac{1}{m(q^l)(t)} \right)^j, \quad (\text{IV.32})$$

where C and j are universal constants.

Proof: Again, as in the previous subsection, the new term is less singular than the terms treated in [13, Section 6.6]. Hence we deal with them with no problem. \square

IV.D.8 Energy estimates on the curve

In this section we give the proof of the following lemma when, again, $k = 4$. The case $k > 4$ is left to the reader. Regarding $\|\partial_\alpha^4 z\|_{L^2}^2$ let us remark that we have

$$\|\partial_\alpha^4 z\|_{L^2}^2(t) = \int_{\mathbb{T}} \frac{Q^2 \sigma |z_\alpha|^2}{Q^2 \sigma |z_\alpha|^2} |\partial_\alpha^4 z|^2 d\alpha \leq \frac{|z_\alpha|^2}{m(Q^2 \sigma)(t)} \int_{\mathbb{T}} \frac{Q^2 \sigma}{|z_\alpha|^2} |\partial_\alpha^4 z|^2 d\alpha. \quad (\text{IV.33})$$

Lemma IV.10 *Let $z(\alpha, t)$ and $\omega(\alpha, t)$ be a solution of (I.19-I.20). Then, the following a priori estimate holds:*

$$\frac{d}{dt} \left(\|z\|_{H^{k-1}}^2 + \int_{-\pi}^{\pi} \frac{Q^2 \sigma}{|z_\alpha|^2} |\partial_\alpha^k z|^2 d\alpha + \|\mathcal{F}(z)\|_{L^\infty}^2 \right) \leq S(t) + CE^p(t), \quad (\text{IV.34})$$

for

$$S(t) = \int_{-\pi}^{\pi} 2Q^2 \sigma \frac{\partial_\alpha^k z \cdot z_\alpha^\perp}{|z_\alpha|^3} \Lambda(\partial_\alpha^{k-1} \varphi) d\alpha, \quad (\text{IV.35})$$

and $k \geq 4$, where C and p are constants that depend only on k .

(The term $S(t)$ is uncontrolled but it will appear in the equation of the evolution of φ with the opposite sign.)

Proof: Using (IV.27) and (IV.33) one gets easily

$$\begin{aligned} \frac{d}{dt} \|z\|_{H^3}^2 &\leq C \int_{-\pi}^{\pi} (|z(\alpha)| |z_t(\alpha)| + |\partial_\alpha^3 z(\alpha)| |\partial_\alpha^3 z_t(\alpha)|) d\alpha \\ &\leq CE^p(t). \end{aligned}$$

We obtain

$$\frac{d}{dt} \|\mathcal{F}(z)\|_{L^\infty}^2 \leq CE^p(t)$$

in a similar manner as in [13, Section 7.2]. It remains to deal with the quantity

$$\begin{aligned} \frac{d}{dt} \int_{-\pi}^{\pi} \frac{Q^2 \sigma}{|z_\alpha|^2} |\partial_\alpha^4 z|^2 d\alpha &= \int_{-\pi}^{\pi} \left(\frac{Q^2 \sigma}{|z_\alpha|^2} \right)_t |\partial_\alpha^4 z|^2 d\alpha + \int_{-\pi}^{\pi} \frac{2Q^2 \sigma}{|z_\alpha|^2} \partial_\alpha^4 z \cdot \partial_\alpha^4 z_t d\alpha \\ &= I_1 + I_2. \end{aligned}$$

The bounds (IV.27), (IV.33) and (IV.32) give us

$$I_1 \leq CE^p(t).$$

Next for I_2 we write

$$\begin{aligned} I_2 &= \int_{-\pi}^{\pi} \frac{2Q^2 \sigma}{|z_\alpha|^2} \partial_\alpha^4 z \cdot \partial_\alpha^4 (Q^2 BR) d\alpha + \int_{-\pi}^{\pi} \frac{2Q^2 \sigma}{|z_\alpha|^2} \partial_\alpha^4 z \cdot \partial_\alpha^4 (c \partial_\alpha z) d\alpha \\ &= J_1 + J_2. \end{aligned}$$

The most singular terms in J_1 are given by K_1 , K_2 , K_3 and K_4 :

$$K_1 = \frac{1}{\pi} PV \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \frac{Q^4 \sigma}{|z_\alpha|^2} \partial_\alpha^4 z \cdot \frac{(\partial_\alpha^4 z - \partial_\alpha^4 z')^\perp}{|z - z'|^2} \omega' d\beta d\alpha,$$

$$K_2 = -\frac{2}{\pi} PV \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \frac{Q^4 \sigma}{|z_\alpha|^2} \partial_\alpha^4 z \cdot \frac{(z - z')^\perp}{|z - z'|^4} (z - z') \cdot (\partial_\alpha^4 z - \partial_\alpha^4 z') \omega' d\beta d\alpha,$$

$$K_3 = \frac{1}{\pi} PV \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \frac{Q^4 \sigma}{|z_\alpha|^2} \partial_\alpha^4 z \cdot \frac{(z - z')^\perp}{|z - z'|^2} \partial_\alpha^4 \omega' d\beta d\alpha,$$

and

$$K_4 = \frac{2}{\pi} \int_{-\pi}^{\pi} \frac{Q^3 \sigma}{|z_\alpha|^2} \partial_\alpha^4 z \cdot BR \nabla Q(z) \cdot \partial_\alpha^4 z d\alpha,$$

where the prime denotes a function in the variable $\alpha - \beta$, i.e. $f' = f(\alpha - \beta)$.

Then we write:

$$\begin{aligned} K_1 &= \frac{1}{\pi} PV \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \frac{Q^4(\alpha) \sigma(\alpha)}{|z_\alpha|^2} \partial_\alpha^4 z(\alpha) \cdot \frac{(\partial_\alpha^4 z(\alpha) - \partial_\alpha^4 z(\beta))^\perp}{|z(\alpha) - z(\beta)|^2} \omega(\beta) d\beta d\alpha \\ &= \frac{1}{\pi |z_\alpha|^2} PV \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \partial_\alpha^4 z(\alpha) \cdot \frac{(\partial_\alpha^4 z(\alpha) - \partial_\alpha^4 z(\beta))^\perp}{|z(\alpha) - z(\beta)|^2} \frac{Q^4(\alpha) \sigma(\alpha) \omega(\beta) + Q^4(\beta) \sigma(\beta) \omega(\alpha)}{2} d\beta d\alpha \\ &\quad + \frac{1}{\pi |z_\alpha|^2} PV \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \partial_\alpha^4 z(\alpha) \cdot \frac{(\partial_\alpha^4 z(\alpha) - \partial_\alpha^4 z(\beta))^\perp}{|z(\alpha) - z(\beta)|^2} \frac{Q^4(\alpha) \sigma(\alpha) \omega(\beta) - Q^4(\beta) \sigma(\beta) \omega(\alpha)}{2} d\beta d\alpha \\ &= L_1 + L_2. \end{aligned}$$

That is, we have performed a manipulation in K_1 , allowing us to show that L_1 , its most singular term, vanishes:

$$\begin{aligned} L_1 &= \frac{-1}{\pi |z_\alpha|^2} PV \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \partial_\alpha^4 z(\beta) \cdot \frac{(\partial_\alpha^4 z(\alpha) - \partial_\alpha^4 z(\beta))^\perp}{|z(\alpha) - z(\beta)|^2} \frac{Q^4(\alpha) \sigma(\alpha) \omega(\beta) + Q^4(\beta) \sigma(\beta) \omega(\alpha)}{2} d\beta d\alpha \\ &= \frac{1}{2\pi |z_\alpha|^2} PV \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} (\partial_\alpha^4 z(\alpha) - \partial_\alpha^4 z(\beta)) \cdot \frac{(\partial_\alpha^4 z(\alpha) - \partial_\alpha^4 z(\beta))^\perp}{|z(\alpha) - z(\beta)|^2} \frac{Q^4(\alpha) \sigma(\alpha) \omega(\beta) + Q^4(\beta) \sigma(\beta) \omega(\alpha)}{2} d\beta d\alpha \\ &= 0. \end{aligned}$$

The term L_2 involves a S.I.O. (Singular Integral Operator) acting on $\partial_\alpha^4 z(\alpha)$ thanks to the minus sign between the two terms $Q^4 \sigma \omega$. One can show that

$$L_2 \leq C \|\mathcal{F}(z)\|_{L^\infty}^2 \|z\|_{H^3}^k \|\omega\|_{C^{1,\delta}} \|\sigma\|_{C^{1,\delta}} \|Q^4\|_{C^{1,\delta}} \|\partial_\alpha^4 z\|_{L^2}^2 \leq CE^p(t).$$

Inside K_2 we find that $(z - z') \cdot (\partial_\alpha^4 z - \partial_\alpha^4 z')$ can be written as follows:

$$\begin{aligned} (z - z') \cdot (\partial_\alpha^4 z - \partial_\alpha^4 z') &= (z - z' - z_\alpha \beta) \cdot (\partial_\alpha^4 z - \partial_\alpha^4 z') \\ &\quad - \beta (z_\alpha - z'_\alpha) \cdot \partial_\alpha^4 z' \\ &\quad + \beta (z_\alpha \cdot \partial_\alpha^4 z - z'_\alpha \cdot \partial_\alpha^4 z'), \end{aligned} \tag{IV.36}$$

then using that

$$z_\alpha \cdot \partial_\alpha^4 z = -3\partial_\alpha^2 z \cdot \partial_\alpha^3 z, \quad (\text{IV.37})$$

we can split K_2 as a sum of S.I.O.s operating on $\partial_\alpha^4 z(\alpha)$, plus a kernel of the form $\frac{\eta(\alpha, \beta)}{\beta^2}$ acting on $\partial_\alpha^2 z \cdot \partial_\alpha^3 z$ with $\eta \in \mathcal{C}^2$ allowing us to obtain again the estimate

$$K_2 \leq CE^p(t).$$

Note that below we will also use a variant of (IV.37), namely

$$z_\alpha \cdot (\partial_\alpha^4 z - \partial_\alpha^4 z') = (z'_\alpha - z_\alpha) \cdot \partial_\alpha^4 z' - 3(\partial_\alpha^2 z \cdot \partial_\alpha^3 z - \partial_\alpha^2 z' \cdot \partial_\alpha^3 z'). \quad (\text{IV.38})$$

The term K_3 is a sum of

$$L_3 = \frac{1}{\pi} \int_{-\pi}^{\pi} \frac{Q^4 \sigma}{|z_\alpha|^2} \partial_\alpha^4 z \cdot \int_{-\pi}^{\pi} \left[\frac{(z - z')^\perp}{|z - z'|^2} - \frac{z_\alpha^\perp}{|z_\alpha|^2 2 \tan(\beta/2)} \right] \partial_\alpha^4 \omega' d\beta d\alpha,$$

plus the following term:

$$L_4 = \int_{-\pi}^{\pi} Q^4 \sigma \frac{\partial_\alpha^4 z \cdot z_\alpha^\perp}{|z_\alpha|^4} H(\partial_\alpha^4 \omega) d\alpha.$$

We can integrate by parts on L_3 with respect to β since $\partial_\alpha^4 \omega' = -\partial_\beta(\partial_\alpha^3 \omega')$. This calculation gives a S.I.O. acting on $\partial_\alpha^3 \omega$ which can be estimated as before.

Next in L_4 we write

$$L_4 = \int_{-\pi}^{\pi} Q^4 \sigma \frac{\partial_\alpha^4 z \cdot z_\alpha^\perp}{|z_\alpha|^4} \Lambda(\partial_\alpha^3 \omega) d\alpha$$

and decompose further

$$\begin{aligned} L_4 &= \int_{-\pi}^{\pi} 2Q^2 \sigma \frac{\partial_\alpha^4 z \cdot z_\alpha^\perp}{|z_\alpha|^3} \left[\frac{Q^2}{2|z_\alpha|} \Lambda(\partial_\alpha^3 \omega) - \Lambda(\partial_\alpha^3 (\frac{Q^2}{2|z_\alpha|} \omega)) \right] d\alpha \\ &\quad + \int_{-\pi}^{\pi} 2Q^2 \sigma \frac{\partial_\alpha^4 z \cdot z_\alpha^\perp}{|z_\alpha|^3} \Lambda(\partial_\alpha^3 \varphi) d\alpha \\ &\quad + \int_{-\pi}^{\pi} 2Q^2 \sigma \frac{\partial_\alpha^4 z \cdot z_\alpha^\perp}{|z_\alpha|^3} \Lambda(\partial_\alpha^3 (c|z_\alpha|)) d\alpha \\ &= M_{-1} + S + M_1, \end{aligned}$$

for $S(t)$ given by (IV.35). In M_{-1} we find a commutator that allows us to obtain

$$M_{-1} \leq CE^p(t).$$

Using (IV.17) for M_1 we have

$$M_1 = -2 \int_{-\pi}^{\pi} H(Q^2 \sigma \frac{\partial_\alpha^4 z \cdot z_\alpha^\perp}{|z_\alpha|^3}) \partial_\alpha^4 (c|z_\alpha|) d\alpha = N_1 + N_2 + N_3 + N_4,$$

where

$$\begin{aligned} N_1 &= 2 \int_{-\pi}^{\pi} H(Q^2 \sigma \frac{\partial_{\alpha}^4 z \cdot z_{\alpha}^{\perp}}{|z_{\alpha}|^3}) Q^2 BR_{\alpha} \cdot \frac{\partial_{\alpha}^4 z}{|z_{\alpha}|} d\alpha, \\ N_2 &= 2 \int_{-\pi}^{\pi} H(Q^2 \sigma \frac{\partial_{\alpha}^4 z \cdot z_{\alpha}^{\perp}}{|z_{\alpha}|^3}) Q^2 \partial_{\alpha}^4 BR \cdot \frac{z_{\alpha}}{|z_{\alpha}|} d\alpha, \\ N_3 &= 4 \int_{-\pi}^{\pi} H(Q^2 \sigma \frac{\partial_{\alpha}^4 z \cdot z_{\alpha}^{\perp}}{|z_{\alpha}|^3}) Q \nabla Q \cdot \partial_{\alpha}^4 z BR \cdot \frac{z_{\alpha}}{|z_{\alpha}|} d\alpha, \end{aligned}$$

and N_4 is given by the rest of the terms which can be controlled easily by the estimates from Section IV.D.1 for the Birkhoff-Rott integral.

Regarding N_1 a straightforward calculation gives

$$N_1 \leq CE^p(t),$$

and analogously for N_3

$$N_3 \leq CE^p(t).$$

Again, in N_2 we consider the most singular terms given by

$$\begin{aligned} O_1 &= \int_{-\pi}^{\pi} H(Q^2 \sigma \frac{\partial_{\alpha}^4 z \cdot z_{\alpha}^{\perp}}{|z_{\alpha}|^3}) \frac{z_{\alpha}}{|z_{\alpha}|} \cdot \frac{Q^2}{\pi} PV \int_{-\pi}^{\pi} \frac{(\partial_{\alpha}^4 z - \partial_{\alpha}^4 z')^{\perp}}{|z - z'|^2} \omega' d\beta d\alpha, \\ O_2 &= - \int_{-\pi}^{\pi} H(Q^2 \sigma \frac{\partial_{\alpha}^4 z \cdot z_{\alpha}^{\perp}}{|z_{\alpha}|^3}) \frac{z_{\alpha}}{|z_{\alpha}|} \cdot \frac{Q^2}{2\pi} PV \int_{-\pi}^{\pi} \frac{(z - z')^{\perp}}{|z - z'|^4} (z - z') \cdot (\partial_{\alpha}^4 z - \partial_{\alpha}^4 z') \omega' d\alpha d\beta, \\ O_3 &= 2 \int_{-\pi}^{\pi} H(Q^2 \sigma \frac{\partial_{\alpha}^4 z \cdot z_{\alpha}^{\perp}}{|z_{\alpha}|^3}) Q^2 \frac{z_{\alpha}}{|z_{\alpha}|} \cdot BR(z, \partial_{\alpha}^4 \omega) d\alpha. \end{aligned}$$

Using the decomposition (IV.36) we can easily estimate O_2 as in our discussion of K_2 .

