# On the existence of positive periodic solutions for $n$-species Lotka-Volterra competitive systems with distributed delays and impulses 

Mimia Benhadri ${ }^{\text {a }}$, Tomás Caraballo ${ }^{\text {b }}$<br>${ }^{\text {a }}$ LAMAHIS Lab, Faculty of Sciences, Department of Mathematics, Univ Skikda, P.O. Box 26, Skikda 21000, Algeria.<br>emails: mbenhadri@yahoo.com<br>${ }^{\mathrm{b}}$ Departamento de Ecuaciones Difererenciales y Análisis Numérico, Universidad de Sevilla, c/ Tarfia s/n, 41012-Sevilla (Spain)<br>email: caraball@us.es


#### Abstract

In this paper, we investigate the existence of positive periodic solutions for an $n$-species Lotka-Volterra system with distributed delays and impulsive effect. In the process we use integrating factors and convert the given Lotka-Volterra differential equation into an equivalent integral equation. Then we construct appropriate mappings and use Krasnoselskii's fixed point theorem to show the existence of a positive periodic solution of this system. In particular, the results improve some previous ones in the literature. Finally, as an application, we exhibit an example to illustrate the effectiveness of our abstract results.


AMS Subject Classifications: 34K20, 34K13, 92B20
Keywords: Krasnoselskii's fixed point theorem; positive periodic solutions; Lotka-Volterra competition systems; Variable delays; impulses.

## 1 Introduction

It is well known that the theory of impulsive differential equations has become an important area of scientific activity. Many evolution processes are characterized by the fact that at certain moments of time they experience an abrupt change of state. These short term perturbations act instantaneously, that is in the form of impulses. Equations of this kind are found in almost every domain of applied sciences, numerous examples can be found in, e.g., $[2,3,18,19,27]$. For example, many biological phenomena involving fields such as economics,
mechanics, electronics, telecommunications, medicine and biology, etc. (see [19]). Thus, impulsive differential equations appear as a natural description of observed evolution phenomena of several real world problems. However, besides impulsive effects, time delay is present in many fields in our society. In recent years, non-autonomous delay differential equations have been used in the study of population ecology and infectious diseases, population dynamics. Indeed, a famous model for population dynamics is the Lotka-Volterra competition system. Due to its theoretical and practical significance, Lotka-Volterra systems have been extensively and intensively studied for the past few years (see, $[5,6,14,23,24,25,26,29,30])$. On the other hand, a very basic and important qualitative problem is the study of periodic solutions of delay differential equations with or without impulsive effects which has attracted the interest of many mathematicians (we refer the reader to $[1,7,10,12,15,16,17,20,21,22,28]$ ). For instance, in 2006, by using the method of Krasnoselskii's fixed point theorem, Tang and Zhou [25] investigated the existence of positive periodic solutions of the following system with deviating arguments:

$$
\begin{equation*}
x_{i}^{\prime}(t)=x_{i}(t)\left[r_{i}(t)-\sum_{j=1}^{n} a_{i j}(t) x_{j}\left(t-\tau_{i j}(t)\right)\right], i=1,2, \ldots, n \tag{1.1}
\end{equation*}
$$

By the same method as the one in [25], Zhang et al. investigated in [30] the existence and global attractivity of positive periodic solutions of 3 -species LotkaVolterra predator-prey systems with infinite delays as follows:

$$
\left\{\begin{array}{c}
x_{1}^{\prime}(t)=x_{1}(t)\left(r_{1}(t)-c_{11}(t) x_{1}(t)-c_{12}(t) \int_{-\infty}^{t} K_{12}(s-t) x_{2}(s) d s\right.  \tag{1.2}\\
\left.\quad+c_{13}(t) \int_{-\infty}^{t} K_{13}(s-t) x_{3}(s) d s\right) \\
x_{2}^{\prime}(t)=x_{2}(t)\left(r_{2}(t)-c_{21}(t) \int_{-\infty}^{t} K_{21}(s-t) x_{1}(s) d s-c_{22}(t) x_{2}(t)\right. \\
\left.\quad+c_{23}(t) \int_{-\infty}^{t} K_{23}(s-t) x_{3}(s) d s\right) \\
x_{3}^{\prime}(t)=x_{3}(t)\left(r_{3}(t)+c_{31}(t) \int_{-\infty}^{t} K_{31}(s-t) x_{1}(s) d s\right. \\
\\
\left.\quad+c_{32}(t) \int_{-\infty}^{t} K_{32}(s-t) x_{2}(s) d s-c_{33}(t) x_{3}(t)\right)
\end{array}\right.
$$

Very recently, Benhadri et al. improved in [1] the results of Zhang et al. [25] to the generalized nonimpulsive nonlinear Lotka-Volterra competition with deviating arguments of the form:

$$
\begin{align*}
x_{i}^{\prime}(t)= & x_{i}(t)\left\{r_{i}(t)-\sum_{j=1}^{n} a_{i j}(t) x_{j}(t)-\sum_{j=1}^{n} b_{i j}(t) f_{j}\left(x_{j}(t)\right)\right. \\
& \left.-\sum_{j=1}^{n} c_{i j}(t) g_{j}\left(x_{j}\left(t-\tau_{i j}(t)\right)\right)\right\}  \tag{1.3}\\
& i=1,2, \ldots, n .
\end{align*}
$$

The authors derived some sufficient conditions for the existence of positive periodic solutions of (1.3).

In this paper, motivated by the content in [1] and [25], we generalize system (1.1) to a model with variable and distributed delays and impulses,

$$
\begin{align*}
& x_{i}^{\prime}(t)=x_{i}(t)\left\{r_{i}(t)-\sum_{j=1}^{n} a_{i j}(t) h_{j}\left(x_{j}(t)\right)-\sum_{j=1}^{n} b_{i j}(t) f_{j}\left(x_{j}\left(t-\tau_{i j}(t)\right)\right)\right. \\
& \quad-\sum_{j=1}^{n} c_{i j}(t) \int_{-\infty}^{t} D_{i j}(t, s) g_{j}\left(x_{j}(s) d s\right\},  \tag{1.4}\\
& i=1,2, \ldots, n, t \neq t_{k}, t>0, \\
& x_{i}\left(t_{k}^{+}\right)-x_{i}\left(t_{k}^{-}\right)=I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right), t=t_{k}, k \in \mathbb{Z}^{+},
\end{align*}
$$

where $x(t)=\left[x_{1}(t), x_{2}(t), . ., x_{n}(t)\right]^{T} \in \mathbb{R}^{n}$. The expression $\Delta x_{i}\left(t_{k}\right)=x_{i}\left(t_{k}^{+}\right)-$ $x_{i}\left(t_{k}^{-}\right)=I_{i k}\left(t_{i k}, x_{i}\left(t_{k}\right)\right)$ denotes the impulse at moment $t_{k}$, and $t_{1}<t_{2}<\ldots$, is a strictly increasing sequence such that $t_{k}$ goes to infinity, $x_{i}\left(t_{k}^{+}\right)$and $x_{i}\left(t_{k}^{-}\right)$ stand for the right-hand and the left-hand limits of $x_{i}(t)$ at the impulsive moment $t_{k}$ respectively. Consider that $I_{i k}(\cdot, \cdot) \in C\left(\mathbb{R}^{+} \times \mathbb{R}^{+}, \mathbb{R}^{+}\right), i=1,2, \ldots, n$, $k=1,2, \ldots$, shows the impulsive perturbation at the moment $t_{k}$. Since we are searching for the existence of periodic solutions for equation (1.4), it is natural to assume that $r_{i}, a_{i j}, b_{i j}, c_{i j} \in C\left(\mathbb{R}^{+}, \mathbb{R}^{+}\right)$are all $\omega$-periodic functions $(\omega>0)$ with respect to $t$,

$$
\begin{align*}
a_{i j}(t+\omega) & =a_{i j}(t), \tau_{i j}(t+\omega)=\tau_{i j}(t), D_{i j}(t+\omega, s+\omega)=D_{i j}(t, s) \\
b_{i j}(t+\omega) & =b_{i j}(t) \text { and } c_{i j}(t+\omega)=c_{i j}(t) \tag{1.5}
\end{align*}
$$

for, $i, j=1,2, \ldots, n$, with $\tau_{i j}$ being scalar functions, continuous, and $\tau_{i j}(t) \geq$ $\tau_{i j}^{*}>0$ with

$$
\begin{align*}
\widehat{r}_{i} & =\frac{1}{\omega} \int_{0}^{\omega} r_{i}(s) d s>0 \\
\widehat{a}_{i j} & =\frac{T_{j}}{\omega} \int_{0}^{\omega} a_{i j}(s) d s \geq 0 \\
\widehat{b}_{i j} & =\frac{F_{j}}{\omega} \int_{0}^{\omega} b_{i j}(s) d s \geq 0, \widehat{c}_{i j}=\frac{R_{j} E_{i j}}{\omega} \int_{0}^{\omega} c_{i j}(s) d s \geq 0 \\
\widehat{\beta}_{i k} & =\frac{1}{\omega} \sum_{0 \leq t_{k}<\omega} \lambda_{i k}\left(t_{k}\right) \geq 0, k \in \mathbb{Z}^{+} \tag{1.6}
\end{align*}
$$

for $i, j=1,2, \ldots, n$, where $T_{j}, F_{j}$ and $\lambda_{i k}, R_{j}, E_{i j}$ are given in $\left(H_{1}\right)-\left(H_{5}\right)$. We also assume that the functions $D_{i j} \in C\left(\mathbb{R}^{+} \times \mathbb{R}^{+}, \mathbb{R}^{+}\right)$and $f_{i}, g_{i}, h_{i} \in$
$C\left(\mathbb{R}^{+}, \mathbb{R}^{+}\right), i, j=1,2, \ldots, n$,

$$
\begin{aligned}
f(x(t)) & =\left[f_{1}\left(x_{1}(t)\right), f_{2}\left(x_{2}(t)\right), \ldots, f_{n}\left(x_{n}(t)\right)\right]^{T} \in \mathbb{R}_{+}^{n} \\
g(x(t)) & =\left[g_{1}\left(x_{1}(t)\right), g_{2}\left(x_{2}(t)\right), \ldots, g_{n}\left(x_{n}(t)\right)\right]^{T} \in \mathbb{R}_{+}^{n} \\
h(x(t)) & =\left[h_{1}\left(x_{1}(t)\right), h_{2}\left(x_{2}(t)\right), \ldots, h_{n}\left(x_{n}(t)\right)\right]^{T} \in \mathbb{R}_{+}^{n}
\end{aligned}
$$

are positive and continuous in their respective arguments.
Throughout this paper, we will assume the following hypotheses:
$\left(H_{1}\right)$ There exist nonnegative constants $\bar{T}_{j}, T_{j}$, such that for all $x \in \mathbb{R}^{+}$,

$$
\begin{equation*}
\bar{T}_{j} x \leq h_{j}(x) \leq T_{j} x, j=1,2, \ldots, n \tag{1.7}
\end{equation*}
$$

