# Non-Linear Stochastic Partial Differential Equations with delays: Existence and uniqueness of solutions 

Tomás Caraballo Garrido<br>Dpto. de Análisis Matemático. Facultad de Matemáticas (Universidad de Sevilla).

Apartado de correos 1.160. 41080-Sevilla
Clasificación A.M.S.: 60H, 35K.

## 1. Introduction

The main aim of this paper is to study stochastic PDE's with delay terms. In fact, we prove existence and uniqueness of solution (in Itô's sense) for a rather general type of stochastic PDEs with non linear monotone operators and with delays. We deal with the following stochastic parabolic equation:

$$
\left\{\begin{array}{l}
d x(t)+[A(t, x(t))+B(t, x(\tau(t)))+f(t)] d t=[C(t, x(\rho(t)))+g(t)] d w_{t}, \quad t>0  \tag{1}\\
x(0)=x_{0}
\end{array}\right.
$$

where $A(t,),. B(t,),. C(t,$.$) are families of operators in Hilbert spaces, non linear eventually, and$ satisfying a monotonicity condition; $w_{t}$ is a Hilbert valued Wiener process, and $\tau, \rho$ are delay functions.

When there are not delays $(\tau(t)=\rho(t)=0)$, the equation (1) has been studied: in the case $B=C=0$, for $A$ non linear, in Bensoussan [2] and Curtain [5], and for some type of non linear operators $A$, in Bensoussan-Temam [3] and Marcus [7]; in the case $C \neq 0, B=0$, for linear $A$ and $C$, in Balakrishann [1], for linear $A$ and non linear $C$ in Dawson [6], and for non linear monotone $A$ and Lipschitz continuous $C$ in Pardoux [8].

In the case with deviating arguments, Real [9] studies a rather general case when all of the operators are linear and there exists a term which is a non continuous martingale. However, we have not found in the literature the case we are going to analyze here.

We will adapt to our problem one of the most important method for solving non linear PDEs: the monotonicity method. Pardoux [8] also used an adaptation of that method for another type of non linear monotone equations: when $B=0$ and without delays.

## 2. Statement of the problem and the main results

The theory of stochastic integrals in Hilbert spaces is well developed (see [8], for example).
We consider the classical pair of real separable Hilbert spaces $V, H$ satisfying $V \hookrightarrow H$ (injection continuous and dense).

We will denote by $\|\|,.|$.$| and \|.\|_{*}$ the norms in $V, H$ and $V^{\prime}$ respectively; by $\langle.,$.$\rangle the$ duality product between $V^{\prime}, V$, and by (...) the scalar product in $H$.

Let us fix $T>0$ and, let $w_{t}$ be a Wiener process defined on the complete probability space $(\Omega, \mathcal{F}, P)$ and taking values in the separable Hilbert space $K$, with incremental covariance operator $W$. Let $\left(\mathcal{F}_{t}\right)_{t \geq 0}$ be the $\sigma$-algebra generated by $\left\{w_{s}, 0 \leq s \leq t\right\}$, then $w_{t}$ is a martingale relative to $\left(\mathcal{F}_{t}\right)_{t \geq 0}$.

As an abuse of notation, we also use $|$.$| for the norm in the linear continuous operator space$ $\mathcal{L}(K, H)$.

We denote by $I^{p}(0, T ; V)$, for $p>1$, the space of $V$-valued processes $(x(t))_{t \in[0, T]}$ (we will write $x(t)$ for short) measurable (from $[0, T] \times \Omega$ in $V$ ), and satisfying:
i) $x(t)$ is $\mathcal{F}_{t}$-measurable a.e. in $t$ (in the sequel, we will write a.e.t.)
ii) $E \int_{0}^{T}\left|x_{t}\right|^{p} d t<+\infty$.