In O_3 we find

$$z_{\alpha} \cdot BR(z, \partial_{\alpha}^4 \omega) = \frac{z_{\alpha}}{2\pi} \cdot \int_{-\pi}^{\pi} \frac{(z - z' - z_{\alpha} \beta)^{\perp}}{|z - z'|^2} \partial_{\alpha}^4 \omega' d\beta.$$

Above we can integrate by parts as in our discussion of L_3 . We find that

$$O_3 \leq CE^p(t).$$

Next we split O_1 into a S.I.O. acting on $(\partial_{\alpha}^4 z)^{\perp}$, which can be estimated as before, plus the term

$$P_1 = \int_{-\pi}^{\pi} H(Q^2 \sigma \frac{\partial_{\alpha}^4 z \cdot z_{\alpha}^{\perp}}{|z_{\alpha}|^3}) Q^2 \omega \frac{z_{\alpha}}{|z_{\alpha}|^3} \cdot \Lambda((\partial_{\alpha}^4 z)^{\perp}) d\alpha.$$

Then the following estimate for the commutator

$$\|Q^2 \omega \frac{z_{\alpha}}{|z_{\alpha}|^3} \cdot \Lambda((\partial_{\alpha}^4 z)^{\perp}) - \Lambda(Q^2 \omega \frac{z_{\alpha}}{|z_{\alpha}|^3} \cdot (\partial_{\alpha}^4 z)^{\perp})\|_{L^2} \leq CE^p(t)$$

yields

$$P_1 \leq CE^p(t) + R$$

where

$$R = - \int_{-\pi}^{\pi} Q^2 \sigma \frac{\partial_{\alpha}^4 z \cdot z_{\alpha}^{\perp}}{|z_{\alpha}|^3} \partial_{\alpha} (Q^2 \omega \frac{z_{\alpha}}{|z_{\alpha}|^3} (\partial_{\alpha}^4 z)^{\perp}) d\alpha.$$

Using that

$$\int_{-\pi}^{\pi} Hf(\alpha) \Lambda g(\alpha) d\alpha = - \int_{-\pi}^{\pi} f(\alpha) \partial_{\alpha} g(\alpha) d\alpha.$$

We can write

$$R = \int_{-\pi}^{\pi} Q^2 \sigma \frac{\partial_{\alpha}^4 z \cdot z_{\alpha}^{\perp}}{|z_{\alpha}|^3} \partial_{\alpha} (Q^2 \omega) \frac{\partial_{\alpha}^4 z \cdot z_{\alpha}^{\perp}}{|z_{\alpha}|^3} d\alpha + \int_{-\pi}^{\pi} Q^2 \sigma \frac{\partial_{\alpha}^4 z \cdot z_{\alpha}^{\perp}}{|z_{\alpha}|^3} Q^2 \omega \partial_{\alpha} \left(\frac{\partial_{\alpha}^4 z \cdot z_{\alpha}^{\perp}}{|z_{\alpha}|^3} \right) d\alpha$$

and a straightforward integration by parts let us control R . This calculation allows us to get

$$P_1 \leq CE^p(t).$$

We can easily show that

$$K_4 \leq CE^p(t)$$

because we can bound $Q^3 \sigma BR \nabla Q$ in L^{∞} . So finally we have controlled J_1 in the following manner:

$$J_1 \leq CE^p(t) + S.$$

To finish the proof let us observe that the term J_2 can be estimated integrating by parts, using the identity $\partial_{\alpha}^4 z \cdot \partial_{\alpha} z = -3 \partial_{\alpha}^3 z \cdot \partial_{\alpha}^2 z$ to treat its most singular component. We have obtained

$$\int_{\mathbb{T}} \frac{Q^2 \sigma}{|z_{\alpha}|^2} \partial_{\alpha}^4 z \cdot \partial_{\alpha} z \partial_{\alpha}^4 c d\alpha = 3 \int_{\mathbb{T}} \frac{1}{|z_{\alpha}|^2} \partial_{\alpha} (Q^2 \sigma \partial_{\alpha}^3 z \cdot \partial_{\alpha}^2 z) \partial_{\alpha}^3 c d\alpha$$

and this yields the desired control. \square

IV.D.9 Energy estimates for ω

In this section we show the following result.

Lemma IV.11 *Let $z(\alpha, t)$ and $\omega(\alpha, t)$ be a solution of (I.19-I.20). Then, the following a priori estimate holds:*

$$\frac{d}{dt} \|\omega\|_{H^{k-2}}^2 \leq CE^p(t), \quad (\text{IV.39})$$

for $k \geq 4$, where C and p are constants that depend only on k .

Proof: We will discuss the case $k = 4$, leaving the other cases to the reader. Formula (IV.28) shows easily that

$$\frac{d}{dt} \|\omega\|_{H^2}^2(t) \leq \left(\|\mathcal{F}(z)\|_{L^\infty}^2(t) + \|z\|_{H^4}^2(t) + \|\omega\|_{H^3}^2(t) + \|\varphi\|_{H^3}^2(t) + \sum_{l=0}^4 \frac{1}{m(q^l)(t)} \right)^j$$

which together with (IV.29) yields

$$\frac{d}{dt} \|\omega\|_{H^2}^2(t) \leq CE^p(t).$$

□

IV.D.10 Finding the Rayleigh-Taylor function in the equation for $\partial_\alpha \varphi_t$.

In this section we get the R-T function in the evolution equation for $\partial_\alpha \varphi_t$.

Lemma IV.12 *Let $z(\alpha, t)$ and $\omega(\alpha, t)$ be a solution of (I.19-I.20). Then, the following identity holds:*

$$\varphi_{\alpha t} = NICE - \frac{\varphi}{|z_\alpha|} \varphi_{\alpha\alpha} - Q^2 \sigma \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \quad (\text{IV.40})$$

where NICE satisfies

$$\int_{-\pi}^{\pi} \Lambda(\partial_\alpha^{k-1} \varphi) \partial_\alpha^{k-2} (NICE) d\alpha \leq CE^p(t) \quad (\text{IV.41})$$

and

$$\|NICE\|_{H^{k-2}} \leq CE^p(t) \quad (\text{IV.42})$$

for $k \geq 4$, where C and p are constants that depend only on k .

Proof: We will give the proof for $k = 4$. From now on, when we show that a term f satisfies

$$\int_{-\pi}^{\pi} \Lambda(\partial_\alpha^3 \varphi) \partial_\alpha^2 f d\alpha \leq CE^p(t) \quad \text{and} \quad \|f\|_{H^2} \leq CE^p(t)$$

we say that this term is ‘‘NICE’’. Then, f becomes part of NICE and by abuse of notation we denote f by NICE. Notice that, whenever we can estimate the L^2 norm of $\Lambda^{1/2} \partial_\alpha^2 f$ by $CE^p(t)$, then f is NICE.

We use (IV.22) to compute

$$\begin{aligned} \varphi_{\alpha t} = & -B(t) \varphi_\alpha - \partial_\alpha \left(\frac{Q^2}{2|z_\alpha|} \left(\frac{\varphi^2}{Q^2} \right)_\alpha \right) - \underbrace{\left(Q^2 (BR_t \cdot \frac{z_\alpha}{|z_\alpha|} + \frac{(gP_2^{-1}(z))_\alpha}{|z_\alpha|}) \right)_\alpha}_{(3a)} \\ & + \left(QQ_t \frac{\omega}{|z_\alpha|} \right)_\alpha - \left(2cBR \cdot \frac{z_\alpha}{|z_\alpha|} QQ_\alpha \right)_\alpha - \left(\frac{Q_\alpha}{Q} c^2 |z_\alpha| \right)_\alpha - \left(\frac{Q^3}{|z_\alpha|} |BR|^2 Q_\alpha \right)_\alpha \\ & \underbrace{- (c|z_\alpha|)_{\alpha t}}_{(3b)}. \end{aligned}$$

Expanding (3) = (3a) + (3b):

$$\begin{aligned}
(3) &= (3a) + (3b) = - \left(Q^2 BR_t \cdot \frac{z_\alpha}{|z_\alpha|} \right)_\alpha - (c|z_\alpha|)_{\alpha t} \\
&= - (Q^2 BR_t)_\alpha \cdot \frac{z_\alpha}{|z_\alpha|} - Q^2 BR_t \cdot \left(\frac{z_\alpha}{|z_\alpha|} \right)_\alpha - \left(|z_\alpha| B(t) - (Q^2 BR)_\alpha \cdot \frac{z_\alpha}{|z_\alpha|} \right)_t \\
&= - Q^2 BR_t \cdot \left(\frac{z_\alpha}{|z_\alpha|} \right)_\alpha - (|z_\alpha| B(t))_t + (Q^2 BR)_\alpha \cdot \left(\frac{z_\alpha}{|z_\alpha|} \right)_t + 2(QQ_t BR)_\alpha \cdot \frac{z_\alpha}{|z_\alpha|}.
\end{aligned}$$

We use that

$$\left(\frac{z_\alpha}{|z_\alpha|} \right)_\alpha = \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^2} \cdot \frac{z_\alpha^\perp}{|z_\alpha|}; \quad \left(\frac{z_\alpha}{|z_\alpha|} \right)_t = \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^2} \cdot \frac{z_\alpha^\perp}{|z_\alpha|}$$

to find

$$\begin{aligned}
\varphi_{\alpha t} &= \underbrace{-B(t)\varphi_\alpha}_{(4)} - \underbrace{\frac{\partial_\alpha^2(\varphi^2)}{2|z_\alpha|}}_{(5)} + \underbrace{\partial_\alpha \left(\frac{Q_\alpha}{|z_\alpha|Q} \varphi^2 \right)}_{(6)} - Q^2 BR_t \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} - (|z_\alpha| B(t))_t \\
&\quad + \underbrace{(Q^2 BR)_\alpha \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(13)} + \underbrace{2(QQ_t BR)_\alpha \cdot \frac{z_\alpha}{|z_\alpha|}}_{(7)} - \underbrace{\left(Q^2 \frac{gP_2^{-1}(z)}{|z_\alpha|} \right)_\alpha}_{(8)} + \underbrace{\left(QQ_t \frac{\omega}{|z_\alpha|} \right)_\alpha}_{(9)} \\
&\quad - \underbrace{\left(2cBR \cdot \frac{z_\alpha}{|z_\alpha|} QQ_\alpha \right)_\alpha}_{(10)} - \underbrace{\left(\frac{Q_\alpha}{Q} c^2 |z_\alpha| \right)_\alpha}_{(11)} - \underbrace{\left(\frac{Q^3}{|z_\alpha|} |BR|^2 Q_\alpha \right)_\alpha}_{(12)}. \tag{IV.43}
\end{aligned}$$

The term $(|z_\alpha| B(t))_t$ depends only on t so it is going to be part of NICE.

$$(4) = -B(t)\varphi_\alpha \text{ is NICE (at the level of } \varphi_\alpha \text{).}$$

$$(5) = -\frac{\partial_\alpha^2(\varphi^2)}{2|z_\alpha|} = -\frac{\varphi_\alpha^2}{|z_\alpha|} - \frac{\varphi}{|z_\alpha|} \varphi_{\alpha\alpha}.$$

The first term is at the level of φ_α so it is NICE. The second one is the transport term which appears in (IV.54).

$$(6) = \partial_\alpha \left(\frac{Q_\alpha}{|z_\alpha|Q} \varphi^2 \right) = -\frac{Q_\alpha^2 \varphi^2}{|z_\alpha|Q^2} + \frac{2Q_\alpha \varphi \varphi_\alpha}{|z_\alpha|Q} + \frac{\varphi^2}{Q} \left(\frac{Q_\alpha}{|z_\alpha|} \right)_\alpha.$$

Above we find the first term at the level of z_α so it is NICE. The second term is at the level of φ_α so it is NICE. We write the last one as

$$\frac{\varphi^2}{Q} \left(\frac{Q_\alpha}{|z_\alpha|} \right)_\alpha = \frac{\varphi^2}{Q} z_\alpha \cdot \left(\nabla^2 Q(z) \cdot \frac{z_\alpha}{|z_\alpha|} \right) + \frac{\varphi^2}{Q} \nabla Q \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.$$

The first term is at the level of z_α so it is NICE. For the second term we have used that

$$\left(\frac{z_\alpha}{|z_\alpha|}\right)_\alpha = \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^2} \cdot \frac{z_\alpha^\perp}{|z_\alpha|}.$$

Finally:

$$(6) = \text{NICE} + \frac{\varphi^2}{Q} \nabla Q \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.$$

$$(7) = 2(QQ_t BR)_\alpha \cdot \frac{z_\alpha}{|z_\alpha|} = 2Q_\alpha Q_t BR \cdot \frac{z_\alpha}{|z_\alpha|} + 2Q \left(\frac{Q_t}{|z_\alpha|}\right)_\alpha BR \cdot z_\alpha + 2QQ_t BR_\alpha \cdot \frac{z_\alpha}{|z_\alpha|}.$$

The first term is at the level of $z_\alpha, z_t, BR \sim z_\alpha$ so it is NICE. We use that

$$\frac{Q_{t\alpha}}{|z_\alpha|} = \frac{Q_{\alpha t}}{|z_\alpha|} = \frac{(\nabla Q(z) \cdot z_\alpha)_t}{|z_\alpha|} = \left(\nabla Q(z) \cdot \frac{z_\alpha}{|z_\alpha|}\right)_t - \nabla Q(z) \cdot z_\alpha \left(\frac{1}{|z_\alpha|}\right)_t.$$

Using equation (IV.21)

$$\frac{z_\alpha \cdot z_{\alpha t}}{|z_\alpha|^2} = B(t)$$

and

$$\left(\frac{z_\alpha}{|z_\alpha|}\right)_t = \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^2} \cdot \frac{z_\alpha^\perp}{|z_\alpha|}$$

we find that

$$\begin{aligned} \frac{Q_{t\alpha}}{|z_\alpha|} &= z_t \cdot \left(\nabla^2 Q(z) \cdot \frac{z_\alpha}{|z_\alpha|}\right) + \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ &\quad + \nabla Q(z) \cdot \frac{z_\alpha}{|z_\alpha|} B(t). \end{aligned} \tag{IV.44}$$

That yields

$$\begin{aligned} (7) &= 2(QQ_t BR)_\alpha \frac{z_\alpha}{|z_\alpha|} = \text{NICE} + \underbrace{2QBR \cdot z_\alpha z_t \cdot \left(\nabla^2 Q(z) \cdot \frac{z_\alpha}{|z_\alpha|}\right)}_{\text{NICE (at the level of } z_\alpha, z_t, BR)} \\ &\quad + 2QBR \cdot z_\alpha \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3} + \underbrace{2QBR \cdot z_\alpha \nabla Q(z) \cdot \frac{z_\alpha}{|z_\alpha|} B(t)}_{\text{NICE (at the level of } z_\alpha, z_t, BR)} \\ &\quad + 2QQ_t BR_\alpha \cdot \frac{z_\alpha}{|z_\alpha|}. \end{aligned}$$

Finally:

$$(7) = 2(QQ_t BR)_\alpha \frac{z_\alpha}{|z_\alpha|} = \text{NICE} + 2QBR \cdot z_\alpha \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3} + 2QQ_t BR_\alpha \cdot \frac{z_\alpha}{|z_\alpha|}.$$

$$\begin{aligned}
(8) &= - \left(Q^2 \frac{(gP_2^{-1}(z))_\alpha}{|z_\alpha|} \right)_\alpha = - \left(Q^2 \nabla g P_2^{-1}(z) \cdot \frac{z_\alpha}{|z_\alpha|} \right)_\alpha \\
&= - \underbrace{2Q \nabla Q \cdot z_\alpha \nabla g P_2^{-1}(z) \cdot \frac{z_\alpha}{|z_\alpha|}}_{\text{NICE (at the level of } z_\alpha)} - \underbrace{Q^2 z_\alpha \cdot \left(\nabla^2 g P_2^{-1}(z) \cdot \frac{z_\alpha}{|z_\alpha|} \right)}_{\text{NICE (at the level of } z_\alpha)} \\
&\quad - Q^2 \nabla g P_2^{-1}(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3},
\end{aligned}$$

which means

$$(8) = - \left(Q^2 \frac{(gP_2^{-1}(z))_\alpha}{|z_\alpha|} \right)_\alpha = \text{NICE} - Q^2 \nabla g P_2^{-1}(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.$$

