

Abstract Voronoi diagrams

Rolf Klein*

Universität Bonn, Institut für Informatik I

Abstract

Abstract Voronoi diagrams are a unifying framework that covers many types of concrete Voronoi diagrams. This talk reports on the state of the art, including recent progress.

Introduction

Concrete Voronoi diagrams [1] are mostly defined in terms of sites and distance, and both concepts can vary greatly. Abstract Voronoi diagrams [6] are built on what most concrete diagrams have in common: a system of simple bisecting curves $J(p, q) = J(q, p)$, where p, q are just indices from a set S of n elements. Each curve $J(p, q)$ divides the plane into two domains, $D(p, q)$ and $D(q, p)$. The *abstract Voronoi region* of p with respect to S is defined by

$$VR(p, S) := \bigcap_{q \in S \setminus \{p\}} D(p, q)$$

and the *abstract Voronoi diagram* of S is just the plane minus all Voronoi regions.

An interesting question is what properties to require of the curves $J(p, q)$. They should be as weak as possible for generality, but strong enough to ensure that useful “Voronoi” structures result from the above definitions. It turns out [7] that the following are sufficient.

- (A1) Each curve $J(p, q)$, where $p \neq q$, is unbounded. After stereographic projection to the sphere, it can be completed to a closed Jordan curve through the north pole.

For any three indices p, q, r in S , and $S' := \{p, q, r\}$,

- (A2) each Voronoi region $VR(p, S')$ is path-wise connected,
- (A3) each point of the plane belongs to the closure of a Voronoi region $VR(p, S')$.

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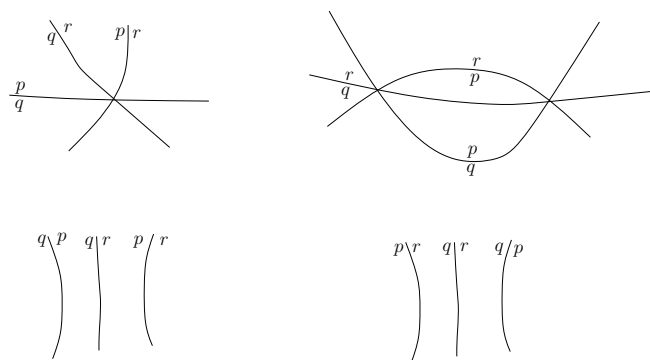


Figure 1: Admissible curve systems

Informally, if the bisecting curves are unbounded and behave decently, and if any triplet $J(p, q), J(p, r), J(q, r)$ is situated as shown in Figure 1, the AVD theory applies.

1 Results

This means that structural results and efficient algorithms become available without further effort [7].

Theorem 1 $V(S)$ is a planar graph of complexity $O(n)$. It can be constructed in an expected number of $O(n \log n)$ many steps.

If we replace Axiom A2 by the more general requirement

- (A2') Each Voronoi region $VR(p, S')$ has at most s connected components

(and assume that any two curves intersect only finitely often), the above result can be generalized as follows [3].

Theorem 2 Abstract Voronoi diagrams with disconnected regions can be computed in an expected number of

$$O\left(s^2 n \sum_{j=3}^n \frac{m_j}{j}\right)$$

steps, where m_j denotes the average number of faces per region in all AVDs of j sites from S .

One can extend the definition of abstract Voronoi diagrams to orders $k > 1$ by defining

$$\text{VR}^k(P, S) := \bigcap_{p \in P, q \in S \setminus P} D(p, q).$$

For order $k = n - 1$, the resulting AVDs are trees [9] of linear size. In the general case the following complexity result holds. Here we assume that all curves are in general position, and that the standard Voronoi-regions are non-empty.

Theorem 3 *The abstract order- k Voronoi diagram $V^k(S)$ has at most $2k(n - k)$ many faces. This bound can be achieved.*

2 Conclusion

Open is the case of closed bisecting curves.

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