$\left(H_{2}\right)$ There exist nonnegative constants $\bar{F}_{j}, F_{j}$ such that for all $x \in \mathbb{R}^{+}$,

$$
\begin{equation*}
\bar{F}_{j} x \leq f_{j}(x) \leq F_{j} x, j=1,2, \ldots, n . \tag{1.8}
\end{equation*}
$$

$\left(H_{3}\right)$ There exist nonnegative constants $\bar{R}_{j}, R_{j}$ such that for all $x \in \mathbb{R}^{+}$,

$$
\begin{equation*}
\bar{R}_{j} x \leq g_{j}(x) \leq R_{j} x, j=1,2, \ldots, n \tag{1.9}
\end{equation*}
$$

$\left(H_{4}\right)$ There exist nonnegative constants $\bar{E}_{i j}, E_{i j}$ such that for all $t \in \mathbb{R}^{+}$,

$$
\begin{equation*}
\bar{E}_{i j} \leq \int_{-\infty}^{t} D_{i j}(t, s) d s \leq E_{i j}, i, j=1,2, \ldots, n \tag{1.10}
\end{equation*}
$$

$\left(H_{5}\right)$ There exists an integer $q>0$ such that $t_{k+q}=t_{k}+\omega, I_{i(k+q)}=I_{i k}$, $k \in \mathbb{Z}^{+}$, where

$$
\begin{equation*}
[0, \omega] \cap\left\{t_{k}, k=1,2, \ldots\right\}=\left\{t_{1}, t_{2}, \ldots, t_{q}\right\} . \tag{1.11}
\end{equation*}
$$

For convenience, we introduce the notion

$$
f^{M}=\max _{t \in[0, \omega]}\{|f(t)|\}, \quad \delta_{i}=e^{-\int_{0}^{\omega} r_{i}(t) d t}, i=1,2 \ldots
$$

where $f$ is a continuous and $\omega$-periodic function.
The paper is organized as follows. In Section 2, we recall some results which are necessary for our analysis. The existence of positive periodic solutions of system (1.4) by using the Krasonoselskii fixed point theorem is proved in Section 3. Finally, in Section 4, we exhibit an example to show the validity of our result.

## 2 Preliminaries

Throughout this paper, a vector $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right)^{T} \in \mathbb{R}^{n}$ is said to be positive if $x_{i} \geq 0,1 \leq i \leq n$.

First, we recall the following definitions. Let $I \subset \mathbb{R}$ be an interval, and denote by $P C\left(I, \mathbb{R}^{n}\right)$ the set of operators $x: I \rightarrow \mathbb{R}^{n}$ which are continuous for $t \in I$, $t \neq t_{k}$ and have discontinuities of the first kind at the points $t_{k} \in I,\left(k \in \mathbb{Z}^{+}\right)$ but are continuous from the left at these points.

The proofs of the main results in this paper are based on an application of Krasnoselskii's fixed point theorem in cones. Firstly, we need to introduce some definitions and lemmas.

Definition 2.1 (See $[10,18])$ A function $x_{i}: \mathbb{R} \rightarrow(0,+\infty)$ is said to be $a$ positive solution of (1.4), if the following conditions are satisfied

1) $x_{i}(t)$ is absolutely continuous on each $\left(t_{k}, t_{k+1}\right)$;
2) for each $k \in \mathbb{Z}^{+}, x_{i}\left(t_{k}^{+}\right)$and $x_{i}\left(t_{k}^{-}\right)$exist and $x_{i}\left(t_{k}^{-}\right)=x_{i}\left(t_{k}\right)$;
3) $x_{i}(t)$ satisfies the first equation of (1.4) for almost everywhere in $\mathbb{R}$ and $x_{i}\left(t_{k}\right)$ satisfies the second equation of (1.4) at impulsive point $t_{k}, k \in \mathbb{Z}^{+}$.

Definition 2.2 Let $X$ be a Banach space and let $K$ be a closed, nonempty subset of $X . K$ is a cone if
i) $\alpha x+\beta y \in K$ for all $x, y \in K$ and all $\alpha, \beta \geq 0$;
ii) $x,-x \in K$ imply $x=0$.

Theorem 2.1. (Krasnoselskii, [13]). Let $X$ be a Banach space, and let $K \subset X$ be a cone in $X$. Assume that $\Omega_{1}$ and $\Omega_{2}$ are open subsets of $X$ with $0 \in \Omega_{1}$, $\bar{\Omega}_{1} \subset \Omega_{2}$ and let

$$
\Phi: K \cap\left(\bar{\Omega}_{2} \backslash \Omega_{1}\right) \rightarrow K
$$

be a completely continuous operator such that either
a) $\|\Phi x\| \leq\|x\|$ for $x \in K \cap \partial \Omega_{1}$ and $\|\Phi x\| \geq\|x\|$ for $x \in K \cap \partial \Omega_{2}$; or
b) $\|\Phi x\| \geq\|x\|$ for $x \in K \cap \partial \Omega_{1}$ and $\|\Phi x\| \leq\|x\|$ for $x \in K \cap \partial \Omega_{2}$.

Then $\Phi$ has a fixed point in $K \cap\left(\bar{\Omega}_{2} \backslash \Omega_{1}\right)$.

## 3 Existence of positive periodic solutions

As we mentioned previously, one of our main objectives in this paper is to improve the work carried out in [25], and to extend it to investigate a wider class of differential equations with impulsive effects presented in (1.4). In particular, by using Kranoselskii's fixed point theorem on cones, we will establish a sufficient condition ensuring the existence of positive $\omega$-periodic solutions of equation (1.4). This section will be splitted into two parts: in the first one, we will focuse on the existence of positive periodic solutions when we use subquadratic impulse functions, while in the second part, we will consider the case in which the impulse effects are sublinear (most frequently used in the published literature).

Let us start by obtaining an equivalent formulation for our problem (1.4).
Lemma 3.1. The function $x(\cdot)$ is an $\omega$-periodic solution of equation (1.4) if
and only if $x(\cdot)$ is an $\omega$-periodic solution of the following equation:

$$
\begin{align*}
x_{i}(t)=\int_{t}^{t+\omega} G_{i}(t, s) & x_{i}(s) \times\left[\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)\right. \\
& +\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right) \\
& +\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z) d z\right\} d s  \tag{3.1}\\
& +\sum_{t \leq t_{k}<t+\omega} G_{i}\left(t, t_{k}\right) I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right),
\end{align*}
$$

where

$$
\begin{equation*}
G_{i}(t, s)=\frac{e^{-\int_{t}^{s} r_{i}(\xi) d \xi}}{1-e^{-\int_{0}^{\omega} r_{i}(\xi) d \xi}}, s \in[t, t+\omega], i=1,2, \ldots, n \tag{3.2}
\end{equation*}
$$

and we assume

$$
e^{-\int_{0}^{\omega} r_{i}(\xi) d \xi} \neq 1
$$

Proof. Unlike the procedure carried out in [25], where the authors used the variation of constants formula to rewrite the original equation as an integral equation, we have to proceed in a very different way which is motivated and justified by the appearance of the impulsive terms in our problem. Assume that $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right)^{T} \in X$, is a periodic solution of equation (1.4). Then, we have

$$
\begin{align*}
& \frac{d}{d t}\left[x_{i}(t) \exp \left(-\int_{0}^{t} r_{i}(s) d s\right)\right] \\
& =\exp \left(-\int_{0}^{t} r_{i}(s) d s\right) x_{i}(t) \\
& \quad \times\left\{-\sum_{j=1}^{n} a_{i j}(t) h_{j}\left(x_{j}(t)\right)-\sum_{j=1}^{n} b_{i j}(t) f_{j}\left(x_{j}\left(t-\tau_{i j}(t)\right)\right)\right. \\
&  \tag{3.3}\\
& \left.\quad-\sum_{j=1}^{n} c_{i j}(t) \int_{-\infty}^{t} D_{i j}(t, s) g_{j}\left(x_{j}(s)\right) d s\right\} \\
& t \neq t_{k}, \quad i=1,2, \ldots, n .
\end{align*}
$$