Next

$$(9) = \left(Q Q_t \frac{\omega}{|z_\alpha|} \right)_\alpha = \underbrace{Q_\alpha Q_t \frac{\omega}{|z_\alpha|}}_{\text{NICE (at the level of } z_\alpha, z_t)} + Q \frac{Q_{\alpha t}}{|z_\alpha|} \omega + Q Q_t \left(\frac{\omega}{|z_\alpha|} \right)_\alpha.$$

We use (IV.44) to deal with $\frac{Q_{\alpha t}}{|z_\alpha|}$. We find that

$$(9) = \left(Q Q_t \frac{\omega}{|z_\alpha|} \right)_\alpha = \text{NICE} + Q \omega \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3} + Q Q_t \left(\frac{\omega}{|z_\alpha|} \right)_\alpha.$$

For the next term

$$\begin{aligned}
(10) &= - \left(2cBR \cdot \frac{z_\alpha}{|z_\alpha|} Q Q_\alpha \right)_\alpha = \underbrace{-2cBR \cdot \frac{z_\alpha}{|z_\alpha|} Q_\alpha^2}_{\text{NICE as before}} - \left(2cBR \cdot \frac{z_\alpha}{|z_\alpha|} \right)_\alpha Q Q_\alpha \\
&\quad - 2cBR \cdot z_\alpha Q \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} - \underbrace{2cBR \cdot \frac{z_\alpha}{|z_\alpha|} Q z_\alpha \cdot (\nabla^2 Q(z)) \cdot z_\alpha}_{\text{NICE as before}}.
\end{aligned}$$

Therefore

$$\begin{aligned}
(10) &= - \left(2cBR \cdot \frac{z_\alpha}{|z_\alpha|} Q Q_\alpha \right)_\alpha = \text{NICE} - \left(2cBR \cdot \frac{z_\alpha}{|z_\alpha|} \right)_\alpha Q Q_\alpha \\
&\quad - 2cBR \cdot z_\alpha Q \nabla Q \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.
\end{aligned}$$

Next

$$(11) = - \left(\frac{Q_\alpha}{Q} c^2 |z_\alpha| \right)_\alpha = - (c^2 |z_\alpha|)_\alpha \frac{Q_\alpha}{Q} - \frac{c^2 |z_\alpha|^2}{Q} \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ - \frac{z_\alpha \cdot (\nabla^2 Q(z) \cdot z_\alpha)}{Q} c^2 |z_\alpha| + \frac{Q_\alpha^2}{Q^2} c^2 |z_\alpha|.$$

The fact that the last two terms are NICE, allows us to find that

$$(11) = - \left(\frac{Q_\alpha}{Q} c^2 |z_\alpha| \right)_\alpha = \text{NICE} - (c^2 |z_\alpha|)_\alpha \frac{Q_\alpha}{Q} - \frac{c^2 |z_\alpha|^2}{Q} \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.$$

Finally:

$$(12) = - \left(\frac{Q^3}{|z_\alpha|} |BR|^2 Q_\alpha \right)_\alpha = \underbrace{- \frac{3Q^2 Q_\alpha^2 |BR|^2}{|z_\alpha|}}_{\text{NICE}} - \frac{Q^3}{|z_\alpha|} (|BR|^2)_\alpha Q_\alpha \\ - \underbrace{\frac{Q^3}{|z_\alpha|} |BR|^2 z_\alpha \cdot (\nabla^2 Q(z) \cdot z_\alpha) - Q^3 |BR|^2 \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{\text{NICE}}$$

which implies that

$$(12) = - \left(\frac{Q^3}{|z_\alpha|} |BR|^2 Q_\alpha \right)_\alpha = \text{NICE} - \frac{Q^3}{|z_\alpha|} (|BR|^2)_\alpha Q_\alpha - Q^3 |BR|^2 \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.$$

We gather all the formulas from (4) to (12), keeping term (13) unchanged. They yield:

$$\varphi_{\alpha t} = \text{NICE} - \frac{\varphi}{|z_\alpha|} \varphi_{\alpha\alpha} \\ + \underbrace{\frac{\varphi^2}{Q} \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(16a)} - \underbrace{Q^2 BR_t \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(15a)} - \underbrace{Q^2 \nabla g P_2^{-1}(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(15b)} \\ + \underbrace{Q \omega \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(18a)} + \underbrace{Q Q_t \left(\frac{\omega}{|z_\alpha|} \right)_\alpha}_{(14a)} + \underbrace{2Q BR \cdot z_\alpha \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(18b)} \\ + \underbrace{Q Q_t 2BR_\alpha \cdot \frac{z_\alpha}{|z_\alpha|}}_{(14b)} - \underbrace{\left(2cBR \cdot \frac{z_\alpha}{|z_\alpha|} \right)_\alpha}_{(17a)} Q Q_\alpha - \underbrace{2cBR \cdot z_\alpha Q \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(16b)}$$

$$\begin{aligned}
& \underbrace{-(c^2|z_\alpha)_\alpha \frac{Q_\alpha}{Q}}_{(17b)} \underbrace{- \frac{c^2|z_\alpha|^2}{Q} \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(16c)} \underbrace{- \frac{Q^3}{|z_\alpha|} (|BR|^2)_\alpha Q_\alpha}_{(17c)} \\
& \underbrace{- Q^3 |BR|^2 \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(16d)} + (Q^2 BR)_\alpha \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3}.
\end{aligned}$$

We compute

$$\begin{aligned}
(14) &= (14a) + (14b) = QQ_t \left(\frac{\omega}{|z_\alpha|} \right)_\alpha + QQ_t 2BR_\alpha \cdot \frac{z_\alpha}{|z_\alpha|} \\
&= 2 \frac{Q_t}{Q} Q^2 \left(\frac{\omega}{2|z_\alpha|} \right)_\alpha + 2 \frac{Q_t}{Q} Q^2 BR_\alpha \cdot \frac{z_\alpha}{|z_\alpha|} \\
&= 2 \frac{Q_t}{Q} \varphi_\alpha - 2 \frac{Q_t}{Q} (Q^2)_\alpha \frac{\omega}{2|z_\alpha|} - 2 \frac{Q_t}{Q} (Q^2)_\alpha BR \cdot \frac{z_\alpha}{|z_\alpha|} + 2 \frac{Q_t}{Q} (|z_\alpha| B(t)).
\end{aligned}$$

The last formula allows us to conclude that (14)=NICE.

We reorganize gathering

$$(15) = (15a) + (15b),$$

$$(16) = (16a) + (16b) + (16c) + (16d),$$

$$(17) = (17a) + (17b) + (17c)$$

and

$$(18) = (18a) + (18b)$$

as follows:

$$\begin{aligned}
\varphi_{\alpha t} = \text{NICE} & - \frac{\varphi}{|z_\alpha|} \varphi_{\alpha\alpha} - \underbrace{Q^2 (BR_t \cdot z_\alpha^\perp + \nabla g P_2^{-1}(z) \cdot z_\alpha^\perp) \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(15)} \\
& - \underbrace{Q^3 \left(|BR|^2 + \frac{c^2|z_\alpha|^2}{Q^4} + 2c \frac{BR \cdot z_\alpha}{Q^2} - \frac{\varphi^2}{Q^4} \right) \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(16)} \\
& + (Q^2 BR)_\alpha \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3} + \underbrace{(Q\omega + 2QBR \cdot z_\alpha) \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(18)} \\
& - \underbrace{\left(\frac{Q^3 (|BR|^2)_\alpha}{|z_\alpha|} + \frac{(c^2|z_\alpha)_\alpha}{Q} + \left(2cBR \cdot \frac{z_\alpha}{|z_\alpha|} \right)_\alpha Q \right) Q_\alpha}_{(17)}.
\end{aligned}$$

We add and subtract terms in order to find the R-T condition. We recall here that

$$\begin{aligned}\sigma \equiv & \left(BR_t + \frac{\varphi}{|z_\alpha|} BR_\alpha \right) \cdot z_\alpha^\perp + \frac{\omega}{2|z_\alpha|^2} \left(z_{\alpha t} + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \right) \cdot z_\alpha^\perp \\ & + Q \left| BR + \frac{\omega}{2|z_\alpha|^2} z_\alpha \right|^2 \nabla Q(z) \cdot z_\alpha^\perp + \nabla g P_2^{-1}(z) \cdot z_\alpha^\perp.\end{aligned}$$

Then, we find

$$\begin{aligned}\varphi_{\alpha t} = & \text{NICE} - \frac{\varphi}{|z_\alpha|} \varphi_{\alpha\alpha} \\ & - Q^2 \left(\left(BR_t + \frac{\varphi}{|z_\alpha|} BR_\alpha \right) \cdot z_\alpha^\perp + \frac{\omega}{2|z_\alpha|^2} \left(z_{\alpha t} + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \right) \cdot z_\alpha^\perp + \nabla g P_2^{-1}(z) \cdot z_\alpha^\perp \right) \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ & + \underbrace{(Q^2 BR)_\alpha \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3} + Q^2 \left(\frac{\varphi}{|z_\alpha|} BR_\alpha \cdot z_\alpha^\perp + \frac{\omega}{2|z_\alpha|^2} \left(z_{\alpha t} + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \right) \cdot z_\alpha^\perp \right) \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(19)} \\ & - Q^3 \left(|BR|^2 + \frac{c^2 |z_\alpha|^2}{Q^4} + 2c \frac{BR \cdot z_\alpha}{Q^2} - \frac{\varphi^2}{Q^4} \right) \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ & + (Q\omega + 2QBR \cdot z_\alpha) \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ & - \left(\frac{Q^3 (|BR|^2)_\alpha}{|z_\alpha|} + \frac{(c^2 |z_\alpha|)_\alpha}{Q} + \left(2cBR \cdot \frac{z_\alpha}{|z_\alpha|} \right)_\alpha Q \right) Q_\alpha.\end{aligned}$$

Line (19) can be written as

$$\begin{aligned}(19) = & (Q^2 BR)_\alpha \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3} + Q^2 BR_\alpha \cdot z_\alpha^\perp \frac{\varphi}{|z_\alpha|} \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} + \frac{Q^2 \omega}{2|z_\alpha|^2} \left(z_{\alpha t} + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \right) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ = & (Q^2 BR)_\alpha \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3} + (Q^2 BR)_\alpha \cdot z_\alpha^\perp \frac{\varphi}{|z_\alpha|} \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} + \frac{Q^2 \omega}{2|z_\alpha|^2} \left(z_{\alpha t} \cdot z_\alpha^\perp + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \cdot z_\alpha^\perp \right) \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ & - 2QQ_\alpha BR \cdot z_\alpha^\perp \frac{\varphi}{|z_\alpha|} \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ = & (Q^2 BR)_\alpha \cdot z_\alpha^\perp \frac{1}{|z_\alpha|^3} \left(z_{\alpha t} \cdot z_\alpha^\perp + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \cdot z_\alpha^\perp \right) + \frac{Q^2 \omega}{2|z_\alpha|^2} \frac{1}{|z_\alpha|^3} \left(z_{\alpha t} \cdot z_\alpha^\perp + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \cdot z_\alpha^\perp \right) z_{\alpha\alpha} \cdot z_\alpha^\perp \\ & - 2QQ_\alpha BR \cdot z_\alpha^\perp \frac{\varphi}{|z_\alpha|} \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ = & \frac{1}{|z_\alpha|^3} \left(z_{\alpha t} \cdot z_\alpha^\perp + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \cdot z_\alpha^\perp \right) \left((Q^2 BR)_\alpha \cdot z_\alpha^\perp + \frac{Q^2 \omega}{2|z_\alpha|^2} z_{\alpha\alpha} \cdot z_\alpha^\perp \right) \\ & - 2QQ_\alpha BR \cdot z_\alpha^\perp \frac{\varphi}{|z_\alpha|} \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.\end{aligned}$$

We expand $z_{\alpha t}$ to find

$$(19) = \frac{1}{|z_\alpha|^3} \left((Q^2 BR)_\alpha \cdot z_\alpha^\perp + \frac{Q^2 \omega}{2|z_\alpha|^2} z_{\alpha\alpha} \cdot z_\alpha^\perp \right)^2 \\ - 2QQ_\alpha BR \cdot z_\alpha^\perp \frac{\varphi}{|z_\alpha|} \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.$$

We denote

$$D(\alpha) = (Q^2 BR)_\alpha \cdot z_\alpha^\perp + \frac{Q^2 \omega}{2|z_\alpha|^2} z_{\alpha\alpha} \cdot z_\alpha^\perp. \quad (\text{IV.45})$$

We claim that

$$D(\alpha) = \text{AN}(\alpha) + |z_\alpha| H(\partial_\alpha \varphi) \quad (\text{IV.46})$$

where

$$\|\text{AN}\|_{H^3} \leq CE^p(t). \quad (\text{IV.47})$$

That means

$$(D(\alpha))^2 = \text{NICE}.$$

Thus

$$(19) = \text{NICE} - 2QQ_\alpha BR \cdot z_\alpha^\perp \frac{\varphi}{|z_\alpha|} \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.$$

We write

$$D(\alpha) = \underbrace{2QQ_\alpha BR \cdot z_\alpha^\perp}_{\text{part of AN, at the level of } z_\alpha} + \underbrace{Q^2 \frac{1}{2\pi} PV \int \frac{(z_\alpha - z'_\alpha) \cdot z_\alpha}{|z - z'|^2} \omega' d\beta}_{\text{part of AN, we use (IV.38)}} \\ - \underbrace{Q^2 \frac{1}{\pi} PV \int \frac{(z - z') \cdot z_\alpha}{|z - z'|^4} (z - z') \cdot (z_\alpha - z'_\alpha) \omega' d\beta}_{\text{part of AN, we use (IV.36) and (IV.37)}} \\ + \underbrace{Q^2 BR(z, \omega_\alpha) \cdot z_\alpha^\perp}_{\text{AN} + \frac{Q^2}{2} H(\omega_\alpha)} + \frac{Q^2 \omega}{2|z_\alpha|^2} z_{\alpha\alpha} \cdot z_\alpha^\perp.$$

Therefore

$$D(\alpha) = \text{AN} + |z_\alpha| Q^2 H \left(\left(\frac{\omega}{2|z_\alpha|} \right)_\alpha \right) + \frac{Q^2 \omega}{2|z_\alpha|^2} z_{\alpha\alpha} \cdot z_\alpha^\perp \\ = \text{AN} + |z_\alpha| H \left(\left(\frac{Q^2 \omega}{2|z_\alpha|} \right)_\alpha \right) + \frac{Q^2 \omega}{2|z_\alpha|^2} z_{\alpha\alpha} \cdot z_\alpha^\perp \\ = \text{AN} + |z_\alpha| H(\partial_\alpha \varphi) + H((c|z_\alpha|^2)_\alpha) + \frac{Q^2 \omega}{2|z_\alpha|^2} z_{\alpha\alpha} \cdot z_\alpha^\perp \\ = \text{AN} + |z_\alpha| H(\varphi_\alpha) - H((Q^2 BR)_\alpha \cdot z_\alpha) + \frac{Q^2 \omega}{2|z_\alpha|^2} z_{\alpha\alpha} \cdot z_\alpha^\perp.$$

We have

$$\begin{aligned}
(Q^2 BR)_\alpha \cdot z_\alpha &= \underbrace{2QQ_\alpha BR \cdot z_\alpha}_{\text{AN}} + Q^2 \frac{1}{2\pi} PV \int \frac{(z_\alpha - z'_\alpha)^\perp \cdot z_\alpha}{|z - z'|^2} \omega' d\beta \\
&\quad - \underbrace{Q^2 \frac{1}{\pi} PV \int \frac{(z - z')^\perp \cdot z_\alpha}{|z - z'|^4} (z - z') \cdot (z_\alpha - z'_\alpha) \omega' d\beta}_{\text{AN, we use that } (z - z')^\perp \cdot z_\alpha = (z - z' - \beta z_\alpha)^\perp \cdot z_\alpha} \\
&\quad + \underbrace{Q^2 \frac{1}{2\pi} PV \int \frac{(z - z')^\perp \cdot z_\alpha}{|z - z'|^2} \omega'_\alpha d\beta}_{\text{AN, we use that } (z - z')^\perp \cdot z_\alpha = (z - z' - \beta z_\alpha)^\perp \cdot z_\alpha}.
\end{aligned}$$