For short, we shall write $L^{2}(\Omega ; C(-h, T ; H))$ instead of $L^{2}(\Omega, \mathcal{F}, d P ; C(-h, T ; H))$.
Let $A(t,):. V \rightarrow V^{\prime}$ be a family of non linear operators defined a.e.t., and let $p>1$. We make the following hypotheses:
(a.1) Coercivity: $\exists \alpha>0, \lambda \in R: \quad 2\langle A(t, x), x\rangle+\lambda|x|^{2} \geq \alpha\|x\|^{p}, \forall x \in V$, a.e.t.
(a.2) Monotonicity: $2\langle A(t, x)-A(t, y), x-y\rangle+\lambda|x-y|^{2} \geq 0, \forall x, y \in V$, a.e.t.
(a.3) Boundedness: $\quad \exists \beta>0:\|A(t, x)\|_{*} \leq \beta\|x\|^{p-1}, \forall x \in V$, a.e.t.
(a.4) Hemicontinuity: $\theta \in R \rightarrow\langle A(t, x+\theta y), z\rangle \in R$ is continuous $\forall x, y, z \in V$, a.e.t.
(a.5) Measurability: $\quad t \in(0, T) \rightarrow A(t, x) \in V^{\prime}$ is Lebesgue - measurable $\forall x \in V$, a.e.t.

Let $B(t,):. H \rightarrow H$ be a family of operators defined a.e.t., and satisfying:
(b.1) $\quad B(t, 0)=0$
(b.2) Lipschitz condition: $\exists k_{1}: \quad|B(t, x)-B(t, y)| \leq k_{1}|x-y|, \quad \forall x, y \in H$, a.e.t.
(b.3) Measurability: $\quad t \in(0, T) \rightarrow B(t, x) \in H$ is Lebesgue-measurable, $\forall x \in V$.

And let $C(t,):. H \rightarrow \mathcal{L}(K, H)$ be another family defined a.e.t. and verifying:
(c.1) $\quad C(t, 0)=0$
(c.2) Lipschitz condition: $\exists k_{2}: \quad|C(t, x)-C(t, y)| \leq k_{2}|x-y|, \quad \forall x, y \in H$, a.e.t.
(c.3) Measurability: $\quad t \in(0, T) \rightarrow C(t, x) \in \mathcal{L}(K, H)$ is Lebesgue-measurable $\forall x \in H$.

We also consider two measurable functions (of delay) $\rho, \tau:[0, T] \rightarrow[0, T]$, such that

$$
0 \leq \rho(t), \tau(t) \leq t, \quad \forall t \in[0, T]
$$

For $f, g$ we suppose that

$$
\begin{equation*}
f \in I^{2}(0, T ; H), g \in I^{2}(0, T ; \mathcal{L}(K, H)) \tag{f.g}
\end{equation*}
$$

And finally, we are given an initial value $x_{0} \in L^{2}\left(\Omega, \mathcal{F}_{0}, P ; H\right)$.
Now, we state the following problem:

$$
\left\{\begin{array}{l}
\text { To find a process } x \in I^{p}(0, T ; V) \cap L^{2}(\Omega ; C(0, T ; H)) \text { such that : }  \tag{PC}\\
\begin{array}{c}
x(t)+\int_{0}^{t}[A(s, x(s))+B(s, x(\tau(s)))+f(s)] d s \\
\quad=x_{0}+\int_{0}^{t}[C(s, x(\rho(s)))+g(s)] d w_{s}, \quad P-\text { a.s., } \forall t \in[0, T]
\end{array}
\end{array}\right.
$$

The main result we prove is the following theorem

## Theorem 1

Assume the precedent conditions. Then, there exists a unique solution of $(P C)$ in $I^{p}(0, T ; V) \cap L^{2}(\Omega ; C(0, T ; H))$.