Integrating the above equation over $[t, t+\omega]$, we have

$$
\begin{aligned}
& x_{i}(s) e^{-\int_{0}^{s} r_{i}(\xi) d \xi} \left\lvert\, \begin{array}{l}
t_{m_{1}}+n \omega \\
t
\end{array}\right. \\
&+x_{i}(s) e^{-\int_{0}^{s} r_{i}(\xi) d \xi} \left\lvert\, \begin{array}{l}
t_{m_{2}}+n \omega \\
t_{m_{1}}+n \omega
\end{array}+\ldots\right. \\
&=\left.\int_{t}(s) e^{-\int_{0}^{s} r_{i}(\xi) d \xi}\right|_{t_{m_{q}}+n \omega} ^{t+\omega} \\
& t_{i}(s) \exp \left(-\int_{0}^{s} r_{i}(\xi) d \xi\right)\left\{-\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)\right. \\
&-\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)-\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z)\right) d z\right\} d s
\end{aligned}
$$

where $t_{m_{k}}+n \omega \in(t, t+\omega), m_{k} \in\{1,2, \ldots, q\}, k=1,2, \ldots, q, n \in \mathbb{Z}^{+}$. Therefore,

$$
\begin{aligned}
& \quad x_{i}(t) e^{-\int_{0}^{t} r_{i}(\xi) d \xi}\left[1-e^{-\int_{t}^{t+\omega} r_{i}(\xi) d \xi}\right] \\
& \quad+\sum_{t \leq t_{k}<t+\omega} \Delta x_{i}\left(t_{m_{k}}\right) e^{-\int_{0}^{t_{m_{k}}+n \omega}} r_{i}(\xi) d \xi \\
& =\int_{t}^{t+\omega} x_{i}(s) \exp \left(-\int_{0}^{s} r_{i}(\xi) d \xi\right) \\
& \quad \times\left\{\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)+\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right.\right. \\
& \left.\quad+\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z)\right) d z\right\} d s
\end{aligned}
$$

which can be transformed into

$$
\begin{align*}
x_{i}(t)= & \int_{t}^{t+\omega} G_{i}(t, s) x_{i}(s) \\
& \times\left\{\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)+\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right.\right. \\
& \left.+\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z)\right) d z\right\} d s \\
& +\sum_{t \leq t_{k}<t+\omega} G_{i}\left(t, t_{k}\right) I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right), i=1,2,, \ldots, n \tag{3.4}
\end{align*}
$$

Thus, $x_{i}$ is a periodic solution of (3.1). If $x=\left(x_{1}(t), x_{2}(t), \ldots, x_{n}(t)\right)^{T} \in K$, is
a periodic solution of (3.1), for any $t=t_{k}$, from (3.1) we obtain

$$
\begin{aligned}
& x_{i}^{\prime}(t)= G_{i}(t, t+\omega) x_{i}(t+\omega) \\
& \times\left(\sum_{j=1}^{n} a_{i j}(t+\omega) h_{j}\left(x_{j}(t+\omega)\right)+\sum_{j=1}^{n} b_{i j}(t+\omega) f_{j}\left(x_{j}\left(t+\omega-\tau_{j}(t+\omega)\right)\right.\right. \\
&\left.+\sum_{j=1}^{n} c_{i j}(t+\omega) \int_{-\infty}^{t+\omega} D_{i j}(t+\omega, s) g_{j}\left(x_{j}(s)\right) d s\right) \\
& \quad-G_{i}(t, t) x_{i}(t)\left(\sum_{j=1}^{n} a_{i j}(t) h_{j}\left(x_{j}(t)\right)+\sum_{j=1}^{n} b_{i j}(t) f_{j}\left(x_{j}\left(t-\tau_{i j}(t)\right)\right.\right. \\
&\left.+\sum_{j=1}^{n} c_{i j}(t) \int_{-\infty}^{t} D_{i j}(t, s) g_{j}\left(x_{j}(s)\right) d s\right)+r_{i}(t) x_{i}(t) \\
&= x_{i}(t)\left(r_{i}(t)-\sum_{j=1}^{n} a_{i j}(t) h_{j}\left(x_{j}(t)\right)-\sum_{j=1}^{n} b_{i j}(t) f_{j}\left(x_{j}\left(t-\tau_{i j}(t)\right)\right.\right. \\
&\left.-\sum_{j=1}^{n} c_{i j}(t) \int_{-\infty}^{t} D_{i j}(t, s) g_{j}\left(x_{j}(s)\right) d s\right) .
\end{aligned}
$$

For any $t=t_{j}, j \in \mathbb{Z}^{+}$, we have from (3.1) that

$$
\begin{aligned}
x_{i}\left(t_{j}^{+}\right)-x_{i}\left(t_{j}\right)=\int_{t_{j}}^{t_{j}+\omega} & {\left[G_{i}\left(t_{j}^{+}, s\right)-G_{i}\left(t_{j}, s\right)\right] x_{i}(s) } \\
& \times\left\{\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)\right. \\
& +\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right) \\
& +\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z) d z\right\} d s \\
& +\sum_{t_{j}^{+} \leq t_{k}<t_{j}+\omega} G_{i}\left(t_{j}^{+}, t_{k}\right) I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right) \\
& -\sum_{t_{j} \leq t_{k}<t_{j}+\omega} G_{i}\left(t_{j}, t_{k}\right) I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right) \\
=\quad I_{i k}\left(t_{k},\right. & \left.x_{i}\left(t_{k}\right)\right) .
\end{aligned}
$$

Hence $x_{i}$ is a positive $\omega$-periodic solution of (1.4). Thus, the proof of Lemma 3.1 is completed.

Define now

$$
\begin{align*}
P C\left(\mathbb{R}, \mathbb{R}^{n}\right)= & \left\{x=\left(x_{1}, x_{2}, \ldots, x_{n}\right)^{T}\right.  \tag{3.5}\\
: & \mathbb{R} \rightarrow \mathbb{R}^{n} \mid x \in C\left(\left(t_{k}, t_{k+1}\right), \mathbb{R}^{n}\right), \text { such that } \\
& \left.x\left(t_{k}^{-}\right), x\left(t_{k}^{+}\right) \text {exist and } x\left(t_{k}^{-}\right)=x\left(t_{k}\right), k \in \mathbb{Z}_{+}\right\} .
\end{align*}
$$

To apply Theorem 2.1, we need to define a Banach space $C_{\omega}$, a closed subset $S$ of $C_{\omega}$ and construct one mapping. Thus, we let $\left(C_{\omega},\|\cdot\|\right)=(X,\|\cdot\|)$ where

$$
\begin{equation*}
C_{\omega}=\left\{x=\left(x_{1}, x_{2}, \ldots, x_{n}\right)^{T}: x \in P C\left(\mathbb{R}, \mathbb{R}^{n}\right), x(t+\omega)=x(t), t \in \mathbb{R}\right\} \tag{3.6}
\end{equation*}
$$

with the norm

$$
\begin{equation*}
\|x\|=\sum_{i=1}^{n}\left|x_{i}\right|_{0},\left|x_{i}\right|_{0}=\max _{t \in[0, \omega]}\left|x_{i}(t)\right|, i=1,2, \ldots, n, \forall x \in C_{\omega} \tag{3.7}
\end{equation*}
$$

Then, $C_{\omega}$ with the norm $\|$.$\| is a Banach space.$
We denote $\theta=\min \left(1, \theta_{1}, \theta_{2}, \theta_{3}\right)$, where

$$
\theta_{1}=\min _{j=\overline{1, n}}\left(\frac{\bar{T}_{j}}{T_{j}}\right), \theta_{2}=\min _{j=\overline{1, n}}\left(\frac{\bar{F}_{j}}{F_{j}}\right), \theta_{3}=\min _{j=\overline{1, n}}\left\{\min _{i=\overline{1, n}}\left(\frac{\bar{E}_{i j}}{E_{i j}}\right) \frac{\bar{R}_{j}}{R_{j}}\right\}
$$

and

$$
\sigma=\min \left\{e^{-\widehat{r}_{i} \omega}, i=1,2, \ldots, n\right\}
$$

Let $K$ be the cone in $C_{\omega}$ defined by

$$
K=\left\{x(\cdot)=\left(x_{1}, x_{2}, \ldots, x_{n}\right)^{T} \in C_{\omega}: x_{i}(t) \geq \sigma\left|x_{i}\right|_{0}, i=1,2, \ldots, n, \forall t \in \mathbb{R}\right\}
$$

Use (3.1) to define the operator $\Phi: C_{\omega} \rightarrow C_{\omega}$ by

$$
(\Phi x)(t):=\left[\left(\Phi_{1} x\right)(t),\left(\Phi_{2} x\right)(t), \ldots,\left(\Phi_{n} x\right)(t)\right]^{T}
$$

where

$$
\begin{align*}
\left(\Phi_{i} x\right)(t)= & \int_{t}^{t+\omega} G_{i}(t, s) x_{i}(s)\left\{\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)\right. \\
& +\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right) \\
& +\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z) d z\right\} d s \\
& +\sum_{t \leq t_{k}<t+\omega} G_{i}\left(t, t_{k}\right) I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right) \tag{3.8}
\end{align*}
$$

$$
G_{i}(t, s)=\frac{e^{-\int_{t}^{s} r_{i}(\xi) d \xi}}{1-e^{-\int_{0}^{\omega} r_{i}(\xi) d \xi}}, s \in[t, t+\omega], i=1,2, \ldots, n .
$$

It is clear that $G_{i}(t+\omega, s+\omega)=G_{i}(t, s),\left(\partial G_{i}(t, s) / \partial t\right)=r_{i}(t) G_{i}(t, s)$, $G_{i}(t, t+\omega)-G_{i}(t, t)=-1$, and

$$
\begin{equation*}
A_{i}:=\frac{\delta_{i}}{1-\delta_{i}} \leq G_{i}(t, s) \leq \frac{1}{1-\delta_{i}}=: B_{i}, t, s \in \mathbb{R}, i=1,2, \ldots, n \tag{3.9}
\end{equation*}
$$

By (2.6), it is easy to check that $x \in C_{\omega}$ is an $\omega$-periodic solution of equation (1.4) provided $x$ is a fixed point of $\Phi$.