For the second term on the right one finds

$$\begin{aligned}
\partial_\alpha^3 \left(\frac{Q^2}{2\pi} PV \int \frac{(z_\alpha - z'_\alpha)^\perp \cdot z_\alpha}{|z - z'|^2} \omega' d\beta \right) &= \frac{Q^2}{2\pi} PV \int \frac{(\partial_\alpha^4 z_\alpha - \partial_\alpha^4 z')^\perp \cdot z_\alpha}{|z - z'|^2} \omega' d\beta \\
&\quad + \frac{Q^2}{2\pi} PV \int \frac{(z_\alpha - z'_\alpha)^\perp}{|z - z'|^2} \omega' d\beta \cdot \partial_\alpha^4 z + \frac{Q^2}{2\pi} PV \int \frac{(z_\alpha - z'_\alpha)^\perp \cdot z_\alpha}{|z - z'|^2} \partial_\alpha^3 \omega' d\beta \\
&\quad - \frac{Q^2}{\pi} PV \int \frac{(z_\alpha - z'_\alpha)^\perp \cdot z_\alpha}{|z - z'|^4} (z - z') \cdot (\partial_\alpha^3 z - \partial_\alpha^3 z') \omega' d\beta + \text{l.o.t.},
\end{aligned}$$

where in l.o.t. we gather the terms of lower order. Then, all the terms above can be estimated in L^2 but the first one on the right. That is equal to

$$\frac{1}{2} H \left(Q^2 \frac{\partial_\alpha^5 z^\perp \cdot z_\alpha}{|z_\alpha|^2} \omega \right)$$

plus a commutator which can be estimated in L^2 . This means that

$$(Q^2 BR)_\alpha \cdot z_\alpha = \text{AN} + \frac{1}{2} H \left(Q^2 \frac{z_{\alpha\alpha}^\perp \cdot z_\alpha}{|z_\alpha|^2} \omega \right).$$

Taking Hilbert transforms:

$$-H \left((Q^2 BR)_\alpha \cdot z_\alpha \right) = \text{AN} - \frac{1}{2} H^2 \left(Q^2 \frac{z_{\alpha\alpha}^\perp \cdot z_\alpha}{|z_\alpha|^2} \omega \right) = \text{AN} + \frac{1}{2} Q^2 \frac{z_{\alpha\alpha}^\perp \cdot z_\alpha}{|z_\alpha|^2} \omega.$$

Using that $z_{\alpha\alpha}^\perp \cdot z_\alpha = -z_{\alpha\alpha} \cdot z_\alpha^\perp$ we complete the proof of (IV.46). Thus (19) yields

$$\begin{aligned}
\varphi_{\alpha t} = & \text{NICE} - \frac{\varphi}{|z_\alpha|} \varphi_{\alpha\alpha} \\
& - Q^2 \left(\left(BR_t + \frac{\varphi}{|z_\alpha|} BR_\alpha \right) \cdot z_\alpha^\perp + \frac{\omega}{2|z_\alpha|^2} \left(z_{\alpha t} + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \right) \cdot z_\alpha^\perp + \nabla g P_2^{-1}(z) \cdot z_\alpha^\perp \right) \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\
& - Q^3 \left(|BR|^2 + \frac{c^2 |z_\alpha|^2}{Q^4} + 2c \frac{BR \cdot z_\alpha}{Q^2} - \frac{\varphi^2}{Q^4} \right) \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\
& + (Q\omega + 2QBR \cdot z_\alpha) \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\
& - \underbrace{\left(\frac{Q^3(|BR|^2)_\alpha}{|z_\alpha|} + \frac{(c^2|z_\alpha|)_\alpha}{Q} + \left(2cBR \cdot \frac{z_\alpha}{|z_\alpha|} \right)_\alpha Q \right)}_{(20)} Q_\alpha \\
& - \underbrace{2QQ_\alpha BR \cdot z_\alpha^\perp \frac{\varphi}{|z_\alpha|} \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}}_{(21)}.
\end{aligned}$$

For (20) we write

$$\begin{aligned}
|z_t|^2 &= Q^4 |BR|^2 + c^2 |z_\alpha|^2 + 2Q^2 c BR \cdot z_\alpha \\
\Rightarrow \frac{|z_t|^2}{Q|z_\alpha|} &= \frac{Q^3 |BR|^2}{|z_\alpha|} + \frac{c^2 |z_\alpha|}{Q} + 2Qc BR \cdot \frac{z_\alpha}{|z_\alpha|}.
\end{aligned}$$

Now

$$(20) = \text{NICE} - \frac{(|z_t|^2)_\alpha}{Q|z_\alpha|} Q_\alpha,$$

which means

$$(20) + (21) = \text{NICE} - \frac{(|z_t|^2)_\alpha}{Q|z_\alpha|} Q_\alpha - 2QQ_\alpha BR \cdot z_\alpha^\perp \frac{\varphi}{|z_\alpha|} \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.$$

We write

$$\begin{aligned}
z_{\alpha t} &= \underbrace{(z_{\alpha t} \cdot z_\alpha)}_{\text{only depends on } t} \frac{z_\alpha}{|z_\alpha|^2} + (z_{\alpha t} \cdot z_\alpha^\perp) \frac{z_\alpha^\perp}{|z_\alpha|^2} \\
&= \underbrace{B(t)}_{\text{See (IV.21)}} z_\alpha + ((Q^2 BR)_\alpha \cdot z_\alpha^\perp + cz_{\alpha\alpha} \cdot z_\alpha^\perp) \frac{z_\alpha^\perp}{|z_\alpha|^2} \\
&= B(t) z_\alpha + \underbrace{D(\alpha)}_{\text{as in (IV.45)}} \frac{z_\alpha^\perp}{|z_\alpha|^2} - \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \cdot z_\alpha^\perp \frac{z_\alpha^\perp}{|z_\alpha|^2}.
\end{aligned}$$

Writing $z_t = Q^2 BR + cz_\alpha$ we compute

$$\begin{aligned} z_{\alpha t} \cdot z_t &= \underbrace{Q^2 BR \cdot z_\alpha B(t)}_{\text{NICE}} + \underbrace{DQ^2 BR \cdot \frac{z_\alpha^\perp}{|z_\alpha|^2}}_{\text{NICE because } D \text{ is nice}} \\ &\quad - \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \cdot z_\alpha^\perp Q^2 BR \cdot \frac{z_\alpha^\perp}{|z_\alpha|^2} + \underbrace{cB(t)|z_\alpha|^2}_{\text{NICE}}. \end{aligned}$$

To simplify we write

$$z_{\alpha t} \cdot z_t = \text{NICE} - \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \cdot z_\alpha^\perp Q^2 BR \cdot \frac{z_\alpha^\perp}{|z_\alpha|^2}.$$

Setting the above formula in the expression of (20)+(21) allows us to find

$$(20) + (21) = \text{NICE}.$$

This yields

$$\begin{aligned} \varphi_{\alpha t} = &\text{NICE} - \frac{\varphi}{|z_\alpha|} \varphi_{\alpha\alpha} \\ &- Q^2 \left(\left(BR_t + \frac{\varphi}{|z_\alpha|} BR_\alpha \right) + \frac{\omega}{2|z_\alpha|^2} \left(z_{\alpha t} + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \right) + \nabla g P_2^{-1}(z) \right) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ &- Q^3 \left(|BR|^2 + \frac{c^2|z_\alpha|^2}{Q^4} + 2c \frac{BR \cdot z_\alpha}{Q^2} - \frac{\varphi^2}{Q^4} \right) \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ &+ (Q\omega + 2QBR \cdot z_\alpha) \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3}. \end{aligned}$$

We now complete the formula for σ in (IV.2) to find

$$\begin{aligned} \varphi_{\alpha t} = &\text{NICE} - \frac{\varphi}{|z_\alpha|} \varphi_{\alpha\alpha} - Q^2 \sigma \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ &+ Q^3 \underbrace{\left| BR + \frac{\omega}{2|z_\alpha|^2} z_\alpha \right|^2}_{(22)} \nabla Q \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ &+ Q^3 \underbrace{\left(-|BR|^2 - \frac{c^2|z_\alpha|^2}{Q^4} - 2c \frac{BR \cdot z_\alpha}{Q^2} + \frac{\varphi^2}{Q^4} \right)}_{(23)} \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ &+ \underbrace{(Q\omega + 2QBR \cdot z_\alpha) \nabla Q(z)}_{(24)} \cdot z_\alpha^\perp \frac{z_{\alpha t} \cdot z_\alpha^\perp}{|z_\alpha|^3}. \end{aligned}$$

Expanding

$$\frac{\varphi^2}{Q^4} = \frac{\omega^2}{4|z_\alpha|^2} + \frac{c^2|z_\alpha|^2}{Q^4} - \frac{\omega c}{Q^2}$$

we find

$$(22) + (23) = Q^3 \left(\frac{\omega^2}{2|z_\alpha|^2} + BR \cdot z_\alpha \frac{\omega}{|z_\alpha|^2} - 2c \frac{BR \cdot z_\alpha}{Q^2} - \frac{\omega c}{Q^2} \right) \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.$$

Writing

$$z_{\alpha t} \cdot z_\alpha^\perp = (Q^2 BR)_\alpha \cdot z_\alpha^\perp + cz_{\alpha\alpha} \cdot z_\alpha^\perp$$

we obtain that

$$(24) = (Q\omega + 2QBR \cdot z_\alpha) \nabla Q(z) \cdot z_\alpha^\perp \frac{(Q^2 BR)_\alpha \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ + (Q\omega + 2QBR \cdot z_\alpha) \nabla Q(z) \cdot z_\alpha^\perp c \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.$$

Thus

$$(22) + (23) + (24) = Q^3 \left(\frac{\omega^2}{2|z_\alpha|^2} + BR \cdot z_\alpha \frac{\omega}{|z_\alpha|^2} \right) \nabla Q(z) \cdot z_\alpha^\perp \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ + (Q\omega + 2QBR \cdot z_\alpha) \nabla Q(z) \cdot z_\alpha^\perp \frac{(Q^2 BR)_\alpha \cdot z_\alpha^\perp}{|z_\alpha|^3} \\ = Q \nabla Q(z) \cdot z_\alpha^\perp (\omega + 2BR \cdot z_\alpha) \left(\frac{Q^2 \omega}{2|z_\alpha|^2} \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} + \frac{(Q^2 BR)_\alpha \cdot z_\alpha^\perp}{|z_\alpha|^3} \right) \\ = Q \nabla Q(z) \cdot z_\alpha^\perp (\omega + 2BR \cdot z_\alpha) \frac{1}{|z_\alpha|^3} D(\alpha) \\ = \text{NICE}.$$

Finally, we obtain

$$\varphi_{\alpha t} = \text{NICE} - \frac{\varphi}{|z_\alpha|} \varphi_{\alpha\alpha} - Q^2 \sigma \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.$$

□

Corollary IV.13 *If we disregard the condition on the H^{k-2} norm for the definition of the NICE terms, imposing only the first condition, then*

$$\varphi_{\alpha t} = \text{NICE} - Q^2 \sigma \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3}.$$

IV.D.11 Higher order derivatives of σ

In this section we deal with the highest order derivative of the R-T function. We show that

Lemma IV.14 *Let $z(\alpha, t)$ and $\omega(\alpha, t)$ be a solution of (I.19-I.20). Then, the following identity holds:*

$$\partial_\alpha^{k-1}(Q^2\sigma) = ANN + |z_\alpha|H(\partial_\alpha^{k-1}\varphi_t) + \varphi H(\partial_\alpha^k\varphi) \quad (\text{IV.48})$$

where ANN satisfies

$$\|ANN\|_{L^2} \leq CE^p(t) \quad (\text{IV.49})$$

for $k \geq 4$, where C and p are constants that depend only on k .

Proof: We show the proof for $k = 4$. From now on, if a term f satisfies

$$\|f\|_{L^2} \leq CE^p(t)$$

we say that this term becomes part of ANN. By abuse of notation we will denote f by ANN. We recall

$$\begin{aligned} Q^2\sigma = & Q^2 \left(BR_t + \frac{\varphi}{|z_\alpha|} BR_\alpha \right) \cdot z_\alpha^\perp + \frac{Q^2\omega}{2|z_\alpha|^2} \left(z_{\alpha t} + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \right) \cdot z_\alpha^\perp \\ & + \underbrace{Q^3 \left| BR + \frac{\omega}{2|z_\alpha|^2} z_\alpha \right|^2 \nabla Q \cdot z_\alpha^\perp}_{\text{this term is in } H^3 \text{ so its third derivative is in ANN}} + \underbrace{Q^2 \nabla g P_2^{-1}(z) \cdot z_\alpha^\perp}_{\text{this term is also in } H^3}. \end{aligned}$$

We write

$$\begin{aligned} \frac{Q^2\omega}{2|z_\alpha|^2} \left(z_{\alpha t} + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \right) \cdot z_\alpha^\perp &= \frac{Q^2\omega}{2|z_\alpha|^2} \left((Q^2 BR)_\alpha \cdot z_\alpha^\perp + c z_{\alpha\alpha} \cdot z_\alpha^\perp + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \cdot z_\alpha^\perp \right) \\ &= \frac{Q^2\omega}{2|z_\alpha|^2} \left((Q^2 BR)_\alpha \cdot z_\alpha^\perp + \left(c + \frac{\varphi}{|z_\alpha|} \right) z_{\alpha\alpha} \cdot z_\alpha^\perp \right) \\ &= \frac{Q^2\omega}{2|z_\alpha|^2} \left((Q^2 BR)_\alpha \cdot z_\alpha^\perp + \frac{Q^2\omega}{2|z_\alpha|^2} z_{\alpha\alpha} \cdot z_\alpha^\perp \right) \\ &= \frac{Q^2\omega}{2|z_\alpha|^2} D(\alpha). \end{aligned}$$

Above we use (IV.45) and (IV.46) to find

$$\frac{Q^2\omega}{2|z_\alpha|^2} \left(z_{\alpha t} + \frac{\varphi}{|z_\alpha|} z_{\alpha\alpha} \right) \cdot z_\alpha^\perp = AN + \frac{Q^2\omega}{2|z_\alpha|} H(\varphi_\alpha), \quad (\text{IV.50})$$

where AN is as in (IV.47). The remaining terms in $Q^2\sigma$ are

$$L = Q^2 BR_t \cdot z_\alpha^\perp + \frac{Q^2\varphi}{|z_\alpha|} BR_\alpha \cdot z_\alpha^\perp.$$

We take 3 derivatives and consider the most dangerous characters:

$$\partial_\alpha^3(L) = M_1 + M_2 + M_3 + ANN,$$

where

$$\begin{aligned}
M_1 &= Q^2 BR(z, \partial_\alpha^3 \omega_t) \cdot z_\alpha^\perp + \frac{Q^2 \varphi}{|z_\alpha|} BR(z, \partial_\alpha^4 \omega) \cdot z_\alpha^\perp, \\
M_2 &= Q^2 \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{(\partial_\alpha^3 z_t - \partial_\alpha^3 z'_t) \cdot z_\alpha}{|z - z'|^2} \omega' d\beta \\
&\quad + \frac{Q^2 \varphi}{|z_\alpha|} \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{(\partial_\alpha^4 z - \partial_\alpha^4 z') \cdot z_\alpha}{|z - z'|^2} \omega' d\beta, \\
M_3 &= -\frac{Q^2}{\pi} \int_{-\pi}^{\pi} \frac{(z - z') \cdot z_\alpha}{|z - z'|^4} (z - z') \cdot (\partial_\alpha^3 z_t - \partial_\alpha^3 z'_t) \omega' d\beta \\
&\quad - \frac{Q^2 \varphi}{|z_\alpha| \pi} \int_{-\pi}^{\pi} \frac{(z - z') \cdot z_\alpha}{|z - z'|^4} (z - z') \cdot (\partial_\alpha^4 z - \partial_\alpha^4 z') \omega' d\beta.
\end{aligned}$$