Proof. (See [4]) Uniqueness follows from Ito's formula and Gronwall's inequality. For the existence, we consider the equations

$$
\begin{gather*}
x^{1}(t)+\int_{0}^{t}\left[A\left(s, x^{1}(s)\right)+\frac{\lambda}{2} x^{1}(s)\right] d s+\int_{0}^{t} f(s) d s=x_{0}+\int_{0}^{t} g(s) d w_{s}  \tag{*}\\
x^{n+1}(t)+\int_{0}^{t}\left[A\left(s, x^{n+1}(s)\right)+\frac{\lambda}{2} x^{n+1}(s)\right] d s+\int_{0}^{t} B\left(s, x^{n}(\tau(s))\right) d s+\int_{0}^{t} f(s) d s \\
=x_{0}+\int_{0}^{t} \frac{\lambda}{2} x^{n}(s) d s+\int_{0}^{t} C\left(s, x^{n}(\rho(s))\right) d w_{s}+\int_{0}^{t} g(s) d w_{s}, \quad \forall n=1,2,3, \ldots
\end{gather*}
$$

and we prove that there exists a sequence of solutions for $(*)-(* *), \quad\left\{x^{n}\right\}_{n \geq 1} \subset I^{p}(0, T ; V) \cap$ $L^{2}(\Omega ; C(0, T ; H))$.

Last, we prove that the sequence $\left\{x^{n}\right\}$ is convergent in $I^{p}(0, T ; V) \cap L^{2}(\Omega ; C(0, T ; H))$, and the limit process is the solution of $(P C)$.

Remark 1.- We observe that theorem 1 also holds when $V$ is a separable and reflexive Banach space with $V \hookrightarrow H$.
Remark 2.- We note that theorem 1 holds when $\rho, \tau$ take negative values.

## Theorem 2

Assume the hypotheses in theorem 1, but changing ( $\rho . \tau$ ) by the following:

$$
\exists h>0 \text { such that }-h \leq \tau(t), \rho(t) \leq t, \forall t \in[0, T],
$$

and let $\psi$ be a process such that $\psi \in I^{p}(-h, 0 ; V) \cap L^{2}(\Omega ; C(-h, 0 ; H)$ ) (where these spaces are defined in the obvious manner, setting $\left.\mathcal{F}_{t}=\mathcal{F}_{0}, \forall t \in[-h, 0]\right)$. Then, there exists a unique process $x \in I^{p}(-h, T ; V) \cap L^{2}(\Omega ; C(-h, T ; H))$ such that,
$(P C)^{\prime} \quad\left\{\begin{aligned} x(t) & +\int_{0}^{t}[A(s, x(s))+B(s, x(\tau(s)))+f(s)] d s \\ & =\psi(0)+\int_{0}^{t}[C(s, x(\rho(s)))+g(s)] d w_{s}, \quad P-\text { a.s., } \quad \forall t \in[0, T], \\ x(t) & =\psi(t), \quad t \in(-h, 0]\end{aligned}\right.$
Proof. See Caraballo [4] |
Remark 3.- Some examples are given in Caraballo [4] in order to justify the results.

## References

[1] A. Balakrishnan, Stochastic bilinear partial differential equations, U.S.-Italy Conference on Variable Structure Systems, Oregon (1974).
[2] A. Bensoussan, Filtrage optimal des systemes linéaires, Dunod.
[3] A. Bensoussan and R. Temam, Equations aux dérivées partielles stochastiques non linéaires, Israel J. Math., 11 (1972), 95-129.
[4] T. Caraballo, Existence and uniqueness of solutions for non-linear sxtochastic PDE's, to appear in Collectanea Mathematica.
[5] R. Curtain, Stochastic differential equations in Hilbert spaces, Ph. D. Thesis, Brown University (1969).
[6] D. Dawson, Stochastic evolution equation, Math. Biosc.,15 (1972)
[7] R. Marcus, Parabolic Ito equations, Trans. Am. Math. Soc., 198 (1974), 177-190.
[8] E. Pardoux, Équations aux Dérivées Partielles Stochastiques non Linéaires Monotones, Thesis, University of Paris XI (1975).
[9] J. Real, Stochastic Partial Differential Equations with Delays, Stochastics 8, 2 (1982-83), 81-102.

## To appear in Collectanea Mathematica