Lemma 3.2. Assume that $\left(H_{1}\right)-\left(H_{5}\right)$ hold, then $\Phi: K \rightarrow K$ defined by Equation (3.8) is well defined, namely, $\Phi K \subset K$.

Proof. From (3.8) it is easy to verify that $(\Phi x)(\cdot)$ is continuous in $\left(t_{k}, t_{k+1}\right)$, and $(\Phi x)\left(t_{k}^{+}\right)$and $(\Phi x)\left(t_{k}^{-}\right)$exist, and $(\Phi x)\left(t_{k}^{-}\right)=(\Phi x)\left(t_{k}\right)$ for $k \in \mathbb{Z}^{+}$. Moreover, for any $x \in K$,

$$
\begin{aligned}
&\left(\Phi_{i} x\right)(t+\omega) \\
&= \int_{t+\omega}^{t+2 \omega} G_{i}(t+\omega, s) x_{i}(s)\left\{\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)\right. \\
&+\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right) \\
&+\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z) d z\right\} d s \\
&+\sum_{t+\omega \leq t_{k}<t+2 \omega} G_{i}\left(t, t_{k}\right) I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right) \\
&= \int_{t}^{t+\omega} G_{i}(t+\omega, s+\omega) x_{i}(s+\omega) \times \\
& \quad \times\left\{\sum_{j=1}^{n} a_{i j}(s+\omega) h_{j}\left(x_{j}(s+\omega)\right)+\sum_{j=1}^{n} b_{i j}(s+\omega) f_{j}\left(x_{j}(s+\omega)\right)\right. \\
& \quad+\sum_{j=1}^{n} c_{i j}(s+\omega) \int_{-\infty}^{s+\omega} D_{i j}(s+\omega, z) g_{j}\left(u_{j}(z) d z\right\} d s \\
& \quad+\sum_{t \leq t_{k}<t+\omega} G_{i}\left(t, t_{k}\right) I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right)
\end{aligned}
$$

$$
\begin{aligned}
= & \int_{t}^{t+\omega} G_{i}(t, s) x_{i}(s)\left\{\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)+\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right)\right. \\
& +\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z) d z\right\} d s \\
& +\sum_{t \leq t_{k}<t+\omega} G_{i}\left(t, t_{k}\right) I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right) \\
= & \left(\Phi_{i} x\right)(t), i=1,2, \ldots, n .
\end{aligned}
$$

That is $\left(\Phi_{i} x\right)(t+\omega)=\left(\Phi_{i} x\right)(t), t \in[0, \omega]$. Thus $\Phi x \in C_{\omega}$. Moreover, from (3.8) and (3.9), we have for $x \in K$

$$
\begin{aligned}
\left|\left(\Phi_{i} x\right)\right|_{0} \leq & \frac{1}{1-\delta_{i}} \int_{0}^{\omega} x_{i}(s)\left\{\left[\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)\right.\right. \\
& +\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right) \\
& +\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z) d z\right] d s \\
& \left.+\sum_{t \leq t_{k}<t+\omega} I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right)\right\}
\end{aligned}
$$

and

$$
\begin{aligned}
\left(\Phi_{i} x\right) \geq & \frac{\delta_{i}}{1-\delta_{i}} \int_{0}^{\omega} x_{i}(s)\left\{\left[\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)+\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right)\right.\right. \\
& +\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z) d z\right] d s \\
& \left.+\sum_{t \leq t_{k}<t+\omega} I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right)\right\} \\
\geq & \frac{A_{i}}{B_{i}}\left|\left(\Phi_{i} x\right)\right|_{0} \\
\geq & \sigma\left|\left(\Phi_{i} x\right)\right|_{0}, i=1,2, \ldots, n .
\end{aligned}
$$

Hence, $\Phi K \subset K$. This completes the proof of Lemma 3.2.

### 3.1 The case of subquadratic impulses.

In this section we consider subquadratic impulse functions.

Lemma 3.3. In addition to conditions $\left(H_{1}\right)-\left(H_{5}\right)$, we further assume the following one:
$\left(H_{6}\right)$ There exist nonnegative functions $\bar{\lambda}_{i k}, \lambda_{i k} \in C\left(\mathbb{R}^{+}, \mathbb{R}^{+}\right)$such that for all $x \in \mathbb{R}^{+}$,

$$
\bar{\lambda}_{i k}(t) x^{2} \leq I_{i k}(t, x) \leq \lambda_{i k}(t) x^{2}, i=1,2, \ldots, n, k=1,2, \ldots
$$

Then $\Phi: K \rightarrow K$ defined by equation (3.8) is completely continuous.
Proof. Set

$$
\begin{align*}
\Gamma_{i}(t, x)(t)= & x_{i}(t)\left[\sum_{j=1}^{n} a_{i j}(t) h_{j}\left(x_{j}(t)\right)+\sum_{j=1}^{n} b_{i j}(t) f_{j}\left(x_{j}\left(t-\tau_{i j}(t)\right)\right)\right.  \tag{3.10}\\
& \left.+\sum_{j=1}^{n} c_{i j}(t) \int_{-\infty}^{t} D_{i j}(t, s) g_{j}\left(x_{j}(s)\right) d s\right], t \in \mathbb{R}
\end{align*}
$$

We first show that $\Phi$ is continuous. Since $h, f, g$ and $I$ are continuous in $x$, it follows that, for any $L_{0}>0$ and $\varepsilon>0$, there exists $\mu_{1}>0$ such that for $\|x\| \leq L_{0},\|y\| \leq L_{0}$, and $\|x-y\|<\mu_{1}$ it follows

$$
\begin{equation*}
\left|\Gamma_{i}(s, x)(s)-\Gamma_{i}(s, y)(s)\right|<\frac{\varepsilon}{2 n B \omega}, s \in \mathbb{R}^{+}, i=1,2, \ldots, n \tag{3.11}
\end{equation*}
$$

where $B=\max _{1 \leq i \leq n} B_{i}$. For any $L_{0}>0$ and $\varepsilon>0$, there exists $\mu_{2}>0$ such that for $\|x\| \leq L_{0},\|y\| \leq L_{0}$, and $\|x-y\|<\mu_{2}$

$$
\begin{equation*}
\left|I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right)-I_{i k}\left(t_{k}, y_{i}\left(t_{k}\right)\right)\right|<\frac{\varepsilon}{2 q B n}, q \in \mathbb{Z}^{+} i=1,2, \ldots, n \tag{3.12}
\end{equation*}
$$

Therefore, if $x, y \in C_{\omega}$ with $\|x\| \leq L_{0},\|y\| \leq L_{0}$, and $\|x-y\| \leq \mu$, where $\mu=\min \left(\mu_{1}, \mu_{2}\right)$ then, from (3.8), (3.9) , (3.11) and (3.12),

$$
\begin{aligned}
\left|\left(\Phi_{i} x\right)-\left(\Phi_{i} y\right)\right|_{0} \leq & B \int_{t}^{t+\omega}\left|\Gamma_{i}(s, x)(s)-\Gamma_{i}(s, y)(s)\right| d s \\
& +\sum_{t \leq t_{k}<t+\omega}\left|G_{i}\left(t, t_{k}\right)\right|\left|I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right)-I_{i k}\left(t_{k}, y_{i}\left(t_{k}\right)\right)\right| \\
\leq & B \frac{\omega \varepsilon}{2 n B \omega}+B q \frac{\varepsilon}{2 q B n} \\
< & \frac{\varepsilon}{n}, i=1,2, \ldots, n
\end{aligned}
$$

This yields

$$
\|\Phi x-\Phi y\|=\sum_{i=1}^{n}\left|\left(\Phi_{i} x\right)-\left(\Phi_{i} y\right)\right|_{0}<\varepsilon
$$

which implies that $\Phi$ is continuous on $K$.
We let

$$
S=\left\{x(\cdot)=\left(x_{1}(\cdot), x_{2}(\cdot), \ldots, x_{n}(\cdot)\right)^{T} \in C_{\omega}:\|x\| \leq L\right\}
$$

where $L$ is a non-negative constant. For any $x \in S$, it follows from (3.8) and (3.9) that

$$
\begin{aligned}
\left(\Phi_{i} x\right)(t)= & \int_{t}^{t+\omega} G_{i}(t, s) x_{i}(s)\left\{\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)+\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right)\right. \\
& +\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z) d z\right\} d s \\
& +\sum_{t \leq t_{k}<t+\omega} G_{i}\left(t, t_{k}\right) I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right) \\
\leq & \frac{L^{2}}{1-\delta_{i}} \int_{0}^{\omega}\left[\sum_{j=1}^{n} A_{j} a_{i j}(s)+\sum_{j=1}^{n} F_{j} b_{i j}(s)+\sum_{j=1}^{n} R_{j} E_{i j} c_{i j}(s)\right] d s \\
& +\frac{L^{2}}{1-\delta_{i}} \sum_{t \leq t_{k}<t+\omega} \lambda_{i k}\left(t_{k}\right) \\
:=\quad & B_{i}^{*}, \quad i=1,2, \ldots, n
\end{aligned}
$$

and, consequently,

$$
\|\Phi x\|=\sum_{i=1}^{n}\left|\left(\Phi_{i} x\right)\right|_{0} \leq \sum_{i=1}^{n} B_{i}^{*}, \quad \forall x \in S
$$