Here we point out that in order to deal with BR_t in the less singular terms we proceed using estimate (IV.30). In M_2 we find

$$M_2 = \frac{Q^2 \omega}{2|z_\alpha|^2} \Lambda(\partial_\alpha^3 z_t \cdot z_\alpha) + \frac{Q^2 \varphi \omega}{2|z_\alpha|^3} \Lambda(\partial_\alpha^4 z \cdot z_\alpha) + \text{ANN}.$$

For the second term we use the usual trick

$$\partial_\alpha^4 z \cdot z_\alpha = -3\partial_\alpha^3 z \cdot z_{\alpha\alpha}.$$

For the first term we recall that

$$\begin{aligned}
|z_\alpha|^2 = A(t) &\Rightarrow z_\alpha \cdot z_{\alpha t} = \frac{1}{2} A'(t) \Rightarrow (z_\alpha \cdot z_{\alpha t})_\alpha = 0 \\
&\Rightarrow z_{\alpha\alpha} \cdot z_{\alpha t} + z_\alpha \cdot z_{\alpha\alpha t} = 0 \Rightarrow z_{\alpha\alpha\alpha} \cdot z_{\alpha t} + 2z_{\alpha\alpha} \cdot z_{\alpha\alpha t} + z_\alpha \cdot z_{\alpha\alpha\alpha t} = 0 \\
&\Rightarrow z_\alpha \cdot z_{\alpha\alpha\alpha t} = -2z_{\alpha\alpha} \cdot z_{\alpha\alpha t} - z_{\alpha\alpha\alpha} \cdot z_{\alpha t}.
\end{aligned}$$

This allows us to control M_2 . For M_3 we find

$$M_3 = -\frac{Q^2 \omega}{|z_\alpha|^2} \Lambda(z_\alpha \cdot \partial_\alpha^3 z_t) - \frac{Q^2 \varphi \omega}{|z_\alpha|^3} \Lambda(z_\alpha \cdot \partial_\alpha^4 z) + \text{ANN}$$

so it can be estimated as M_2 . There remains M_1 . Using that $(z - z')^\perp \cdot z_\alpha^\perp = (z - z') \cdot z_\alpha$ we find

$$M_1 = \frac{Q^2}{2} H(\partial_\alpha^3 \omega_t) + \frac{Q^2 \varphi}{2|z_\alpha|} H(\partial_\alpha^4 \omega) + \text{ANN}. \quad (\text{IV.51})$$

We compute

$$\begin{aligned}
\frac{Q^2}{2} H(\partial_\alpha^3 \omega_t) &= H\left(\partial_\alpha^3 \left(\frac{Q^2 \omega}{2}\right)_t\right) + \text{ANN} \\
&= H(\partial_\alpha^3 (|z_\alpha| \varphi)_t) + H(\partial_\alpha^3 (|z_\alpha| c)_t) + \text{ANN} \\
&= |z_\alpha| H(\partial_\alpha^3 \varphi_t) + H(\partial_\alpha^2 \partial_t (-(Q^2 BR)_\alpha \cdot z_\alpha)) + \text{ANN}. \quad (\text{IV.52})
\end{aligned}$$

We compute the most singular term in

$$\begin{aligned}
\partial_\alpha^2 \partial_t (-(Q^2 BR)_\alpha \cdot z_\alpha) &= -\frac{Q^2}{2\pi} \int_{-\pi}^{\pi} \frac{(\partial_\alpha^3 z_t - \partial_\alpha^3 z'_t)^\perp \cdot z_\alpha}{|z - z'|^2} \omega' d\beta \\
&+ \underbrace{\frac{Q^2}{\pi} \int_{-\pi}^{\pi} \frac{(z - z')^\perp \cdot z_\alpha}{|z - z'|^4} (z - z') \cdot (\partial_\alpha^3 z_t - \partial_\alpha^3 z'_t) \omega' d\beta}_{\text{extra cancelation in } (z - z')^\perp \cdot z_\alpha = (z - z' - z_\alpha \beta)^\perp \cdot z_\alpha} \\
&- \underbrace{\frac{Q^2}{2\pi} PV \int_{-\pi}^{\pi} \frac{(z - z')^\perp \cdot z_\alpha}{|z - z'|^2} \partial_\alpha^3 \omega'_t d\beta}_{\text{extra cancelation as above}} + \text{ANN}.
\end{aligned}$$

This shows that

$$\partial_\alpha^2 \partial_t (-(Q^2 BR)_\alpha \cdot z_\alpha) = -\frac{Q^2 \omega}{2|z_\alpha|^2} \Lambda(\partial_\alpha^3 z_t^\perp \cdot z_\alpha) + \text{ANN}.$$

That gives

$$\partial_\alpha^2 \partial_t (-(Q^2 BR)_\alpha \cdot z_\alpha) = -\Lambda \left(\frac{Q^2 \omega}{2|z_\alpha|^2} \partial_\alpha^3 z_t^\perp \cdot z_\alpha \right) + \text{ANN},$$

which implies

$$H(\partial_\alpha^2 \partial_t (-(Q^2 BR)_\alpha \cdot z_\alpha)) = \partial_\alpha \left(\frac{Q^2 \omega}{2|z_\alpha|^2} \partial_\alpha^3 z_t^\perp \cdot z_\alpha \right) + \text{ANN} = -\frac{Q^2 \omega}{2|z_\alpha|^2} \partial_\alpha \left(\partial_\alpha^3 z_t \cdot z_\alpha^\perp \right) + \text{ANN}.$$

Plugging the above formula in (IV.52) we find that

$$\begin{aligned}
\frac{Q^2}{2} H(\partial_\alpha^3 \omega_t) &= |z_\alpha| H(\partial_\alpha^3 \varphi_t) - \frac{Q^2 \omega}{2|z_\alpha|^2} \partial_\alpha \left(\partial_\alpha^3 z_t \cdot z_\alpha^\perp \right) + \text{ANN} \\
&= |z_\alpha| H(\partial_\alpha^3 \varphi_t) - \frac{Q^2 \omega}{2|z_\alpha|^2} \partial_\alpha \left(\partial_\alpha^3 (Q^2 BR) \cdot z_\alpha^\perp \right) - \frac{Q^2 \omega}{2|z_\alpha|^2} \partial_\alpha \left(c \partial_\alpha^4 z \cdot z_\alpha^\perp \right) \\
&+ \text{ANN}.
\end{aligned}$$

As we did before, we expand $\partial_\alpha(\partial_\alpha^3(Q^2 BR) \cdot z_\alpha^\perp)$ to find

$$\begin{aligned}
\partial_\alpha(\partial_\alpha^3(Q^2 BR) \cdot z_\alpha^\perp) &= 2Q \nabla Q(z) \cdot \partial_\alpha^4 z BR \cdot z_\alpha^\perp + \frac{Q^2}{2\pi} PV \int \frac{(\partial_\alpha^4 z - \partial_\alpha^4 z') \cdot z_\alpha}{|z - z'|^2} \omega' d\beta \\
&- \frac{Q^2}{\pi} PV \int \frac{(z - z') \cdot z_\alpha}{|z - z'|^4} (z - z') \cdot (\partial_\alpha^4 z - \partial_\alpha^4 z') \omega' d\beta \\
&+ \frac{Q^2}{2\pi} PV \int \frac{(z - z') \cdot z_\alpha}{|z - z'|^2} \partial_\alpha^4 \omega' d\beta + \text{ANN}.
\end{aligned}$$

Therefore, we can use (IV.36), (IV.37) and (IV.37) to show that the most dangerous term is given by $Q^2 \frac{1}{2} H(\partial_\alpha^4 \omega)$. It implies

$$\partial_\alpha(\partial_\alpha^3(Q^2 BR) \cdot z_\alpha^\perp) = Q^2 \frac{1}{2} H(\partial_\alpha^4 \omega) + \text{ANN}$$

and therefore

$$\frac{Q^2}{2}H(\partial_\alpha^3\omega_t) = |z_\alpha|H(\partial_\alpha^3\varphi_t) - \frac{Q^2\omega}{2|z_\alpha|^2} \frac{Q^2}{2}H(\partial_\alpha^4\omega) - \frac{Q^2\omega}{2|z_\alpha|^2}c\partial_\alpha\left(\partial_\alpha^4z \cdot z_\alpha^\perp\right) + \text{ANN}.$$

We use the above formula and expand φ to find

$$\begin{aligned} M_1 &= \frac{Q^2}{2}H(\partial_\alpha^3\omega_t) + \frac{Q^2\varphi}{2|z_\alpha|}H(\partial_\alpha^4\omega) + \text{ANN} \\ &= |z_\alpha|H(\partial_\alpha^3\varphi_t) - \frac{Q^2}{2}cH(\partial_\alpha^4\omega) - \frac{Q^2\omega}{2|z_\alpha|^2}c\partial_\alpha\left(\partial_\alpha^4z \cdot z_\alpha^\perp\right) + \text{ANN} \\ &= |z_\alpha|H(\partial_\alpha^3\varphi_t) - c|z_\alpha|H\left(\partial_\alpha^4\left(\frac{Q^2\omega}{2|z_\alpha|}\right)\right) - \frac{Q^2\omega}{2|z_\alpha|^2}c\partial_\alpha\left(\partial_\alpha^4z \cdot z_\alpha^\perp\right) + \text{ANN} \\ &= |z_\alpha|H(\partial_\alpha^3\varphi_t) - c|z_\alpha|H(\partial_\alpha^4\varphi) - c|z_\alpha|H(\partial_\alpha^4(c|z_\alpha|)) - \frac{Q^2\omega}{2|z_\alpha|^2}c\partial_\alpha\left(\partial_\alpha^4z \cdot z_\alpha^\perp\right) + \text{ANN}. \end{aligned}$$

We will show that

$$-c|z_\alpha|H(\partial_\alpha^4(c|z_\alpha|)) - \frac{Q^2\omega}{2|z_\alpha|^2}c\partial_\alpha\left(\partial_\alpha^4z \cdot z_\alpha^\perp\right) = \text{ANN}. \quad (\text{IV.53})$$

It yields

$$\frac{Q^2}{2}H(\partial_\alpha^3\omega_t) + \frac{Q^2\varphi}{2|z_\alpha|}H(\partial_\alpha^4\omega) = |z_\alpha|H(\partial_\alpha^3\varphi_t) - c|z_\alpha|H(\partial_\alpha^4\varphi) + \text{ANN}$$

that together with (IV.50) allows us to obtain (IV.48). We have

$$\begin{aligned} -c|z_\alpha|H(\partial_\alpha^4(c|z_\alpha|)) - \frac{Q^2\omega}{2|z_\alpha|^2}c\partial_\alpha\left(\partial_\alpha^4z \cdot z_\alpha^\perp\right) &= -cH(\partial_\alpha^4(c|z_\alpha|^2)) - \frac{Q^2\omega}{2|z_\alpha|^2}c\partial_\alpha\left(\partial_\alpha^4z \cdot z_\alpha^\perp\right) \\ &= cH(\partial_\alpha^3((Q^2BR)_\alpha \cdot z_\alpha)) - \frac{Q^2\omega}{2|z_\alpha|^2}c\partial_\alpha\left(\partial_\alpha^4z \cdot z_\alpha^\perp\right). \end{aligned}$$

We repeat the calculation for dealing with the most dangerous terms in

$$\partial_\alpha^3((Q^2BR)_\alpha \cdot z_\alpha) = \Lambda\left(\partial_\alpha^4z^\perp \cdot z_\alpha \frac{\omega Q^2}{2|z_\alpha|^2}\right) + \text{ANN}.$$

We recognized as before terms in ANN using that $(z - z')^\perp \cdot z_\alpha$ gives an extra cancellation. We find that

$$\begin{aligned} cH(\partial_\alpha^3((Q^2BR)_\alpha \cdot z_\alpha)) - \frac{Q^2\omega}{2|z_\alpha|^2}c\partial_\alpha\left(\partial_\alpha^4z \cdot z_\alpha^\perp\right) \\ &= cH\left(\Lambda\left(\partial_\alpha^4z^\perp \cdot z_\alpha \frac{\omega Q^2}{2|z_\alpha|^2}\right)\right) - \frac{Q^2\omega}{2|z_\alpha|^2}c\partial_\alpha\left(\partial_\alpha^4z \cdot z_\alpha^\perp\right) + \text{ANN} \\ &= -c\partial_\alpha\left(\partial_\alpha^4z^\perp \cdot z_\alpha \frac{\omega Q^2}{2|z_\alpha|^2}\right) - \frac{Q^2\omega}{2|z_\alpha|^2}c\partial_\alpha\left(\partial_\alpha^4z \cdot z_\alpha^\perp\right) + \text{ANN}. \end{aligned}$$

Using that $\partial_\alpha^4z^\perp \cdot z_\alpha = -\partial_\alpha^4z \cdot z_\alpha^\perp$ we are done proving (IV.53). \square

IV.D.12 Energy estimates for φ

In this section we prove the following result.

Lemma IV.15 *Let $z(\alpha, t)$ and $\omega(\alpha, t)$ be a solution of (I.19-I.20). Then, the following a priori estimate holds:*

$$\frac{d}{dt} \|\varphi\|_{H^{k-\frac{1}{2}}}^2(t) \leq -S(t) + CE^p(t) \quad (\text{IV.54})$$

for $k \geq 4$, where C and p are constants that depend only on k .

Proof: We shall present the details in the case $k = 4$, leaving the other cases to the reader.

Using the estimates obtained before one has

$$\frac{d}{dt} \|\varphi\|_{L^2}^2(t) \leq CE^p(t).$$

Developing the derivative using Lemma IV.12, we get that:

$$\begin{aligned} \frac{d}{dt} \|\Lambda^{1/2}(\partial_\alpha^3 \varphi)\|_{L^2}^2(t) &= 2 \int_{\mathbb{T}} \Lambda(\partial_\alpha^3 \varphi) \partial_\alpha^3 \varphi_t d\alpha \\ &= I_1 + I_2 + I_3, \end{aligned} \quad (\text{IV.55})$$

where

$$\begin{aligned} I_1 &= 2 \int_{\mathbb{T}} \Lambda(\partial_\alpha^3 \varphi) \partial_\alpha^2 (\text{NICE}) d\alpha, & I_2 &= -2 \int_{\mathbb{T}} \Lambda(\partial_\alpha^3 \varphi) \partial_\alpha^2 \left(\frac{\varphi}{|z_\alpha|} \varphi_{\alpha\alpha} \right) d\alpha, \\ I_3 &= -2 \int_{\mathbb{T}} \Lambda(\partial_\alpha^3 \varphi) \partial_\alpha^2 \left(Q^2 \sigma \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \right) d\alpha. \end{aligned}$$

We use (IV.41) to control I_1 . The most singular term in I_2 is the one given by

$$\begin{aligned} -2 \int_{\mathbb{T}} \frac{1}{|z_\alpha|} \Lambda(\partial_\alpha^3 \varphi) \partial_\alpha^4 \varphi d\alpha &= 2 \int_{\mathbb{T}} \frac{1}{|z_\alpha|} \Lambda^{1/2}(\partial_\alpha^3 \varphi) \left[\varphi \Lambda^{1/2}(\partial_\alpha^4 \varphi) - \Lambda^{1/2}(\varphi \partial_\alpha^4 \varphi) \right] d\alpha \\ &\quad + \int_{\mathbb{T}} \frac{1}{|z_\alpha|} \partial_\alpha \varphi |\Lambda^{1/2}(\partial_\alpha^3 \varphi)|^2 d\alpha. \end{aligned}$$

Using the commutator estimate

$$\|g \Lambda^{1/2}(\partial_\alpha f) - \Lambda^{1/2}(g \partial_\alpha f)\|_{L^2} \leq \|g\|_{C^2} \|f\|_{H^{1/2}} \quad (\text{IV.56})$$

we can bound I_2 . In I_3 we split further considering the most singular terms

$$\begin{aligned} J_1 &= -2 \int_{\mathbb{T}} \Lambda(\partial_\alpha^3 \varphi) Q^2 \sigma z_{\alpha\alpha} \cdot \partial_\alpha^2 \left(\frac{z_\alpha^\perp}{|z_\alpha|^3} \right) d\alpha, \\ J_2 &= -2 \int_{\mathbb{T}} \Lambda(\partial_\alpha^3 \varphi) Q^2 \sigma \frac{\partial_\alpha^4 z \cdot z_\alpha^\perp}{|z_\alpha|^3} d\alpha, \end{aligned}$$

$$J_3 = -2 \int_{\mathbb{T}} \Lambda(\partial_\alpha^3 \varphi) \partial_\alpha^2 (Q^2 \sigma) \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} d\alpha.$$

The term J_1 can be estimated as before. Recalling (IV.35) we see that $J_2 = -S(t)$. It remains to control J_3 in order to find (IV.54).