This shows that $\Phi(S)$ is uniformly bounded.
To show that $\Phi(S)$ is equicontinuous, let $x \in S$, we calculate $\frac{d}{d t}\left(\Phi_{i} x\right)(t)$ and show that it is uniformly bounded. Indeed, by taking derivative in (3.8) we have

$$
\begin{aligned}
\left|\left(\Phi_{i} x\right)^{\prime}(t)\right| \leq & \mid r_{i}(t)\left(\Phi_{i} x\right)(t)-x_{i}(t)\left[\sum_{j=1}^{n} a_{i j}(t) h_{j}\left(x_{j}(t)\right)\right. \\
& +\sum_{j=1}^{n} b_{i j}(t) f_{j}\left(x_{j}\left(t-\tau_{i j}(t)\right)\right) \\
& +\sum_{j=1}^{n} c_{i j}(t) \int_{-\infty}^{t} D_{i j}(t, s) g_{j}\left(x_{j}(s) d s\right] \mid \\
\leq & r_{i}^{M} B_{i}^{*}+L^{2} \sum_{j=1}^{n}\left(A_{j} a_{i j}^{M}+F_{j} b_{i j}^{M}+E_{i j} R_{j} c_{i j}^{M}\right) \\
i= & 1,2, \ldots, n,
\end{aligned}
$$

and

$$
\left\|(\Phi x)^{\prime}\right\| \leq \sum_{j=1}^{n}\left[r_{i}^{M} B_{i}^{*}+L^{2} \sum_{j=1}^{n}\left(A_{j} a_{i j}^{M}+F_{j} b_{i j}^{M}+E_{i j} R_{j} c_{i j}^{M}\right)\right]
$$

Hence, $\Phi S \subset C_{\omega}$ is a family of uniformly bounded and equi-continuous functions. By the Ascoli-Arzelà Theorem, the operator $\Phi$ is compact, and therefore completely continuous. The proof is complete.

We can now state and prove our main result in this paper.
Theorem 3.1. Assume hypotheses $\left(H_{1}\right)-\left(H_{6}\right)$ and the next one as well: $\left(H_{7}\right)$ The linear system

$$
\sum_{j=1}^{n}\left(\widehat{a}_{i j}+\widehat{b}_{i j}+\widehat{c}_{i j}\right) x_{j}+\widehat{\beta}_{i k} x_{i}=\widehat{r}_{i}, i=1,2, \ldots, n, k=1,2, \ldots
$$

possesses a unique positive solution. Then, system (1.4) possesses at least one positive $\omega$-periodic solution.

Proof. Let

$$
x^{*}=\left(x_{1}^{*}, x_{2}^{*}, \ldots, x_{n}^{*}\right)^{T}
$$

with $x_{i}^{*}>0, i=1,2, \ldots, n$, be a positive solution of (1.12). Set

$$
\begin{aligned}
& m_{0}=\min _{1 \leq i \leq n}\left\{\widehat{r}_{i} A_{i}\right\}, \\
& M_{0}=\max _{1 \leq i \leq n}\left\{\widehat{r}_{i} B_{i}\right\} .
\end{aligned}
$$

Then $0<m_{0}<M_{0}<+\infty$. Choose a constant $M \geq M_{0}$ such that $\frac{1}{M \omega}<1$.
Let $\alpha_{1}=\frac{1}{M \omega}$ and

$$
\Omega_{1}=\left\{x(t)=\left(x_{1}(t), x_{2}(t), \ldots, x_{n}(t)\right)^{T} \in C_{\omega}:\left|x_{i}\right|_{0}<\alpha_{1} x_{i}^{*}, i=1,2, \ldots, n\right\} .
$$

If $x \in K \cap \partial \Omega_{1}$, then

$$
\sigma\left|x_{i}\right|_{0} \leq x_{i}(t) \leq\left|x_{i}\right|_{0}=\alpha_{1} x_{i}^{*}, i=1,2, \ldots, n
$$

and

$$
\begin{aligned}
\left(\Phi_{i} x\right)(t) \leq & B_{i} \int_{0}^{\omega}\left\{\left[x_{i}(s) \sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)\right.\right. \\
& +x_{i}(s) \sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right) \\
& +x_{i}(s) \sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z) d z\right] d s \\
& \left.+\sum_{t \leq t_{k}<t+\omega} I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right)\right\} \\
\leq & B_{i} \int_{0}^{\omega}\left|x_{i}\right|_{0} \sum_{j=1}^{n} T_{j} a_{i j}(s)\left|x_{j}\right|_{0} d s+B_{i} \int_{0}^{\omega}\left|x_{i}\right|_{0} \sum_{j=1}^{n} F_{j} b_{i j}(s)\left|x_{j}\right|_{0} d s \\
& +B_{i} \int_{0}^{\omega}\left|x_{i}\right|_{0} \sum_{j=1}^{n} R_{j} E_{i j} c_{i j}(s)\left|x_{j}\right|_{0} d s+B_{i}\left|x_{i}\right|_{0} \sum_{t \leq t_{k}<t+\omega} \lambda_{i}\left(t_{k}\right)\left|x_{i}\right|_{0} \\
\leq & \alpha_{1} B_{i} \omega\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{a}_{i j} x_{j}^{*}+\alpha_{1} B_{i} \omega\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{b}_{i j} x_{j}^{*} \\
& +\alpha_{1} B_{i} \omega\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{c}_{i j} x_{j}^{*}+\alpha_{1} B_{i} \omega\left|x_{i}\right|_{0} \widehat{\beta}_{i k} x_{i}^{*} \\
= & \alpha_{1} B_{i} \omega\left|x_{i}\right|_{0}\left[\sum_{j=1}^{n}\left(\widehat{a}_{i j}+\widehat{b}_{i j}+\widehat{c}_{i j}\right) x_{j}^{*}+\widehat{\beta}_{i k} x_{i}^{*}\right] \\
= & \left(B_{i} \widehat{r}_{i}\right) \alpha_{1} \omega\left|x_{i}\right|_{0} \\
\leq & \alpha_{1} M_{0} \omega\left|x_{i}\right|_{0} \\
\leq & \left|x_{i}\right|_{0}, \quad i=1,2, \ldots, n .
\end{aligned}
$$

Hence for any $x \in K \cap \partial \Omega_{1}$

$$
\|\Phi x\|=\sum_{i=1}^{n}\left|\left(\Phi_{i} x_{i}\right)\right|_{0} \leq \sum_{i=1}^{n}\left|x_{i}\right|_{0}=\|x\|
$$

On the other hand, choose $0<m \leq m_{0}$ such that $\frac{1}{\sigma^{2} m \theta \omega}>1$. Let $\alpha_{2}=\frac{1}{\sigma^{2} m \theta \omega}$ and

$$
\Omega_{2}=\left\{x \in C_{\omega}:\left|x_{i}\right|_{0}<\alpha_{2} x_{i}^{*}, i=1,2, \ldots, n\right\}
$$

If $x \in K \cap \partial \Omega_{2}$, then $\sigma\left|x_{i}\right|_{0} \leq x_{i}(t) \leq\left|x_{i}\right|_{0}=\alpha_{2} x_{i}^{*}, i=1,2, \ldots, n$, and, conse-
quently

$$
\begin{aligned}
& \left(\Phi_{i} x\right)(t) \geq A_{i} \int_{0}^{\omega} x_{i}(s)\left\{\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)+\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right)\right. \\
& +\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z) d z\right\} d s \\
& +\sum_{t \leq t_{k}<t+\omega} G_{i}\left(t, t_{k}\right) I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right) \\
& \geq \sigma^{2} A_{i}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \int_{0}^{\omega} a_{i j}(s) T_{j}\left[\min _{j=\overline{1, n}}\left(\frac{\bar{T}_{j}}{T_{j}}\right)\right]\left|x_{j}\right|_{0} d s \\
& +\sigma^{2} A_{i}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \int_{0}^{\omega} F_{j}\left[\min _{i=\overline{1, n}}\left(\frac{\bar{F}_{j}}{F_{j}}\right)\right] b_{i j}(s)\left|x_{j}\right|_{0} d s \\
& +\sigma^{2} A_{i}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \int_{0}^{\omega} E_{i j} R_{j}\left\{\left[\min _{i=1, n}\left(\frac{\bar{E}_{i j}}{E_{i j}}\right)\right] \times\left(\frac{\bar{R}_{j}}{R_{j}}\right)\right\} c_{i j}(s)\left|x_{j}\right|_{0} d s \\
& +\sigma^{2} A_{i}\left|x_{i}\right|_{0} \sum_{t \leq t_{k}<t+\omega} \lambda_{i k}\left(t_{k}\right)\left|x_{i}\left(t_{k}\right)\right|_{0} \\
& \geq \theta_{1} \times \sigma^{2} A_{i} \omega \alpha_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{a}_{i j} x_{j}^{*}+\theta_{2} \times \sigma^{2} A_{i} \omega \alpha_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{b}_{i j} x_{j}^{*} \\
& +\theta_{3} \times \sigma^{2} A_{i} \omega \alpha_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{c}_{i j} x_{j}^{*}+1 \times \sigma^{2} A_{i} \omega \alpha_{2}\left|x_{i}\right|_{0} \widehat{\beta}_{i k} x_{i}^{*} \\
& \geq \theta \times \sigma^{2} A_{i} \omega \alpha_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{a}_{i j} x_{j}^{*}+\theta \times \sigma^{2} A_{i} \omega \alpha_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{b}_{i j} x_{j}^{*} \\
& +\theta \times \sigma^{2} A_{i} \omega \alpha_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{c}_{i j} x_{j}^{*} \\
& +\theta \times \sigma^{2} A_{i} \omega \alpha_{2}\left|x_{i}\right|_{0} \widehat{\beta}_{i k} x_{i}^{*} \\
& =\theta A_{i} \omega \sigma^{2} \alpha_{2}\left|x_{i}\right|_{0}\left(\sum_{j=1}^{n}\left(\widehat{a}_{i j}+\widehat{b}_{i j}+\widehat{c}_{i j}\right) x_{j}^{*}+\widehat{\beta}_{i k} x_{i}^{*}\right) \\
& =\left(A_{i} \widehat{r}_{i}\right) \theta \omega \sigma^{2} \alpha_{2}\left|x_{i}\right|_{0} \\
& \geq m_{0} \theta \omega \sigma^{2} \alpha_{2}\left|x_{i}\right|_{0} \\
& \geq\left|x_{i}\right|_{0}, i=1,2, \ldots, n,
\end{aligned}
$$

and thus

$$
\|\Phi x\|=\sum_{i=1}^{n}\left|\left(\Phi_{i} x_{i}\right)\right|_{0} \geq \sum_{i=1}^{n}\left|x_{i}\right|_{0}=\|x\|, \forall x \in K \cap \partial \Omega_{2}
$$

Obviously, $\Omega_{1}$ and $\Omega_{2}$ are open bounded subsets of $C_{\omega}$ with $0 \in \Omega_{1} \subset$ $\bar{\Omega}_{1} \subset \Omega_{2}$. Hence, $\Phi: K \cap\left(\bar{\Omega}_{2} \backslash \Omega_{1}\right) \rightarrow K$ is a completely continuous operator and satisfies condition (a) in Theorem 2.1. By Krasnoselskii's Theorem, there exists a fixed point $x^{*}(\cdot)=\left(x_{1}^{*}(\cdot), x_{2}^{*}(\cdot), \ldots, x_{n}^{*}(\cdot)\right)^{T} \in K \cap\left(\bar{\Omega}_{2} \backslash \Omega_{1}\right)$ such that $x^{*}(\cdot)=\left(\Phi x^{*}\right)(\cdot)$, i.e., $x^{*}$ is a positive $\omega-$ periodic solution of system (1.4). The proof is completed.

### 3.2 The case of sublinear impulse functions

In the case of sublinear impulses we can prove similar results for system (1.4).
Theorem 3.2. Assume that $\left(H_{1}\right)-\left(H_{5}\right)$ hold, assume further that:
$\left(H_{8}\right)$ There exist nonnegative functions $\bar{\lambda}_{i k}, \lambda_{i k} \in C\left(\mathbb{R}^{+}, \mathbb{R}^{+}\right)$such that for all $x \in \mathbb{R}^{+}$,

$$
\bar{\lambda}_{i k}(t) x \leq I_{i k}(t, x) \leq \lambda_{i k}(t) x, i=1,2, \ldots, n, k=1,2, \ldots
$$

$\left(H_{9}\right)$ The linear system

$$
\sum_{j=1}^{n}\left(\widehat{a}_{i j}+\widehat{b}_{i j}+\widehat{c}_{i j}\right) x_{j}=\widehat{r}_{i}, i=1,2, \ldots, n, k=1,2, \ldots
$$

possesses a unique positive solution. Then, system (1.4) possesses at least one positive $\omega$-periodic solution.

Proof. To prove that $\Phi: K \rightarrow K$ is completely continuous is similar to the corresponding proof in Lemma 3.2. We only need to prove (a) in Theorem 2.1. Let

$$
x^{*}=\left(x_{1}^{*}, x_{2}^{*}, \ldots, x_{n}^{*}\right)^{T}
$$

with $x_{i}^{*}>0, i=1,2, \ldots, n$, be a positive solution of (1.12). Set

$$
\begin{aligned}
& \widetilde{m}_{0}=\min \left\{\min _{1 \leq i \leq n}\left\{\widehat{r}_{i} A_{i}\right\}, \min _{1 \leq i \leq n}\left\{A_{i} \widehat{\beta}_{i k}\right\}\right\} \\
& \widetilde{M}_{0}=\max \left\{\max _{1 \leq i \leq n}\left\{\widehat{r}_{i} B_{i}\right\}, \max _{1 \leq i \leq n}\left\{B_{i} \widehat{\beta}_{i k}\right\}\right\}
\end{aligned}
$$

Choose a constant $\widetilde{M} \geq \widetilde{M}_{0}$ such that $0<\frac{1-\widetilde{M} \omega}{\widetilde{M} \omega}<1$ where $0<\widetilde{M} \omega<1$.
Let $\eta_{1}=\frac{1-\widetilde{M} \omega}{\widetilde{M} \omega}$ and

$$
\widehat{\Omega}_{1}=\left\{x(t)=\left(x_{1}(t), x_{2}(t), \ldots, x_{n}(t)\right)^{T} \in C_{\omega}:\left|x_{i}\right|_{0}<\eta_{1} x_{i}^{*}, i=1,2, \ldots, n\right\} .
$$

If $x \in K \cap \partial \widehat{\Omega}_{1}$, then

$$
\sigma\left|x_{i}\right|_{0} \leq x_{i}(t) \leq\left|x_{i}\right|_{0}=\eta_{1} x_{i}^{*}, i=1,2, \ldots, n
$$

and

$$
\begin{aligned}
\left(\Phi_{i} x\right)(t) \leq & B_{i} \int_{0}^{\omega}\left\{\left[x_{i}(s) \sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)\right.\right. \\
& +x_{i}(s) \sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right) \\
& +x_{i}(s) \sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z) d z\right] d s \\
& \left.+\sum_{t \leq t_{k}<t+\omega} I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right)\right\} \\
\leq & B_{i} \int_{0}^{\omega}\left|x_{i}\right|_{0} \sum_{j=1}^{n} T_{j} a_{i j}(s)\left|x_{j}\right|_{0} d s+B_{i} \int_{0}^{\omega}\left|x_{i}\right|_{0} \sum_{j=1}^{n} F_{j} b_{i j}(s)\left|x_{j}\right|_{0} d s \\
& +B_{i} \int_{0}^{\omega}\left|x_{i}\right|_{0} \sum_{j=1}^{n} R_{j} E_{i j} c_{i j}(s)\left|x_{j}\right|_{0} d s+B_{i}\left|x_{i}\right|_{0} \sum_{t \leq t_{k}<t+\omega} \lambda_{i}\left(t_{k}\right)\left|x_{i}\right|_{0} \\
\leq & \eta_{1} B_{i} \omega\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{a}_{i j} x_{j}^{*}+\eta_{1} B_{i} \omega\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{b}_{i j} x_{j}^{*} \\
& +\eta_{1} B_{i} \omega\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{c}_{i j} x_{j}^{*}+B_{i} \omega \widehat{\beta}_{i k}\left|x_{i}\right|_{0} \\
= & \eta_{1} B_{i} \omega\left|x_{i}\right|_{0}\left\{\sum_{j=1}^{n}\left(\widehat{a}_{i j}+\widehat{b}_{i j}+\widehat{c}_{i j}\right) x_{j}^{*}\right\}+B_{i} \omega \widehat{\beta}_{i k}\left|x_{i}\right|_{0} \\
= & \omega\left(B_{i} \widehat{r}_{i}\right) \eta_{1}\left|x_{i}\right|_{0}+\omega\left(B_{i} \widehat{\beta}_{i k}\right)\left|x_{i}\right|_{0} \\
\leq & \eta_{1} \widetilde{M_{0}} \omega\left|x_{i}\right|_{0}+\widetilde{M}_{0} \omega \mid x_{0}, \quad i=1,2, \ldots, n \\
& n
\end{aligned}
$$

Hence for any $x \in K \cap \partial \widehat{\Omega}_{1}$

$$
\|\Phi x\|=\sum_{i=1}^{n}\left|\left(\Phi_{i} x\right)\right|_{0} \leq \sum_{i=1}^{n}\left|x_{i}\right|_{0}=\|x\|
$$

On the other hand, choose $0<\widetilde{m} \leq \widetilde{m}_{0}$ such that $\frac{1-\sigma \widetilde{m} \theta \omega}{\sigma^{2} \widetilde{m} \theta \omega}>1$ where
$0<\sigma \widetilde{m} \theta \omega<1$. Let $\eta_{2}=\frac{1-\sigma \widetilde{m} \theta \omega}{\sigma^{2} \widetilde{m} \theta \omega}$ and

$$
\widehat{\Omega}_{2}=\left\{x \in C_{\omega}:\left|x_{i}\right|_{0}<\eta_{2} x_{i}^{*}, i=1,2, \ldots, n\right\}
$$

If $x \in K \cap \partial \widehat{\Omega}_{2}$, then $\sigma\left|x_{i}\right|_{0} \leq x_{i}(t) \leq\left|x_{i}\right|_{0}=\eta_{2} x_{i}^{*}, i=1,2, \ldots, n$, and, consequently

$$
\begin{aligned}
\left(\Phi_{i} x\right)(t) \geq & A_{i} \int_{0}^{\omega} x_{i}(s)\left\{\sum_{j=1}^{n} a_{i j}(s) h_{j}\left(x_{j}(s)\right)+\sum_{j=1}^{n} b_{i j}(s) f_{j}\left(x_{j}\left(s-\tau_{i j}(s)\right)\right)\right. \\
& +\sum_{j=1}^{n} c_{i j}(s) \int_{-\infty}^{s} D_{i j}(s, z) g_{j}\left(x_{j}(z) d z\right\} d s \\
& +\sum_{t \leq t_{k}<t+\omega} G_{i}\left(t, t_{k}\right) I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right) \\
\geq & \sigma^{2} A_{i}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \int_{0}^{\omega} a_{i j}(s) T_{j}\left[\min _{j=\overline{1, n}}\left(\frac{\bar{T}_{j}}{T_{j}}\right)\right]\left|x_{j}\right|_{0} d s \\
& +\sigma^{2} A_{i}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \int_{0}^{\omega} F_{j}\left[\min _{i=\overline{1, n}}\left(\frac{\bar{F}_{j}}{F_{j}}\right)\right] b_{i j}(s)\left|x_{j}\right|_{0} d s \\
& +\sigma^{2} A_{i}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \int_{0}^{\omega} E_{i j} R_{j}\left\{\left[\min _{i=\overline{1, n}}\left(\frac{\bar{E}_{i j}}{E_{i j}}\right)\right] \times\left(\frac{\bar{R}_{j}}{R_{j}}\right)\right\} c_{i j}(s)\left|x_{j}\right|_{0} d s \\
& +\sigma A_{i} \sum_{t \leq t_{k}<t+\omega} \lambda_{i k}\left(t_{k}\right)\left|x_{i}\left(t_{k}\right)\right|_{0} \\
\geq & \theta_{1} \times \sigma^{2} A_{i} \omega \eta_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{a}_{i j} x_{j}^{*}+\theta_{2} \times \sigma^{2} A_{i} \omega \eta_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{b}_{i j} x_{j}^{*} \\
& +\theta_{3} \times \sigma^{2} A_{i} \omega \eta_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{c}_{i j} x_{j}^{*}+1 \times \sigma A_{i} \omega\left|x_{i}\right|_{0} \widehat{\beta}_{i k}
\end{aligned}
$$