We decompose $J_3 = K_1 + K_2$ where

$$K_1 = 2 \int_{\mathbb{T}} H(\partial_\alpha^3 \varphi) \partial_\alpha^2 (Q^2 \sigma) \partial_\alpha \left(\frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \right) d\alpha$$

and

$$K_2 = 2 \int_{\mathbb{T}} H(\partial_\alpha^3 \varphi) \partial_\alpha^3 (Q^2 \sigma) \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} d\alpha.$$

Inequality (IV.31) for $k = 4$ allows us to obtain

$$K_1 \leq CE^p(t).$$

To finish the proof we use formula (IV.48) for $k = 4$ to find $K_2 = L_1 + L_2 + L_3$ where

$$L_1 = 2 \int_{\mathbb{T}} H(\partial_\alpha^3 \varphi) \text{ANN} \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} d\alpha,$$

$$L_2 = 2 \int_{\mathbb{T}} H(\partial_\alpha^3 \varphi) |z_\alpha| H(\partial_\alpha^3 \varphi_t) \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} d\alpha,$$

$$L_3 = 2 \int_{\mathbb{T}} H(\partial_\alpha^3 \varphi) \varphi H(\partial_\alpha^4 \varphi) \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} d\alpha.$$

The term L_1 can be easily estimated using (IV.49). For L_2 we substitute the expression (IV.54) for $\partial_\alpha^3 \varphi_t$ to get $L_2 = M_1 + M_2 + M_3$:

$$M_1 = 2 \int_{\mathbb{T}} H(\partial_\alpha^3 \varphi) |z_\alpha| H(\partial_\alpha^2 (\text{NICE})) \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} d\alpha.$$

$$M_2 = -2 \int_{\mathbb{T}} H(\partial_\alpha^3 \varphi) |z_\alpha| H(\partial_\alpha^2 \left(\frac{\varphi \varphi_{\alpha\alpha}}{|z_\alpha|} \right)) \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} d\alpha.$$

$$M_3 = -2 \int_{\mathbb{T}} H(\partial_\alpha^3 \varphi) |z_\alpha| H(\partial_\alpha^2 (Q^2 \sigma \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3})) \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} d\alpha.$$

By equation (IV.41), M_1 is bounded. M_2 is bounded knowing that we have room for half derivative in the term which is not the third factor. Finally we can bound M_3 in virtue of Lemma IV.8. To finish, in L_3 we integrate by parts to find

$$L_3 = - \int_{\mathbb{T}} |H(\partial_\alpha^3 \varphi)|^2 \partial_\alpha \left(\varphi \frac{z_{\alpha\alpha} \cdot z_\alpha^\perp}{|z_\alpha|^3} \right) d\alpha \leq CE^p(t)$$

using Sobolev embedding. □

IV.D.13 Energy estimates for $\frac{|z_\alpha|^2}{m(Q^2\sigma)(t)} + \sum_{l=0}^4 \frac{1}{m(q^l)(t)}$.

Lemma IV.16 *Let $z(\alpha, t)$ and $\omega(\alpha, t)$ be a solution of (I.19-I.20). Then, the following a priori estimate holds:*

$$\frac{d}{dt} \left(\frac{|z_\alpha|^2}{m(Q^2\sigma)(t)} + \sum_{l=0}^4 \frac{1}{m(q^l)(t)} \right) \leq CE^p(t) \quad (\text{IV.57})$$

for $k \geq 4$, where C and p are constants that depend only on k .

Proof: Inequalities (IV.27) and (IV.32) show that $(Q^2\sigma) \in C^1([0, T] \times [-\pi, \pi])$ for some T and therefore $m(Q^2\sigma)(t)$ is a Lipschitz function differentiable almost everywhere by Rademacher's theorem. Let

$$m(Q^2\sigma)(t) = \min_{\alpha \in [-\pi, \pi]} (Q^2\sigma)(\alpha, t) = (Q^2\sigma)(\alpha_t, t).$$

We can calculate the derivative of $m(Q^2\sigma)(t)$, to obtain

$$(m(Q^2\sigma))'(t) = (Q^2\sigma)_t(\alpha_t, t)$$

for almost every t . Then it follows that:

$$\frac{d}{dt} \left(\frac{1}{m(Q^2\sigma)} \right) (t) = -\frac{(Q^2\sigma)_t(\alpha_t, t)}{(m(Q^2\sigma))^2(t)}$$

almost everywhere. By using the previous a priori estimates for the L^∞ bounds, we get to

$$\frac{d}{dt} \left(\frac{|z_\alpha|^2}{m(Q^2\sigma)} \right) (t) \leq CE^p(t).$$

On the other hand, we can apply the same argument to $\frac{1}{m(q^l)(t)}$. Denoting again by α_t the point where the minimum is attained we have that:

$$\frac{d}{dt} \left(\frac{1}{m(q^l)} \right) (t) = -\frac{z_t(\alpha_t, t) \cdot (z(\alpha_t, t) - q^l)}{(m(q^l))^3(t)}$$

which again can be easily bounded and we get (IV.57), as desired. \square

IV.E Proof of short-time existence (Theorem I.7)

To conclude the proof of the local existence, we shall use the previous a priori estimates. We now introduce a regularized version of the evolution equation which is well-posed for short time independently of the sign condition on $\sigma(\alpha, t)$ at $t = 0$. But for $\sigma(\alpha, 0) > 0$, we shall find a time of existence uniformly in the regularization, allowing us to take the limit.

Now, let $z^{\varepsilon,\delta,\mu}(\alpha, t)$ be a solution of the following system (compare with (IV.20)):

$$z_t^{\varepsilon,\delta,\mu}(\alpha, t) = \phi_\delta * \phi_\delta * \left(Q^2(z^{\varepsilon,\delta,\mu}) BR(z^{\varepsilon,\delta,\mu}, \omega^{\varepsilon,\delta,\mu}) \right) (\alpha, t) + \phi_\mu * \left(c^{\varepsilon,\delta,\mu} \left(\phi_\mu * \partial_\alpha z^{\varepsilon,\delta,\mu} \right) \right) (\alpha, t), \quad (\text{IV.58})$$

$$\begin{aligned} \omega_t^{\varepsilon,\delta,\mu} = & \frac{|\partial_\alpha z^{\varepsilon,\delta,\mu}|}{Q^2(z^{\varepsilon,\delta,\mu})} \phi_\delta * \phi_\delta * \left(\frac{Q^2(z^{\varepsilon,\delta,\mu})}{|\partial_\alpha z^{\varepsilon,\delta,\mu}(\alpha, t)|} \left[-2BR(z^{\varepsilon,\delta,\mu}, \omega^{\varepsilon,\delta,\mu})_t \cdot z_\alpha^{\varepsilon,\delta,\mu} \right. \right. \\ & - 2Q(z^{\varepsilon,\delta,\mu}) Q(z^{\varepsilon,\delta,\mu})_\alpha |BR(z^{\varepsilon,\delta,\mu}, \omega^{\varepsilon,\delta,\mu})|^2 - \partial_\alpha \left(\frac{(\varphi^{\varepsilon,\delta,\mu})^2}{Q(z^{\varepsilon,\delta,\mu})^2} \right) \\ & + \frac{c^{\varepsilon,\delta,\mu} |z_\alpha^{\varepsilon,\delta,\mu}|^2}{\pi Q(z^{\varepsilon,\delta,\mu})^2} \int_{-\pi}^{\pi} (Q(z^{\varepsilon,\delta,\mu})^2 BR(z^{\varepsilon,\delta,\mu}, \omega^{\varepsilon,\delta,\mu}))_\beta \cdot \frac{z_\beta^{\varepsilon,\delta,\mu}}{|z_\beta^{\varepsilon,\delta,\mu}|^2} d\beta \\ & - \frac{4c^{\varepsilon,\delta,\mu} Q(z^{\varepsilon,\delta,\mu})_\alpha BR(z^{\varepsilon,\delta,\mu}, \omega^{\varepsilon,\delta,\mu}) \cdot z_\alpha^{\varepsilon,\delta,\mu}}{Q(z^{\varepsilon,\delta,\mu})} \\ & \left. \left. - \frac{2(c^{\varepsilon,\delta,\mu})^2 |z_\alpha^{\varepsilon,\delta,\mu}|^2 Q(z^{\varepsilon,\delta,\mu})_\alpha - 2\partial_\alpha (gP_2^{-1}(z^{\varepsilon,\delta,\mu})) \right] \right) \\ & - \frac{2|\partial_\alpha z^{\varepsilon,\delta,\mu}(\alpha, t)|}{Q^2(z^{\varepsilon,\delta,\mu})} \left(Q(z^{\varepsilon,\delta,\mu}) \partial_t Q(z^{\varepsilon,\delta,\mu}) \frac{\omega^{\varepsilon,\delta,\mu}}{|\partial_\alpha z^{\varepsilon,\delta,\mu}|} - \frac{Q^2(z^{\varepsilon,\delta,\mu}) \omega^{\varepsilon,\delta,\mu}}{2|\partial_\alpha z^{\varepsilon,\delta,\mu}|^3} \partial_\alpha z^{\varepsilon,\delta,\mu} \cdot \partial_\alpha \partial_t z^{\varepsilon,\delta,\mu} \right) \\ & + \frac{2|\partial_\alpha z^{\varepsilon,\delta,\mu}(\alpha, t)|}{Q^2(z^{\varepsilon,\delta,\mu})} \phi_\delta * \phi_\delta * \left(Q(z^{\varepsilon,\delta,\mu}) \partial_t Q(z^{\varepsilon,\delta,\mu}) \frac{\omega^{\varepsilon,\delta,\mu}}{|\partial_\alpha z^{\varepsilon,\delta,\mu}|} - \frac{Q^2(z^{\varepsilon,\delta,\mu}) \omega^{\varepsilon,\delta,\mu}}{2|\partial_\alpha z^{\varepsilon,\delta,\mu}|^3} \partial_\alpha z^{\varepsilon,\delta,\mu} \cdot \partial_\alpha \partial_t z^{\varepsilon,\delta,\mu} \right) \\ & - 2\varepsilon \frac{|\partial_\alpha z^{\varepsilon,\delta,\mu}|}{Q^2(z^{\varepsilon,\delta,\mu})} \Lambda(\phi_\mu * \phi_\mu * \varphi^{\varepsilon,\delta,\mu}), \end{aligned} \quad (\text{IV.59})$$

$z^{\varepsilon,\delta,\mu}(\alpha, 0) = z_0(\alpha)$ and $\omega^{\varepsilon,\delta,\mu}(\alpha, 0) = \omega_0(\alpha)$ for $\varepsilon > 0, \delta > 0, \mu > 0$, ϕ_δ and ϕ_μ even mollifiers, and

$$\begin{aligned} c^{\varepsilon,\delta,\mu}(\alpha) = & \frac{\alpha + \pi}{2\pi} \int_{-\pi}^{\pi} \frac{\partial_\beta z^{\varepsilon,\delta,\mu}(\beta)}{|\partial_\beta z^{\varepsilon,\delta,\mu}(\beta)|^2} \cdot \phi_\delta * \phi_\delta * (\partial_\beta (Q^2(z^{\varepsilon,\delta,\mu})(\beta) BR(z^{\varepsilon,\delta,\mu}, \omega^{\varepsilon,\delta,\mu}))(\beta)) d\beta \\ & - \int_{-\pi}^{\alpha} \frac{\partial_\beta z^{\varepsilon,\delta,\mu}(\beta)}{|\partial_\beta z^{\varepsilon,\delta,\mu}(\beta)|^2} \cdot \phi_\delta * \phi_\delta * (\partial_\beta (Q^2(z^{\varepsilon,\delta,\mu})(\beta) BR(z^{\varepsilon,\delta,\mu}, \omega^{\varepsilon,\delta,\mu}))(\beta)) d\beta, \\ \varphi^{\varepsilon,\delta,\mu} = & \frac{Q^2(z^{\varepsilon,\delta,\mu}) \omega^{\varepsilon,\delta,\mu}}{2|\partial_\alpha z^{\varepsilon,\delta,\mu}|} - c^{\varepsilon,\delta,\mu}, \end{aligned}$$

$$B^{\varepsilon,\delta,\mu}(t) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{\partial_\alpha z^{\varepsilon,\delta,\mu}(\alpha, t)}{|\partial_\alpha z^{\varepsilon,\delta,\mu}(\alpha, t)|^2} \cdot \partial_\alpha (Q^2(z^{\varepsilon,\delta,\mu}) BR(z^{\varepsilon,\delta,\mu}, \omega^{\varepsilon,\delta,\mu}))(\alpha, t) d\alpha,$$

$$\begin{aligned} c^{\varepsilon,\delta,\mu} = & \phi_\delta * \phi_\delta * \left(\frac{\alpha + \pi}{2\pi} \int_{-\pi}^{\pi} \frac{\partial_\beta z^{\varepsilon,\delta,\mu}(\beta)}{|\partial_\beta z^{\varepsilon,\delta,\mu}(\beta)|} \cdot (\partial_\beta (Q^2(z^{\varepsilon,\delta,\mu}) BR(z^{\varepsilon,\delta,\mu}, \omega^{\varepsilon,\delta,\mu}))(\beta)) d\beta \right) \\ & - \phi_\delta * \phi_\delta * \left(\int_{-\pi}^{\alpha} \frac{\partial_\beta z^{\varepsilon,\delta,\mu}(\beta)}{|\partial_\beta z^{\varepsilon,\delta,\mu}(\beta)|} \cdot (\partial_\beta (Q^2(z^{\varepsilon,\delta,\mu}) BR(z^{\varepsilon,\delta,\mu}, \omega^{\varepsilon,\delta,\mu}))(\beta)) d\beta \right). \end{aligned}$$

We start proving the following lemma:

Lemma IV.17 *Let $z^{\varepsilon,\delta,\mu}(\alpha, t) \in H^4(\mathbb{T})$, $\omega^{\varepsilon,\delta,\mu}(\alpha, t) \in H^2(\mathbb{T})$, $\varphi^{\varepsilon,\delta,\mu}(\alpha, t) \in H^3(\mathbb{T})$. Then $\omega^{\varepsilon,\delta,\mu}(\alpha, t) \in H^3(\mathbb{T})$.*

Proof: We can write $\omega^{\varepsilon,\delta,\mu}$ as:

$$\omega^{\varepsilon,\delta,\mu} = \frac{2|\partial_\alpha z^{\varepsilon,\delta,\mu}|}{Q^2(z^{\varepsilon,\delta,\mu})} \left(\varphi^{\varepsilon,\delta,\mu} + \mathcal{C}^{\varepsilon,\delta,\mu} \right).$$