$$
\begin{aligned}
\geq & \theta \times \sigma^{2} A_{i} \omega \eta_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{a}_{i j} x_{j}^{*}+\theta \times \sigma^{2} A_{i} \omega \eta_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{b}_{i j} x_{j}^{*} \\
& +\theta \times \sigma^{2} A_{i} \omega \eta_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n} \widehat{c}_{i j} x_{j}^{*} \\
& +\theta \times \sigma A_{i} \omega\left|x_{i}\right|_{0} \widehat{\beta}_{i k} \\
= & \theta A_{i} \omega \sigma^{2} \eta_{2}\left|x_{i}\right|_{0} \sum_{j=1}^{n}\left(\widehat{a}_{i j}+\widehat{b}_{i j}+\widehat{c}_{i j}\right) x_{j}^{*} \\
& +\theta \times \sigma\left(A_{i} \widehat{\beta}_{i k}\right) \omega\left|x_{i}\right|_{0} \\
= & \left(A_{i} \widehat{r}_{i}\right) \theta \omega \sigma^{2} \eta_{2}\left|x_{i}\right|_{0}+\left(A_{i} \widehat{\beta}_{i k}\right) \omega \theta \sigma\left|x_{i}\right|_{0} \\
\geq & \widetilde{m}_{0} \theta \omega \sigma^{2} \eta_{2}\left|x_{i}\right|_{0}+\widetilde{m}_{0} \theta \omega \sigma\left|x_{i}\right|_{0} \\
\geq & \left|x_{i}\right|_{0}, i=1,2, \ldots, n,
\end{aligned}
$$

and therefore

$$
\|\Phi x\|=\sum_{i=1}^{n}\left|\left(\Phi_{i} x\right)\right|_{0} \geq \sum_{i=1}^{n}\left|x_{i}\right|_{0}=\|x\|, \forall x \in K \cap \partial \widehat{\Omega}_{2}
$$

Hence, $\Phi: K \cap\left(\widehat{\widehat{\Omega}}_{2} \backslash \widehat{\Omega}_{1}\right) \rightarrow K$ is a completely continuous operator and satisfies condition (a) in Theorem 2.1. Consequently, there exists a fixed point $x^{*}(\cdot)=\left(x_{1}^{*}(\cdot), x_{2}^{*}(\cdot), \ldots, x_{n}^{*}(\cdot)\right)^{T} \in K \cap\left(\overline{\widehat{\Omega}}_{2} \backslash \widehat{\Omega}_{1}\right)$ such that $x^{*}(\cdot)=\left(\Phi x^{*}\right)(\cdot)$. Therefore, system (1.4) has a positive $\omega$-periodic solution. The proof is completed.

Remark 3.1: The method applied in this paper can be used to treat a more general nonlinear impulse function. For instance, assuming that $I_{i k}(\cdot, x)$ satisfies
$\left(H_{10}\right)$ There exist nonnegative functions $\bar{\lambda}_{i k}, \lambda_{i k} \in C\left(\mathbb{R}^{+}, \mathbb{R}^{+}\right)$and $\digamma \in$ $C\left(\mathbb{R}_{+}^{n}, \mathbb{R}_{+}^{n}\right)$ such that for all $x \in \mathbb{R}_{+}^{n}$,

$$
\bar{\lambda}_{i k}(t) \digamma(\|x\|) \leq I_{i k}(t, x) \leq \lambda_{i k}(t) \digamma(\|x\|), i=1,2, \ldots, n, k=1,2, \ldots
$$

Note that $\left(H_{6}\right)$ and $\left(H_{8}\right)$ are special cases of condition $\left(H_{10}\right)$ which has been used in $[6,7,8]$.

Remark 3.2: Notice that when $a_{i j}=0$ in the second term on the right hand side of (1.4), $I_{i k}\left(t_{k}, x\left(t_{k}\right)\right)=0, f_{j}\left(x_{j}\right)=0$, and $g_{j}\left(x_{j}\right)=x_{j}$, we can easily derive the corresponding results in [25]. Therefore, the results presented in this paper improve and extend the main results in Ref. [25].

## 4 An example

In this section, we analyze an example to show the effectiveness of our result.

Example 4.1. Let us consider the following system:

$$
\begin{align*}
x_{i}^{\prime}(t)= & x_{i}(t)\left\{r_{i}(t)-\sum_{j=1}^{2} b_{i j}(t) f_{j}\left(x_{j}\left(t-\tau_{i j}(t)\right)\right)\right. \\
& -\sum_{j=1}^{2} c_{i j}(t) \int_{-\infty}^{t} D_{i j}(t, s) g_{j}\left(x_{j}(s) d s\right\},  \tag{4.1}\\
t \neq & t_{k}=\frac{1}{2} k \pi, k \in \mathbb{Z}^{+}, t>0 \\
x_{i}\left(t_{k}^{+}\right)-x_{i}\left(t_{k}^{-}\right)= & I_{i k}\left(t_{k}, x_{i}\left(t_{k}\right)\right)=\frac{x_{i}^{2}\left(t_{k}\right)}{\cos \left(2 t_{k}\right)}\left(\left|\sin x_{i}\left(t_{k}\right)\right|+1\right), \tag{4.2}
\end{align*}
$$

for $i=1,2$. This model corresponds to system (1.4) when $n=2, \omega=2 \pi$. Let

$$
r_{1}(t)=\frac{1}{2}(1+\sin 2 t), r_{2}(t)=\frac{1}{3}(1+\cos 2 t),
$$

and $\tau_{i j} \in\left(\mathbb{R}^{+}, \mathbb{R}^{+}\right)$be arbitrary continuous functions which satisfy $\tau_{i j}(t+\omega)=$ $\tau_{i j}(t), i=1,2$.
We then have

$$
\begin{aligned}
& \widehat{r}_{1}=\frac{1}{\omega} \int_{0}^{\omega} r_{1}(t) d t=\frac{1}{4 \pi} \int_{0}^{2 \pi}(1+\sin 2 t) d t=\frac{1}{2} \\
& \widehat{r}_{2}=\frac{1}{\omega} \int_{0}^{\omega} r_{2}(t) d t=\frac{1}{6 \pi} \int_{0}^{2 \pi}(1+\cos 2 t) d t=\frac{1}{3}
\end{aligned}
$$

and it is straightforward to check that $A_{i} \leq G_{i}(t, s) \leq B_{i}$, for $i=1,2$, where

$$
G_{i}(t, s)=\frac{1}{1-e^{-\widehat{r}_{i} \omega}} \exp \left(-\int_{t}^{s} r_{i}(\xi) d \xi\right), i=1,2
$$

and

$$
\begin{array}{rlrl}
A_{1} & :=\frac{e^{-\widehat{r}_{1} \omega}}{1-e^{-\widehat{r}_{1} \omega}}=\frac{e^{-\pi}}{1-e^{-\pi}}, & A_{2}:=\frac{e^{-\widehat{r}_{2} \omega}}{1-e^{-\widehat{r}_{2} \omega}}=\frac{e^{-\frac{2 \pi}{3}}}{1-e^{-\frac{2 \pi}{3}}} \\
B_{1}:=\frac{1}{1-e^{-\widehat{r}_{1} \omega}}=\frac{1}{1-e^{-\pi}}, & B_{2}:=\frac{1}{1-e^{-\widehat{r}_{2} \omega}}=\frac{1}{1-e^{-\frac{2 \pi}{3}}}
\end{array}
$$

Let

$$
\begin{aligned}
f_{j}(x) & =\frac{x}{2} e^{(\sin x)+1}, \quad g_{j}(x)=\frac{x}{3}\left(e^{|\cos x|}+1\right), \\
I_{i}(t, x) & =\frac{\pi x^{2}}{\cos 2 t}(|\sin x|+1), \quad i, j=1,2
\end{aligned}
$$

and

$$
\begin{aligned}
D_{i j}(t, s)=e^{s-t}(\cos t+2) \times \frac{3}{2}, & i \neq j=1,2 \\
D_{i j}(t, s)=e^{s-t}(\sin t+4) \times \frac{1}{3}, & i=j=1,2
\end{aligned}
$$

Since $|\sin x| \leq 1$ and $|\cos x| \leq 1$ for $x \in \mathbb{R}^{+}$, we have

$$
\begin{aligned}
& \bar{F}_{j} x \leq f_{j}(x) \leq F_{j} x, \\
& \bar{R}_{j} x \leq g_{j}(x) \leq R_{j} x,
\end{aligned}
$$

and

$$
\begin{aligned}
\frac{3}{2} & =\bar{E}_{i j} \leq \int_{-\infty}^{t} D_{i j}(t, s) d s \leq E_{i j}=\frac{9}{2}, i \neq j \\
1 & =\bar{E}_{i j} \leq \int_{-\infty}^{t} D_{i j}(t, s) d s \leq E_{i j}=\frac{5}{3}, i=j
\end{aligned}
$$

and

$$
\bar{\lambda}_{i}(t) x^{2} \leq I_{i}(t, x) \leq \lambda_{i}(t) x^{2}
$$

where $F_{j}=\frac{e^{2}}{2}, \bar{F}_{j}=\frac{1}{2}, R_{j}=\frac{e+1}{3}, \bar{R}_{j}=\frac{2}{3}, \bar{\lambda}_{i}(t)=\frac{\pi}{\cos 2 t}, \lambda_{i}(t)=$ $\frac{2 \pi}{\cos 2 t}, i, j=1,2$.