Taking three derivatives yields

$$\begin{aligned} \partial_\alpha^3 \omega^{\varepsilon,\delta,\mu} &= \text{SAFE} + \frac{2|\partial_\alpha z^{\varepsilon,\delta,\mu}|}{Q^2(z^{\varepsilon,\delta,\mu})} \partial_\alpha^3 \mathcal{C}^{\varepsilon,\delta,\mu} \\ &= \text{SAFE} - \frac{2|\partial_\alpha z^{\varepsilon,\delta,\mu}|}{Q^2(z^{\varepsilon,\delta,\mu})} \phi_\delta * \phi_\delta * \partial_\alpha^2 \left(\frac{\partial_\alpha z^{\varepsilon,\delta,\mu}}{|\partial_\alpha z^{\varepsilon,\delta,\mu}|} \cdot (\partial_\alpha(Q^2(z^{\varepsilon,\delta,\mu})BR(z^{\varepsilon,\delta,\mu}, \omega^{\varepsilon,\delta,\mu}))) \right) \\ &= \text{SAFE} - \frac{2|\partial_\alpha z^{\varepsilon,\delta,\mu}|}{Q^2(z^{\varepsilon,\delta,\mu})} \phi_\delta * \phi_\delta * \left(\frac{\partial_\alpha z^{\varepsilon,\delta,\mu}}{|\partial_\alpha z^{\varepsilon,\delta,\mu}|} \cdot (Q^2(z^{\varepsilon,\delta,\mu})\partial_\alpha^3 BR(z^{\varepsilon,\delta,\mu}, \omega^{\varepsilon,\delta,\mu})) \right) \\ &= \text{SAFE} - \frac{2|\partial_\alpha z^{\varepsilon,\delta,\mu}|}{Q^2(z^{\varepsilon,\delta,\mu})} \phi_\delta * \phi_\delta * \left(\frac{\partial_\alpha z^{\varepsilon,\delta,\mu}}{|\partial_\alpha z^{\varepsilon,\delta,\mu}|} \cdot (Q^2(z^{\varepsilon,\delta,\mu})BR(z^{\varepsilon,\delta,\mu}, \partial_\alpha^3 \omega^{\varepsilon,\delta,\mu})) \right) \end{aligned}$$

where SAFE means bounded in L^2 . Using the representation

$$BR(z^{\varepsilon,\delta,\mu}, \partial_\alpha^3 \omega^{\varepsilon,\delta,\mu}) = \text{SAFE} + \frac{1}{2} \frac{(\partial_\alpha z^{\varepsilon,\delta,\mu})^\perp}{|\partial_\alpha z^{\varepsilon,\delta,\mu}|^2} H(\partial_\alpha^3 \omega^{\varepsilon,\delta,\mu})$$

we get that

$$\partial_\alpha^3 \omega^{\varepsilon,\delta,\mu} = \text{SAFE} - \frac{2|\partial_\alpha z^{\varepsilon,\delta,\mu}|}{Q^2(z^{\varepsilon,\delta,\mu})} \phi_\delta * \phi_\delta * \underbrace{\left(Q^2(z^{\varepsilon,\delta,\mu}) \frac{1}{2} \frac{(\partial_\alpha z^{\varepsilon,\delta,\mu})^\perp}{|\partial_\alpha z^{\varepsilon,\delta,\mu}|^2} H(\partial_\alpha^3 \omega^{\varepsilon,\delta,\mu}) \cdot \frac{\partial_\alpha z^{\varepsilon,\delta,\mu}}{|\partial_\alpha z^{\varepsilon,\delta,\mu}|} \right)}_{=0}$$

and we are done. We should remark that the lemma holds independently of δ , μ and ε . \square

We define a distance between data (z, ω) and $(\underline{z}, \underline{\omega})$ by taking

$$d((z, \omega), (\underline{z}, \underline{\omega})) = \|z - \underline{z}\|_{H^4} + \|\omega - \underline{\omega}\|_{H^2} + \|\varphi - \underline{\varphi}\|_{H^3}$$

where φ and $\underline{\varphi}$ arise from (z, ω) and $(\underline{z}, \underline{\omega})$ respectively by (IV.18). Let XX denote the resulting metric space. The proof of Lemma IV.17 gives also the following

Corollary IV.18 *The map $(z, \omega) \mapsto \omega$ is Lipschitz from any ball in XX into $H^3(\mathbb{T})$.*

We note that throughout this section we will repeatedly use the following commutator estimate for convolutions:

$$\|\phi_\delta * (\partial_\alpha f g) - g \phi_\delta * (\partial_\alpha f)\|_{L^2} \leq C \|\partial_\alpha g\|_{L^\infty} \|f\|_{L^2}, \quad (\text{IV.60})$$

where the constant C is independent of δ, f and g . We can now operate to get the following expression for $\varphi^{\varepsilon, \delta, \mu}$:

$$\begin{aligned}
\partial_t \varphi^{\varepsilon, \delta, \mu} &= \frac{Q(z^{\varepsilon, \delta, \mu}) \partial_t Q(z^{\varepsilon, \delta, \mu}) \omega^{\varepsilon, \delta, \mu}}{|\partial_\alpha z^{\varepsilon, \delta, \mu}|} - \frac{Q^2(z^{\varepsilon, \delta, \mu}) \omega^{\varepsilon, \delta, \mu}}{2|\partial_\alpha z^{\varepsilon, \delta, \mu}|^3} \partial_\alpha z^{\varepsilon, \delta, \mu} \cdot \partial_t \partial_\alpha z^{\varepsilon, \delta, \mu} + \frac{Q^2(z^{\varepsilon, \delta, \mu}) \partial_t \omega^{\varepsilon, \delta, \mu}}{2|\partial_\alpha z^{\varepsilon, \delta, \mu}|} - \partial_t \mathcal{C}^{\varepsilon, \delta, \mu} \\
&= \phi_\delta * \phi_\delta * \left(\frac{Q^2(z^{\varepsilon, \delta, \mu})}{2|\partial_\alpha z^{\varepsilon, \delta, \mu}(\alpha, t)|} \left[-2BR(z^{\varepsilon, \delta, \mu}, \omega^{\varepsilon, \delta, \mu})_t \cdot z_\alpha^{\varepsilon, \delta, \mu} \right. \right. \\
&\quad - 2Q(z^{\varepsilon, \delta, \mu}) Q(z^{\varepsilon, \delta, \mu})_\alpha |BR(z^{\varepsilon, \delta, \mu}, \omega^{\varepsilon, \delta, \mu})|^2 - \partial_\alpha \left(\frac{(\varphi^{\varepsilon, \delta, \mu})^2}{Q(z^{\varepsilon, \delta, \mu})^2} \right) \\
&\quad + \frac{c^{\varepsilon, \delta, \mu} |z_\alpha^{\varepsilon, \delta, \mu}|^2}{\pi Q(z^{\varepsilon, \delta, \mu})^2} \int_{-\pi}^{\pi} (Q(z^{\varepsilon, \delta, \mu})^2 BR(z^{\varepsilon, \delta, \mu}, \omega^{\varepsilon, \delta, \mu}))_\beta \cdot \frac{z_\beta^{\varepsilon, \delta, \mu}}{|z_\beta^{\varepsilon, \delta, \mu}|^2} d\beta \\
&\quad - \frac{4c^{\varepsilon, \delta, \mu} Q(z^{\varepsilon, \delta, \mu})_\alpha BR(z^{\varepsilon, \delta, \mu}, \omega^{\varepsilon, \delta, \mu}) \cdot z_\alpha^{\varepsilon, \delta, \mu}}{Q(z^{\varepsilon, \delta, \mu})} \\
&\quad \left. \left. - \frac{2(c^{\varepsilon, \delta, \mu})^2 |z_\alpha^{\varepsilon, \delta, \mu}|^2 Q(z^{\varepsilon, \delta, \mu})_\alpha}{Q(z^{\varepsilon, \delta, \mu})^3} - 2\partial_\alpha \left(gP_2^{-1}(z^{\varepsilon, \delta, \mu}) \right) \right] \right) \\
&\quad + \phi_\delta * \phi_\delta * \left(Q(z^{\varepsilon, \delta, \mu}) \partial_t Q(z^{\varepsilon, \delta, \mu}) \frac{\omega^{\varepsilon, \delta, \mu}}{|\partial_\alpha z^{\varepsilon, \delta, \mu}|} - \frac{Q^2(z^{\varepsilon, \delta, \mu}) \omega^{\varepsilon, \delta, \mu}}{2|\partial_\alpha z^{\varepsilon, \delta, \mu}|^3} \partial_\alpha z^{\varepsilon, \delta, \mu} \cdot \partial_\alpha \partial_t z^{\varepsilon, \delta, \mu} \right) \\
&\quad - \varepsilon \Lambda (\phi_\mu * \phi_\mu * \varphi^{\varepsilon, \delta, \mu}) - \partial_t \mathcal{C}^{\varepsilon, \delta, \mu}.
\end{aligned}$$

The RHS of the evolution equations for $z^{\varepsilon, \delta, \mu}$ and $\varphi^{\varepsilon, \delta, \mu}$ are Lipschitz in the spaces $H^4(\mathbb{T})$ and $H^{3+\frac{1}{2}}(\mathbb{T})$ since they are mollified. For the case of $\omega^{\varepsilon, \delta, \mu}$ (Lipschitz in the space $H^2(\mathbb{T})$) we use that for δ small enough $\phi_\delta * \phi_\delta$ is close to the identity and the a priori bounds. In all of the cases we have taken advantage of Lemma IV.17. Therefore we can solve (IV.58-IV.59) for short time, thanks to Picard's theorem.

Now, we can perform energy estimates as in the a priori case to get uniform bounds in μ and we can let μ go to zero. The energy estimates that we can get are the following:

$$\begin{aligned}
&\frac{d}{dt} \left(\|z^{\varepsilon, \delta, \mu}\|_{H^4}^2 + \|\mathcal{F}(z^{\varepsilon, \delta, \mu})\|_{L^\infty}^2 + \|\omega^{\varepsilon, \delta, \mu}\|_{H^2}^2 + \|\varphi^{\varepsilon, \delta, \mu}\|_{H^{3+\frac{1}{2}}}^2 + \sum_{l=0}^4 \frac{1}{m^{\varepsilon, \delta, \mu}(q^l)} \right) (t) \\
&\leq C(\varepsilon, \delta) \left(\|z^{\varepsilon, \delta, \mu}\|_{H^4}^2 + \|\mathcal{F}(z^{\varepsilon, \delta, \mu})\|_{L^\infty}^2 + \|\omega^{\varepsilon, \delta, \mu}\|_{H^2}^2 + \|\varphi^{\varepsilon, \delta, \mu}\|_{H^{3+\frac{1}{2}}}^2 + \sum_{l=0}^4 \frac{1}{m^{\varepsilon, \delta, \mu}(q^l)} \right)^j (t).
\end{aligned}$$

We should note that for the new system without the ϕ_μ mollifier, the length of the tangent vector $|\partial_\alpha z^{\varepsilon, \delta}|$ is now constant in space and depends only on time. Lemma IV.17 still applies and we can still perform energy estimates as in the a priori case. The only difference relies on the fact that we should have to move the mollifiers and apply the estimate (IV.60). We should also remark that because of the dissipative term $\varepsilon \Lambda \varphi^{\varepsilon, \delta}$ it is enough to use the following estimate

$$\frac{1}{2} \frac{d}{dt} \|\Lambda^{1/2}(\partial_\alpha^3 \varphi^{\varepsilon, \delta})\|_{L^2}^2 = \int \Lambda(\partial_\alpha^3 \varphi^{\varepsilon, \delta}) \partial_t \partial_\alpha^3 \varphi^{\varepsilon, \delta} d\alpha \leq \frac{\varepsilon}{64} \|\Lambda(\partial_\alpha^3 \varphi^{\varepsilon, \delta})\|_{L^2}^2 + C(\varepsilon) \|\partial_t \partial_\alpha^3 \varphi^{\varepsilon, \delta}\|_{L^2}^2$$

and hence require only that $\partial_t \varphi^{\varepsilon, \delta} \in H^3(\mathbb{T})$ (instead of the $H^{3+\frac{1}{2}}(\mathbb{T})$ that was required before) except for the transport term that can be estimated as in subsection IV.D.12. The estimations are performed following exactly the same steps of subsection IV.D. More precisely, we can get the following energy estimates:

$$\begin{aligned} & \frac{d}{dt} \left(\|z^{\varepsilon, \delta}\|_{H^4}^2 + \|\mathcal{F}(z^{\varepsilon, \delta})\|_{L^\infty}^2 + \|\omega^{\varepsilon, \delta}\|_{H^2}^2 + \|\varphi^{\varepsilon, \delta}\|_{H^{3+\frac{1}{2}}}^2 + \sum_{l=0}^4 \frac{1}{m^{\varepsilon, \delta}(q^l)} \right) (t) \\ & \leq C(\varepsilon) \left(\|z^{\varepsilon, \delta}\|_{H^4}^2 + \|\mathcal{F}(z^{\varepsilon, \delta})\|_{L^\infty}^2 + \|\omega^{\varepsilon, \delta}\|_{H^2}^2 + \|\varphi^{\varepsilon, \delta}\|_{H^{3+\frac{1}{2}}}^2 + \sum_{l=0}^4 \frac{1}{m^{\varepsilon, \delta}(q^l)} \right)^j (t). \end{aligned}$$

Under these conditions, we can let δ go to zero.

Finally, let $z^\varepsilon(\alpha, t)$ be a solution of the following system (compare with (IV.20)):

$$z_t^\varepsilon(\alpha, t) = Q^2(z^\varepsilon)(\alpha, t) BR(z^\varepsilon, \omega^\varepsilon)(\alpha, t) + c^\varepsilon(\alpha, t) \partial_\alpha z^\varepsilon(\alpha, t), \quad (\text{IV.61})$$

$$\begin{aligned} \omega_t^\varepsilon &= -2BR(z^\varepsilon, \omega^\varepsilon)_t \cdot z_\alpha^\varepsilon - 2Q(z^\varepsilon)Q(z^\varepsilon)_\alpha |BR(z^\varepsilon, \omega^\varepsilon)|^2 - \partial_\alpha \left(\frac{(\varphi^\varepsilon)^2}{Q(z^\varepsilon)^2} \right) \\ &+ \frac{c^\varepsilon |z_\alpha^\varepsilon|^2}{\pi Q(z^\varepsilon)^2} \int_{-\pi}^{\pi} (Q(z^\varepsilon)^2 BR(z^\varepsilon, \omega^\varepsilon))_\beta \cdot \frac{z_\beta^\varepsilon}{|z_\beta^\varepsilon|^2} d\beta - \frac{4c^\varepsilon Q(z^\varepsilon)_\alpha BR(z^\varepsilon, \omega^\varepsilon) \cdot z_\alpha^\varepsilon}{Q(z^\varepsilon)} \\ &- \frac{2(c^\varepsilon)^2 |z_\alpha^\varepsilon|^2 Q(z^\varepsilon)_\alpha}{Q(z^\varepsilon)^3} - 2\partial_\alpha (gP_2^{-1}(z^\varepsilon)) - 2\varepsilon \frac{|\partial_\alpha z^\varepsilon|}{Q^2(z^\varepsilon)} \Lambda \varphi^\varepsilon, \end{aligned} \quad (\text{IV.62})$$

$z^\varepsilon(\alpha, 0) = z_0(\alpha)$ and $\omega^\varepsilon(\alpha, 0) = \omega_0(\alpha)$ for $\varepsilon > 0$, where

$$\begin{aligned} c^\varepsilon(\alpha) &= \frac{\alpha + \pi}{2\pi} \int_{-\pi}^{\pi} \frac{\partial_\beta z^\varepsilon(\beta)}{|\partial_\beta z^\varepsilon(\beta)|^2} \cdot \partial_\beta (Q^2(z^\varepsilon)(\beta) BR(z^\varepsilon, \omega^\varepsilon)(\beta)) d\beta \\ &- \int_{-\pi}^{\alpha} \frac{\partial_\beta z^\varepsilon(\beta)}{|\partial_\beta z^\varepsilon(\beta)|^2} \cdot \partial_\beta (Q^2(z^\varepsilon)(\beta) BR(z^\varepsilon, \omega^\varepsilon)(\beta)) d\beta, \end{aligned}$$

$$\varphi^\varepsilon = \frac{Q^2(z^\varepsilon)\omega^\varepsilon}{2|\partial_\alpha z^\varepsilon|} - |\partial_\alpha z^\varepsilon| c^\varepsilon, \quad B^\varepsilon(t) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{\partial_\alpha z^\varepsilon(\alpha, t)}{|\partial_\alpha z^\varepsilon(\alpha, t)|^2} \cdot \partial_\alpha (Q^2(z^\varepsilon) BR(z^\varepsilon, \omega^\varepsilon))(\alpha, t) d\alpha.$$