We can choose $b_{11}(t)=\frac{(1+\cos 2 t)}{3 F_{1}}, b_{12}(t)=\frac{(1+\sin 2 t)}{2 F_{2}}, b_{21}(t)=0, b_{22}(t)=$ $\cos (4 t)$, which implies

$$
\begin{aligned}
& \widehat{b}_{11}=\frac{F_{1}}{\omega} \int_{0}^{\omega} b_{11}(s) d s=\frac{1}{3}, \widehat{b}_{12}=\frac{F_{2}}{\omega} \int_{0}^{\omega} b_{12}(s) d s=\frac{1}{2} \\
& \widehat{b}_{21}=\frac{F_{1}}{\omega} \int_{0}^{\omega} b_{21}(s) d s=0, \widehat{b}_{22}=\frac{F_{2}}{\omega} \int_{0}^{\omega} b_{22}(s) d s=0
\end{aligned}
$$

and also choose $c_{11}(t)=0, c_{12}(t)=\frac{2(1+\cos 4 t)}{E_{1} R_{12}}, c_{21}(t)=\frac{(1+\sin 2 t)}{E_{2} R_{21}}, c_{22}(t)=$ $\frac{(1+\sin 2 t)}{2 E_{2} R_{22}}$, obtaining

$$
\begin{aligned}
& \widehat{c}_{11}=\frac{E_{1} R_{11}}{\omega} \int_{0}^{\omega} c_{11}(s) d s=0, \widehat{c}_{12}=\frac{E_{1} R_{12}}{\omega} \int_{0}^{\omega} c_{12}(s) d s=2 \\
& \widehat{c}_{21}=\frac{E_{2} R_{21}}{\omega} \int_{0}^{\omega} c_{21}(s) d s=1, \widehat{c}_{22}=\frac{E_{2} R_{22}}{\omega} \int_{0}^{\omega} c_{22}(s) d s=\frac{1}{2}
\end{aligned}
$$

Choosing $q=8$, we have

$$
\begin{aligned}
\widehat{\beta}_{i k} & =\frac{1}{\omega} \sum_{0 \leq t_{k}<\omega} \lambda_{i k}\left(t_{k}\right)=\frac{1}{2 \pi} \sum_{k=1}^{q} \frac{2 \pi}{\cos 2 t_{k}} \\
& =\frac{1}{2} \sum_{k=1}^{8} \frac{2}{\cos 2\left(\frac{1}{2} k \pi\right)}=1, i=1,2
\end{aligned}
$$

Moreover, it is easy to verify that the corresponding system of nonlinear equation (4.1),

$$
\left\{\begin{array}{l}
\sum_{j=1}^{2}\left(\widehat{b}_{1 j}+\widehat{c}_{1 j}\right) x_{j}+\widehat{\beta}_{1 k} x_{1}=\widehat{r}_{1} \\
\sum_{j=1}^{2}\left(\widehat{b}_{2 j}+\widehat{c}_{2 j}\right) x_{j}+\widehat{\beta}_{2 k} x_{2}=\widehat{r}_{2},
\end{array}\right.
$$

has a unique positive solution $x=\left(x_{1}, x_{2}\right)=\left(\frac{1}{6}, \frac{1}{9}\right)$. It is straightforward to show that all conditions of Theorem 3.1 are fulfilled. Hence, we conclude that this system possesses at least one positive $2 \pi$-periodic solution.

Acknowledgements. The research of T.C. has been partially supported by FEDER and Ministerio de Ciencia, Innovación y Universidades of Spain (Grant PGC2018-096540-B-I00), and Junta de Andalucía, Spain (Grant US-1254251).

## References

[1] M. Benhadri, T. Caraballo, H. Zeghdoudi, Existence of periodic positive solutions to nonlinear Lotka-Volterra competition systems, Opuscula Math., 40 (2020), no.3, 341-360.
[2] D. D. Bainov, P. S. Simeonov, Impulsive differential equations, Periodic Solutions and Applications, Longman Scientificand Technical, 1993.
[3] D. D. Bainov and P. S. Simeonov, Impulsive differential equations, vol. 28, World Scientific, Singapore, 1995.
[4] F. D. Chen, Periodic solution and almost periodic solution for a delay multispecies logarithmic population model, Appl. Math. Comput., 171 (2005), 760-770.
[5] S. Chen, T. Wang, J. Zhang, Positive periodic solution for non -autonomous competition Lotka-Volterra patch system with time delay, Nonlinear Anal. Real World Appl., 5 (2004), 409-419.
[6] A. Chen and Y. Chen, Existence of solutions to anti-periodic boundary value problem for nonlinear fractional differential equations with impulses, Advances in Difference Equations, 2011(2011), Article ID 915689, 17 pages.
[7] Y. Chen and B. Qin, Multiple positive solutions for first-order impulsive singular integro-differential equations on the half line in a Banach space, Boundary value problems, (2013), 2013:69.
[8] D. Guo, Existence of two positive solutions for a class of third-order impulsive singular integro-differential equations on the half-line in Banach spaces, Boundary Value Problems, (2016), 2016:70.
[9] K. Gopalsamy ,Global asymptotical stability in a periodic Lotka-Volterra system, J. Aust. Math. Soc. Ser. B, 29 (1985), 66-72.
[10] D. J. Guo, Positive solutions to nonlinear operator equations and their applications to nonlinear integral equations, Advances in Mathematics, 13 (1984), no. 4, 294-310, (Chinese).
[11] D. J. Guo, Nonlinear functional analysis, Shandong science and technology press, Shandong, China, 2001, (in Chinese).
[12] D. Hu, Z. Zhang, Four positive periodic solutions to a Lotka-Volterra cooperative system with harvesting terms, Nonlinear Anal. Real World Appl., 11 (2010), 1115-1121.
[13] M. A. Krasnoselskii, Positive solutions of operator equations, Noordhoff, Groningen, 1964.
[14] Y. Kuang, Delay differential equation with application in population dynamics, Academic Press, Boston, 1933.
[15] Y. K. Li, Y. Kuang, Periodic solutions of periodic delay Lotka-Volterra equations and systems, J. Math. Anal. Appl., 255 (2001), no.1, 260-280.
[16] Y.K. Li, L. F. Zhu, Existence of periodic solutions of discrete Lotka-Volterra systems with delays, Bulletin of the Institute of Mathematics, Academia Sinica, 33 (2005), no. 4, 369-380.
[17] Z. Luo, L. Luo., Existence of positive periodic solutions for periodic neutral Lotka-Volterra system with distributed delays and impulses, International Journal of Differential Equations, 2013 (2013), ID 890281, 13 pages.
[18] V. Lakshmikantham, D. D. Bainov, P. S. Simeonov, Theory of impulsive differential equations, vol. 6, World Scientific, Singapore, 1989.
[19] A. M. Samoilenko, N.A. Perestyuk, Impulsive differential equations, World Scientific, Singapore, 1995.
[20] Z. Yang, J. Cao, Positive periodic solutions of neutral Lotka-Volterra system with periodic delays, Appl. Math. Comput., 149 (2004), no. 3, 661-687.
[21] Y. K. Li, Periodic solutions for delay Lotka-Volterra competition systems, J. Math. Anal. Appl., 246 (2000), 230-244.
[22] G. Lin, Y. Hong, Periodic solution in nonautonomous predator-prey system with delays, Nonlinear Anal. Real World Appl., 10 (2009), 1589-1600.
[23] S. Lu, On the existence of positive periodic solutions to a Lotka Volterra cooperative population model with multiple delays, Nonlinear Anal., 68 (2008), 1746-1753.
[24] X. Lv, S. P. Lu, P. Yan, Existence and global attractivity of positive periodic solutions of Lotka-Volterra predator-prey systems with deviating arguments, Nonlinear Anal. Real World Appl., 11 (2010), 574-583.
[25] X. H. Tang, X. Zhou, On positive periodic solution of Lotka-Volterra competition systems with deviating arguments, Proc. Am. Math. Soc., 134 (2006), 2967-2974.
[26] X. H. Tang, D. M. Cao, X. F. Zhou, Global attractivity of positive periodic solution to periodic Lotka-Volterra competition systems with pure delay, J. Differential Equations, 228 (2006), 580-610.
[27] S. T. Zavalishchin, A. N. Sesekin, Dynamic impulse systems, Kluwer Academic Publishers, Dordrecht, The Netherlands, 1997.
[28] G. Zhang, S. S. Cheng, Positive periodic solutions of coupled delay differential systems depending on two parameters, Taiwan. Math. J., 8 (2004), 639-652.
[29] H. Y. Zhao, L. Sun, Periodic oscillatory and global attractivity for chemostat model involving distributed delays, Nonlinear Anal. Real World Appl., 7 (2006), 385-394.
[30] D. Zang, W. Ding , M. Zhu, Existence of positive periodic solutions of competitor competitor mutualist Lotka-Volterra systems with infinite delays, J. Syst. Sci. Complex, 28 (2015), 316-326.