Proceeding as in section IV.C (compare with equation (IV.43)) we find

$$\begin{aligned}
\partial_\alpha \varphi_t^\varepsilon &= -B^\varepsilon(t) \varphi_\alpha^\varepsilon - \frac{\partial_\alpha^2((\varphi^\varepsilon)^2)}{2|\partial_\alpha z^\varepsilon|} + \partial_\alpha \left(\frac{\partial_\alpha Q(z^\varepsilon)}{|\partial_\alpha z^\varepsilon| Q(z^\varepsilon)} (\varphi^\varepsilon)^2 \right) \\
&\quad - Q(z^\varepsilon)^2 \partial_t BR(z^\varepsilon, \omega^\varepsilon) \cdot \partial_\alpha^\perp z^\varepsilon \frac{\partial_\alpha^2 z^\varepsilon \cdot \partial_\alpha^\perp z^\varepsilon}{|\partial_\alpha z^\varepsilon|^3} - \partial_t (|\partial_\alpha z^\varepsilon| B^\varepsilon(t)) \\
&\quad + \partial_\alpha (Q(z^\varepsilon)^2 BR(z^\varepsilon, \omega^\varepsilon)) \cdot \partial_\alpha^\perp z^\varepsilon \frac{\partial_t \partial_\alpha z^\varepsilon \cdot \partial_\alpha^\perp z^\varepsilon}{|\partial_\alpha z^\varepsilon|^3} + 2\partial_\alpha (Q(z^\varepsilon) \partial_t Q(z^\varepsilon) BR(z^\varepsilon, \omega^\varepsilon)) \cdot \frac{\partial_\alpha z^\varepsilon}{|\partial_\alpha z^\varepsilon|} \\
&\quad - \partial_\alpha \left(Q(z^\varepsilon)^2 \frac{\partial_\alpha (gP_2^{-1}(z^\varepsilon))}{|\partial_\alpha z^\varepsilon|} \right) + \partial_\alpha \left(Q(z^\varepsilon) \partial_t Q(z^\varepsilon) \frac{\omega^\varepsilon}{|\partial_\alpha z^\varepsilon|} \right) \\
&\quad - \partial_\alpha \left(2c^\varepsilon BR(z^\varepsilon, \omega^\varepsilon) \cdot \frac{\partial_\alpha z^\varepsilon}{|\partial_\alpha z^\varepsilon|} Q(z^\varepsilon) \partial_\alpha Q(z^\varepsilon) \right) - \partial_\alpha \left(\frac{\partial_\alpha Q(z^\varepsilon)}{Q(z^\varepsilon)} (c^\varepsilon)^2 |\partial_\alpha z^\varepsilon| \right) \\
&\quad - \partial_\alpha \left(\frac{Q(z^\varepsilon)^3}{|\partial_\alpha z^\varepsilon|} |BR(z^\varepsilon, \omega^\varepsilon)|^2 \partial_\alpha Q(z^\varepsilon) \right) - \varepsilon \Lambda \partial_\alpha \varphi^\varepsilon.
\end{aligned} \tag{IV.63}$$

We also define (compare with equation (IV.2))

$$\begin{aligned}
\sigma^\varepsilon &= (\partial_t BR(z^\varepsilon, \omega^\varepsilon) + \frac{\varphi^\varepsilon}{|\partial_\alpha z^\varepsilon|} \partial_\alpha BR(z^\varepsilon, \omega^\varepsilon)) \cdot \partial_\alpha^\perp z^\varepsilon + \frac{1}{2} \frac{\omega^\varepsilon}{|\partial_\alpha z^\varepsilon|^2} (\partial_\alpha z_t^\varepsilon + \frac{\varphi^\varepsilon}{|\partial_\alpha z^\varepsilon|} \partial_\alpha^2 z^\varepsilon) \cdot \partial_\alpha^\perp z^\varepsilon \\
&\quad + Q(z^\varepsilon) \left| BR(z^\varepsilon, \omega^\varepsilon) + \frac{\omega^\varepsilon}{2|\partial_\alpha z^\varepsilon|^2} \partial_\alpha z^\varepsilon \right|^2 (\nabla Q(z^\varepsilon)) \cdot \partial_\alpha^\perp z^\varepsilon + g(\nabla P_2^{-1}(z^\varepsilon)) \cdot \partial_\alpha^\perp z^\varepsilon.
\end{aligned}$$

Remark IV.19 *The system (IV.61-IV.62) is analogous to the system considered in [13, Section 8]. We point out an unfortunate typographical error in that section; the Laplacian should have been written as the square root of the Laplacian.*

For this ε -system (IV.61-IV.62) we now know that there is local-existence for initial data satisfying $\mathcal{F}(z_0)(\alpha, \beta) < \infty$ even if $\sigma^\varepsilon(\alpha, 0)$ does not have the proper sign. In the following we shall show briefly how to obtain a solution of the regularized system with $z^\varepsilon \in C([0, T^\varepsilon], H^k)$, $\varphi^\varepsilon \in C([0, T^\varepsilon], H^{k-\frac{1}{2}})$, $\omega^\varepsilon \in C([0, T^\varepsilon], H^{k-2})$ for $k \geq 4$.

The next step is to integrate the system during a time T independent of ε . We will show that for this system we have

$$\frac{d}{dt} E(t) \leq CE^p(t), \tag{IV.64}$$

where $E(t)$ is given by the analogous formula (IV.23) for the ε -system, and C and p are constants independent of ε .

In the following we shall see what is the impact of the ε system on the a priori estimates and check that there is no practical impact for sufficiently small ε . To do that, we will show the corresponding uniform estimates for $k = 4$ and leave to the reader the remaining easier cases. Let us consider the one corresponding to I_3 in section IV.D.12, we have

$$I_3^\varepsilon = -2 \int_{-\pi}^{\pi} \frac{1}{|\partial_\alpha z^\varepsilon|^3} \Lambda(\partial_\alpha^3 \varphi^\varepsilon(\alpha)) \partial_\alpha^2 (Q^2(z^\varepsilon) \sigma^\varepsilon \partial_\alpha^2 z^\varepsilon \cdot \partial_\alpha^\perp z^\varepsilon) d\alpha.$$

Proceeding in the same way as before, we can perform the same splittings and get uniform bounds such that $I_3^\varepsilon = -S^\varepsilon + M_4^\varepsilon + \text{“bounded terms”}$ where S^ε corresponds to S in (IV.35),

$$|\text{“bounded terms”}| \leq CE^p(t),$$

and

$$M_4^\varepsilon = -2\varepsilon \int_{-\pi}^{\pi} \frac{\partial_\alpha^2 z^\varepsilon \cdot \partial_\alpha^\perp z^\varepsilon}{|\partial_\alpha z^\varepsilon|^2} H(\partial_\alpha^3 \varphi^\varepsilon) H(\Lambda \partial_\alpha^3 \varphi^\varepsilon) d\alpha.$$

Then we can write M_4^ε as follows

$$M_4^\varepsilon = -2\varepsilon \int_{-\pi}^{\pi} \Lambda^{\frac{1}{2}} \left(\frac{\partial_\alpha^2 z^\varepsilon \cdot \partial_\alpha^\perp z^\varepsilon}{|\partial_\alpha z^\varepsilon|^2} H(\partial_\alpha^3 \varphi^\varepsilon) \right) \Lambda^{\frac{1}{2}} (H \partial_\alpha^3 \varphi^\varepsilon) d\alpha,$$

and therefore, for small ε

$$M_4^\varepsilon \leq \|\Lambda^{\frac{1}{2}} \partial_\alpha^3 \varphi^\varepsilon\|_{L^2}^2 + \text{“bounded terms”},$$

which gives

$$\frac{d}{dt} E(t) \leq CE^p(t) - \frac{\varepsilon}{2} \|\Lambda(\partial_\alpha^3 \varphi)\|_{L^2}^2.$$

This finally shows (IV.64) and therefore

$$E(t) \leq (Ct(1-p) + E^{1-p}(0))^{1/(1-p)}.$$

Now we are in position to extend the time of existence T^ε so long as the above estimate works and obtain a time T dependent only on the initial data (arc-chord, Rayleigh-Taylor, distance to the points q^0, \dots, q^4 , and Sobolev norms of z, ω , and φ). We can let ε tend to 0, and get a solution of the original system. This concludes the proof.

Acknowledgements

AC, DC, FG and JGS were partially supported by the grant MTM2008-03754 of the MCINN (Spain) and the grant StG-203138CDSIF of the ERC. CF was partially supported by NSF grant DMS-0901040. FG was partially supported by NSF grant DMS-0901810. We are grateful to CCC of Universidad Aut3noma de Madrid for computing facilities.

References

- [1] T. Alazard, N. Burq, and C. Zuily. On the water-wave equations with surface tension. *Duke Math. J.*, 158(3):413–499, 2011.
- [2] T. Alazard and G. M3tivier. Paralinearization of the Dirichlet to Neumann operator, and regularity of three-dimensional water waves. *Comm. Partial Differential Equations*, 34(10-12):1632–1704, 2009.

- [3] B. Alvarez-Samaniego and D. Lannes. Large time existence for 3D water-waves and asymptotics. *Invent. Math.*, 171(3):485–541, 2008.
- [4] D. M. Ambrose and N. Masmoudi. The zero surface tension limit of two-dimensional water waves. *Comm. Pure Appl. Math.*, 58(10):1287–1315, 2005.
- [5] G. R. Baker, D. I. Meiron, and S. A. Orszag. Generalized vortex methods for free-surface flow problems. *J. Fluid Mech.*, 123:477–501, 1982.
- [6] J. T. Beale, T. Y. Hou, and J. Lowengrub. Convergence of a boundary integral method for water waves. *SIAM J. Numer. Anal.*, 33(5):1797–1843, 1996.
- [7] J. T. Beale, T. Y. Hou, and J. S. Lowengrub. Growth rates for the linearized motion of fluid interfaces away from equilibrium. *Comm. Pure Appl. Math.*, 46(9):1269–1301, 1993.
- [8] A. Castro, D. Córdoba, C. Fefferman, F. Gancedo, and J. Gómez-Serrano. Splash singularity for water waves. *Proceedings of the National Academy of Sciences*, 109(3):733–738, 2012.
- [9] A. Castro, D. Córdoba, C. Fefferman, F. Gancedo, and M. López-Fernández. Turning waves and breakdown for incompressible flows. *Proceedings of the National Academy of Sciences*, 108(12):4754–4759, 2011.
- [10] Á. Castro, D. Córdoba, C. Fefferman, F. Gancedo, and M. López-Fernández. Rayleigh-taylor breakdown for the muskat problem with applications to water waves. *Ann. of Math. (2)*, 175:909–948, 2012.
- [11] A. Castro, D. Córdoba, and F. Gancedo. A naive parametrization for the vortex-sheet problem. *Arxiv preprint arXiv:0810.0731*, 2010.
- [12] D. Christodoulou and H. Lindblad. On the motion of the free surface of a liquid. *Comm. Pure Appl. Math.*, 53(12):1536–1602, 2000.
- [13] A. Córdoba, D. Córdoba, and F. Gancedo. Interface evolution: water waves in 2-D. *Adv. Math.*, 223(1):120–173, 2010.
- [14] A. Córdoba, D. Córdoba, and F. Gancedo. Interface evolution: the Hele-Shaw and Muskat problems. *Ann. of Math. (2)*, 173(1):477–542, 2011.
- [15] A. Córdoba, D. Córdoba, and F. Gancedo. Porous media: the Muskat problem in 3d. *Analysis & PDE*, 2012. To appear.
- [16] D. Coutand and S. Shkoller. Well-posedness of the free-surface incompressible Euler equations with or without surface tension. *J. Amer. Math. Soc.*, 20(3):829–930, 2007.
- [17] D. Coutand and S. Shkoller. On the finite-time splash singularity for the 3-D free-surface Euler equations. *Arxiv preprint arXiv:1201.4919*, 2012.

- [18] W. Craig. An existence theory for water waves and the Boussinesq and Korteweg-de Vries scaling limits. *Comm. Partial Differential Equations*, 10(8):787–1003, 1985.
- [19] P. Germain, N. Masmoudi, and J. Shatah. Global solutions for the gravity water waves equation in dimension 3. *C. R. Math. Acad. Sci. Paris*, 347(15-16):897–902, 2009.
- [20] P. Germain, N. Masmoudi, and J. Shatah. Global solutions for the gravity water waves equation in dimension 3. *Ann. of Math. (2)*, 175:691–754, 2012.
- [21] D. Lannes. Well-posedness of the water-waves equations. *J. Amer. Math. Soc.*, 18(3):605–654, 2005.
- [22] D. Lannes. A stability criterion for two-fluid interfaces and applications. *Arxiv preprint arXiv:1005.4565*, 2010.
- [23] H. Lindblad. Well-posedness for the motion of an incompressible liquid with free surface boundary. *Ann. of Math. (2)*, 162(1):109–194, 2005.
- [24] R. Moore and F. Bierbaum. *Methods and applications of interval analysis*, volume 2. Society for Industrial & Applied Mathematics, 1979.
- [25] V. I. Nalimov. The Cauchy-Poisson problem. *Dinamika Splošn. Sredy*, (Vyp. 18 Dinamika Zidkost. so Svobod. Granicami):104–210, 1974.
- [26] L. Nirenberg. An abstract form of the nonlinear Cauchy-Kowalewski theorem. *J. Differential Geometry*, 6:561–576, 1972. Collection of articles dedicated to S. S. Chern and D. C. Spencer on their sixtieth birthdays.
- [27] T. Nishida. A note on a theorem of Nirenberg. *J. Differential Geom.*, 12(4):629–633, 1977.
- [28] J. Shatah and C. Zeng. Geometry and a priori estimates for free boundary problems of the Euler equation. *Comm. Pure Appl. Math.*, 61(5):698–744, 2008.
- [29] C. Sulem and P.-L. Sulem. Finite time analyticity for the two- and three-dimensional Rayleigh-Taylor instability. *Trans. Amer. Math. Soc.*, 287(1):127–160, 1985.
- [30] S. Wu. Well-posedness in Sobolev spaces of the full water wave problem in 2-D. *Invent. Math.*, 130(1):39–72, 1997.
- [31] S. Wu. Well-posedness in Sobolev spaces of the full water wave problem in 3-D. *J. Amer. Math. Soc.*, 12(2):445–495, 1999.
- [32] S. Wu. Almost global wellposedness of the 2-D full water wave problem. *Invent. Math.*, 177(1):45–135, 2009.
- [33] S. Wu. Global wellposedness of the 3-D full water wave problem. *Invent. Math.*, 184(1):125–220, 2011.

- [34] H. Yosihara. Gravity waves on the free surface of an incompressible perfect fluid of finite depth. *Publ. Res. Inst. Math. Sci.*, 18(1):49–96, 1982.
- [35] P. Zhang and Z. Zhang. On the free boundary problem of three-dimensional incompressible Euler equations. *Comm. Pure Appl. Math.*, 61(7):877–940, 2008.

Angel Castro

Département de Mathématiques et Applications
École Normale Supérieure
45, Rue d’Ulm, 75005 Paris
Email: castro@dma.ens.fr

Diego Córdoba

Instituto de Ciencias Matemáticas
Consejo Superior de Investigaciones Científicas
C/ Nicolás Cabrera, 13-15
Campus Cantoblanco UAM, 28049 Madrid
Email: dcg@icmat.es

Charles Fefferman

Department of Mathematics
Princeton University
1102 Fine Hall, Washington Rd,
Princeton, NJ 08544, USA
Email: cf@math.princeton.edu

Francisco Gancedo

Departamento de Análisis Matemático
Universidad de Sevilla
C/ Tarfia, s/n
Campus Reina Mercedes, 41012 Sevilla
Email: fgancedo@us.es

Javier Gómez-Serrano

Instituto de Ciencias Matemáticas
Consejo Superior de Investigaciones Científicas
C/ Nicolás Cabrera, 13-15
Campus Cantoblanco UAM, 28049 Madrid
Email: javier.gomez@icmat.es